

2021

AP® Physics 1: Algebra-Based Free-Response Questions

FORMULAE

Q-1 → $R = \frac{u^2 \sin 2\theta}{g}$

Que-2 → $\text{STRESS} = \frac{\text{FORCE}}{\text{AREA}}$

Que-3 → $v_{cm} = \frac{m_1 v_1 + m_2 v_2}{m_1 + m_2}$

Que-4 → $mgh = \frac{1}{2} m v^2$

Que-5 → $\vec{\tau} = \vec{r} \times \vec{f}$



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AP[®] PHYSICS 1 TABLE OF INFORMATION

CONSTANTS AND CONVERSION FACTORS

Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude, $e = 1.60 \times 10^{-19}$ C
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant, $k = 1/4\pi\epsilon_0 = 9.0 \times 10^9$ N·m ² /C ²
Electron mass, $m_e = 9.11 \times 10^{-31}$ kg	Universal gravitational constant, $G = 6.67 \times 10^{-11}$ m ³ /kg·s ²
Speed of light, $c = 3.00 \times 10^8$ m/s	Acceleration due to gravity at Earth's surface, $g = 9.8$ m/s ²

UNIT SYMBOLS	meter, m	kelvin, K	watt, W	degree Celsius, °C
	kilogram, kg	hertz, Hz	coulomb, C	
	second, s	newton, N	volt, V	
	ampere, A	joule, J	ohm, Ω	

PREFIXES		
Factor	Prefix	Symbol
10^{12}	tera	T
10^9	giga	G
10^6	mega	M
10^3	kilo	k
10^{-2}	centi	c
10^{-3}	milli	m
10^{-6}	micro	μ
10^{-9}	nano	n
10^{-12}	pico	p

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
θ	0°	30°	37°	45°	53°	60°	90°
$\sin \theta$	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
$\tan \theta$	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	∞

The following conventions are used in this exam.

- I. The frame of reference of any problem is assumed to be inertial unless otherwise stated.
- II. Assume air resistance is negligible unless otherwise stated.
- III. In all situations, positive work is defined as work done on a system.
- IV. The direction of current is conventional current: the direction in which positive charge would drift.
- V. Assume all batteries and meters are ideal unless otherwise stated.

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AP[®] PHYSICS 1 EQUATIONS

MECHANICS

$$v_x = v_{x0} + a_x t$$

$$x = x_0 + v_{x0} t + \frac{1}{2} a_x t^2$$

$$v_x^2 = v_{x0}^2 + 2a_x(x - x_0)$$

$$\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$$

$$|\vec{F}_f| \leq \mu |\vec{F}_n|$$

$$a_c = \frac{v^2}{r}$$

$$\vec{p} = m\vec{v}$$

$$\Delta \vec{p} = \vec{F} \Delta t$$

$$K = \frac{1}{2} m v^2$$

$$\Delta E = W = F_{\parallel} d = F d \cos \theta$$

$$P = \frac{\Delta E}{\Delta t}$$

$$\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

$$\omega = \omega_0 + \alpha t$$

$$x = A \cos(2\pi f t)$$

$$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$$

$$\tau = r_{\perp} F = r F \sin \theta$$

$$L = I \omega$$

$$\Delta L = \tau \Delta t$$

$$K = \frac{1}{2} I \omega^2$$

$$|\vec{F}_s| = k |\vec{x}|$$

$$U_s = \frac{1}{2} k x^2$$

$$\rho = \frac{m}{V}$$

a = acceleration
 A = amplitude
 d = distance
 E = energy
 f = frequency
 F = force
 I = rotational inertia
 K = kinetic energy
 k = spring constant
 L = angular momentum
 ℓ = length
 m = mass
 P = power
 p = momentum
 r = radius or separation
 T = period
 t = time
 U = potential energy
 V = volume
 v = speed
 W = work done on a system
 x = position
 y = height
 α = angular acceleration
 μ = coefficient of friction
 θ = angle
 ρ = density
 τ = torque
 ω = angular speed

$$\Delta U_g = m g \Delta y$$

$$T = \frac{2\pi}{\omega} = \frac{1}{f}$$

$$T_s = 2\pi \sqrt{\frac{m}{k}}$$

$$T_p = 2\pi \sqrt{\frac{\ell}{g}}$$

$$|\vec{F}_g| = G \frac{m_1 m_2}{r^2}$$

$$\vec{g} = \frac{\vec{F}_g}{m}$$

$$U_G = -\frac{G m_1 m_2}{r}$$

ELECTRICITY

$$|\vec{F}_E| = k \left| \frac{q_1 q_2}{r^2} \right|$$

$$I = \frac{\Delta q}{\Delta t}$$

$$R = \frac{\rho \ell}{A}$$

$$I = \frac{\Delta V}{R}$$

$$P = I \Delta V$$

$$R_s = \sum_i R_i$$

$$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$$

A = area
 F = force
 I = current
 ℓ = length
 P = power
 q = charge
 R = resistance
 r = separation
 t = time
 V = electric potential
 ρ = resistivity

