

KTM 390 Duke / RC 2017

INSTALLATION INSTRUCTIONS







Attention: For a correct RB feeding voltage, check the operation of all motorbike electrical system components (lights, fuse, stock connectors, etc.).

- 1. Turn ignition off.
- 2. Remove the seat and the fuel tank.

_____ Injection section _____

3. Locate and disconnect the grey 2 pin connector placed under the fuel tank (Fig.1).



Fig.1

4. Connect the Rapid Bike connectors in-line of the stock connectors (Fig.2).



Fig.2

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_ T.P.S. section _____

5. Locate the black 6 pin connector placed under the fuel tank on the right hand side of the bike (**Fig.3**).



Fig.3

6. Connect the green wire of the Rapid Bike wiring to the green/yellow striped wire of the stock connector using the posi-tap connector (**Fig.4**).



Fig.4

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Crankshaft sensor section _____

7. Locate and disconnect the white 6 pin connector placed on the left hand side (**Fig.5**).

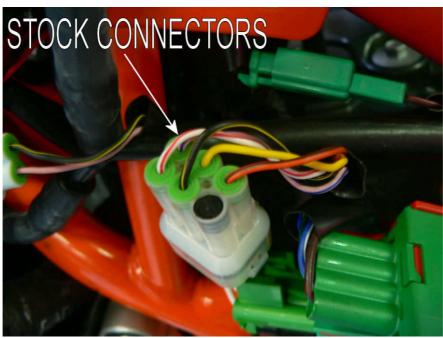


Fig.5

8. Connect the Rapid Bike connectors in-line of the stock connectors (Fig.6).



Fig.6

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O2 sensor section _

9. Locate and disconnect the green 4 pin connector placed behind the left fairing (Fig.7).



Fig.7

10. Connect the Rapid Bike connectors in-line of the stock wiring harness (Fig.8).



Fig.8

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Feeding voltage section _____

11. Locate and disconnect the white 2 pin connector placed under the fuel tank on the right hand side of the bike (**Fig.9**).

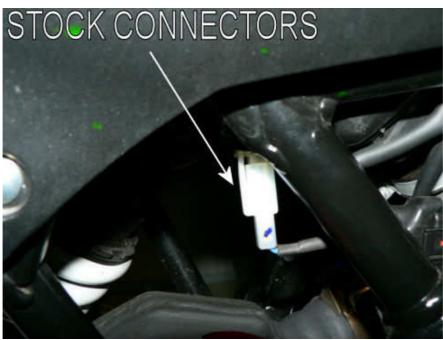


Fig.9

12. Connect the Rapid Bike connectors in-line of the stock wiring harness (Fig.10).



Fig.10

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13. Connect the eyelet of the Rapid Bike wiring harness to the negative pole of the battery (**Fig.11**).



Fig.11

Final section

- 14. Connect Rapid Bike module to the wiring harness.
- 15. Check proper connection of all connectors.
- 16. Fix the module in the gloves compartment (Fig.12).



Fig.12

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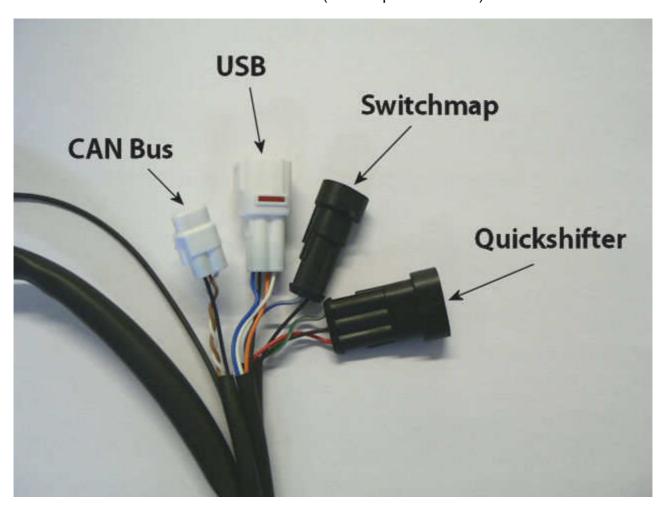


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Accessories section

The Rapid Bike wiring has four other connections for the accessories:

- Connection for the quickshifter sensor (black 3 pin connector)
- Connection for the handlebar switchmap (black 2 pin connector)
- Connection for the CAN Bus interface (white 3 pin connector)
- Connection for the USB interface (white 4 pin connector)



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