







# CHIRO® HULL CARE TOTAL SOLUTION

# Why SLM?

## **SLM FOCUSES ON COMPACT AND PRACTICAL USE**

We are committed to introduce human-robot collaboration technology, under or above water.





Brochure

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# **Mechatronics Technology for Human & Nature**

Based on High Technology & Manpower, SLM Global develops the eco-friendly product & service to contribute Safety of people & environment.

HIRO

# **SLM Global Hull Cleaning Robot System**

SLM Global is pursuing eco-friendly solutions that benefit people and the environment. We are dedicated to create green solutions and services.

We believe that our hull cleaning robot system CHIRO is one of the most feasible and eco friendly alternatives for "Green" shipping CHIRO provides great performance to meet the requirements of marine businesses.

We are striving to be the most competent and reliable partner to our customers.

# **Paradigm change**

# **Hull Clean** to Hull Care



## 

- Cleaning is recommended at every 3 months
- Leave AF coating intact by gentle brushing
- · Quick cleaning operation (typ. 8 hours)
- · Minimum loss of paint film and the performance of AF paint is maintained
- Minimum paint powder is generated and mostly captured instantly The later the hull is cleaned, the shorter AF paint life can be

## **Problems Caused by Hull Fouling**

Hull fouling is a phenomenon that occurs when a ship is exposed to seawater. Marine organisms adhere to the hull,



forming colonies, and growing along the hull.



· 2 years Hull Cleaning contract with S\*\* shipyard

KC certified

- · Supply contract cleaning robot for GNTP
- Accepted as a member of IMO GIA (Global Industry Alliance) Partners

- Established SLM Global Co., Ltd
- Technology Use Contract (Hull Cleaning Robot Technology, Samsung Heavy Industries)

2018

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**SLM**: History

- Venture Business Certification
- ISO9001 certified
- Prototype of CHIRO completed

2019

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- Successful Sea-trial
- External investment attraction and selection for TIPS program
- Established Busan service factory
- Commercial HC service commenced

2020

Human Respect

**₹**₿

Ħ People Safety

Eco-Friendly

- Supply of CHIRO system to Korean Navy
- · Pacific Ocean Marine Industries Co., Ltd. Hull cleaning robot supply contract
- CE certified





Marine Environment



**Challenges for Divers** 



## **Performance and Specifications**

**Dimension** : 1600 × 900 × 600(mm)

Weight: 250kg

Cleaning Speed: 1 knots (@0.5m/sec)

Power Consumption : 12kw (driven by net power)

Time Required : 8 hours (at the fouling rate of 30 or less)

**Cleanable Area** : at least 90% of the underwater surface of a ship (Up to 2m of RC (radius of curvature))

Brush : controls torque and pressure precisely

**Prevention of Pollution** : pump sucks cleaned dust/debris and collects it through an internal filter.

**Navigation Assistance** : depth-contour autonomous straight driving and free rotation in 360 degrees

### Maximum Depth: 50m

**Operation Personnel**: 2~3 people (driving is easy to learn)

# Front Camera Front LED Lights Steering Wheels Brushes Brushes Driving Wheels Rear Camera Rear LED Lights

## STABLE

- Automated moving and cleaning
- Safe and fast operation
- Streamlined shell
- Highly available under 3 knots currents
- Staying still under powercut

## A EFFICIENT

- Needed only 2 operators
- OPEX reduction
- Scalable on demand
- Modular systems easy to maintenance



Easy to control - instinctive car-like vehicle driving

Vision based real-time remote control

• Full electric within a rugged body

Extra torgue cancellation

CONVENIENT

607

## **CHIRO Operation Concept**



Using Crane, LARS, and Auto shackle, robot loading & unloading.
Operation Room Available



• CHIRO can adjust buoyancy, so diver can attach & separate CHIRO easily.



• With compacting component, CHIRO can operate in the ship on the marine area.