WAVES

$$\lambda = \frac{v}{f}$$

f = frequency
 v = speed
 λ = wavelength

GEOMETRY AND TRIGONOMETRY

Rectangle
 $A = bh$

Triangle
 $A = \frac{1}{2} bh$

Circle
 $A = \pi r^2$
 $C = 2\pi r$

Rectangular solid
 $V = \ell wh$

Cylinder
 $V = \pi r^2 \ell$
 $S = 2\pi r \ell + 2\pi r^2$

Sphere
 $V = \frac{4}{3} \pi r^3$
 $S = 4\pi r^2$

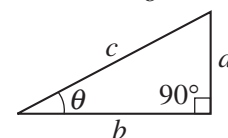
Area and Volume
 A = area
 C = circumference
 V = volume
 S = surface area
 b = base
 h = height
 ℓ = length
 w = width
 r = radius

Right triangle
 $c^2 = a^2 + b^2$

$$\sin \theta = \frac{a}{c}$$

$$\cos \theta = \frac{b}{c}$$

$$\tan \theta = \frac{a}{b}$$



Begin your response to **QUESTION 1** on this page.

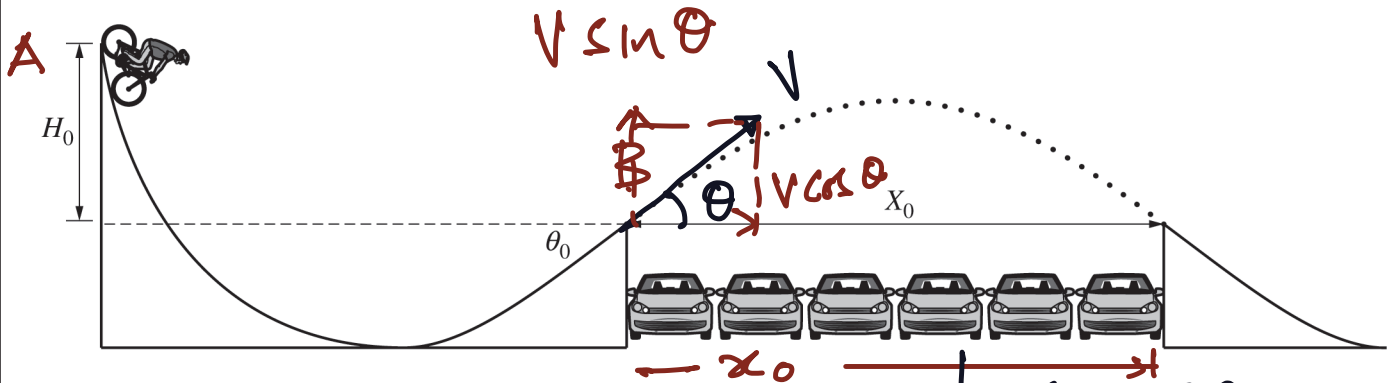
PHYSICS 1

SECTION II

Time—1 hour and 30 minutes

5 Questions

Directions: Questions 1, 4, and 5 are short free-response questions that require about 13 minutes each to answer and are worth 7 points each. Questions 2 and 3 are long free-response questions that require about 25 minutes each to answer and are worth 12 points each. Show your work for each part in the space provided after that part.



Note: Figure not drawn to scale.

6 CARS

$$\text{WIDTH OF 1 CAR} = \frac{X_0}{6}$$

1. (7 points, suggested time 13 minutes)

A stunt cyclist builds a ramp that will allow the cyclist to coast down the ramp and jump over several parked cars, as shown above. To test the ramp, the cyclist starts from rest at the top of the ramp, then leaves the ramp, jumps over six cars, and lands on a second ramp.

H_0 is the vertical distance between the top of the first ramp and the launch point. $X_0 = 4H_0 \cos \theta_0 \sin \theta_0$
 θ_0 is the angle of the ramp at the launch point from the horizontal.
 X_0 is the horizontal distance traveled while the cyclist and bicycle are in the air.
 m_0 is the combined mass of the stunt cyclist and bicycle.

