



UG630 – Five AxisVertical Machining Centers





Machine Overview

Heidenhain TNC 640 CNC Control

15" Touch Screen Display

15,000 RPM Built-In Type Spindle

38HP CAT40 Big Plus Spindle

40m/min Rapid Traverse Rate X/Y/Z Axis

60 Pocket Automatic Tool Changer

Blum Probe and Tool Setter Package

Coolant Through Spindle Prep – 1000PSI

Roller Cam Zero Backlash Design

X, Y, Z Scales and B, C Rotary Encoders

Precision Hand Scraped Machine Metal to Metal Contact Points for Long Term Accuracy, Vibration Dampening and Extended Machine Life





UG630 - Five Axis – High Speed Vertical Machining Centers



Machine Specifications

X Axis Travel 640 mm (25.1")

Y Axis Travel 520 mm (20.4")

Z Axis Travel 460 mm (18.1")

Distance from Spindle Nose to Table-Top 150 – 610 mm (5.9" – 24.0")

Table Height From Plant Floor 791 mm (31.1")

Table Load Capacity 660 lbs (B-Axis @ 0°) / 440 lbs (B-Axis @ 90°)

Spindle Taper CAT40 (Big Plus)

Spindle Motor 38HP

Spindle Speed 15,000RPM

Spindle Type Built in Motor

Rapid Feedrate (X & Y Axes) 40 m/min (1,574 ipm)

Rapid Feedrate (Z Axis) 40 m/min (1,574 ipm)

Chain Type ATC 60 Pockets

Maximum Tool Diameter with Tool in Adjacent Pocket 75 mm (2.9")

Maximum Tool Diameter with Adjacent Pocket Empty 127 mm (5.0")

Maximum Tool Length from Gage Line 300 mm (11.8")

Maximum Tool Weight 7 kg (15.4 lb)

Tool Taper CAT40 Big Plus

Tool Selection Random

Tool Access Bi-Directional

Total Power Required 3 Phase ±10% 220 V (55 kVA)

Power Supply Frequency 50 / 60 Hz

Axis Guideways Linear Roller Guideway

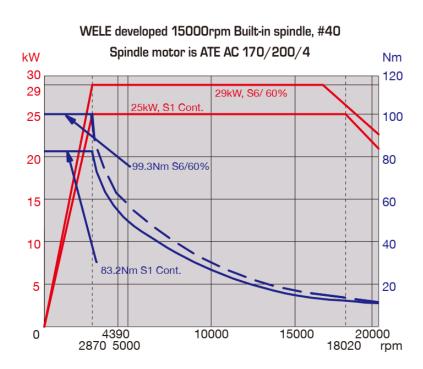












Benefits to Built-In Spindle Design:

G.4 Spindle Balance Specification Achieved as WELE Standard vs G1 Industry Standard – Increased Tool Life and Superior Surface Finish

Reduction in External Connections, Cabling and Wiring

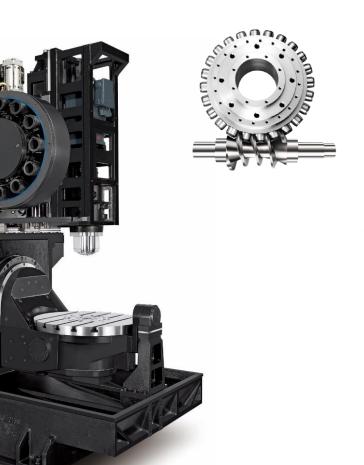
Increased Powerband to High Speed - Increased Torque at Low RPM Range

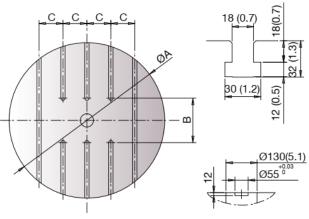
No Motor Coupling to Introduce Outside Vibration



