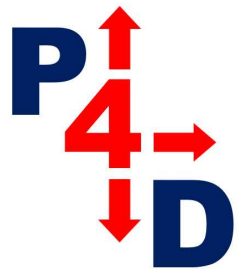


Integrity Management – INS-GPS Concepts

Pipeline Integrity: Inertial Navigation Systems

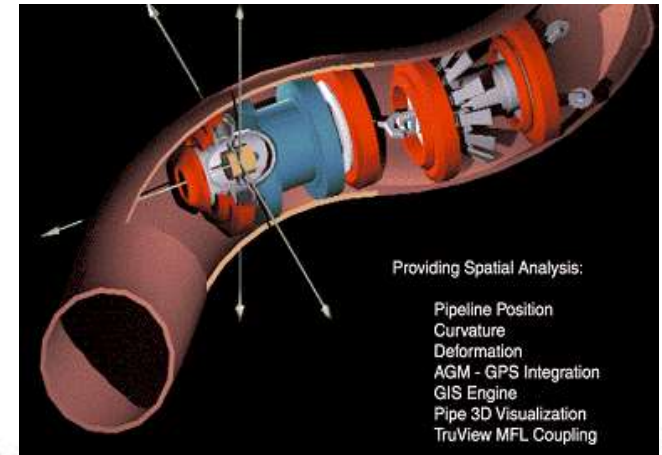
PORTER 4D LLC
Cypress, TX 77429

832 731-0665
281 213-0032

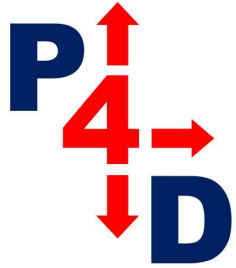


Integrity Management – INS-GPS Concepts

Benefits of INS



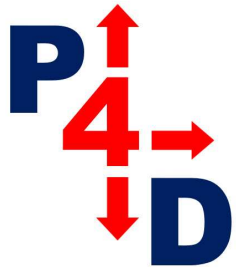
- Continuous **XYZ** pipeline position
 - accurate to +/-1m @ 1σ
 - Direct **GIS** input
 - Accurate and continuous **elevation profile**
 - Accurate spatial feature inventory via **accurate coordinates**.



Integrity Management – INS-GPS Concepts

ILI-INS Baseline -> Benefits

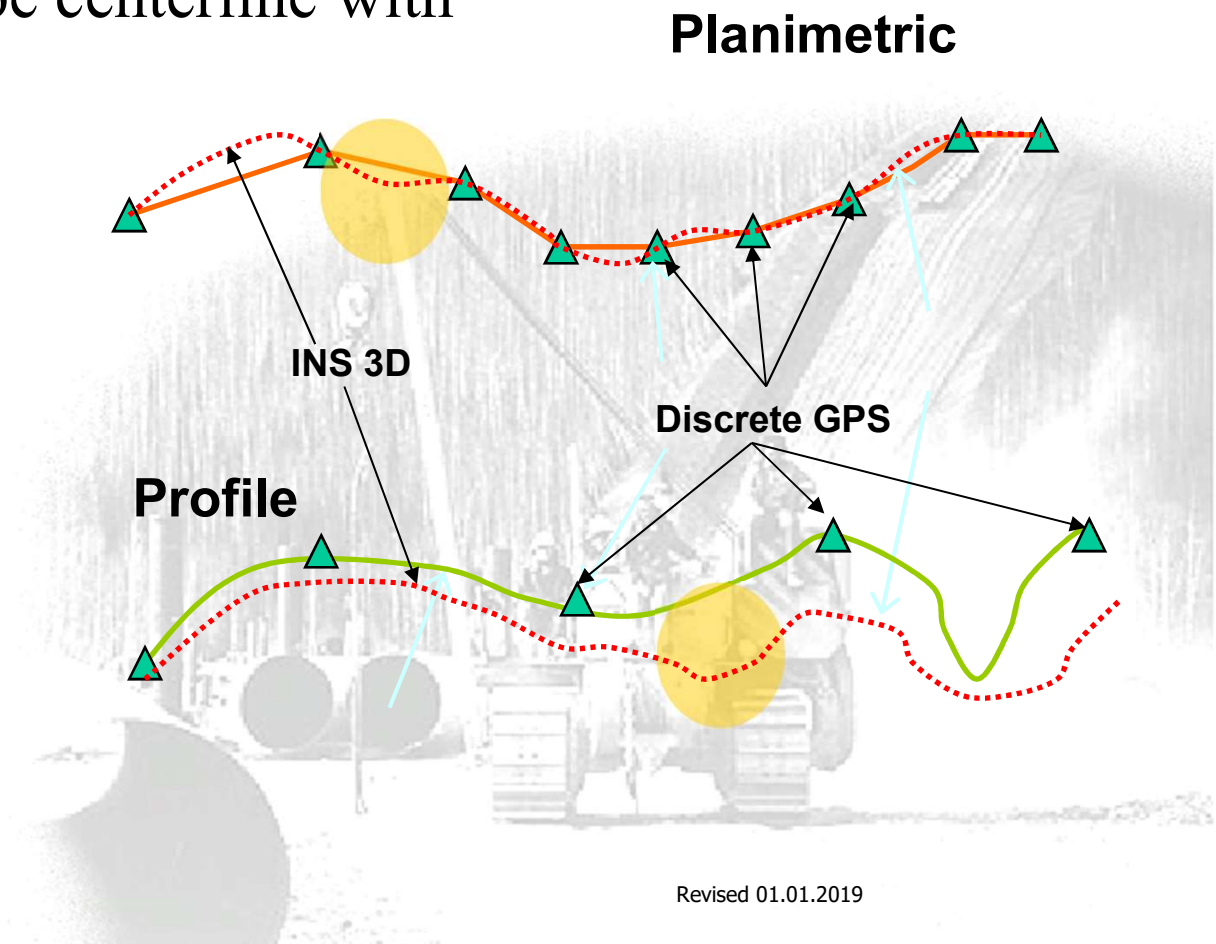
- COMBO ILI
 - INS – 3D Spatial Registration
 - Accurate feature + defect identification
- **Field Operations – accurate location of defects**
- Basis for all subsequent Assessment & Modeling
- Integration Efficiency + Accuracy + Validation
- Integrity Management Platform – Direct Input

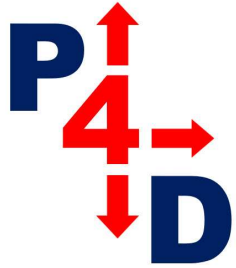


Integrity Management – INS-GPS Concepts

Spatial Registration

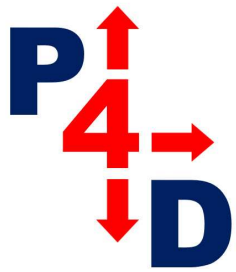
- Registering the pipe centerline with coordinates
- Methods
 - Digitized
 - GPS
 - INS
- Accuracy
 - Mapping Level
 - Engineering
 - RISK





