

Titan

Mini-Recorder

ADF User Manual



Proprietary Notice

This information is furnished for installation, operation, test and maintenance purposes. The information is proprietary in nature and should be treated accordingly. The data shall not be released or used, duplicated or disclosed, in whole or in part, for manufacture or procurement without the written permission of **Mars Labs**.

Copyright

This Technical Manual is copyright © 2015. All rights reserved. Brief excerpts may be made from this manual for technical purposes, as long as they are referenced.

Although this manual is believed to be correct at the time of publication, **Mars Labs**, its employees, or agents involved in the preparation and publication of this manual do not accept any form of liability for its contents or any consequences arising from its use. People using the information contained in this manual should apply, and rely upon, their own skill and judgement to a particular issue which they are considering.

Warning

Only a qualified technician or representative of Mars Labs should attempt to service the components of this system. There are no user-serviceable parts inside.

For safety and protection of the equipment, power must be turned off prior to connecting or disconnecting cables and sensors.

**Titan ADF Mini-Recorder
User Manual v16.3
MNL 1002
November 2015**

Table of Contents

Introduction	
Furnished Accessories	4
Support	4
General Guidelines and Warnings	5
Guidelines for Wiring Sensors	6
Operation	
Front Panel	7
Rear Panel	10
Signal Flow	11
Calibration Modes	12
Formatting Memory Cards	13
Interface	
Analog Input Connector	14
COMM Port	15
GPS Port	15
Sensor Connection Examples	
Full Bridge Sensor	16
Voltage Sensor	17
String Pot Sensor	17
Frequency Sensor	18
Thermocouple Sensor	18
Theory and Operation of Thermocouples	20
Features & Specifications	
Key Features	22
Specifications	22
Supported Sensors	23
Titan Nomenclature	24
Asset Tag / Customer Information Data Entry	25
Troubleshooting	27
Notes and Known Issues	30
Warranty & Repair	31

Introduction

The Titan ADF Mini-Recorder is a fully integrated data acquisition system that features a 16-channel interface with on-board signal conditioning, programmable gain and filtering, A/D conversion, and built-in data storage via an SD memory card data recorder. The Mini-Recorder can be powered by the supplied USB ‘Y’ cable when connected to a PC, or by applying power to the front panel auxiliary power connector when recording remotely.

This manual is intended to provide an overview of the Titan Mini-Recorder, with complete feature descriptions, specifications, setup procedures and operational information. It contains important safety information as well.

Furnished Accessories

The Titan ADF Mini-Recorder is typically shipped with the following items:

1. Titan ADF Mini-Recorder
2. USB or Serial Cable
3. SD Memory Card

A Titan Power Adapter or a mating connector for the Mini-Recorder Auxiliary Power Connector may also be included.

Support

Support for this product is available by contacting the factory during regular business hours (9am – 6pm EST) at 301-470-3278. Additional information can be found on our web site: <http://www.marslabs.com>

General Guidelines and Warnings

Electrostatic Discharge

Electrostatic Discharge (ESD) occurs when a static charge builds up on either yourself or the Titan hardware, and then you touch the Titan hardware. The static spark can be so small that you don't feel it, however, it can flaw a semiconductor. These flaws may generate an immediate failure, or, in most cases, cause a slight reduction in performance which will continue to degrade, eventually leading to failure of the hardware. When you feel a static shock, you are experiencing a minimum of 3,000 volts of electricity.

Even though the input connectors have protection to prevent ESD damage, it is good practice to always ground yourself and the Titan hardware while connecting and removing sensors.



Always use approved ESD handling procedures to prevent ESD damage.

Grounding Titans

In general, grounding the Titan hardware to the test vehicle or test structure will usually reduce noise pickup.

All of the analog inputs of the Titan hardware have a return path to ground. However, it is very important that each sensor have only one return path to avoid ground loops. When testing a vehicle, often the vehicle chassis and Titan can have very large ground imbalances of one or two volts. In such situations, ground the sensors to Titan and use differential inputs across the sensor. A totally floating input (like a 9-Volt battery) must have one side grounded at the point where used, either grounded to Titan or connected to the vehicle chassis ground via a resistor (e.g. 10K ohm).

If there is a possibility that a floating sensor may be occasionally grounded, install a 10K ohm resistor from the minus input to Titan ground. When the sensor is floating, the 10K ohm resistance will reference it to Titan ground, and when it is grounded, the resistor will allow the direct minus input wire to reference the remote chassis ground.



Specific Warnings

1. When using a power adapter with the Titan, always connect the adapter to the Titan before applying power. Never hot plug a Titan device under any circumstances - hot plugging may damage the device!
2. Under no conditions should the 12V and 5V lines on the Titan hardware be shorted together or connected directly to ground.