- (a) Derive an expression for the distance X_0 in terms of H_0 , θ_0 , m_0 , and physical constants, as appropriate.

consider conservation of energy between point A & B $\rightarrow m_0 g H_0 = \frac{1}{2} m_0 v^2$
 $v = \sqrt{2gH_0}$, $x_0 = (v \cos \theta)(t)$, $t = \frac{2v \sin \theta}{g}$
 $x_0 = v \cos \theta \left(\frac{2v \sin \theta}{g} \right) = \frac{2v^2 \sin \theta \cos \theta}{g} = \frac{2 \times 2gH_0 \sin \theta \cos \theta}{g}$

GO ON TO THE NEXT PAGE.

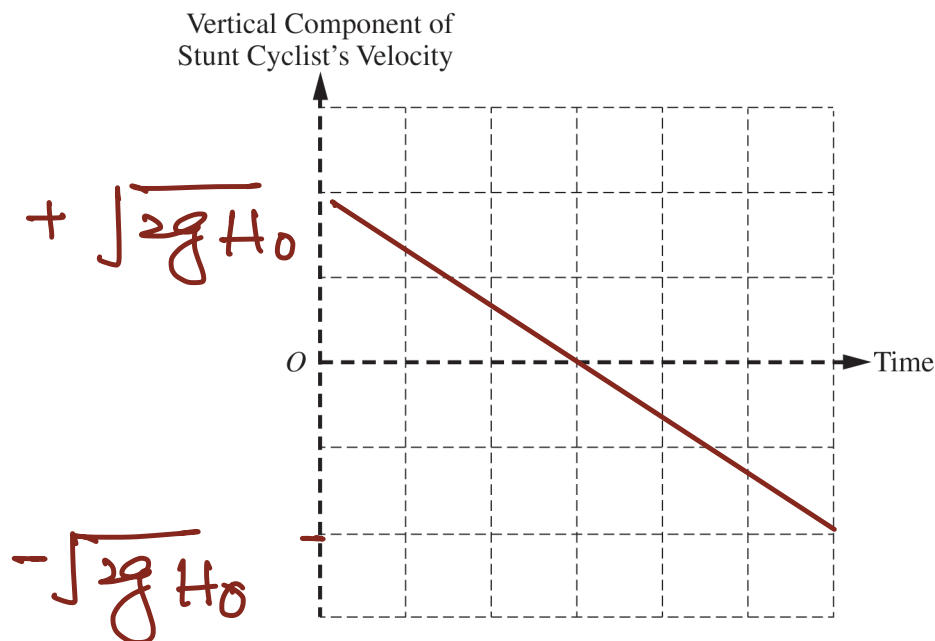
Continue your response to **QUESTION 1** on this page.

- (b) If the vertical distance between the top of the first ramp and the launch point were $2H_0$ instead of H_0 , with no other changes to the first ramp, what is the maximum number of cars that the stunt cyclist could jump over? Justify your answer, using the expression you derived in part (a).

$$\text{For } 2H_0, \quad x_0 = 4(2H_0) \cos \theta \sin \theta \\ = 8H_0 \cos \theta \sin \theta$$

then Range becomes twice, hence He will cross 12 cars

- (c) On the axes below, sketch a graph of the vertical component of the stunt cyclist's velocity as a function of time from immediately after the cyclist leaves the ramp to immediately before the cyclist lands on the second ramp. On the vertical axis, clearly indicate the initial and final vertical velocity components in terms of H_0 , θ_0 , m_0 , and physical constants, as appropriate. Take the positive direction to be upward.



GO ON TO THE NEXT PAGE.

A group of students is investigating how the thickness of a plastic rod affects the maximum force F_{\max} with which the rod can be pulled without breaking. Two students are discussing models to represent how F_{\max} depends on rod thickness.

Student B claims that F_{\max} is directly proportional to the cross-sectional area of the rod—the area of the base of the cylinder, shaded gray in the figure above.

In the table below, list the quantities that would be measured in your experiment. Define a symbol to represent each quantity, and also list the equipment that would be used to measure each quantity. You do not need to fill in every row. If you need additional rows, you may add them to the space just below the table.

Quantity to be Measured	Symbol for Quantity	Equipment for Measurement
FORCE TO BREAK THE ROD	F	FORCE SENSOR
Radius of the rod	$m m$	Ruler

Write answers with black or dark blue ink only. Do NOT write your name. Do NOT write outside the box.

Continue your response to QUESTION 2 on this page.

Describe the overall procedure to be used, referring to the table. Provide enough detail so that another student could replicate the experiment, including any steps necessary to reduce experimental uncertainty. As needed, use the symbols defined in the table and/or include a simple diagram of the setup.