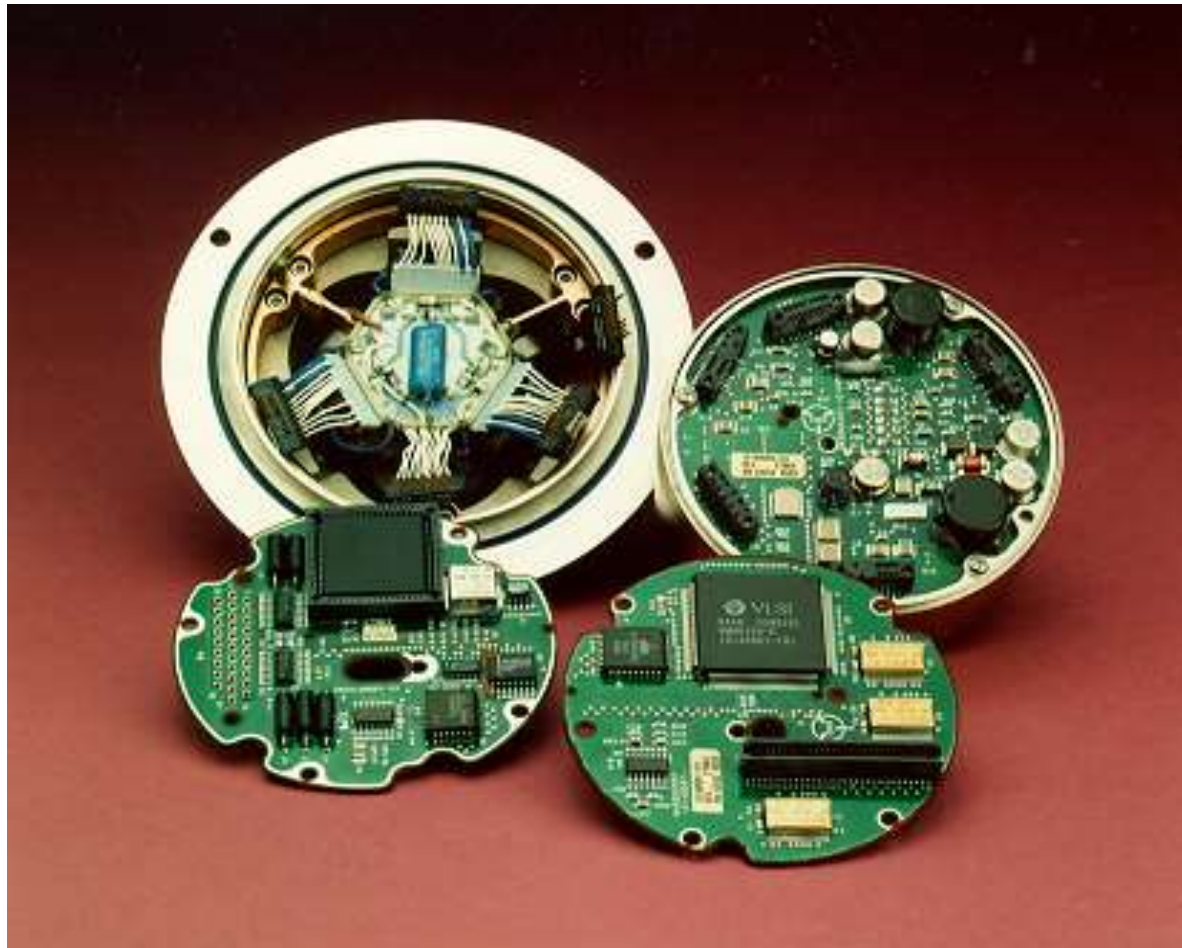
Specific INS Applications

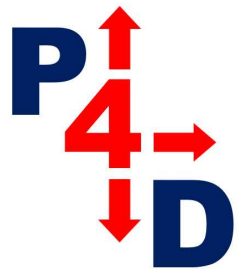
- **Line, Feature Mapping**
- **Geotechnical unstable areas**
- **Frost heave / thaw settlement surveys**
- **Marine free-span detection**
- **River crossing surveys**
- **Dent and buckle discrimination**
- **Temperature / pressure profiling**
- **Pipe joint misalignment**
- **Bend detection and characterization**



Integrity Management – INS-GPS Concepts

IMU Sensor and Electronics





Integrity Management – INS-GPS Concepts

Programs Using the IMU's

Air Force



- JDAM
- WCMD
- JASSM
- GAM
- Range Pods
- MMT

Navy



- JDAM
- JASSM
- ESSM
- Standard Missile
- Vandal Target
- Net Torp
- Tactical Tomahawk
- Harpoon
- JSOW Qualified

Army

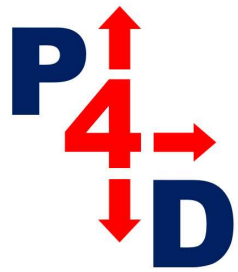


- Stinger
- EFOGM
- GMLRS ATD
- LOSAT
- FMTI

Other

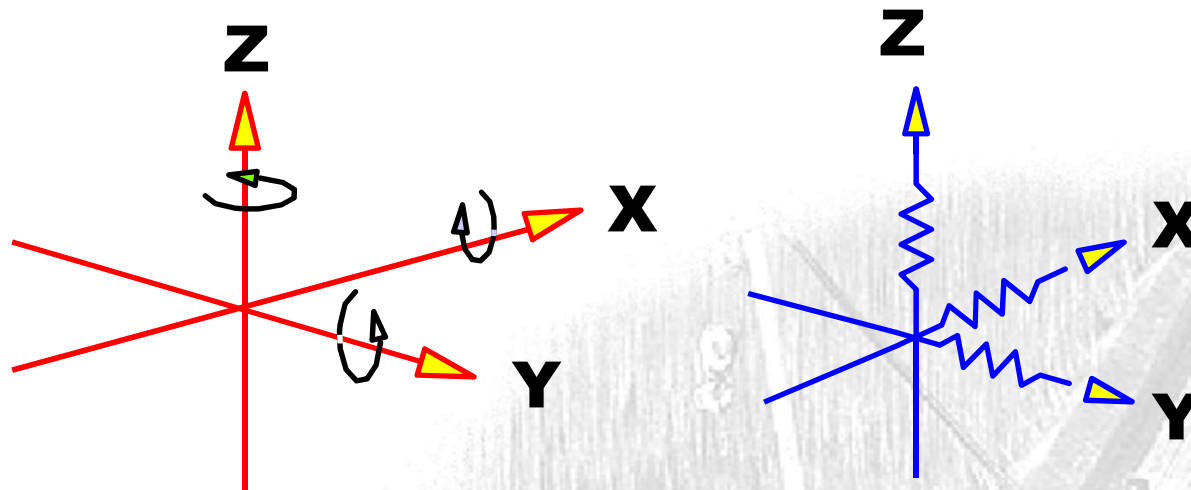


- Tier 3 Minus UAV
- Cypher UAV
- Eagle Eye UAV



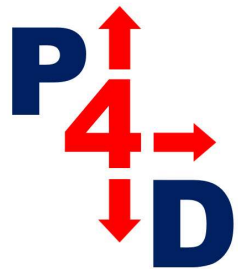
Integrity Management – INS-GPS Concepts

IMU Sensor I/O



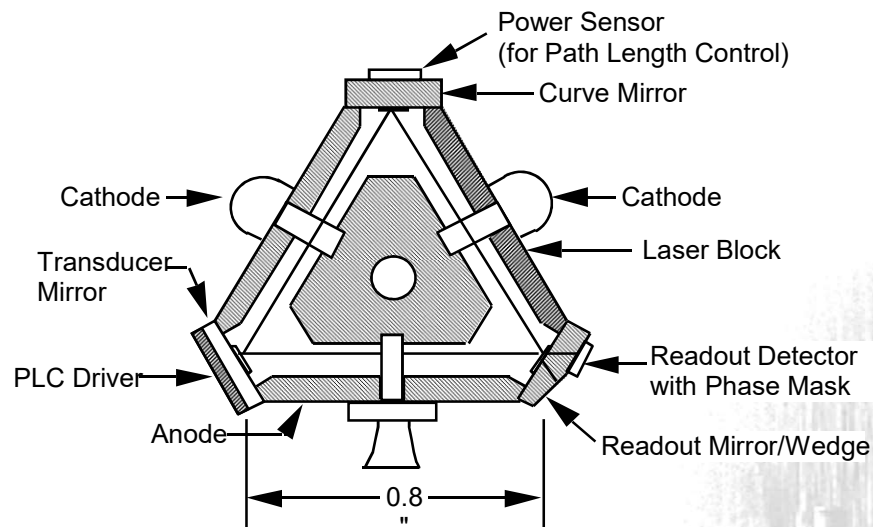
Gyro (RLG/FOG)
Angular Rate ($^{\circ}/\text{sec}$)

