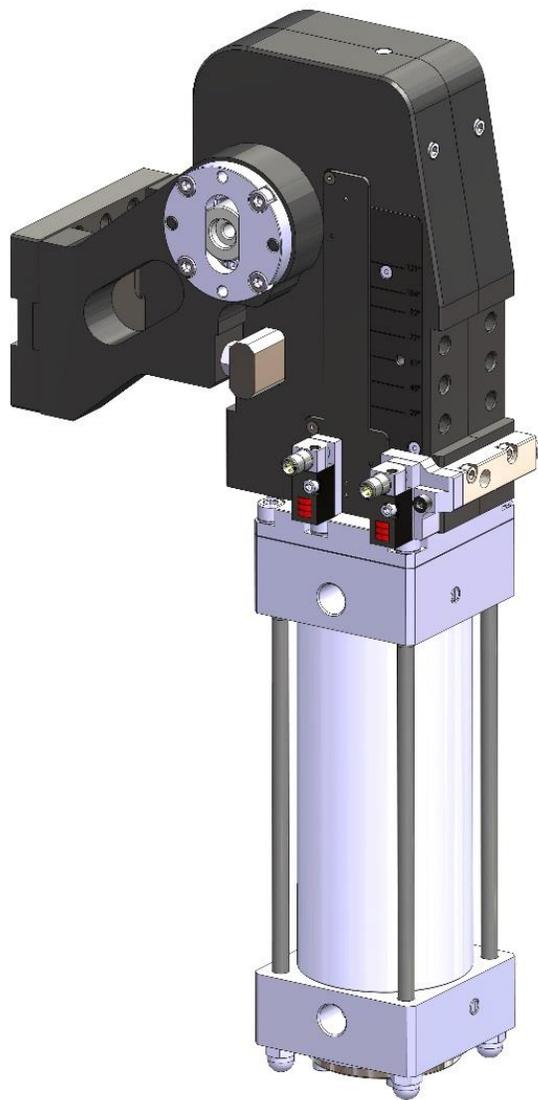
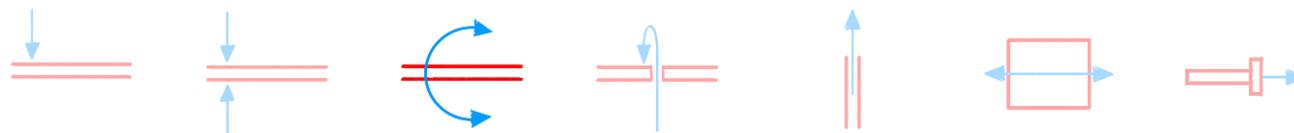


# VEP *AUTOMATION*

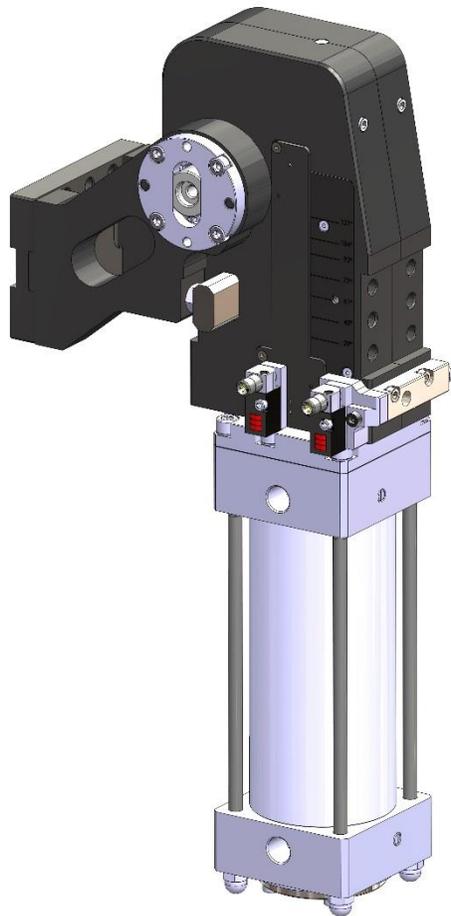


## **RFM.2/RCM.2 (100-125-160-200)**

RFM.2/RCM.2 NEW PIVOT UNITS HYDRAULIC CONTROLLED, WITH OPENING ANGLES EASILY ADJUSTABLE AND SBI LOCK SYSTEM INTEGRATED INTO THE HEADS