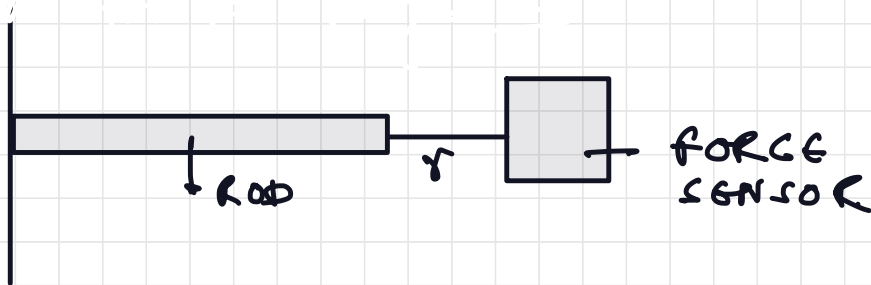
① calculate A , for which δ should be calculated.

$$A = \pi \delta^2$$

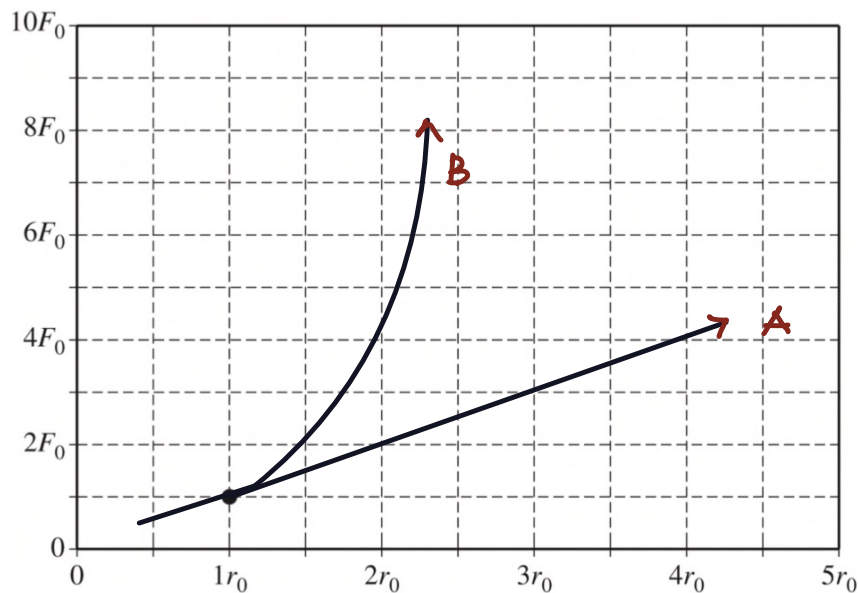
② Record H.sec by applying force and measure force by using force sensor. and Repeat with rod of same thickness

③ Repeat step ① & step ② rods of different material

④ student will then make a graph between F & δ to find the best fit and analyse



(b) For a rod of radius r_0 , it is determined that F_{\max} is F_0 as indicated by the dot on the grid below. On the grid, draw and label graphs corresponding to the two students' models of the dependence of F_{\max} on rod radius. Clearly label each graph "A" or "B," corresponding to the appropriate model.