Accelerometers
Linear Acceleration (m/sec^2)



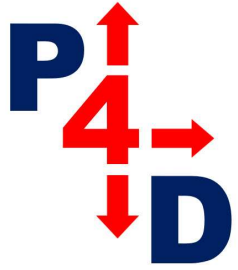
Integrity Management – INS-GPS Concepts

RLG Gyros



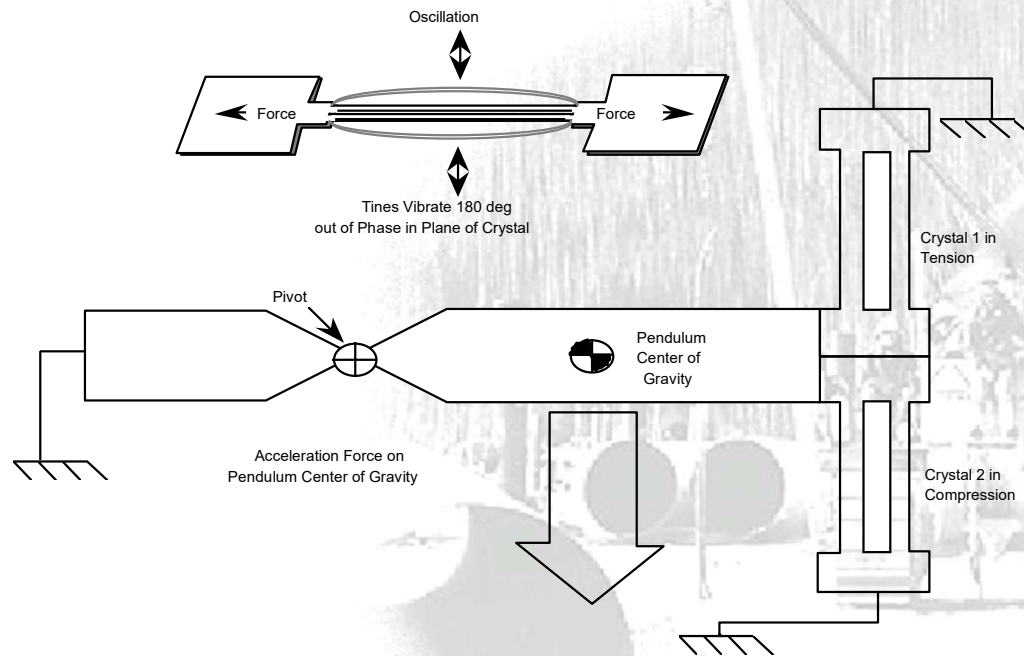
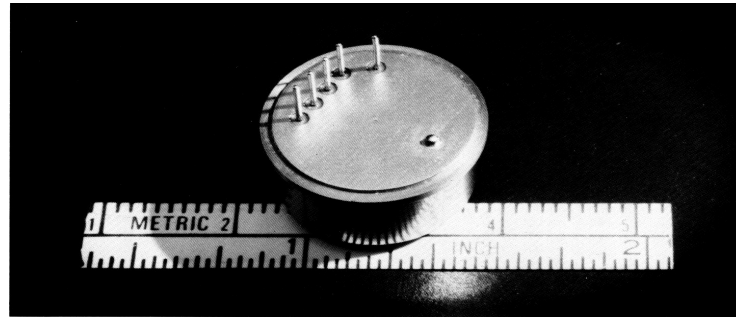
Features

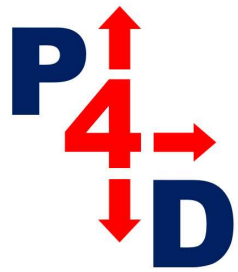
- Rugged, solid-block construction
- Short ROC curved mirror for stability
- Simplified wedge readout
- Simplified PLC transducer
- Dual cathodes for increased gas volume
- Frit seals for mirror and electrodes
- Cold weld pinch-off for high vacuum integrity
- Lapped block mirror mating surfaces



Integrity Management – INS-GPS Concepts

Accelerometers

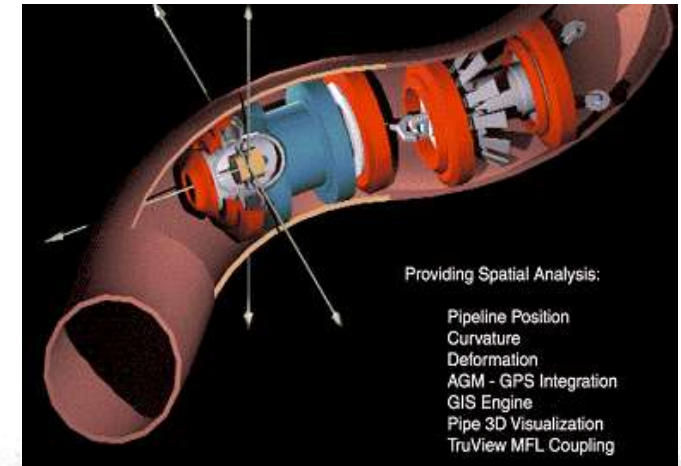


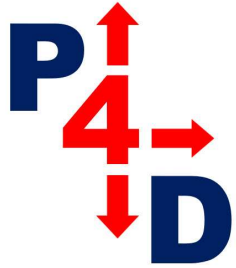


Integrity Management – INS-GPS Concepts

IMU Integration

- Combo Tool Add-in
- Independent Time Based Recorder
- Requires Accurate Odometer data -> velocity
- Requires Accurate AGM timing / positions
- Continuous **XYZ** pipeline position
 - accurate to better than 1m
 - Direct **GIS** input
 - Accurate and continuous **elevation profile**
 - Accurate spatial feature inventory via **accurate coordinates**.