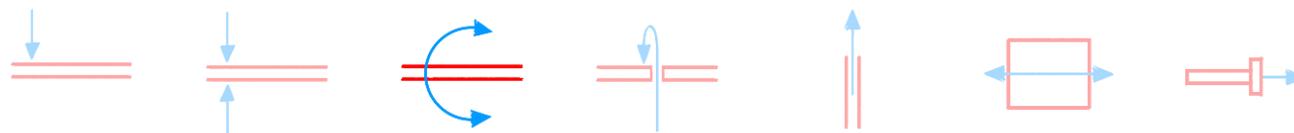


## RFM.2/RCM.2 Mains Features

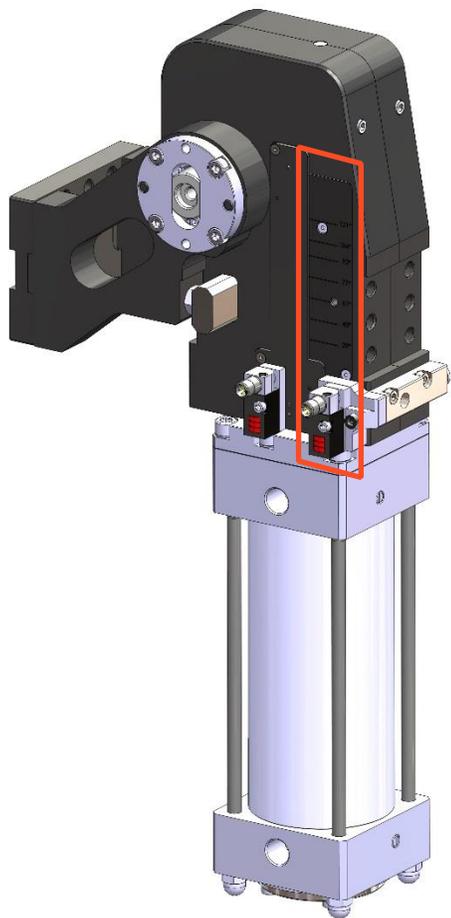


### **New RFM.2/RCM.2 Mains Features:**

1. SBI Lock System (brake) integrated into the head (RFM-RF series) – (Patented)
2. Opening angles easily adjustable (RFM/RCM)
3. Sensors kit
4. Pneumo-Hydraulic motion control
5. External Arms Hard Stop
6. Patent, Parts List, Production
7. Ordination Codes (RFM/RF – RCM/RC)