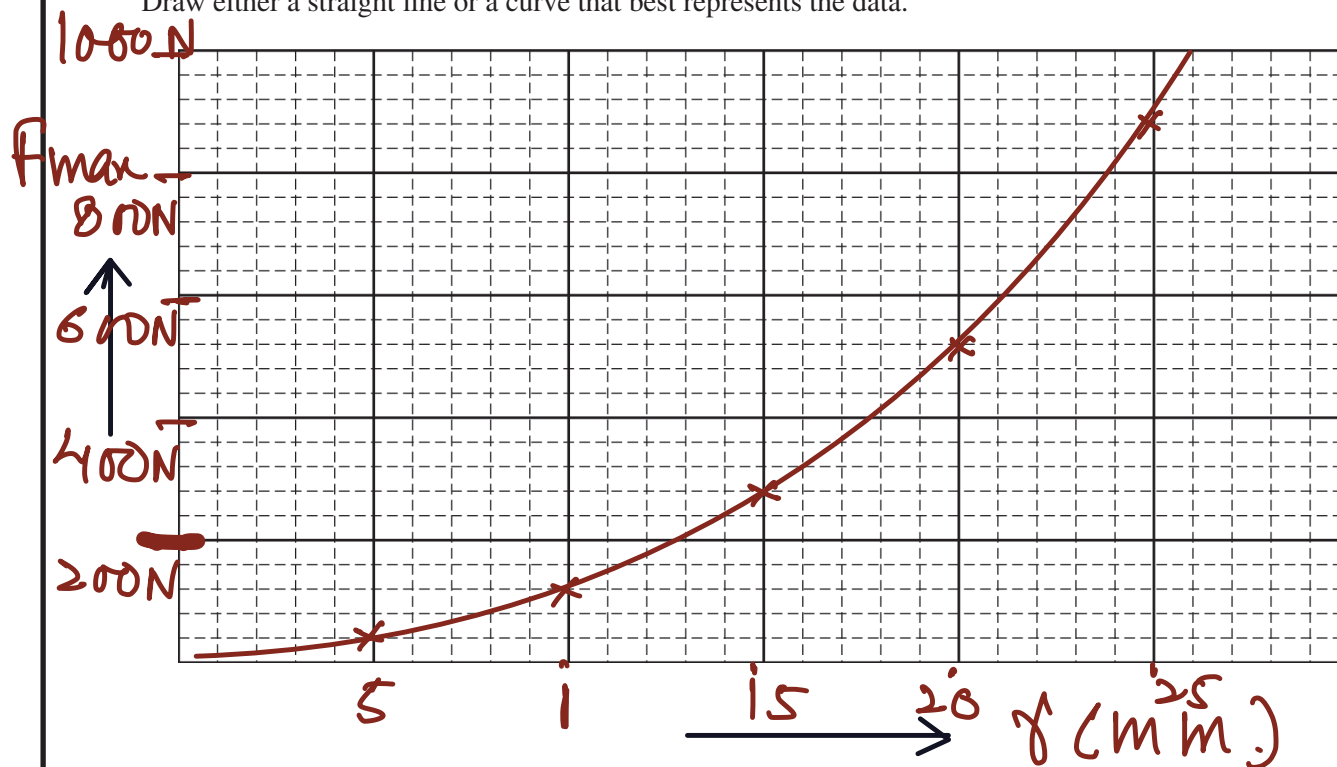


Continue your response to **QUESTION 2** on this page.

The table below shows results of measurements taken by another group of students for rods of different thicknesses.

Rod radius (mm)	0.5	1.0	1.5	2.0	2.5
F_{\max} (N)	40	120	320	520	900

(c) On the grid below, plot the data points from the table. Clearly scale and label all axes, including units. Draw either a straight line or a curve that best represents the data.



(d) Which student's model is more closely represented by the evidence shown in the graph you drew in part (c) ?

____ Student A's model: F_{\max} is directly proportional to the radius of the rod.

✓ Student B's model: F_{\max} is directly proportional to the cross-sectional area of the rod.

Explain your reasoning.

$$F_{\max} \propto r^2 \propto A$$

$$A = \pi r^2$$

GO ON TO THE NEXT PAGE.

Begin your response to **QUESTION 3** on this page. 3. (12 points, suggested time 25 minutes)

(a) A student of mass M_S standing on a smooth surface, uses a stick to push a disk of mass M_D . The student exerts a constant horizontal force of magnitude F_H over the time interval from time $t = 0$ to $t = t_f$ while pushing the disk. Assume there is negligible friction between the disk and the surface.

i. Assuming the disk begins at rest, determine an expression for the final speed V_D of the disk relative to the surface. Express your answer in terms of F_H , t_f , M_S , M_D and physical constants, as appropriate.

$$F_H = M_D a \Rightarrow a = \frac{F_H}{M_D}$$
$$V_D = 0 + a t_f$$

$$V_D = \left(\frac{F_H}{M_D} \right) t_f$$

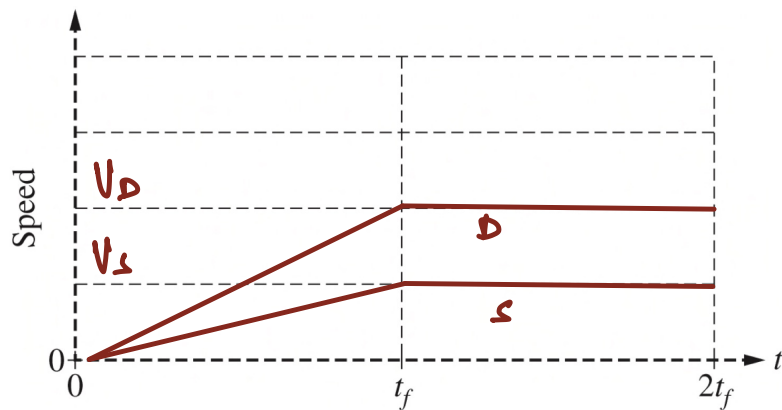
ii. Assume there is negligible friction between the student's shoes and the surface. After time t_f , the student slides with speed V_S . Derive an equation for the ratio V_D/V_S . Express your answer in terms of M_S , M_D and physical constants, as appropriate.

