

# SUPPLEMENTARY EQUIPMENT

**NORTHROP GRUMMAN**

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## NAVIGAT X MK 1 Digital Gyrocompass

- Comprises one single unit.
- Microprocessor controlled.
- Easy to install and easy to service.
- Control and display unit in front cover with 4-digit heading display and 6 operating keys.
- High-speed follow-up system 100°/sec.
- Rate of turn output...
- Integrated TMC interface.
- Compass monitor function.
- Will drive a maximum of 12 analogue repeaters.
- 7 independent serial outputs RS 422 & IEC 61162-1.
- Automatic north speed error correction.
- RS 422 SUPERFAST output.
- Second gyrocompass and magnetic compass inputs.
- Complies with IMO regulations A.424(XI), A.574(14), A.821(19) - High-Speed Code and ISO 8728.
- Type approved, also to the High-Speed Craft Code, in accordance with the EC Council Directive 96/98/EC.
- Rate of turn output type approved in accordance with the EC Council Directive 96/98/EC.



## UNIVERSAL DIGITAL REPEATER



Environmental	Dimensions and Weight	
Temperature range	Console Version	Watertight Housing with
Vibration	Front plate	Bracket Attachment
Protection grade	96 mm x 96 mm	185 mm
	to DIN Standard	Width
	Depth	125 mm
	Height	156.5 mm
	Weight	650 g
		Depth
		160 mm
		Weight
		1450 g

**Type approved** in accordance with the EC Council Directive 96/98/EC.

- Signal Input**
- one RS 422 input with the following protocols:
    - IEC 61162-1: heading gyro, heading magnetic, roll, pitch, rate of turn, X-rate, Y-rate, water speed, ground speed, transverse water speed, transverse ground speed, total/daily miles, wind speed, wind angle, rudder angle, depth, air temperature, water temperature, time.
    - C.PLATH: heading gyro, heading magnetic, rate of turn, roll, pitch.
    - Lehmkuhl: heading.
    - NAVIPILOT: heading gyro, heading magnetic, set heading, speed.

- Status Input** opto-coupler, rating 24 V / 10 mA freeze mode, 180° heading change mode.
- Signal Output** one RS 422 with protocols for the Sperry Marine Voyage Data Printer.
- Status Output** open collector, rating 50V/500mA. Status change according to speed input (threshold can be set in the setup menu).
- Special Feature** Course to Steer Indicator

## NAVIGAT 2100 Fiber-Optic Gyrocompass

- No moving parts.
- Solid-state technology.
- No maintenance during service life.
- High dynamic accuracy.
- Short settling time.
- Heading, roll, pitch and rate sensor.
- Meets all IMO recommendations including high-speed code.
- Data transmission by serial interface.
- IEC 61162-1 FAST & IEC 61161-2 SUPERFAST outputs.
- Second gyrocompass and magnetic compass inputs.
- Compass monitor and heading selector function to NAUT-AW.
- Automatic changeover to emergency power per GMDSS.
- Basic system comprises only three units: Sensor unit, Control and Display Unit and Interface and Power Supply Unit.
- Type approved, also to the High-Speed Craft Code, in accordance with the EC Council Directive 96/98/EC.
- The Rate-of-Turn output is type approved to the High-Speed Craft Code and in accordance with the EC Council Directive 96/98/EC and also fulfills IMO Resolution A.526(13)



## JUPITER Magnetic Compass

A "class A" compass with 180 mm card diameter for installation in NAVIPOL binnacles. Also available with a flux gate and in an overhead mounting. Type approved in accordance with the EC Council Directive 96/98/EC.

## ANALOGUE MAGNETIC COMPASS REPEATER

Magnetic compass heading console repeater with a 360° compass card. 192 mm x 192 mm. Weight 1.5 kg. Data transmission through RS 422 serial interface.



## Steering Control Unit Control and Display Unit

Environment	
<b>Ambient temperature range</b>	
operation	-15° C to +55° C
storage	-25° C to +70° C

Protection grade	
installed	IP32 to DIN 40050

**Environmental testing**  
to EN 60945 (IEC 945 +A1).

Power requirements	
24 VDC (18 V to 36 V)	

**Max. ripple content**  
4 V pp, extreme values should not exceed 36 V or fall below 18 V

<b>Power consumption</b>	10 W max.
<b>Reverse polarity protection</b>	built-in

### Inputs

**Rudder angle feedback signal**  
± 10 V ± 120° max. selectable rudder angle potentiometer resistance 2 kΩ

External steering system ± 10 V ± 120° max. rudder angle

**Flux gate for magnetic compass**  
sine/cosine, Sperry Marine product

**NAV/TRACK interface**  
serial interface for track steering via Sperry Marine VMS or standard waypoint steering with a position receiver