Guidelines for Wiring Sensors

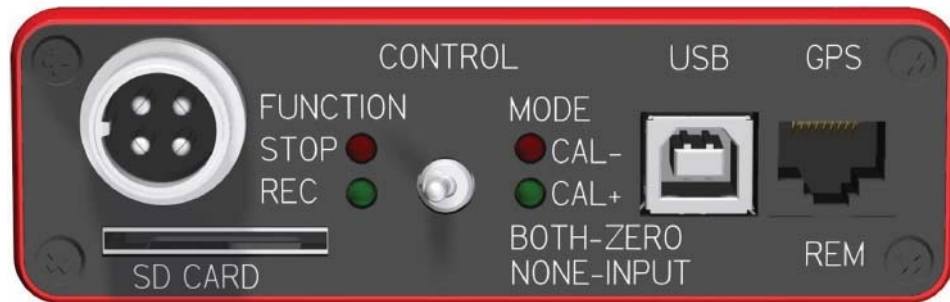
Observe the following guidelines when wiring and connecting sensors to the Titan hardware:

1. Observe polarity of sensor wires
2. Strain relieve all connections
3. Secure cables with wire ties and bundle cables where possible.
4. Secure DB9 connectors by fastening to the Titan chassis
5. For Thermocouples, apply heat shrink to exposed wires
6. Double check all connections prior to connecting the cables to the Titan.
7. Use only heavy gauge CAT-6 cables with locking tabs when connecting to the Titan CPU.
8. When routing cables, be aware of sharp edges and pinch points where cables can bind, or be cut, introducing shorts in the wiring

Operation

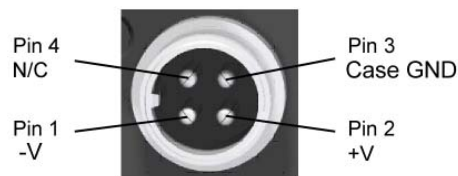
Front Panel

The Titan ADF Mini-Recorder front panel incorporates an SD Memory card slot, a CONTROL toggle switch to initiate remote recording and select calibration modes, connections for USB, GPS, and Auxiliary Power.



Auxiliary Power Connector

The Auxiliary Power Connector is used to power the Titan Mini-Recorder in remote applications. The connector pinout is shown below. The voltage applied to Pin 2 is the operating voltage of the Mini-Recorder (the operating voltage depends on the model).



WARNING: When using a power adapter with a Titan device, always connect the adapter to the device before applying power. Never hot plug a device under any circumstances - hot plugging may damage the device!

NOTE: The mating connector for 4-pin Auxiliary Power input is available from the following sources:

Mars Labs - P/N MLCON10227

Description: 4-Pin Female CB and HAM Radio Microphone Plug

Radio Shack - P/N 274-001

Description: 4-Pin Female CB and HAM Radio Microphone Plug

Westlake Electrical Supply - P/N T609B

Description: 4-Pin Inline Female Mobile Connector

SD Card Slot

The Mini-Recorder accepts Ultra II, Extreme III, or Class 10 SD cards. Make sure to have an SD memory card inserted prior to initiating recording or configuring tests in the Titan Control Software (TCS) application. In order to create a test header file on the SD card, you must configure a test in TCS prior to recording. This is done by creating a new test in TCS, connecting to the Mini-Recorder, configuring the sensors, and initiating a Scan. For more information, consult the TCS User Manual.

NOTE: *If you are using memory cards other than the one supplied, those cards must be formatted prior to use. See page 13 for the procedure on formatting memory cards for the Titan Mini-Recorder.*

CONTROL Switch

The CONTROL switch is a multi-function toggle switch that is used to initiate manual recording and select calibration modes. LEDs to the left and right of the switch indicate the current status of the CONTROL modes.

Stop Mode – The red STOP LED indicates that the Mini-Recorder is not in record mode. If no SD memory card is inserted, the STOP LED will blink continuously. If an SD memory card is inserted, the LED is illuminated solid.

Record (REC) Mode – The green REC LED is illuminated when the Mini-Recorder is recording. To enter record mode, move the toggle switch to the ‘REC’ position and release. To exit record mode, move the toggle switch to the ‘REC’ position a second time and release.

Calibration (CAL) Modes – The Mini-Recorder offers three calibration modes: ‘CAL-’, ‘CAL+’ and ‘CAL 0’. ‘CAL-’ is indicated by a red LED, ‘CAL+’ is indicated by a green LED, and ‘CAL 0’ is indicated by both red and green LEDs. When any of these LEDs are lit, the Mini-Recorder is in CAL mode. To engage CAL mode, move the toggle switch to the ‘CAL’ position and release. Successively toggling the switch will cycle through the three CAL modes as follows:

CAL- → CAL+ → CAL 0 → CAL OFF

USB Port

A USB Type B port that provides communication between the Mini-Recorder and the Titan Control Software (TCS). The port also supplies power to the device.

NOTE: *Mini-Recorders typically require two USB ports to meet the base power requirement with no sensors driven. A special dual USB cable is used for this purpose (one connection provides power and communications, while the other provides power only). When sensor excitation is enabled, however, the USB connection alone may not be able to supply sufficient power to the device and the sensors. If this occurs, external power must be provided through the Auxiliary Power connector.*

GPS Port (Auxiliary Digital Input)

A multi-function port that accepts either a GPS sensor (Garmin 18X-5Hz) or serial data from digital sensors. GPS sensor support is an optional feature on the Titan Mini-Recorder.

Rear Panel

The Titan ADF Mini-Recorder rear panel incorporates two LED status indicators, a communications (COMM) port and a DB37 input connector:



Status Indicators

P (Power) – A green LED indicating that the Mini-Recorder is ON.