No frictional force it means conservation of linear momentum is valid

$$M_D V_D = M_S V_S \Rightarrow$$

$$\frac{V_D}{V_S} = \frac{M_S}{M_D}$$

(b) Assume that the student's mass is greater than that of the disk ($M_s > M_D$). On the grid below, sketch graphs of the speeds of both the student and the disk as functions of time t between $t = 0$ and $t = t_f$. Assume that neither the disk nor the student collides with anything after $t = t_f$. On the vertical axis, label V_D and V_s . Label the graphs "S" and "D" for the student and the disk, respectively.



For student

$$a_s = \frac{F}{M_s}$$

for disc

$$a_D = \frac{F}{M_D}$$

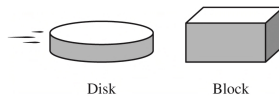
$$M_s > M_D$$

$$a_s < a_D$$

$$V_D = 0 + a_D t_f$$

$$V_s = 0 + a_s t_f$$

$$V_D > V_s$$



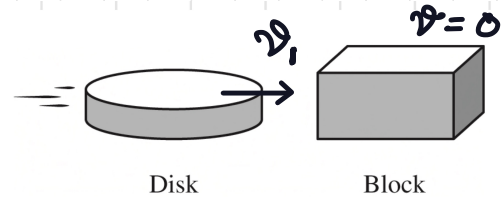
(c) The disk is now moving at a constant speed V_1 on the surface toward a block of mass M_B which is at rest on the surface, as shown above. The disk and block collide head-on and stick together, and the center of mass of the disk-block system moves with speed V_{cm} .

i. Suppose the mass of the disk is much greater than the mass of the block. Estimate the velocity of the center of mass of the disk-block system. Explain how you arrived at your prediction without deriving it mathematically.

Apply conservation of linear momentum

$$M_D V_1 + M_B(0) = (M_D + M_B) V_{cm}$$

$$V_{cm} = \frac{M_D V_1 + M_B(0)}{(M_D + M_B)} = \frac{M_D V_1}{(M_D + M_B)}$$



$$M_D > M_B$$

Hence

$$V_{cm} < V_1$$

slightly less than V_1

ii. Suppose the mass of the disk is much less than the mass of the block. Estimate the velocity of the center of mass of the disk-block system. Explain how you arrived at your prediction without deriving it mathematically.

Velocity of (disk-block) system is much less than V_1 , due to conservation of linear momentum larger mass collision decreases the velocity

iii). Now suppose that neither object's mass is much greater than the other but that they are not necessarily equal. Derive an equation for V_{cm} Express your answer in terms of V_1, M_D, M_B and physical constants, as appropriate.

As per the conservation of linear momentum

$$0 + V_1 M_D = (M_B + M_D) V_{cm}$$

$$V_{cm} = \frac{V_1 M_D}{(M_B + M_D)}$$

iv. Consider the scenario from part (c)(i), where the mass of the disk was much greater than the mass of the block. Does your equation for V_{cm} from part (c)(iii) agree with your reasoning from part (c)(i)?

☒ Yes ☐ No

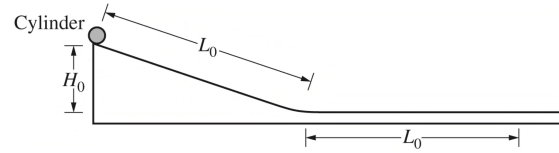
Explain your reasoning by addressing why, according to your equation, v_{cm} becomes (or approaches) a certain value when M_D is much greater than M_B .

$$V_{cm} = \frac{V_i M_D}{(M_B + M_D)}$$

$$\frac{M_D}{M_B + M_D} < 1$$

$$V_i < V_{cm}$$

Begin your response to **QUESTION 4** on this page.



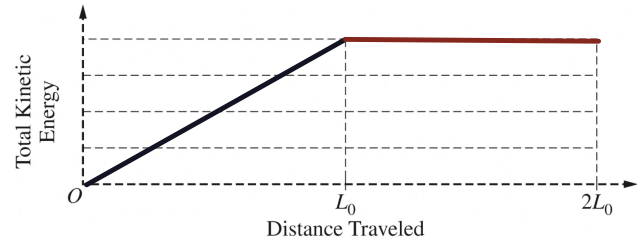
4. (7 points, suggested time 13 minutes)

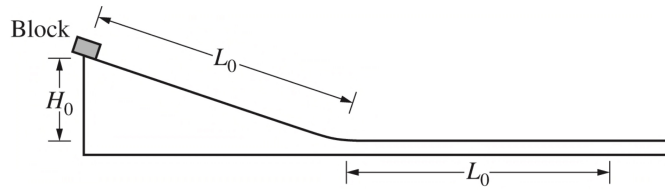
A cylinder of mass m_0 is placed at the top of an incline of length L_0 and height H_0 as shown above, and released from rest. The cylinder rolls without slipping down the incline and then continues rolling along a horizontal surface. (a) On the grid below, sketch a graph that represents the total kinetic energy of the cylinder as a function of the distance traveled by the cylinder as it rolls down the incline and continues to roll across the horizontal surface.