Factory Balance Stand G.4 Specification



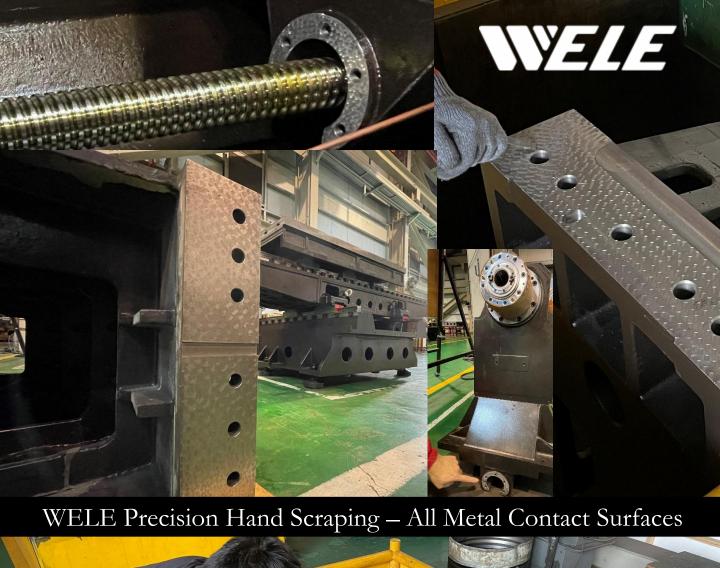




	А	В	С
UG630	650 (25.6)	186 (7.3)	100 (3.9)

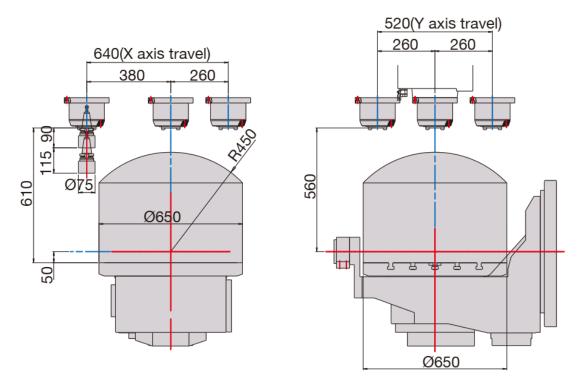
Clamping area	mm/in.	650 / 25.5
Swiveling range of the B-axis	degree	-50 /+110
Rotating range of the C-axis	degree	360
Swiveling speed of the B-axis	rpm	25
Rotating speed of the C-axis	rpm	25
Max. torque of the B-axis	Nm/ft-lb	5,760/4,250
Max. torque of the C-axis	Nm/ft-lb	960/708
Brake torque of the B-axis	Nm/ft-lb	4,490/3,310
Brake torque of the C-axis	Nm/ft-lb	2,570/1,895



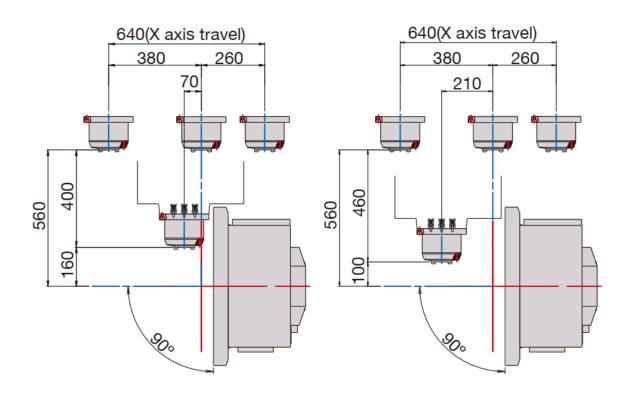




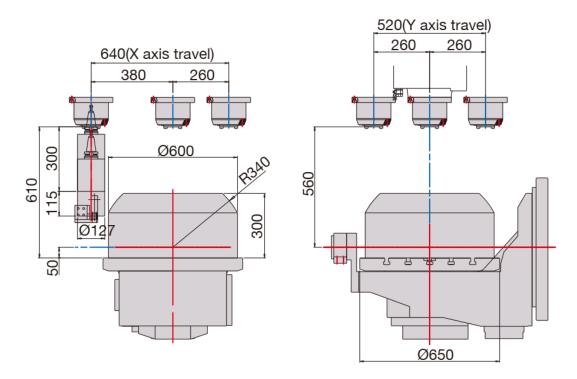




The working envelope area is following the below any condition, 1. When the tool's length(90mm) and diameter (75mm).