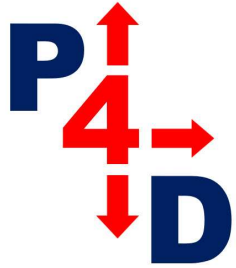


Integrity Management – INS-GPS Concepts

IMU Operation

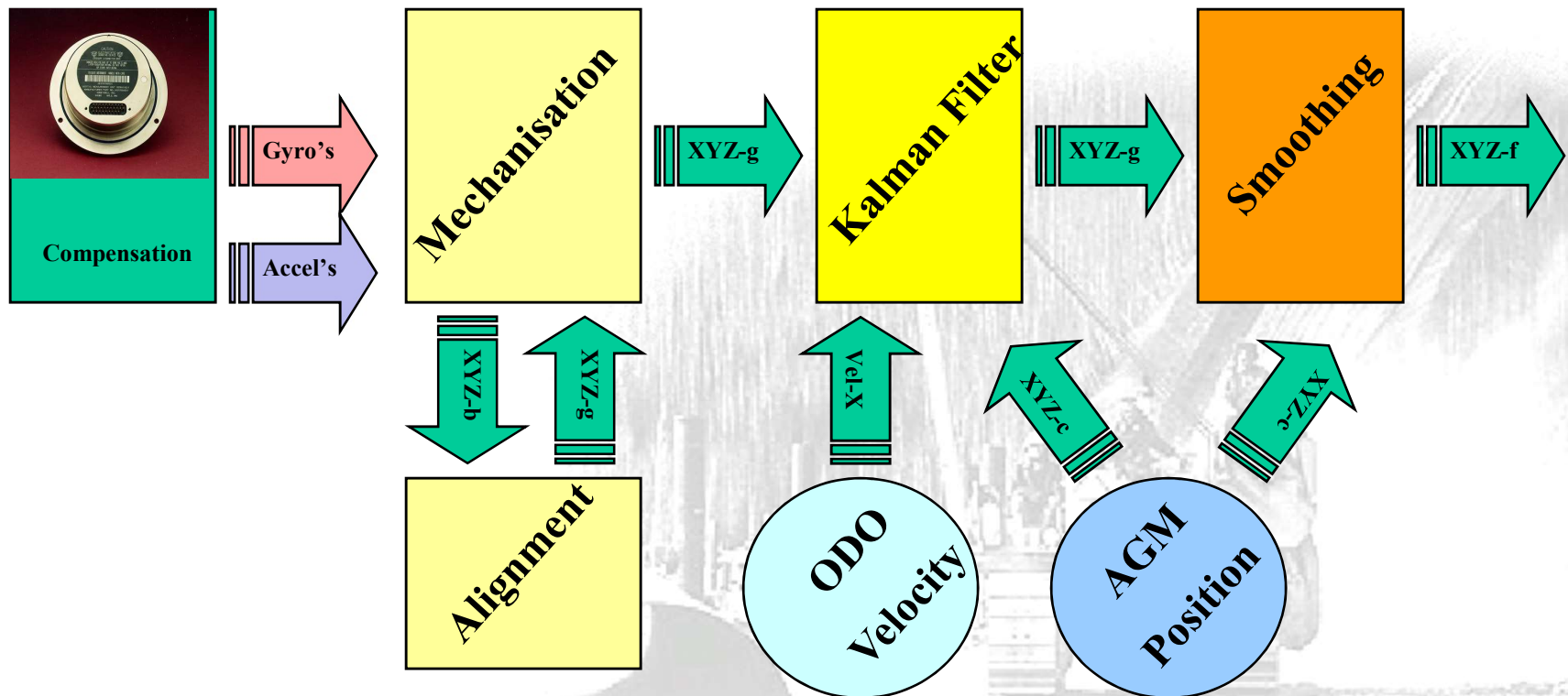
- **GO / No GO indication**
- **Launch calibration**
 - Sensor calibration
 - Launch barrel alignment
 - Stationary period
- **Trap verification**
 - Stationary period
 - ScanIMU – raw data integrity
- **AGM time extraction**

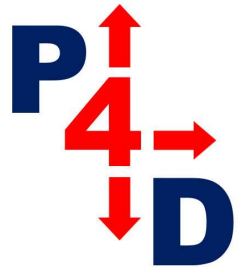




Integrity Management – INS-GPS Concepts

IMU Data Processing

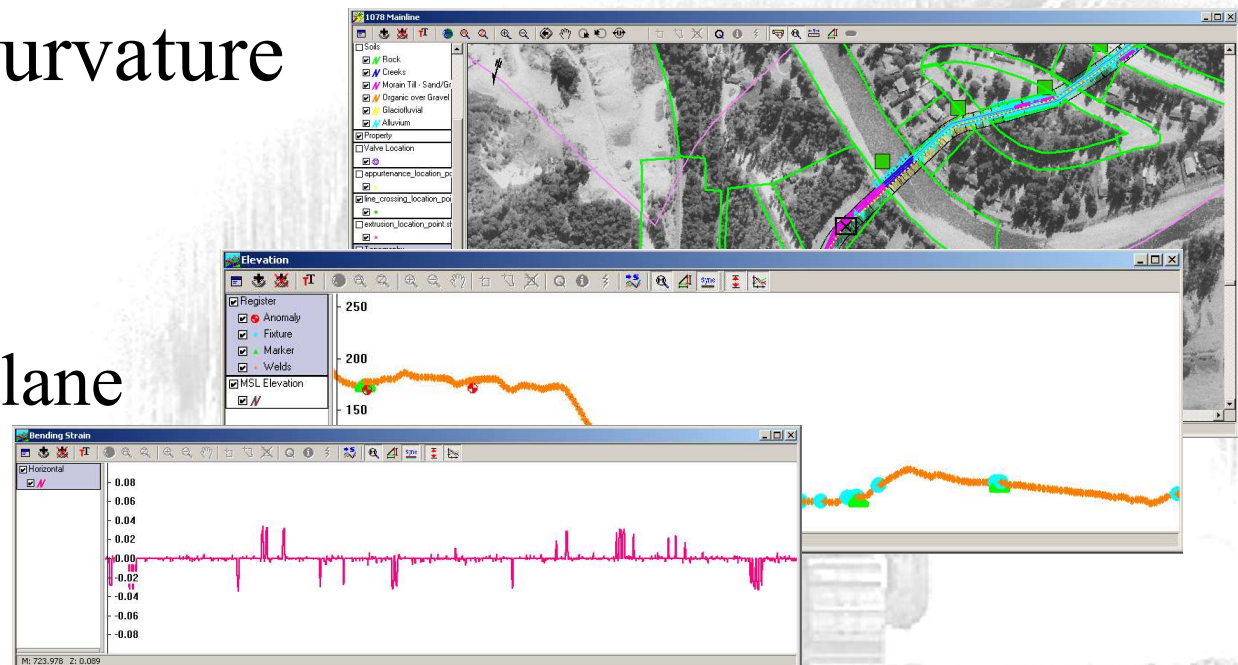


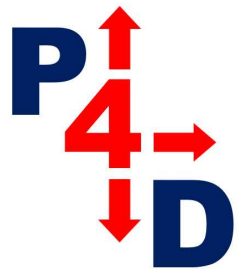


Integrity Management – INS-GPS Concepts

IMU – INS Results

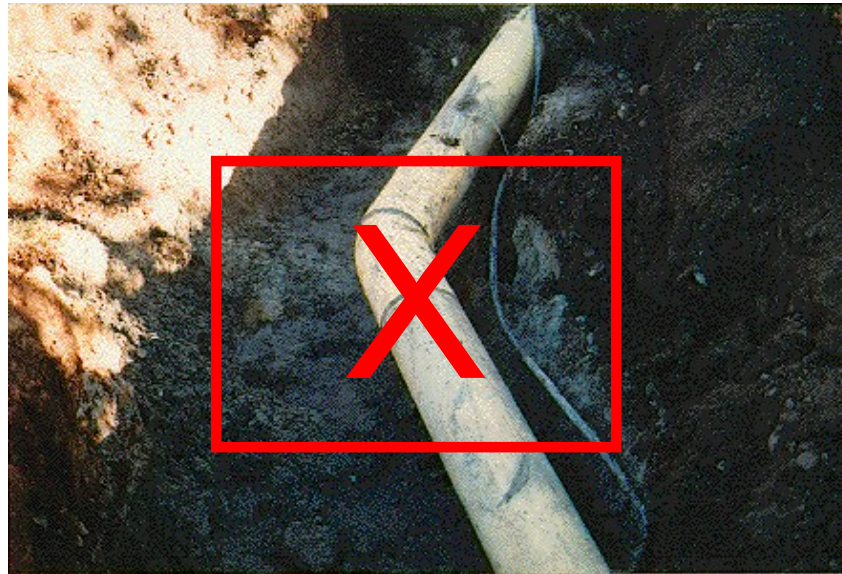
- Continuous Normalized XYZ file
- Continuous Curvature
 - Horizontal
 - Vertical
 - Max out of plane





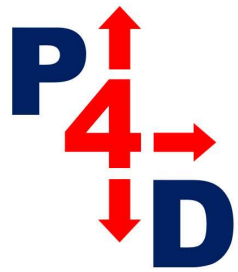
Integrity Management – INS-GPS Concepts

Dig Smart!