$$\frac{1}{2}mv^2 = mgx \quad (x \text{ varies from zero to } H_0)$$
$$KE = mgx$$
$$\boxed{KE \propto x} \quad \text{till } x = H_0$$

At $x = H_0$

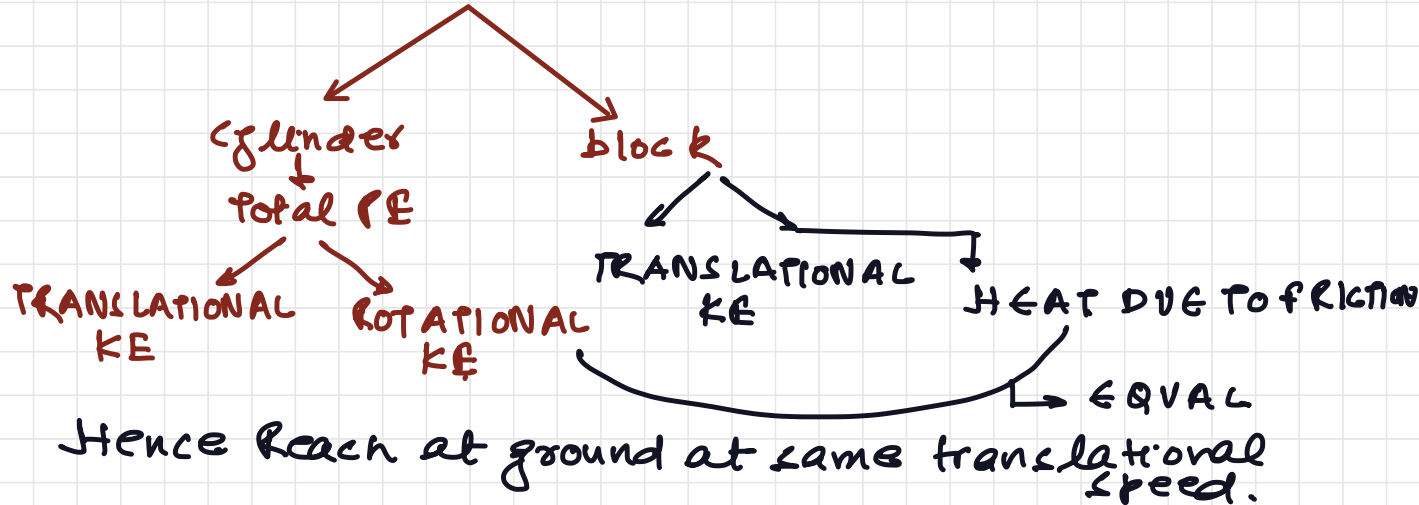
$KE = \text{constant}$



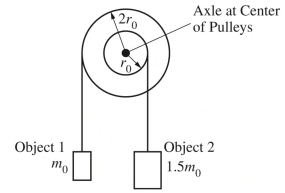


The cylinder is again placed at the top of the incline. A block, also of mass m_0 is placed at the top of a separate rough incline of length L_0 and height H_0 as shown above. When the cylinder and block are released at the same instant, the cylinder begins to roll without slipping while the block begins to accelerate uniformly. The cylinder and the block reach the bottoms of their respective inclines with the same translational speed.

(b) In terms of energy, explain why the two objects reach the bottom of their respective inclines with the same translational speed. Provide your answer in a clear, coherent paragraph-length response that may also contain figures and/or equations.



Begin your response to **QUESTION 5** on this page.



5. (7 points, suggested time 13 minutes)

Two pulleys with different radii are attached to each other so that they rotate together about a horizontal axle through their common center. There is negligible friction in the axle. Object 1 hangs from a light string wrapped around the larger pulley, while object 2 hangs from another light string wrapped around the smaller pulley, as shown in the figure above.

m_0 is the mass of object 1.

$1.5m_0$ is the mass of object 2.

r_0 is the radius of the smaller pulley. $2r_0$ is the radius of the larger pulley.

(a) At time $t = 0$, the pulleys are released from rest and the objects begin to accelerate.