**Speed input** 200 p/nm or IEC 61162-1

**180° turn command** port and starboard

**180° rotation of heading display (for ferries)**

**Gyro / magnetic selection**

**Override status**

**Mute**

**Status signals** AUTO, NFU, Helm, Remote, Ext. System

**Set heading and rudder limit or rate or radius control by joystick or pushbutton**

**Gyrocompass or electronic flux gate**  
two IEC 61162-1

**Heading** IEC 61162-1

Heading gyro HEHDT at 10 Hz

Heading magnetic HCHDT or HCHDM or HCHDG at 10 Hz

**Navigation system data**  
NSD at 1 Hz

### Outputs

**DC solenoid valves**

Outputs two for port two for starboard (solid-state relays)

Type plus or minus swiving

Voltage 12 VDC to 110 VDC

Rating 2.0 A max.

Additional outputs optional

<b>AC solenoid valves</b>	
Outputs	two for port two for starboard (solid-state relays)
Voltage	24 VAC to 230 VAC
Rating	1.0 A max.
Additional outputs	optional

### Outputs and Interfaces

**CAN in accordance with IEC 61162-3**  
for remote control and display units

**Central alarm** IEC 61162-1 bidirectional input/output

**Voyage Data Recorder (VDR)**  
RS 422 9600 bps

**Status and alarm outputs**

- System alarm potential-free contacts
- Off course alarm\* 2 A maximum current
- Override alarm\* 250 V maximum voltage
- Gyro / Mag. status\*
- Ext. system status\*
- Deadman's control\*
- Mute\*

\* max. 4 outputs selectable

**Power failure alarm**

- Primary supply potential-free contacts
- Backup supply 2 A maximum current 250 V maximum voltage