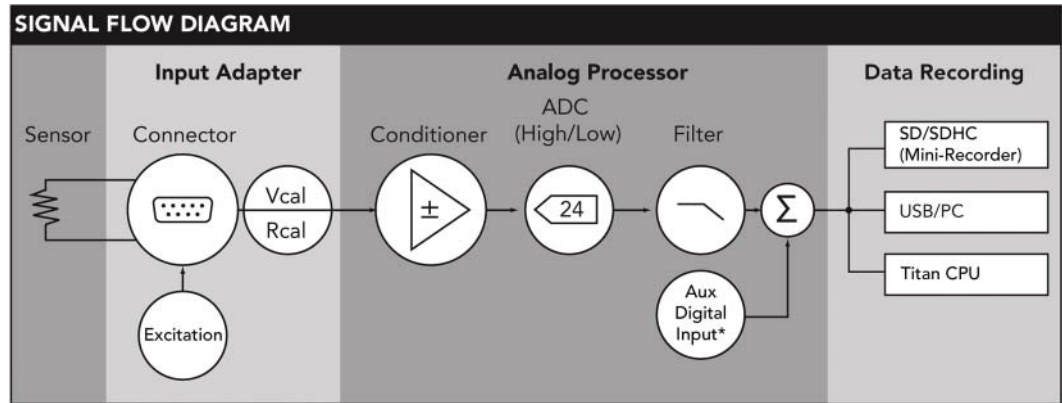
E (Error) – A red LED indicating that a sensor output has meet or exceeded the range for the configured sensor channel as displayed on the TCS ‘Tags & Channels’ screen. If the input exceeds this amount, either positive or negative, the Error LED will be lit for as long as the input exceeds the maximum range. When the input signal falls back into the acceptable range the Error LED will go out. Note that the Error LED will be lit for *any* channel that exceeds the maximum range. If you are viewing signals in the Runtime screen in TCS, the signals will be clipped when they exceed the maximum allowable input.

COMM

An RJ-45 port to interface the Mini-Recorder with the Titan CPU Channel Multiplexer and other connectivity options. Integrated LEDs in the connector (RX & TX) indicate when the Mini-Recorder is receiving or transmitting data through this port.

Signal Flow

The diagram below shows the signal flow of the Titan ADF Mini-Recorder for a single input channel. The Titan Mini-Recorder supports up to 16 channels at 1200 samples per second (low speed operation), or 10,000 samples per second (high speed operation).



The Titan Mini-Recorder features on-board signal conditioning, programmable gain and filtering, and A/D conversion. Each channel features Programmable Excitation, sensor Balance** and Calibration loopback functions (RCal and VCal) to facilitate ease of setup and ensure data integrity. All channels have individual input amplifiers to achieve high accuracy, high inter-channel isolation, and low temperature drifts. Data recording options include recording directly to a PC (via USB), to a Titan CPU Channel Multiplexer, or internally to an SD memory card.

* The Auxiliary Digital Input supports either a Garmin GPS 18X-5Hz sensor or a Titan Digital Pod. The input is labeled ‘GPS’ on the front panel.

** Balance is a function that removes channel offsets. It is configured and controlled via TCS. For more on the Balance function, consult the TCS User Manual.

Calibration Modes

Calibration for the Titan Mini-Recorder can either be activated from the panel switch or under control from TCS.

CAL+ and CAL-

Calibration modes CAL+ and CAL- activate either a shunt resistor on the sensor (if the calibration type for the channel is set to 'RCal'), or places a fixed voltage into the input (if the calibration type for the channel is set to 'VCal'). For VCal, the input is switched over to the CAL voltage (either positive or negative), while RCal maintains the input connection to the sensor, but switches in the shunt resistor.

Balance values (if any) are removed for VCal sensors, but maintained for RCal sensors.

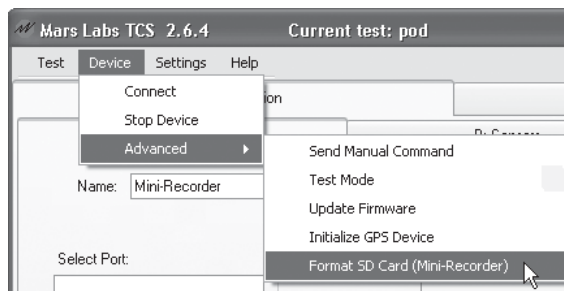
CAL0

CAL0 mode activates a common mode short on the input of all channels, providing an indication of the system offset. Like the CAL+ and CAL- modes, the balance value for VCal sensors is removed, but is maintained for RCal sensors.

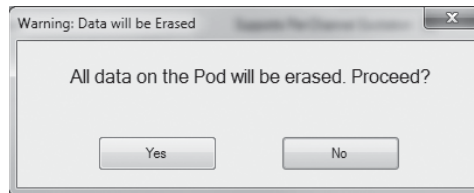
Formatting Memory Cards

New SD memory cards must be formatted for the Mini-Recorder prior to use. New memory cards should always be formatted *in the Mini-Recorder* using the following procedure:

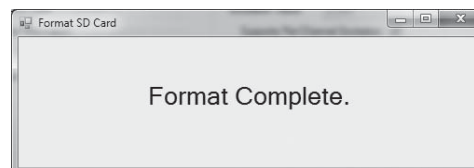
1. If a memory card is inserted, eject the card and power cycle the Mini-Recorder.
2. In TCS, connect [F1] to the Mini-Recorder.
3. Insert the SD memory card.
4. In TCS, select ‘Format SD Card (Mini-Recorder)’ from the Device menu:



5. A warning message will be displayed:



6. Click ‘YES’ to proceed and the card will be formatted. When finished, a ‘Format Complete’ message will be displayed:



7. Close the message window and disconnect in TCS, or proceed with test configurations.

NOTES:

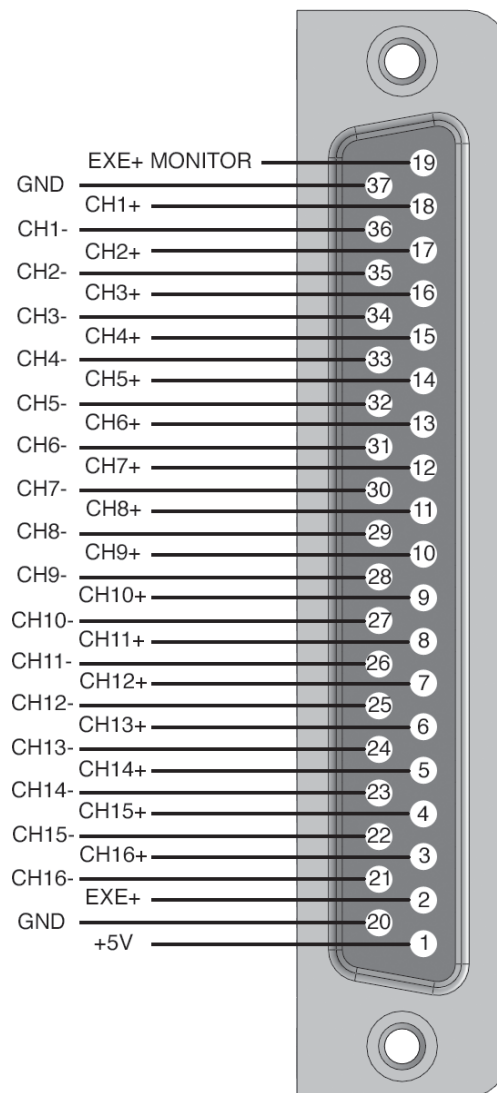
1. Memory cards up to 16GB (Ultra II, Extreme III, or Class 10) supported.
2. The maximum file size that a Pod can handle is 2GB. If your anticipated acquisition approaches or exceeds this amount, enable File Partitioning under “Recording Options” in TCS and adjust the partition size to ‘1000M’ (1GB). File Partitioning breaks up large test files into small chunks; when the chunk size limit is reached, the file is closed out and stored, and a new file is opened. For more on File Partitioning, refer to the TCS User Manual.

Interface

Pinouts for the analog input connector, communications (COMM) port and GPS port are shown below.

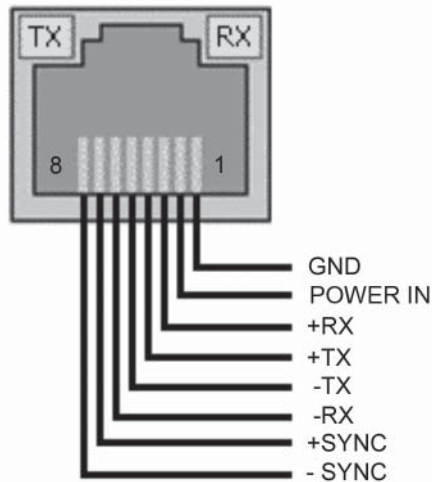
Analog Input Connector:

Titan ADF Mini-Recorder provides analog input on a single DB37F connector. The connector pinout is shown below. A list of supported sensors can be found on page 23.



COMM Port:

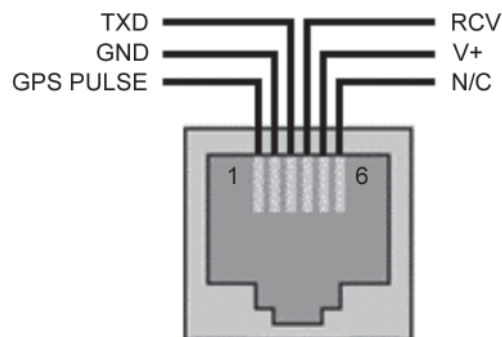
The pinout of the COMM port appears below. The POWER IN pin is internally configured at the factory for +5V, +12V or 0V. A label on the side nearest the COMM connector displays the POWER IN configuration.



NOTE: For information on configuring the COMM port for communication with TCS instead of using the USB port, refer to 'Running with RS-422' in the TCS User Manual

GPS Port:

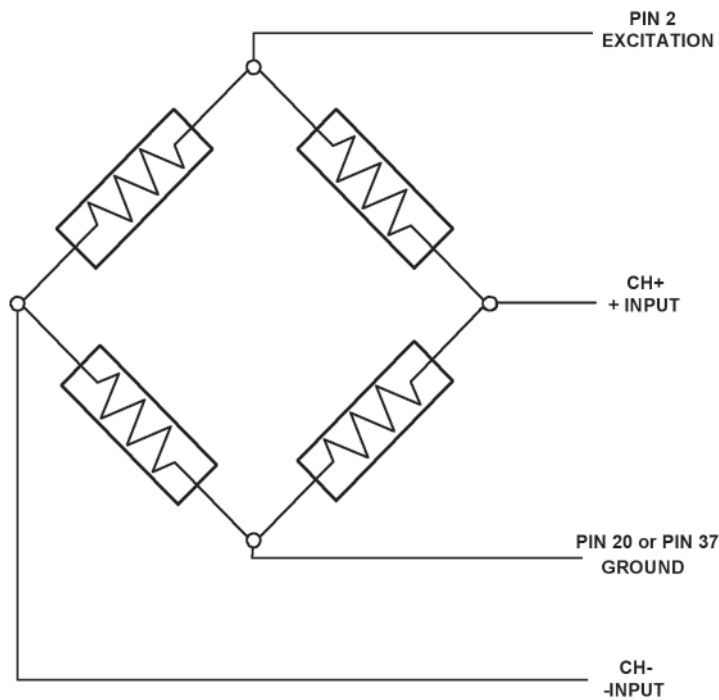
The pinout of the GPS port appears below. The labels identify the signal lines coming *from* the GPS device.