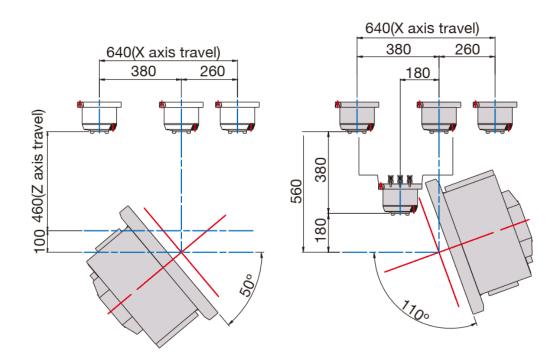






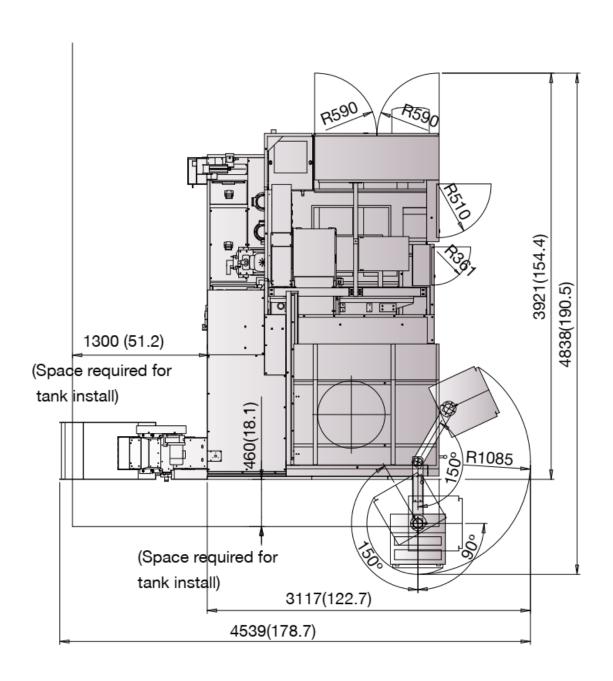
The working envelope area is following the below any condition,

- 1. When the tool's length(300mm) and diameter (127mm).
- 2. The ATLM equipment is installed.