### STEERING CONTROL UNIT

**Dimensions**  
H 151 mm W 392 mm D 425 mm

**Weight** 3 kg

**Cable connections** screw-down terminals

**Protection grade** IP 32

**Magnetic clearance** 0.4 m

### CONTROL AND DISPLAY UNIT

**Front panel dimensions**  
288 mm x 144 mm to DIN standard

**Installation depth** 150 mm

**Weight** 1.5 kg

**Front panel** sealed foil keyboard, illuminated

**Display** graphic liquid crystal, illuminated

**Minimum magnetic clearance (installed) to**

- standard magnetic compass ≤ 0.40 m
- steering magnetic compass ≤ 0.40 m

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**Sperry Marine**



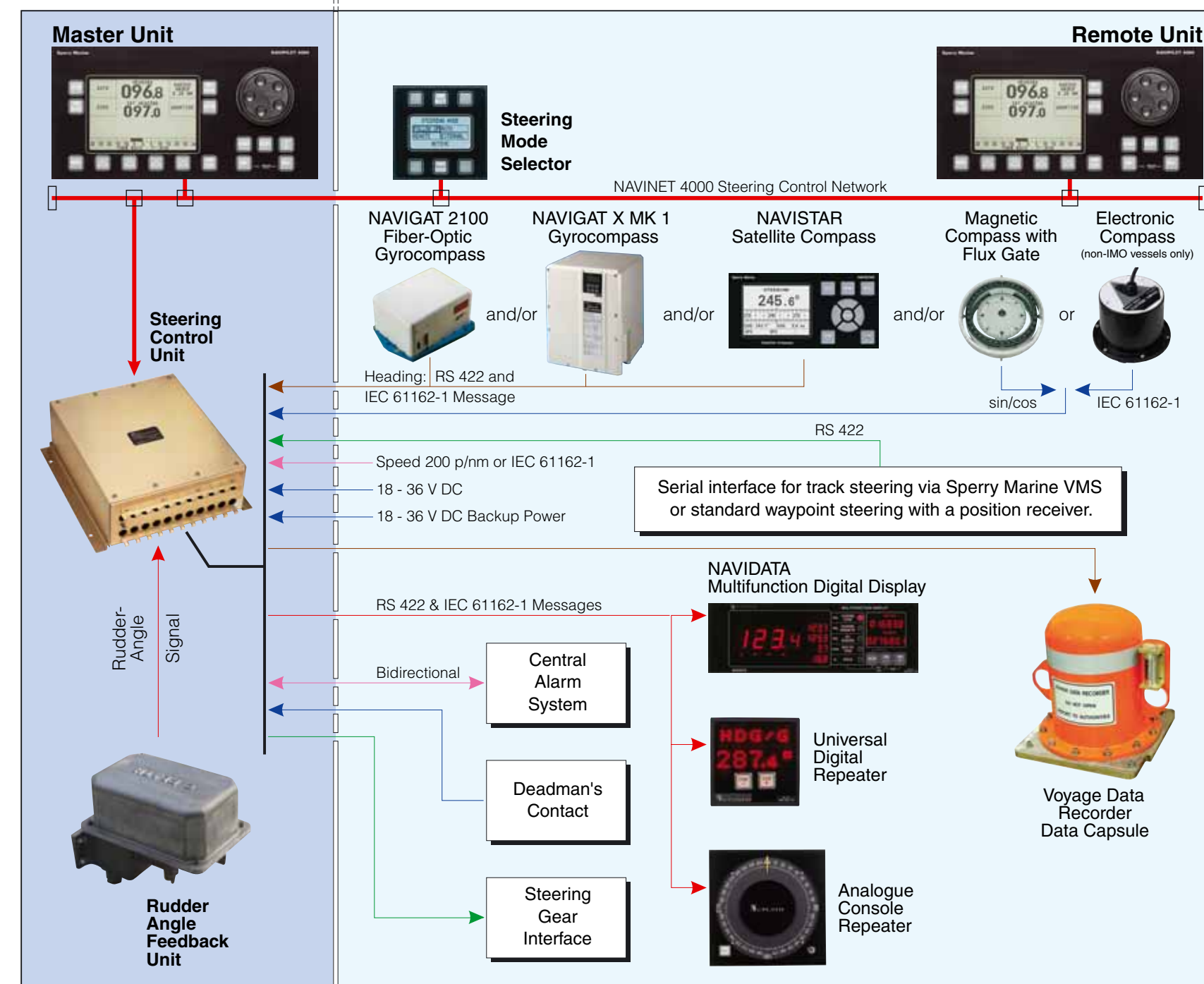
MAJOR ADVANTAGES

- Fully self-tuning, adaptive heading control.
- Manual selection of steering strategy to suit weather conditions.
- Rate and radius control modes.
- Gyrocompass heading interfaces: two RS 422
- Magnetic compass interfaces: IEC 61162-1, sine/cosine
- Serial interface for track steering via Sperry Marine VMS or standard waypoint steering with position receivers.
- Additional remote Control and Display Units possible.
- Operational data remain stored during power failure.
- Clearly arranged graphic liquid crystal display (LCD) with back lighting.
- Logical arrangement of sealed foil keyboard and ergonomic, user-friendly operation.
- Analogue selection of set heading by means of a cardinal control disk, and soft key selection of all other major parameters.
- Analogue output for thruster control, rudder propellers and water jets.
- System utilizes the NAVINET 4000 Steering Control Network.
- Only serial digital interfaces used.
- Display and controls illuminated.
- Meets the requirements of all major classification societies.
- EC type approved by GL Luxembourg to 98/85/EC (Wheel Mark) Specified Standards: ISO/IEC 11674 EN 61162-1, IEC 61162-1, EN 60945, IEC 60945 IMO Resolutions A.342 (X), A.694 (17), A.813 (19), MSC.64 (67) Annex 3

Bottom: Ocean Princess built by Fincantieri for P&O  
 Cover: Voyager of the Seas built by Kvaerner Masa Turku for RCCL.



BASIC SYSTEM ↔ OPTIONAL EQUIPMENT



SYSTEM OVERVIEW

With the introduction of the **NAVIPILOT 4000 Self-Tuning Adaptive Heading Control System**, Sperry Marine continues its traditional philosophy of designing autopilots with the aim of increasing profit by reducing running costs. The innovative NAVIPILOT 4000 is the first autopilot which uses steering control network technology to control a ship and is capable of tuning itself to adapt automatically to the ship's load characteristics and the prevailing weather conditions, thus reducing operational demands and increasing fuel savings and operational safety. Conceived with the most modern computer tools in accordance with IEC 61162-3 (NMEA 2000), the NAVIPILOT 4000 permanently indicates all information required by the most stringent navigation demands:

- Current heading (digital)
  - Set heading
  - Override status
  - Selected heading source
  - Steering modes AUTO, NAV or TRACK
  - Parameters for
    - Rudder limit or
    - Rate-of-turn or radius (steering mode)
    - Weather
  - Preset heading selection
  - 1/10° increments of set heading
- Additional Displays of:
- Load condition
  - Speed (auto / man.)
  - Rudder order or
  - Actual rudder angle or
  - Rate of turn or
  - Cross track error
  - Off course alarm
  - Heading difference alarm