Save \$

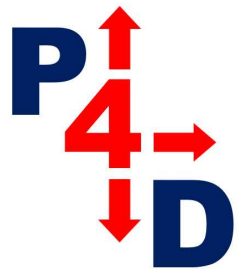




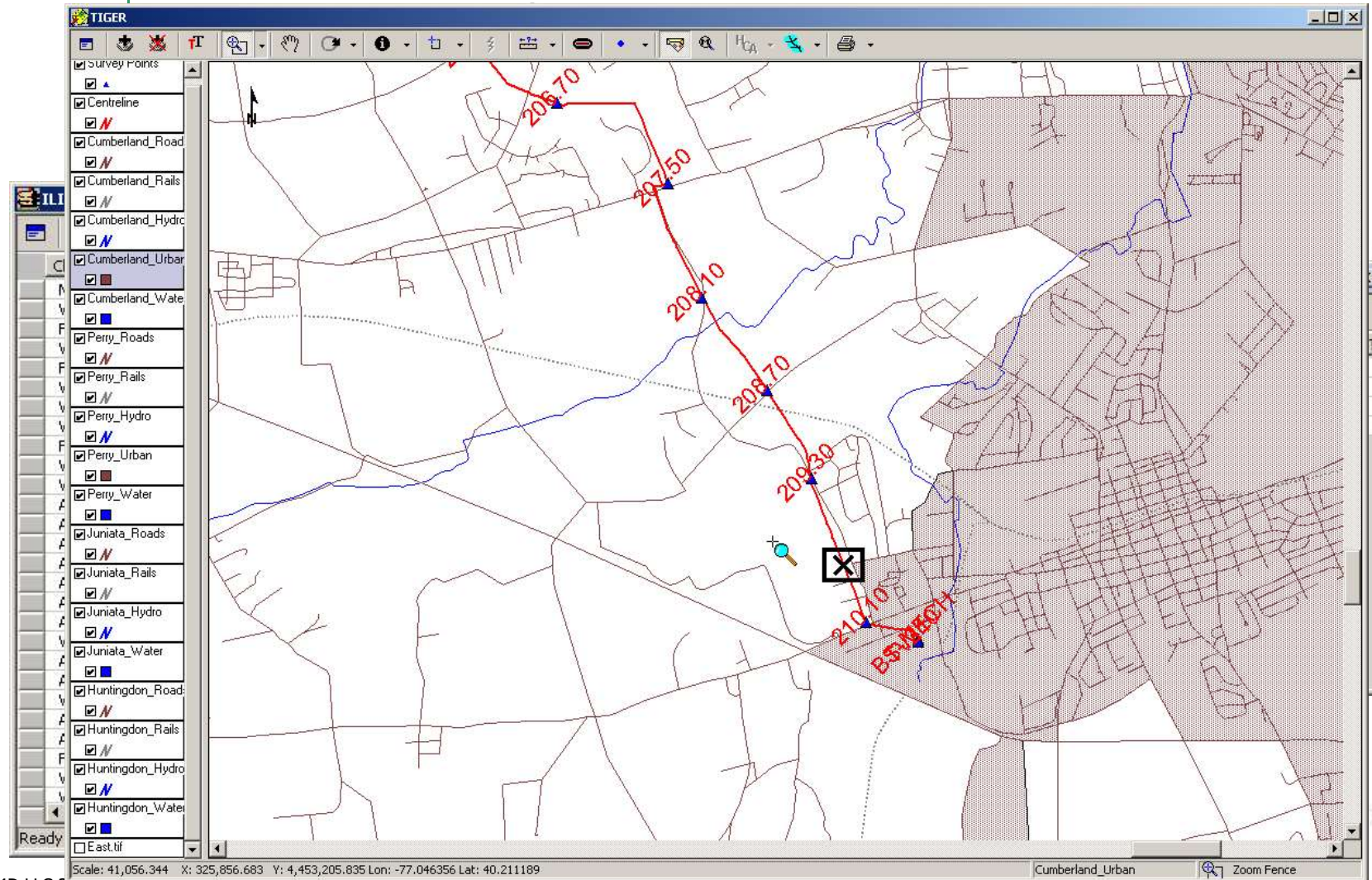
Integrity Management – INS-GPS Concepts

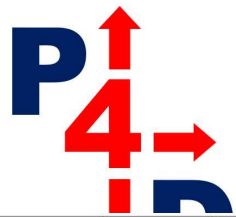
Tactical - Be Here Now!



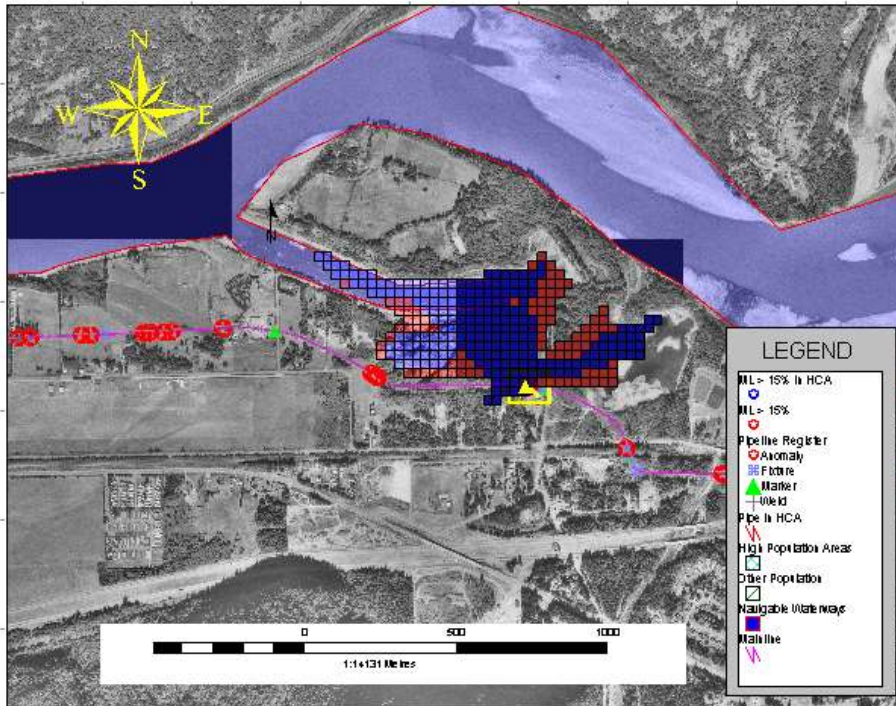


Integrity Management – INS-GPS Concepts



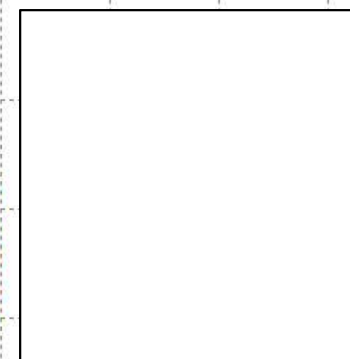
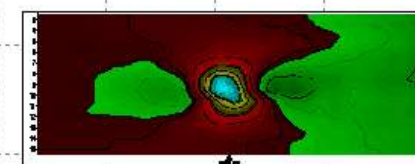
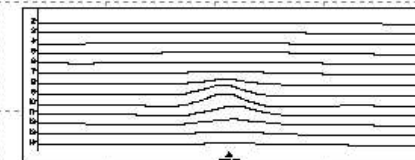
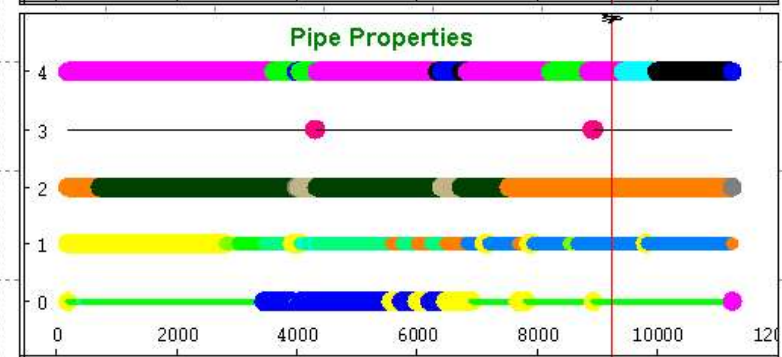
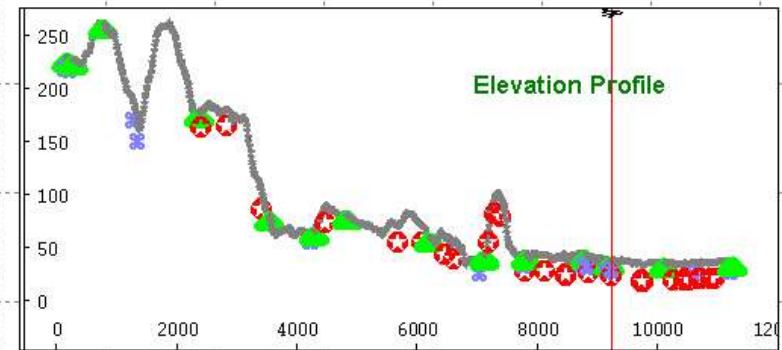


