

Applications















Electronics handling Pick & Place

Biochemical inspection

Lab Automation Semiconductors Precision Assembly

Features-PGE Series



Multiple ways of installation



Gripping feedbacks



Quick response with short cycle time

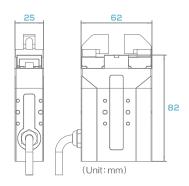
DH-ROBOTICS DH-ROBOTICS

PGE Series

Slim-type parallel grippers

PGE-5

- Precise force control for fragile gripping tasks
- Slim & thin in size, space-saving mounting
- Everything integrated inside, easy-to-use mounting
- Mounting holes on 4 sides, flexible installation
- Gripping feedbacks with drop detection
- Quick response with short cycle time



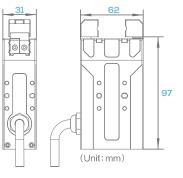
Max payload	0.1 kg*
Opening stroke	0-14 mm
Gripping force	0.8-5 N
Force repeatability	±0.3 N
Weight	0 . 2 kg
Power supply 24	V DC ±10%
Position repeatability	± 0.02 mm
Full-stroke closing time	ne 0.2 s
Ingress protection ratio	ing IP 40
Communication protocols Modbus	I/O RTU(RS 485)



*Related to the shape of object and friction between object and fingertips. The offset of centre of gravity may also influence the payload. Contact DH–Robotics for support if uncertainty remains

PGE-8

- Precise force control for fragile gripping tasks
- Slim & thin in size, space-saving mounting
- Everything integrated inside, easy-to-use mounting
- Mounting holes on 4 sides, flexible installation
- Gripping feedbacks with drop detection
- Quick response with short cycle time



Max payload	0.1 kg*	
Opening stroke	0-14 mm	
Gripping force	2-8 N	
Force repeatability	±0.3 N	
Weight	0.4 kg	
Power supply 24 V	DC ±10%	
Position repeatability ± 0.02 mm		
Full-stroke closing time	0.2 s	
Ingress protection rating	IP 40	
Communication protocols Modbus RT	I /O U(RS 485)	



^{*}Related to the shape of object and friction between object and fingertips. The offset of centre of gravity may also influence the payload. Contact DH–Robotics for support if uncertainty remains

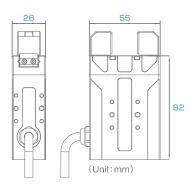
DH-ROBOTICS DH-ROBOTICS

PGE Series

Slim-type parallel grippers

PGE-15

- Precise force control for fragile gripping tasks
- Slim & thin in size, space-saving mounting
- Everything integrated inside, easy-to-use mounting
- Mounting holes on 4 sides, flexible installation
- Gripping feedbacks with drop detection
- Quick response with short cycle time

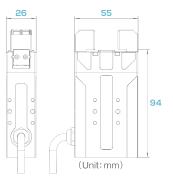


Max payload	0 . 2 kg*
Opening stroke	0-20 mm
Gripping force	6-15 N
Weight	0.2 kg
Power supply 24 \	/ DC ±10%
Position repeatability	± 0.02 mm
Full-stroke closing time	0.3 s
Ingress protection rating	g IP 40
Communication protocols Modbus R	I /O TU(RS 485)



PGE-50

- Precise force control for fragile gripping tasks
- Slim & thin in size, space-saving mounting
- Everything integrated inside, easy-to-use mounting
- Mounting holes on 4 sides, flexible installation
- Gripping feedbacks with drop detection



Max pay l oad	0.5 kg*
Opening stroke	0-20 mm
Gripping force	15-50 N
Weight	0 . 4 kg
Power supply 24 V	√ DC ±10%
Position repeatability	± 0.02 mm
Full-stroke closing time	e 0.3 s
Ingress protection ratin	ig IP 40
Communication protocols Modbus R	I /O TU(RS 485)



^{*}Related to the shape of object and friction between object and fingertips. The offset of centre of gravity may also influence the payload. Contact DH-Robotics for support if uncertainty remains

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