



**End-user**

Educational, Academic, R&D

Industrial

**Weight [kg]**

0.78

0.99

**Max payload [kg]**

pinch grasp

0.83

0.6

power grasp

1.7

2.0

**Voltage [VDC]**

12, 24

24

**Colour**



**Glove**

integrated

interchangeable

**Dimensions [mm]**

width

191

185

length

250

244

thickness

71

83

**Flange interface**

ISO 9409-1-31.5-4-M5

+

+

ISO 9409-1-40-4-M6

+

+

ISO 9409-1-50-4-M6

✓



✓

**Wrist**

fixed

12 pitch pre-sets (0° - 90°)

## Communication protocol

	RS-485	EtherCAT, UDP, Digital I/Os
<b>Software</b>		
 ROS	✓	+
 MATLAB SIMULINK	✓	+
C/C++ API	✓	✓
UR+	✓	✓
Franka App	+	+
<b>Electronic Driver</b>		
	Embedded	External
<b>IP Code</b>		
	—	IP65
<b>Normative compliance</b>		
	—	ISO 12100, ISO/TS 15066, ISO 13849-1/-2, ISO 10210-1/-2, ISO 9409-1-50-4-M6, ISO/TR 20218-1, IEC 60529, IEC 61000-6-2/-6-4

✓ available + on request