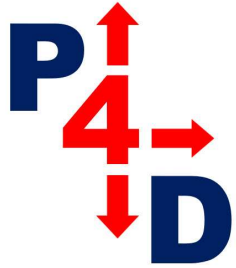
Integrity Management – INS-GPS Concepts



Pipeline Register (Anomalies > 15%)

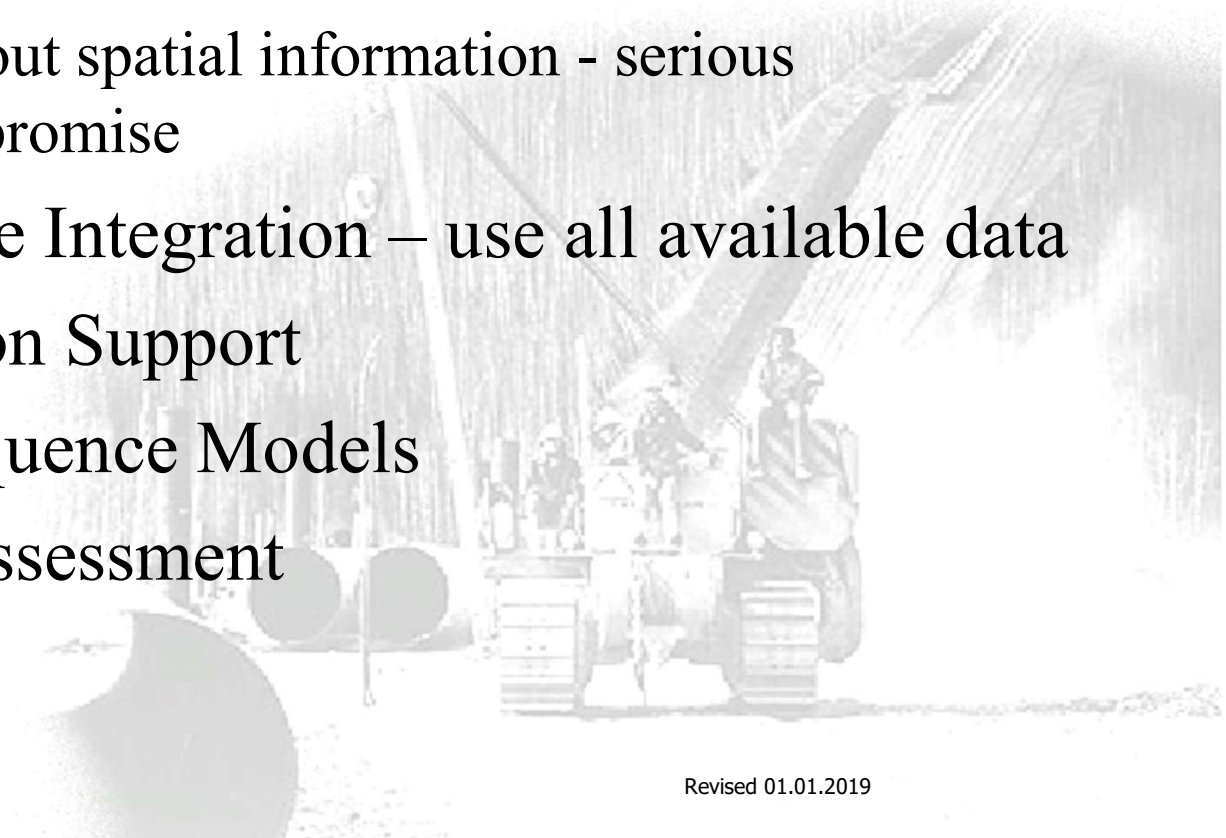
DISTANCE	DESCRIPTION	Cat. Descrip	COMMENT	WALL LOSS	Anomaly Loc	DEPTH	ORIENTATIO
30315.2167	Anomaly	General Corr...	Ex ternal	80	External	80	
29001.475	Anomaly	Circumferenti...	Ex ternal	29	External	180	
33723.8	Anomaly	General Corr...	Ex ternal	26	External	115	
25598.6167	Anomaly	Circumferenti...	Ex ternal	2.5	External	25	
31961.775	Anomaly	Pitting	Ex ternal	2.4	External	165	
21277.9083	Anomaly	General Corr...	Ex ternal	2.4	External	25	
26724.2833	Anomaly	Pitting	Ex ternal	2.3	External	185	
34505.6083	Anomaly	General Corr...	Ex ternal	2.2	External	275	
34268.2333	Anomaly	Axial Groove	Ex ternal	2.2	External	225	
27810.0417	Anomaly	General Corr...	Ex ternal	2.2	External	210	
27809.675	Anomaly	General Corr...	Ex ternal	2.2	External	185	
31963.95	Anomaly	General Corr...	Ex ternal	2.1	External	185	
27811.2083	Anomaly	General Corr...	Ex ternal	2.1	External	195	
27822.0833	Anomaly	General Corr...	Ex ternal	1.9	External	295	
27810.7917	Anomaly	General Corr...	Ex ternal	1.9	External	120	
19941.8083	Anomaly	General Corr...	Ex ternal	1.9	External	65	
34497.2833	Anomaly	General Corr...	Ex ternal	1.8	External	270	