# **Minimum Paint Wear-Out**

- Brush module can move up & down automatically.
- Adjustable brushing pressure and rotation speed



## **Smooth Movement & Coverage wide area**

Tiltable Magnetic-Driving-Wheel
 : In-Wheel Motor Type



# Debris suction and built-in storage

## **Cleaning Debris Filter**

 Brushing and vacuuming take place simultaneously and collect debris swiftly

# **Brushing**

- Easy replacement of brush disks for best result.
- Plate Size : ø350 Circle Type / ø370 / ø380 Circle Type
- Brush Hair Type : ø0.5, ø0.8, ø1.2 ø1.5 (P.P)
- Hybrid (ø1.2 + Grinding Stone)
- Flexible Panel (P.P)



## Brushes for coating area



### Less damaging surface paint

Tested and approved by paint manufacturers





Drivable area of the entire hull surface (cleaning area)



**Cleaning Debris Filter** 





# **Selection of CHIRO Combination**



## **Power Winch / Potable Power & Tether Cable**



## Auto Shackle & LARS (Launching And Recovery System)



## **Operation Room / Operating Console (OP Box)**



## **CHIRO Driving & Operation Program UI**



# **Operation Concept of SLM CHIRO**







- Potable Operating Console Box
- On Board in the sea, the operation is possible using it.



# **CHIFEX - CHIRO Filtering System EXcellence**

## **Performance and Specifications**

Dimension : 2,200× 1,600× 2,000(mm) Weight : 1.5ton Power : 3Ph 220VAC, 10kW Consumable : Diatomite. A few dozen kg for a vessel Processing Capability : 10 ton/hr. (Max. 15 ton/hr.) Separation process : 2-stage continuous processing 1st Stage : up to 500µm (Debris separation by shive screen) 2nd Stage : up to 50µm (Adjustable) Mesh cleansing : Programmable backflush (No needs operation stopping) Filter replacing : No need if not damaged

Waste : Watery mud of paint, bio and diatomite



## **Summary of Test**

Test Item	Unit	Test Result				
		Contam'd Water	Treated Water	Raw Sea water	Removal rate	Test Method (Criteria)
Suspended Particlulate Matter	mg/L	97.20	5.80	3.20	-94%	Standard methods for the examination of ma rine environment (seawater): 2021
TOC	mg/L	13.90	1.85	1.83	-87%	APHA Standard Methods: 2017
DOC	mg/L	1.09	1.64	1.49	50%	APHA Standard Methods: 2017
Cu	ug/L	25.30	7.37	1.05	-71%	APHA Standard Methods: 2017
Zn	ug/L	290.00	43.10	1.86	-85%	APHA Standard Methods: 2017
Fe	ug/L	0.58	0.69	0.31	19%	APHA Standard Methods: 2017
Mn	ug/L	3.47	1.81	0.29	-48%	APHA Standard Methods: 2017
Sb	ug/L	0.14	0.13	0.14	-7%	APHA Standard Methods: 2017
Sn	ug/L	1.50	1.50	1.22	0%	APHA Standard Methods: 2017

# **Operation of CHIRO + CHIFEX**



# Configuration



1st Stage : Collect wastes over 500µm (Disposal on land
 2nd Stage : Purification treatment over 5µm of the wastewater discharge clean water to sea

# **Inspection Robot**

## **Purpose :** To manage the surface of ship and forecast cleaning timing properly



## Inspection Robot – on Boarding

**Dimension**: 727 X 500 X 223(mm) Weight: 30kg (35kg with battery) Speed: 1 knots (@0.5m/sec) Camera: 2EA (Front-top & Bottom) **Operation Distance**: 250m (Installing Mid-Ship, inspection available up to 400m) On-time inspection video, adding mapping, Automatic driving available

### **Total Configuration of Inspection Robot**









Internal

Front

**Operation Console** 

**Tether Cable** 

# HULL CARE SYSTEM - HC database on cloud



- Hull cleaning is viewed managed in online system (visit hullcaresystem.com)
- Cleaning video is popping up at a click on the map
- Special online tool for each CHIRO service vessel



## **Hull Care Total Solution**

- Total solution of hull surface management system
- Keep the history of inspection & cleaning
- To forecast best timing of cleaning
- Detailed recording based on location(parts of ship), and management
- It can support additional special function based on paywall functions
- Additional Plan : Automation of inspection record, combined all of inspection result, etc.





**SLM Products** 







**Hull Care System** 





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