Sensor Connection Examples

The following diagrams define common sensor connections for the Titan ADF.

Full Bridge Sensor

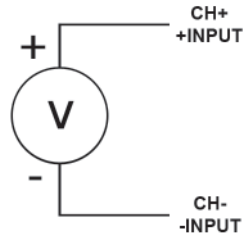


For Full Bridge configurations, the input dividers are set to OFF.



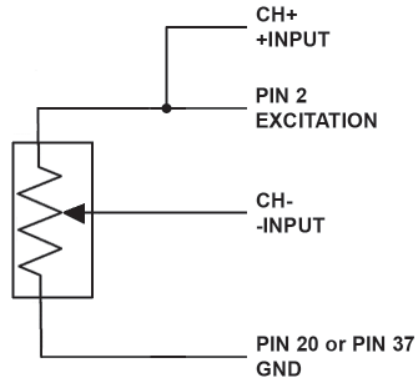
See Guidelines for Wiring Sensors, page 6

Voltage Sensor



For Voltage Sensor configurations, the input dividers must be ON.

String Pot Sensor (Cable Extension Transducer)

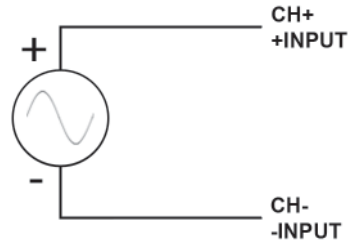


For String Pot Sensor configurations, the input dividers must be OFF.



See Guidelines for Wiring Sensors, page 6

Frequency Sensor

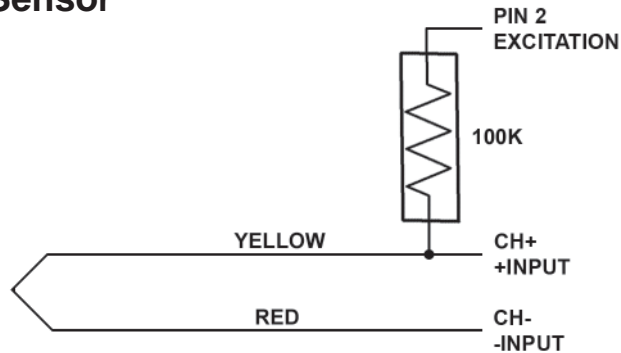


For frequency sensor inputs: TCS GAIN > 4
Input Signal > 4V_{pp}

NOTES:

1. Frequency sensors are only supported on channels 1, 8 & 16; only one frequency sensor may be used at a time
2. Frequency sensor measurements are valid to approximately 7K Hz.
3. For the configuration shown above, the input dividers must be ON.

Thermocouple Sensor



NOTE: Colors shown are for a K type thermocouple

For more information on using Thermocouples with Titan Mini-Recorders, refer to the *Theory and Operation of Thermocouples* (page 20).



See Guidelines for Wiring Sensors, page 6

This page intentionally left blank

Theory and Operation of Thermocouples

This section will address the theory and operation of thermocouples in real-world applications.

A thermocouple consists of a junction between two different metals that produces a voltage related to temperature. All dissimilar metal junctions exhibit this phenomenon, called the “Seebeck effect”. One common thermocouple is the T-Type, which is shown below:



Figure 1. Thermocouple Junction

The voltage on the Copper and Constantan (Cu and C, respectively) leads is related to the temperature of the junction J1 by a polynomial in general, and linearly when the temperature range is small. Connection of those Cu and C leads directly to a copper volt-meter results in one additional junction between the Constantan of the Thermocouple and Copper lead of the Meter, as seen below at junction J2 (J3 is Cu-Cu, which results in zero voltage):

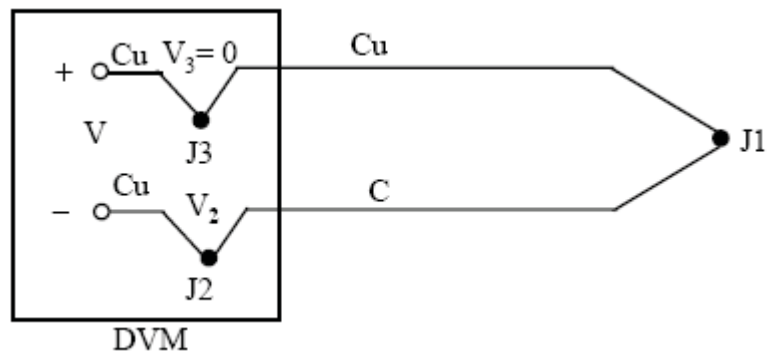


Figure 2. Thermocouple attached to a Digital Volt Meter

Compensation for this additional junction is accounted for within the Titan devices, the details of which are outside the context of this discussion.