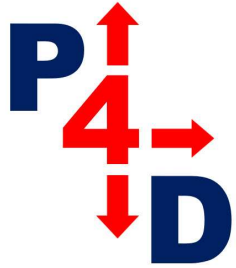




More Informed Decisions

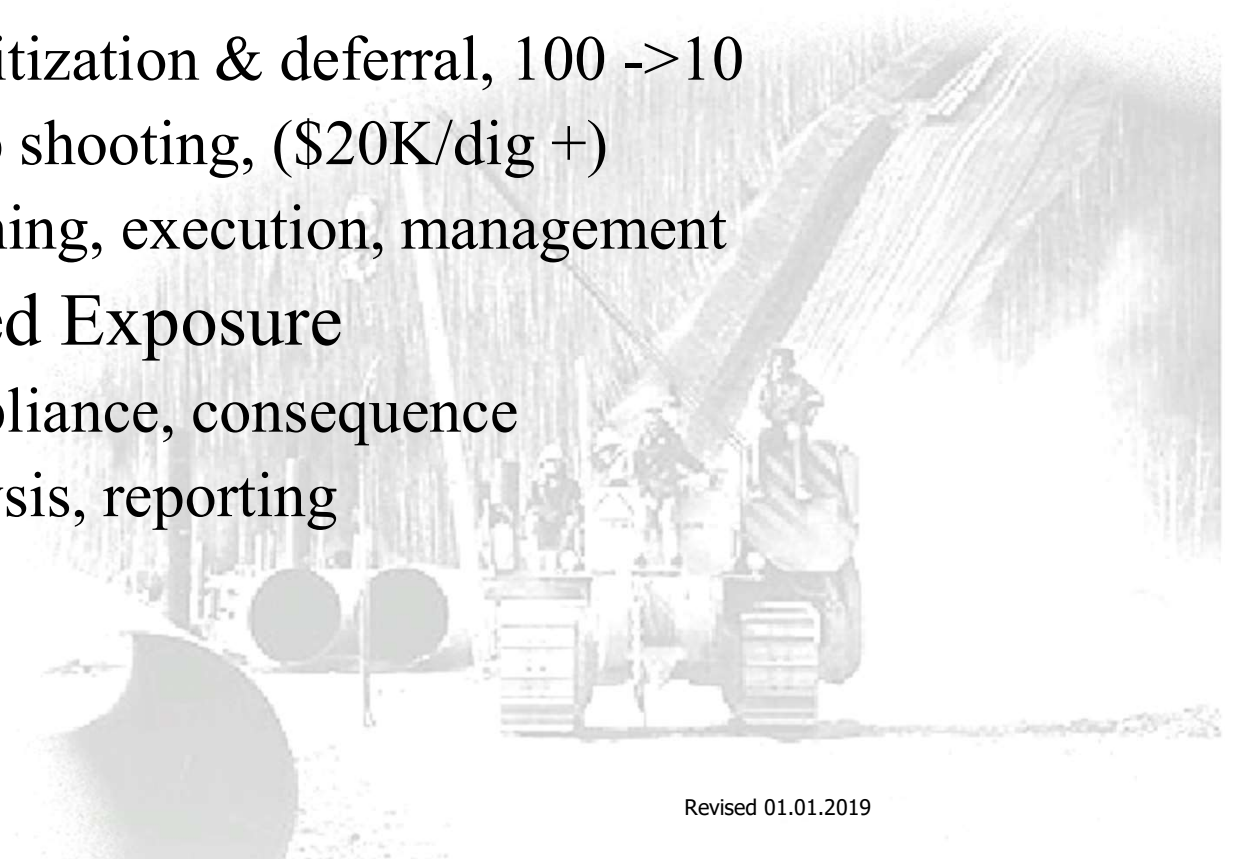
- Leverage Combo Tool Technology (+INS)
 - without spatial information - serious compromise
- Flexible Integration – use all available data
- Decision Support
- Consequence Models
- Risk Assessment

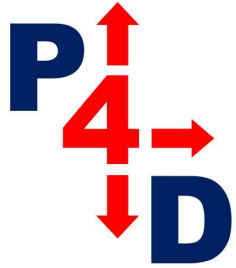




Better Economic Decisions

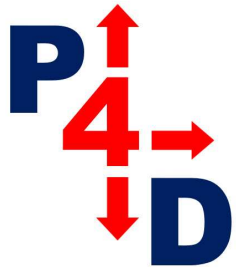
- Reduced Remediation Costs
 - prioritization & deferral, 100 -> 10
 - sharp shooting, (\$20K/dig +)
 - planning, execution, management
- Reduced Exposure
 - compliance, consequence
 - analysis, reporting





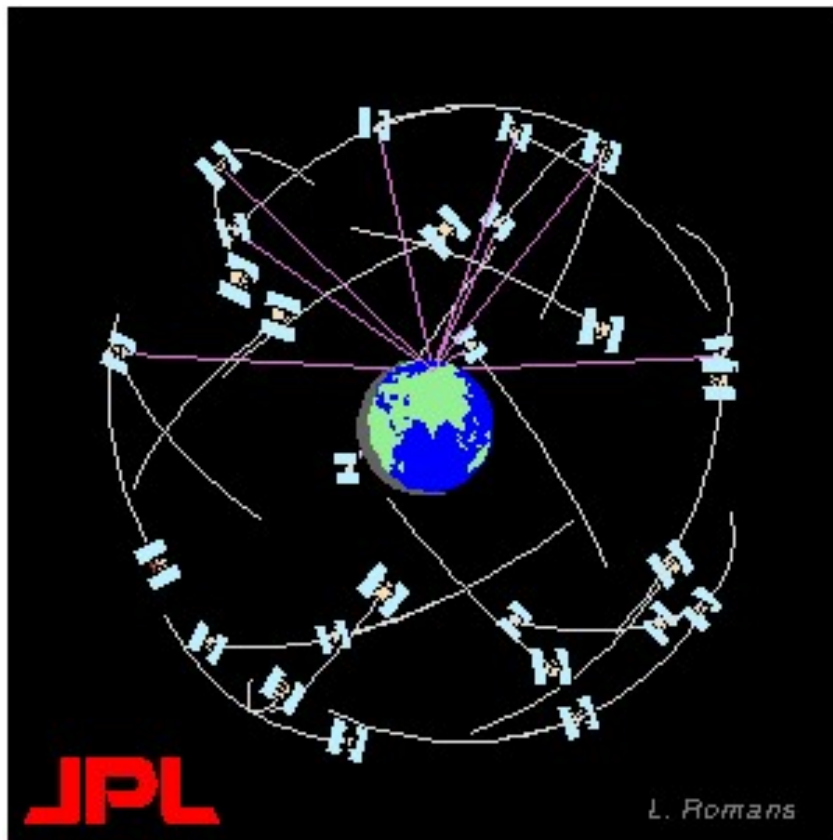
Rapid Solutions

- Turn-around
 - Quicker, more accurate, more reliable
- Integrated
 - Utilization of all corporate data
- Reporting / Dissemination
 - Intranet, WEB, Regulatory Agencies

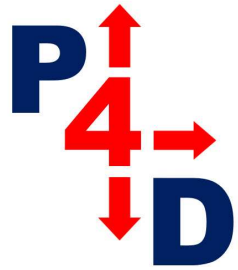


Integrity Management – INS-GPS Concepts

GPS Overview



- 24 SV's @ 20,000 km orbit
- 12 hour orbit, 55 deg-incline
- 5-11 SV's visible
- GPS Modes
 - GPS (GARMIN, 3-5m)
 - DGPS (ProXRS 1-2m)
 - FSS (Precise, 0.005-0.05m)

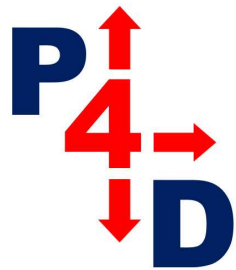


Integrity Management – INS-GPS Concepts

INS, AGM & GPS

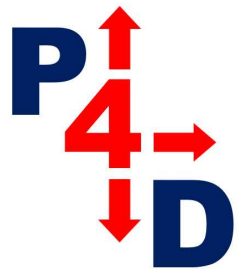
- INS provides **relative** position between survey points
- AGM's provide detection & tracking, and coordinate control for the INS
- GPS provides precise coordinates of appurtenances & AGM's
 - **Absolute** reference for X, Y & Z
 - Centimeter GPS accuracy
- Sub-meter system accuracy.