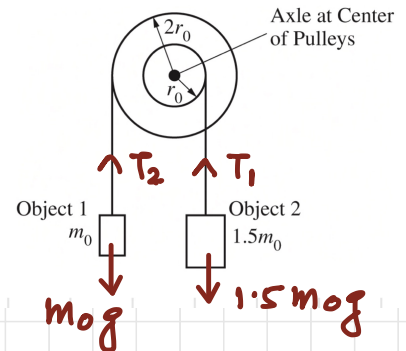
i. Derive an expression for the magnitude of the net torque exerted on the objects-pulleys system about the axle after the pulleys are released. Express your answer in terms of m_0 , r_0 and physical constants, as appropriate.

Torque about centre of the pulley

$$T_2 (2r_0) - T_1 (r_0) = \tau$$

$$m_0 g (2r_0) - 1.5 m_0 g (r_0) = \tau$$

$$\boxed{0.5 m_0 g r_0 = \tau}$$



ii. Object 1 accelerates downward after the pulleys are released. Briefly explain why.

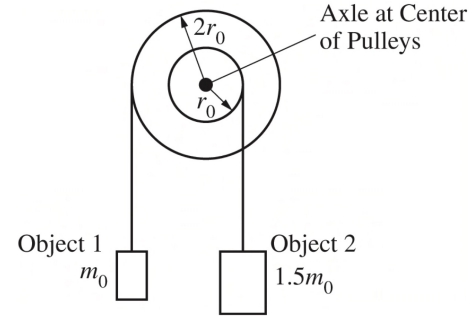
Torque at the centre of the pulley due to object m_0

$$\tau_1 = m_0 g (2r_0)$$

Torque due to object $1.5m_0$

$$\tau_2 = 1.5 m_0 g (r_0)$$

$\tau_1 > \tau_2$ — Hence accelerated downward.



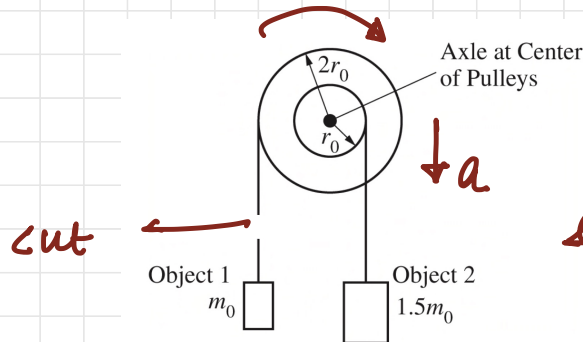
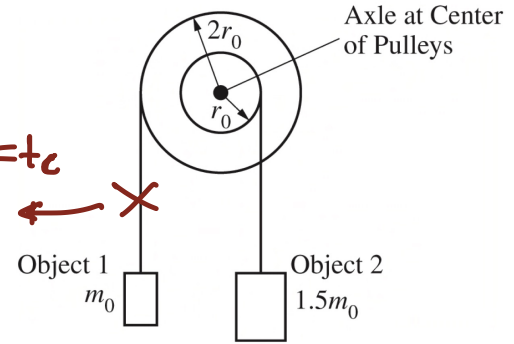
(b) At a later time $t = t_c$, the string of object 1 is cut while the objects are still moving and the pulley is still rotating. Immediately after the string is cut, how do the directions of the angular velocity and angular acceleration of the pulley compare to each other?

✓ Same direction ___ Opposite directions Briefly explain your reasoning.

After cut of string ①

Due to mass $1.5m_0$ acceleration and angular velocity would go in the same direction

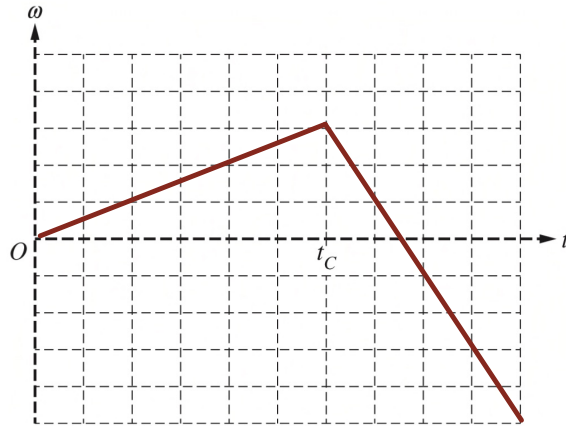
at $t = t_c$
cut ← X



Same direction

(c) On the axes below, sketch a graph of the angular velocity ω of the system consisting of the two pulleys as a function of time t . Include the entire time interval shown. The pulleys are released at $t = 0$, and the string is cut at $t = t_c$.

Released at $t=0$
cut at $\Rightarrow t=t_c$



STOP

END OF EXAM

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New York is the richest country in the whole world, in terms of money and terms of education, New York is number one in both terms, but one thing is to be understood if there is any balance in the field of education, then it is Indian. India is a progressive country but the heritage of India is the education here, education here gives a huge benefit to the whole world.

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