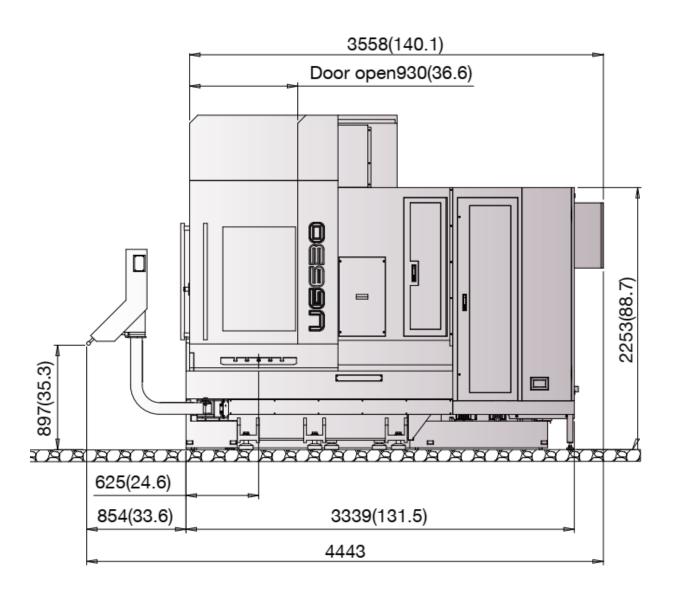


Machine Layout





Machine Layout

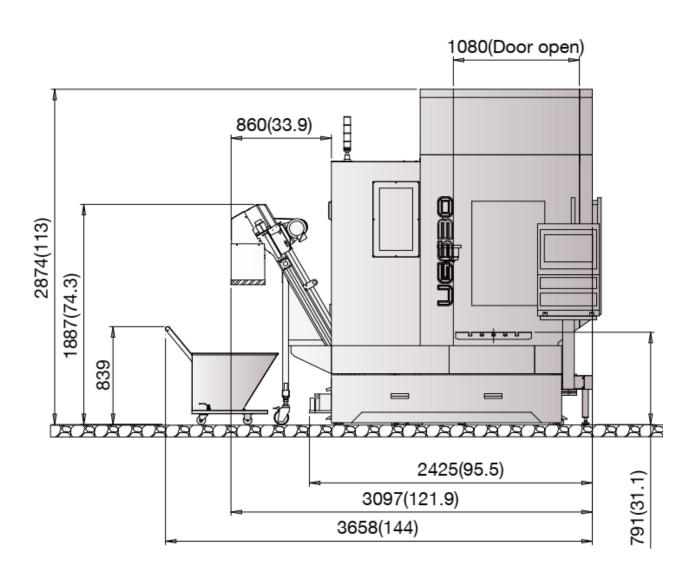


Shipping Dimensions - Reference

Crate #1: 4330mm x 2320mm x 2550mm @ 7,790KGS Crate #2: 4670mm x 1150mm x 2260mm @ 1,150KGS

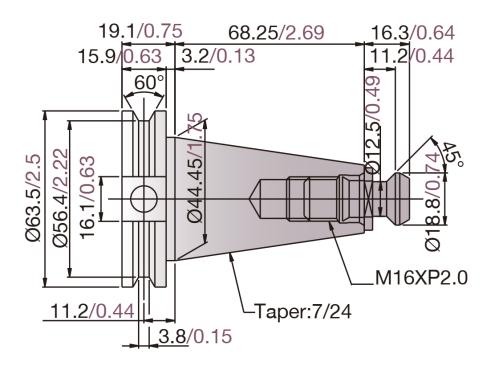


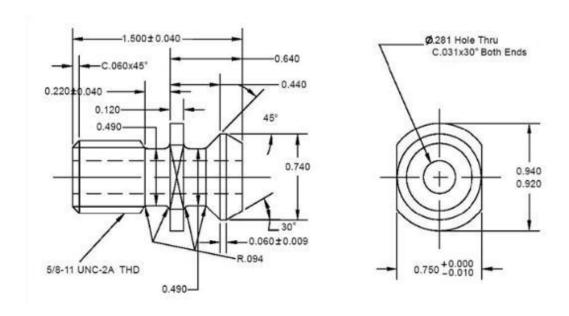
Machine Layout





Retention Knob & Tool Assembly CAT40







	1.0 1.10 17.47.00	
Main computer: MC7522	Processor: Intel Core i7-3 1.7 GHz, dual-core	
	4 GB RAM memory	
Controller unit: CC6106 or	Con Consisting and arread arreaden invents 1 VDD on Ex Det	
CC6108	6 or 8 position and speed encoder inputs 1 VPP or EnDat	
Display: BF750 SSDR 21GB	• 15.1" TFT Solid state disk	
Keyboard TE730	Soliu state uisk	
Reypodiu 1E750	Linear axes 0.1μm	
Input resolution display step	Rotary axes 0.0001°	
	Straight lines in 5 axes	
Interpolation	Straight lines in 3 axes Circle in 3 axes	
	Helical	
	Block processing 0.5ms	
	Position controller 0.2ms	
Cycle time	Speed controller 0.2ms	
	Current controller 0.2ms	
	Linear and nonlinear axis error	
Error compensation	Backlash	
Error compensation	Reversal spikes with circular movements	
	Static friction	
	Sliding friction	
	PLC memory >1GB	
	Program format: statement list	
	PLC cycle time 9 to 30 ms (can be set)	
	PLC inputs 24 Vdc	
Integrated PLC	PLC outputs 24 Vdc	
	Analog inputs ±10 V	
	Analog outputs ±10 V Analog outputs ±10 V	
	• Inputs for thermistors	
	Integrated oscilloscope	
	Trace function	
Commissioning aids for PLC	Table function	
	Log book	
_	Ethernet(1000BaseT)	
Data interfaces	USB 2port	
	HEIDENHAIN conversational language	
Program entry	• ISO	
	 Drilling, tapping with a floating tap holder, rigid tapping Peck drilling, reaming, 	
	boring, counterboring, centering	
Fixed cycles	Milling internal and external threads	
,	Roughing and finishing rectangular and circular pockets	
	Cycles for face milling plane and oblique surfaces	
	Cycles for milling linear and circular slots	
	Hole patterns on circle and line	
	Contour pockets - also contour parallel	
	Contour train	
FK free contour programming	FK free contour programming in HEIDENHAIN conversational format with The support for wealthing a first first project for NC.	
Background programming	graphic support for workpiece drawings not dimensioned for NC	
Axes: 6 control loop	Rotary axis	
·	Synchronized axes	
	Plc axes	
	Position controlled spindle	
Spindle	Spindle orientation	
•	Gear stages	
3-D machining	Motion control with smoothed jerk	
	Programming of cylindrical contours as if in two axes	
Rotary table machining	1 Togramming of cymharical contoars as if in two axes	



