

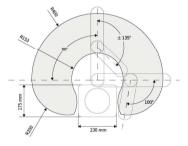




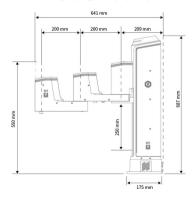
## Technical Parameters

	Reach	400mm			
	Rated Payload	1.5kg			
	Maximum magnitude	Type	Mechanical limitation		Software limitation
		Rear arm	-90° ~90°		-85° ~85°
		Forearm	-135° ~135°		-135° ~135°
		Z-axis screw	0mm~250mm		10mm- 235mm
		End-effector rotation	unlimited		-360° ~360°
	Maximum speed	Joint speed of Forearm and Rear Arm		180°/s	
		Resultant speed of the Forearm and Rear Arm		2000 mm/s	
		Speed of Z Axis		1000 mm/s	
	Repeatability	0.02mm			
	Power	Power Adapter: 100V-240V A Dobot M1: 48V DC			
	Communication interface	Ethernet、RS-232C			
	I/O	22 digital outputs, 24 digital inputs, 6 ADC inputs			
	Software	M1 Studio			
	System	Linux			

### **Operating Space Diagram**



#### **Overall Dimensions**



# DOBOT M1 SCARA Collaborative Robot Arm

DOBOT M1 is the world's first SCARA robot arm for small and mediumsized factories. Lightweight and portable, the 4-axis robot arm delivers fast setup and flexible deployment. M1's effective cost, easy programming and low maintenance make it a perfect automation solution for SMEs.

## **Application Scenarios**

DOBOT

AUTOBOTS INC.



PCB PLUG-IN AN SOLDERING



DEFECT DETECTIO



AUTOMATIC PRODUCTION