



# Embedded Real-Time Operating System Design

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## RTOS.X: Theory, Analysis, Performance and Portability



# Syllabus (1)

	<b>Topics</b>	<b>Text</b>	<b>Milestones</b>
<u>1</u>	Course Description and Objectives, Prerequisite Skills	Preface	Background Material
<u>2</u>	RTOS Overview	Section 1.2	Foundation Concepts
<u>3</u>	Boot Process & Development Environment	Section 3.3	Boot Mode and Development Environment
<u>4</u>	Processor Architecture (1)	Section 3.3	CPU Registers and Addressing Models
<u>5</u>	Processor Architecture (2)	Section 3.3	Addressing Modes and Debugging
<u>6</u>	Critical Hardware Resources	Section 3.3	Interrupt Processing



# Syllabus (2)

	<b>Topics</b>	<b>Text</b>	<b>Milestones</b>
<u>7</u>	RTOS Fundamentals	Chapter 1	Multitasking, Timeslice and Semaphores
<u>8</u>	RTOS API Definition (1)	Chapter 2	RTOS.h header file
<u>9</u>	RTOS API Definition (2)	Chapter 2	RTOS.h header file
<u>10</u>	Real-Time Embedded Systems	Section 1.1	Sample RTOS Use Cases
<u>11</u>	RTOS Requirements	Section 2.1	RTOS Temporal Requirements
<u>12</u>	RTOS Internals	Section 2.1.1	RTOS.c Design / Architecture



# Syllabus (3)

	Topics	Text	Milestones
<u>13</u>	Task Control Block & Task Context	Section 2.1	Primary RTOS Data Structures
<u>14</u>	Context Switching (1)	Section 3.4	Fundamental Operations and Sequences for Context Switching
<u>15</u>	Context Switching (2)	Section 3.4	Detailed Mechanics of Performing a Context Switch between Tasks
<u>16</u>	Counting (“Dijkstra”) Semaphores	Section 2.5	Full Implementation of Counting Semaphores
<u>17</u>	Binary Semaphores & Software Events	Section 2.6 Section 2.7	Full Implementation of Software Events and Binary Semaphores
<u>18</u>	Condition Variables & Message Passing	Section 2.8 Section 2.9	Full Implementation of Condition Variables and Message Passing
<u>19</u>	Process Management	Section 2.2 Section 2.3	Full Implementation of Process Management and Ancillary Functions



# Syllabus (4)

	<b>Topics</b>	<b>Text</b>	<b>Milestones</b>
<u>20</u>	Error Handling	Section 2.4	Handling Errors and Detecting Deadlock
<u>21</u>	Hardware Independence	Section 3.1	How and Why an RTOS should be Portable
<u>22</u>	Validation	Chapter 4	Test Suite to Validate that the RTOS is correct
<u>23</u>	Performance Assessment	Chapter 5	RTOS Temporal Performance Assessment
<u>24</u>	Priority Inheritance	Section 6.2	Priority Ceiling Protocol Theory and Application
<u>25</u>	Earliest Deadline First Scheduling	Section 6.3	EDF Scheduling Theory and Application
<u>26</u>	Multiprocessor Systems	Section 6.4	How the RTOS would operate on multiprocessor platform



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