The purpose of this discussion is to emphasize the sensitivity of the measurement to external effects. By extending the thermocouple with regular hookup wire, for instance, an additional junction is created between the thermocouple and the hookup wire. This will lead to an error in the

measurement unless some compensation for the junction is made. Additionally, by placing the junction J1 in an environment that may affect its output voltage such as in an electrolytic solution, the thermocouple may report misleading values. Finally, connection of the thermocouple to some conductive surface may or may not be of concern. Should that surface have any electrical path back to the Titan Thermocouple device such as a common ground, voltage readings from the thermocouple may be unreliable. **These concerns suggest that any and all electrical isolation (galvanic isolation) precautions should be taken when installing a thermocouple.** The material used to isolate the thermocouple should depend on the application. In most applications where temperatures are within -55 to 260 degrees C, nonconductive epoxy such as J-B Weld may be used. In more extreme temperatures, applications may call for specialty epoxy or cement. For example, if the temperature event under study is very fast the method of isolation must be very quick to change temperature. Omega Engineering sells thermally conductive cement called OmegaBond that is electrically isolating and suitable for such uses. Thin coats of this cement may be applied to thermocouples to isolate them electrically while allowing high thermal conductivity. This cement is suitable for high temperature applications. For more information on OmegaBond, go to:

http://www.omega.com/ppt/pptsc.asp?ref=OB_BOND_CHEM_SET&Nav=temf08

Thermocouples are available in several variants. *Titan Mini-Recorder* devices support **J**, **K**, and **T** type thermocouples (only one type of thermocouple may be used at a time). The table below displays the temperature ranges and related connection information for the three supported thermocouple types.

Type	Temp Range (C)	Positive (+) Lead	Recommended TCS Gain
K	-180 to +1300	Yellow	32
J	-180 to +800	White	32
T	-250 to +400	Blue	32

In summary, when using thermocouples:

- 1) Electrically isolate thermocouples from the environment in which they are used
- 2) Minimize isolation mass around thermocouple when concerned with high-speed temperature events
- 3) Use the appropriate thermocouple for the application
- 4) Use appropriate thermocouple hookup or extension cabling for the type of thermocouple in use
- 5) Always observe the polarity of connections

Features and Specifications

Key Features

- Supports multiple modes of operation:
 - Standalone recording up to 16 channels
 - Connected to a PC recording up to 16 channels
 - Connected to an 8-port Titan CPU Channel Multiplexer for up to 128 channels
- High performance analog front-end with full Balance, $\pm V_{cal}$ and Rcal loopback
- Lightweight, portable unit suitable for in-vehicle applications.
- Sensor input connections via industry-standard DB37 connector
- Simplified user interface provides easy operation under difficult operating conditions.
- Sample rates up to 1200 Hz/channel (low speed) or 10,000 Hz/channel (high speed)

Specifications

Number of Channels	16 fault tolerant channel on a DB-37 connector
Excitation	Fixed 2.048 Volts
Programmable Gain	From $\pm 1/16$ to ± 512 ; Full scale input voltage up to $\pm 32V$
Programmable Filter	8 pole Butterworth for scan rates up to 1200 samples/sec 10 pole Linear Phase for scan rates > 1200 samples/sec
Calibration Modes	Resistive (RCal): $\pm 100K$ ohms per channel (shunt calibration) Voltage (VCal): Precision positive and negative calibration voltages
Sensors Supported	See table, page 23
Recorder	Records data to Secure Digital memory card. Supports SD cards up to 16 GB.
PC Operation	Remote recording and control via USB
Stand-alone operation	Via on-board switches
GPS	Optional GPS support for the Garmin GPS 18X 5Hz; PPS support
Power Requirements	11-32VDC, 3W for base unit
Dimensions	13.9cm x 10.6 cm x 3.4 cm (L x W x H)

Supported Sensors

Analog

The table below shows the types of analog sensors supported by the Titan ADF Mini-Recorder.

Titan Device Type	Input Connector	Sensors Supported				
		Strain Gauge		¹	Differential Voltage ±32V	²
		Full Bridge	Bridge Comp.	TC		Tach
ADF	DB37	16	N	16	16	1

NOTES:

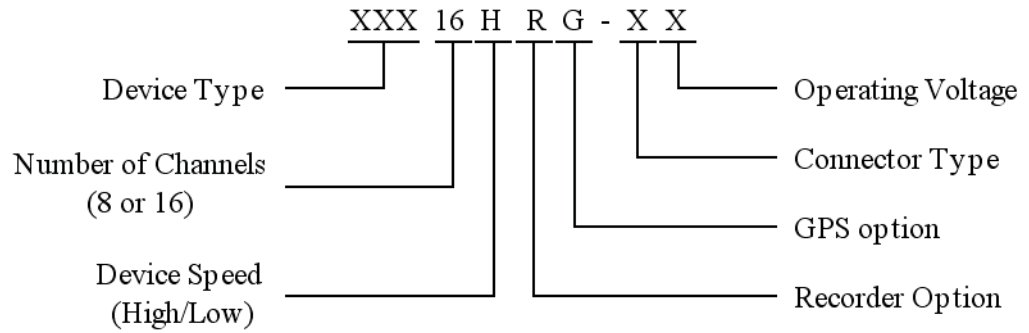
1. Titan devices support Thermocouple (TC) types J, K & T.
2. Supports Tachometer frequencies up to 7KHz. Period or Frequency sensors are only supported on channels 1, 8, and 16, and only one sensor can be used at a time.