Integrity Management – INS-GPS Concepts

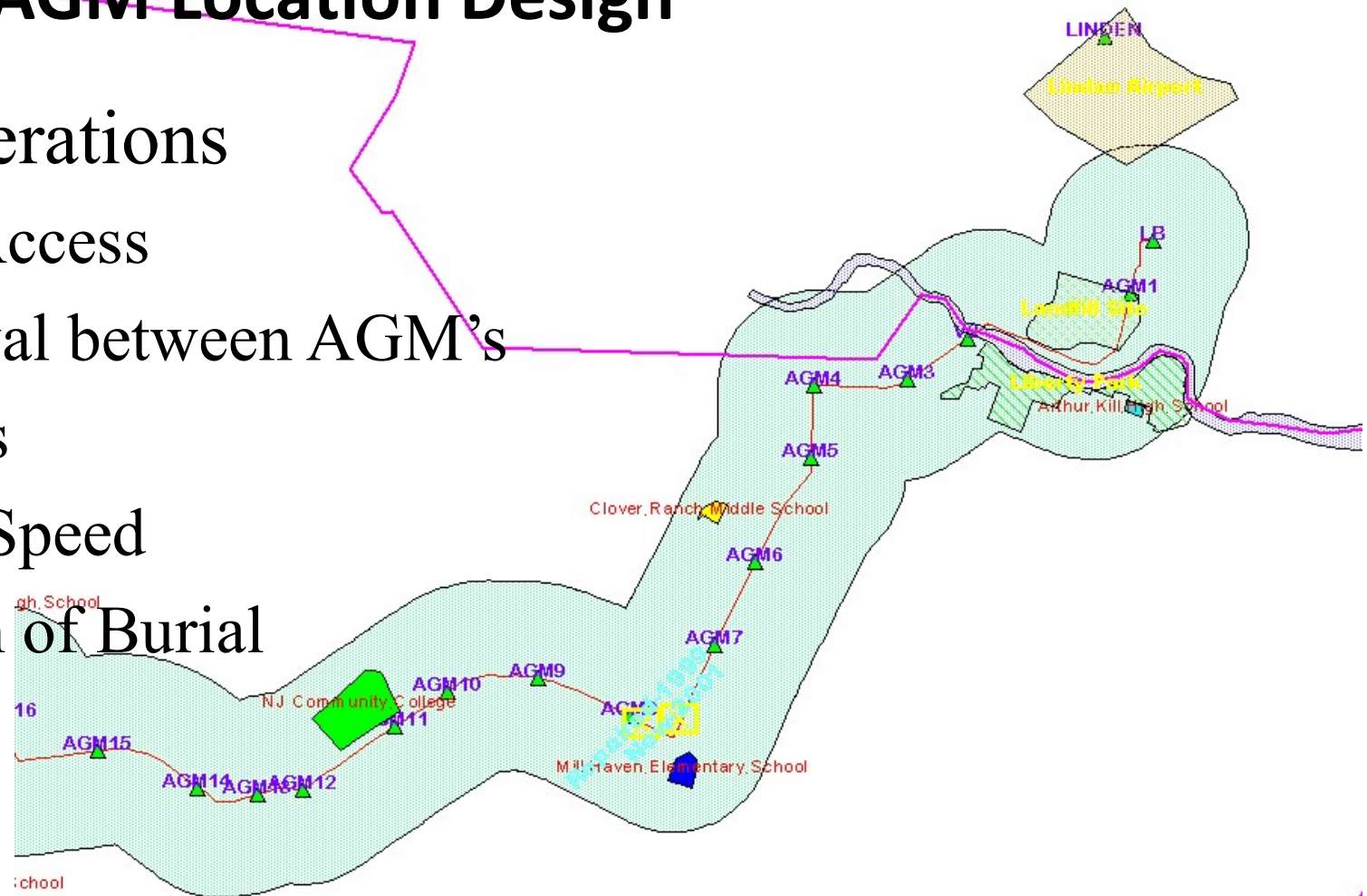
ERROR TYPE	DESCRIPTION	Min. (m)
<i>INS</i>	General inherent error	0.10
<i>Line Location</i>	AGM box locations are staked with line location units. The accuracy of detecting "top center" of the pipeline depends on line diameter, depth of burial, and skill of the operator. This error must be considered.	0.10
<i>AGM - Placement</i>	AGM boxes must be placed exactly over the surveyed marker. Any error in placement will go undetected, and add directly to the final position error.	0.10
<i>AGM - Missed</i>	Generally 1:1000 relative accuracy can be expected, so with each missed AGM, an additional 1 meter can be added.	0.00
<i>AGM - Timing</i>	AGM trigger times must be very accurate. This is used for position updates of the INS. Any error in timing multiplied by the tool speed, will contribute to the along track error.	0.25
<i>Tool Speed</i>	Tool speed must be within the standard requirements for MFL/DEF surveys. For INS, slow speed actually degrades accuracy because it becomes difficult to compute accurate velocity, and drift errors become large. Therefore fast is best.	0.00
<i>Speed Variation</i>	Large speed excursions can be accommodated, only if the odometers remain in contact and within accuracy specifications. The best results todate however, have been in +/-15% average speed variation situations.	0.15
<i>Time Interval</i>	One of the most critical parameters for an INS run, is the time between AGM events. As noted, INS errors accumulate with time, and after 20 minutes become non-linear and difficult to reduce. Therefore, <20 minute intervals are required.	0.25
<i>Trajectory - Bends</i>	The INS has an inherent heading sensitivity, meaning that @ horizontal bends, the biases change, and it become difficult to control errors. Therefore, we try to design the AGM layout to capture most large bends	0.25
TOTAL		1.20

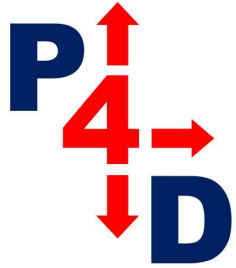


Integrity Management – INS-GPS Concepts

AGM Location Design

- Considerations
 - Site Access
 - Interval between AGM's
 - Bends
 - Line Speed
 - Depth of Burial


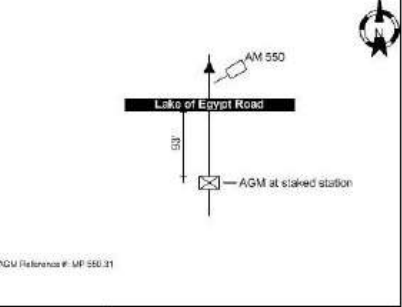


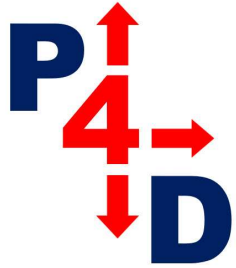


Integrity Management – INS-GPS Concepts

AGM Site Report

- Line Information
- Location
- Survey Summary
- Site Photo
- Site Sketch (recovery)

<div> <div></div> <div>Customer: <input type="text" value="Shell"/></div> <div>Line Name: <input type="text" value="Capline"/></div> <div>Customer Contact: <input type="text" value="AJ Westrope"/></div> <div>Contact Phone: <input type="text" value="901-412-7903"/></div> <div>Land Owner: <input type="text"/></div> <div>Land Owner Phone: <input type="text"/></div> </div>	
Site Information Point ID: <input type="text" value="497"/> Location Type: <input type="text" value="AGM"/> Description: <input type="text" value="AGM MP 549.00 MLV-Union Ridge Ln. #28986+56"/>	Cell Coverage: <input type="text" value="Good"/> Location Marker Name: <input type="text" value="MP 548.99"/> Line Segment: <input type="text"/> County / Parish: <input type="text" value="Williamson"/> State: <input type="text" value="IL"/> Nearest U/S Station: <input type="text" value="Joppe"/> Nearest D/S Station: <input type="text" value="Marion"/> Station Chainage: <input type="text" value="28986.56"/> Equation Chainage: <input type="text"/> Center Of Road Chainage: <input type="text"/> Reference Road: <input type="text" value="Union Ridge Lane"/> Driving Directions From U/S AGM: <div></div> Driving Directions From Town: <div></div>
Survey: Survey Name: <input type="text" value="SC154899"/> Latitude: <input type="text" value="37.602984640"/> Longitude: <input type="text" value="-88.960277240"/> Elevation: <input type="text"/> Elevation (T.O.P.): <input type="text" value="171.735"/> Ht. Correction (to T.O.P.): <input type="text"/> Height Comment: <input type="text"/> Depth Of Cover: <input type="text" value="65 Inches"/>	Site Photo: 
Site Sketch: 	Survey Notes: <input type="text" value="D/S of Valve"/> Survey Field Personnel: <input type="text" value="McNeill Hoogeland DeLeeuw"/> Date: <input type="text" value="Friday, March 28, 2003"/> Time: <input type="text" value="5:23:00 PM"/>
Field Notes: <input type="text" value="Reference AGM at staked station 50' dia of BV 549"/> Marker Field Personnel: <input type="text" value="Doug Dotan"/> Date: <input type="text" value="Tuesday, February 11, 2003"/> Time: <input type="text"/>	



Integrity Management – INS-GPS Concepts

GPS Surveys

- Planning
- Coordination
- Select / Staking / Demarcation
- Reporting
- Coordinate with AGM Layout crew
- MAKE SURE IT'S DONE RIGHT!