	T
	• Mathematical functions =, +, -, *, /, $\sin \alpha$, $\cos \alpha$, angle α from $\sin \alpha$ and $\cos \alpha$,
	• Logical comparisons (=, =/, <, >)
Q parameters programming with variables	Parentheses
a parameters programming with variables	• $\tan \alpha$, arc \sin , arc \cos , arc \tan , an, en, ln, log, absolute value of a number, constant π , negation, truncation before or after decimal point
	Functions for calculating a circle
	Pocket calculator
Drogramming side	Context-sensitive help function for error messages
Programming aids	Graphic support for the programming of cycles
	Comment blocks in the NC program
	Tool radius in the working plane and tool length
Taal aa waa awaati aw	 Radius compensated contour look ahead for up to 99 blocks (M120)
Tool compensation	Three-dimensional tool radius compensation for editing tool data without a
	recalculate an existing program
	Subroutines
Program jumps	Program-section repeat
3 , 1	Calling any program as a subprogram
	Datum shift, rotation, mirroring
Coordinate transformation	Scaling factor (axis specific)
	Tilting the working plane
	Graphical simulation before a program run, even while another program is
	running
Test graphics	Plan view, view in three planes, 3-D view
B - I	Magnification of details
	In the Programming and Editing mode, the contour of the NC blocks is drawn
	on screen while they are being entered (2-D pencil-trace graphics), even while
Programming graphics	another program is running
	Calculation of machining time in the Test Run operating
Machining time	mode
	Display of the current machining time in the Program Run
	operating modes
	 Mid-program startup in any block in the program, returning the tool to the
	calculated nominal position to continue machining
Returning to the contour	Program interruption, contour departure and return
Electronic Handwheels	One HR 510 portable handwheel
Liecti offic Haridwrieers	Superimpose handwheel positioning during program run
Advanced function set 1	Cylinder surface interpolation for rotary table
(standard for 5 axis machine)	Feed rate in mm/min for rotary table
	Tilting the working plane
	Circular interpolation in 3 axes with tilted working plane
Advanced function set 2	3-D tool compensation through surface-normal vectors
(standard for 5 axis machine)	TCPM = Tool Center Point Management
	Tool perpendicular to contour
	Tool radius compensation vertical to the tool direction
	Straight-line interpolation in 5 axes (permit required for export)
	Manual traverse in the active tool-axis system
	X axis: QSY 155F EcoDyn (6.0 kW)
Servo system	• Y axis: QSY 155C EcoDyn (5.7 kW),
	Z axis: QSY 190C EcoDyn (8.9 kW), brake
	A axis: QSY 190C EcoDyn (5.1 kW), brake
	• C axis: QSY 155C EcoDyn (5.1 kW)
	Spindle motor: ATE /15,000