Digital

Using an External Digital Pod, the Titan ADF Mini-Recorder provides digital sensor support for SAE J1939, ISO 15765 (ECU CAN), GPS (Garmin 18X-5Hz), IMU (3DM-GX3), and multiple WFT protocols including Kistler and Michigan Scientific.

Titan Nomenclature

The Titan ADF offers a wide range of configuration options. Titan device configurations are specified by the part number in the following format:



Titan Device Type:

ADF - 'A' Series Differential

Connector Type:

'0' - DB37 Female

Operating Voltage:

'1' - for 12 volt devices

'2' - for 24 volt devices

'3' - for wide input range devices (11 - 32V)

Asset Tag/Customer Information Data Entry

Titan Mini-Recorder firmware (v0.31.10 and higher) permits user-entry and storage of asset tag and other customer-specific information on the device. A dedicated ‘Asset Tag’ field permits entry of up to 15 characters, while a dedicated ‘Customer Information’ field supports up to 31 characters. Once the information is entered, these fields can be locked to prevent changes or tampering. The information is entered using the Manual Command window in TCS using the commands listed below.

To use the commands:

1. Determine beforehand what information will be entered in these fields.
 - You may enter up to 15 characters (not including the asterisk [*]) for the Asset Tag field.
 - You may enter up to 31 characters (not including the asterisk) for the Customer Information field.
 - Character strings may not include a colon (:), a Carriage Return <CR> or a Line Feed <LF>.
2. Enter the Asset Tag information as defined, adding an asterisk to the end of the string as shown below. *Do not set the lock.*
3. Enter the Customer Information as defined, adding an asterisk to the end of the string as shown below. *Do not set the lock.*
4. Using the GET_ASSET_TAG and GET_CUSTOMER commands, confirm that the assigned field values are correct.
5. Issue the SET_ASSET_LOCK command. The Asset Tag and Customer Information fields will then be permanently stored on the device and can be accessed at any time using the GET commands.

The Commands

SET_ASSET_TAG

Syntax: SET_ASSET_TAG<space><15 char string>* <send>
 Summary: Fills the Asset Tag field with up to 15 characters
 Valid Inputs: <15 char string>
 Example: SET_ASSET_TAG ABC-123*
 Valid Outputs: ACK, ERROR

GET_ASSET_TAG

Syntax: GET_ASSET_TAG <send>
 Summary: Returns the Asset Tag character string
 Sample Output: “ABC-123”

SET_CUSTOMER

Syntax: SET_CUSTOMER<space><31 char string>* <send>
Summary: Fills the Customer Information field with up to 31 characters
Valid Inputs: <31 char string>
Example: SET_CUSTOMER My Titan BMS Device*
Valid Outputs: ACK, ERROR

GET_CUSTOMER

Syntax: GET_CUSTOMER <send>
Summary: Returns the Customer Information character string
Sample Output: "My Titan BMS Device"

SET_ASSET_LOCK

Syntax: SET_ASSET_LOCK <send>
Summary: Permanently locks the Asset Tag and Customer Information fields.
Warning: Once used, this command cannot be undone!
Example: SET_ASSET_LOCK
Valid Outputs: ACK, ERROR

GET_ASSET_LOCK

Syntax: GET_ASSET_LOCK <send>
Summary: Returns the state of the Asset Tag and Customer Information field locking mechanism.
Sample Output: "LOCKED", "UNLOCKED"

Troubleshooting

If you are having difficulties configuring, connecting or using your Titan device, refer to the troubleshooting section below. This section addresses common issues with the operation of Titan devices. If your specific issue is not addressed, please contact the factory for additional assistance.

Issue: No power

After connecting the Titan device via USB, the Power LED does not illuminate (no power).

Solution

Titan devices use a special dual-USB cable to provide power from two USB ports, as a single USB connection may not supply sufficient power in some configurations. If both USB connectors are plugged in and the Titan device still isn't powered, try connecting to another USB port pair on the host PC. If the problem persists, try applying power to the Titan device through the Auxiliary Power Connector. If the Titan device still isn't working, contact the factory for additional support.

Issue: Windows holds port open

If you fail to disconnect in TCS before physically disconnecting or powering down the Titan device, Windows holds that port open. When you reconnect, the port appears twice in the *Select Port* field in TCS.

Solution

Click 'Disconnect' in TCS. Physically disconnect the Titan device. In TCS, click 'Query Serial Devices'. This will clear the *Select Port* field and unlock the COM port.

Issue: Windows won't recognize the Titan device when using a DAC

If you are using a Titan DAC with a new installation of TCS, Windows does not recognize the hardware.

Solution

This can happen if the Titan device drivers are not installed. Remove the DAO temporarily from the configuration and plug the Titan device directly into USB. The Windows 'Hardware Install' wizard will recognize that new hardware is connected and begin the driver installation process. Allow this process to complete before reconnecting the DAC.

Issue: No output from sensors

One or more of the connected sensors does not output data.

Solution

If the sensor requires power (excitation) and the Titan device is powered solely from USB, power may be insufficient to run the sensors. If you encounter this problem, apply power through the Auxiliary Power Connector.

Issue: SD Card not recording data/recording wrong data

The SD card doesn't record data, or the SD card appears to be recording data incorrectly.

Solution

To record data properly to an SD card, the Titan device must be loaded with the current test file parameters. If an old test file configuration is used, the data can appear to be corrupted or invalid. To download the current test file, you must be connected to TCS. Configure the test parameters in TCS, then go to the 'Runtime' tab and click 'SCAN'. TCS will download the current test file parameters to the Titan device.

Issue: Cannot record remotely

You cannot record remotely to the Titan device.

Solution

Check to make sure that an SD memory card is properly inserted in the SD memory card slot. Titan devices accept Ultra II, Extreme III, or Class 10 SD cards up to 16GB (Sandisk cards recommended). If a known-good card is properly installed and you still can't record, check to make sure that there is free memory available. Titan devices will not go into remote recording mode if no free space is available on the SD card.

Issue: Cannot record remotely when connected to a Titan CPU

You cannot record remotely when the Titan device is connected to a Titan CPU.

Solution

This is normal operation. When the Mini-Recorder is connected to the CPU, the Mini-Recorder remote recording function is disabled on both panel switch and the remote recording jack.

Issue: “A device attached to the system is not functioning” error

When attempting to connect through TCS to a device that is connected via USB *before* Auxiliary Power is applied, TCS may report an error message:

“A device attached to the system is not functioning”

Solution

To correct the error, perform the following steps:

- a. Disconnect from TCS
- b. Disconnect the USB cable from the Mini-Recorder and remove Auxiliary Power.
- c. Apply Auxiliary Power, allowing the device to initialize, and then remove power.
- d. Apply Auxiliary Power and allow the device to initialize
- e. Reconnect the USB cable
- f. Connect to the device through TCS

To prevent this issue from reoccurring when powering the Mini-Recorder with Auxiliary Power:

- a. Apply Auxiliary Power before connecting to USB.
- b. Remove USB before removing Auxiliary Power.

Notes and Known Issues

This section offers additional operational information about the Titan Mini-Recorder not covered elsewhere.

Known Issues:

General:

The Mini-Recorder will stop running if scanning with USB enumerated but not connected/opened in either TCS or a terminal emulator.

High Speed Issues:

When operating at the 10K Hz scan rate while connected via USB, the Mini-Recorder will support a maximum of 12 channels. If full 16-channel operation with a USB connection is desired, select the 8192 or lesser scan rate.

GPS Issues:

1. GPS does not operate correctly at the 10K Hz scan rate.
2. GPS output does not currently include northing and easting data.

Transferring Large Data Files:

Large data files (greater than 400Mb) transferred from the SD memory through the Mini-Recorder can result in transfer errors. For this reason, large data files should be transferred directly from the SD memory to the test PC.

Calibration:

Calibration values deviate by a factor of 2 for a gain of 256, and by a factor of 4 for a gain of 512.

In-Vehicle:

For In-Vehicle applications, if the Mini-Recorder is powered from the vehicle and running when the vehicle is started, the device may require power-cycling.

Remote acquisitions larger than 2GB:

The maximum remote file size that a Pod can handle is 2GB. Remote files larger than 2GB will not show up properly when “Browse Device” is selected in the ‘Browse Remote Files’ tab. If your anticipated acquisition approaches or exceeds this amount, enable File Partitioning under “Recording Options” in TCS and adjust the partition size to ‘1000M’ (1GB). File Partitioning breaks up large test files into small chunks; when the chunk size limit is reached, the file is closed out and stored, and a new file is opened. For more on File Partitioning, refer to the TCS User Manual.

Digital Pod Issues

When using a digital pod with a full load, i.e., two CAN Channels, a GPS, and IMU, in Low Speed mode at 1024 or 1200 Hz, you cannot remotely record while the device is connected over USB and scanning. Attempting to do this will cause a failure in the system and the device will have to be power-cycled to restore normal operation.

Warranty

Mars Labs warrants all their manufactured equipment to be free from defects in material and workmanship. **Mars Labs** liability under this warranty is limited to servicing or adjusting any equipment returned to the factory for that purpose, and to replace any defective parts thereof. The warranty remains effective for 365 days following delivery to the original purchaser. During this time, equipment will only receive repair when the original purchaser prepays all return transportation charges, and **Mars Labs** finds to its satisfaction that the equipment is indeed defective.

If the fault has been caused by misuse or abnormal conditions of operation, normal service charges will prevail. In this case, an estimate will be submitted before work is started. **Mars Labs** must authorize any warranty returns.

Mars Labs reserves the right to make changes in the design of its instruments without incurring any obligation to make the same changes on equipment previously purchased.

This warranty will be void if unauthorized alterations or modifications are found which impede the repair or testing of the equipment.

Receipt of Equipment

The equipment should be tested as soon as it is received. If the equipment is damaged in any way, a claim should be obtained by the claim agent, and this report should be forwarded to **Mars Labs**.

Mars Labs will then advise the customer of the disposition to be made of the equipment and arrange for repair or replacement. When referring to this equipment for any reason, the model number, serial number and purchase order number should be included.

Malfunction

If the unit fails to operate, or any fault develops, **Mars Labs** should be notified, giving full details of the difficulty, including model number and serial number. Upon receipt of this information, **Mars Labs** will provide service data and shipping instructions.

This warranty is expressly in lieu of all other obligations or liabilities on the part of **Mars Labs**, which neither assumes nor authorizes any person to assume for it any other liability in connection with the sale of its equipment. Contact:

Mars Labs
29 C Street
Laurel, MD
20707
(301) 470-3278
email: Support@MarsLabs.com