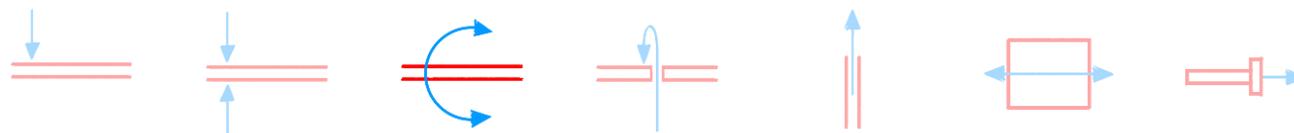


## 1. SBI Lock System integrated into the mechanical head (RFM-RF)

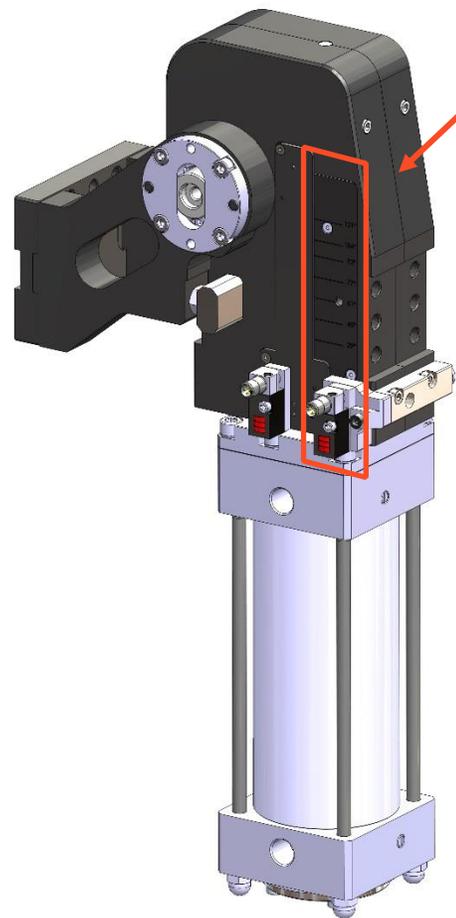


### 1) SBI Lock System integrated into the mechanical head (Brake) Pivot Units **RFM-RF**





## 1. SBI Lock System integrated into the mechanical head (RFM-RF)



RFM Mechanical SBI Lock System integrated into the Head

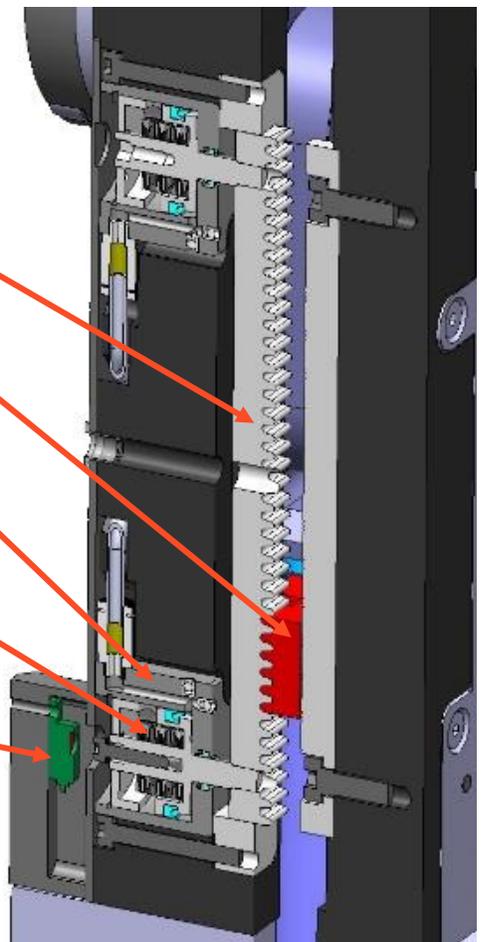
Main Teeth Bar Rack

Opposed Teeth Rack

Single Effect Pneumatic Cylinders

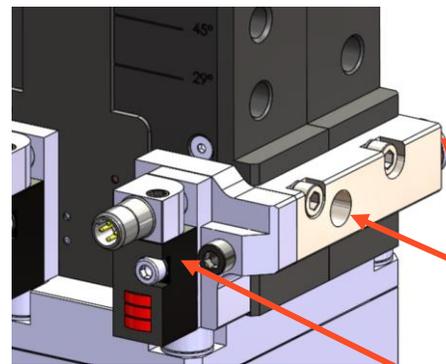
Disc Springs (Bauer)

SBI Lock System Off Inductive Sensor



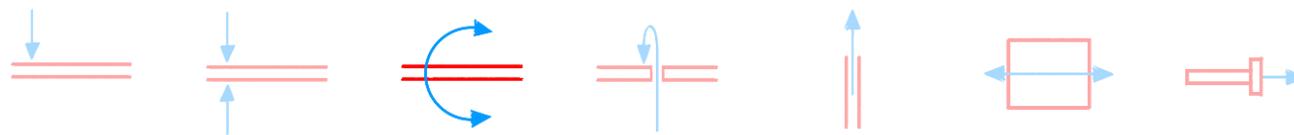
### Advantages:

- Secure and reliable braking (no piston rod lock system)
- Mechanical Teeth Bar Rack locker concept (no Hydraulic oil)
- Reduced arms gap in back position
- Integrated into the head (reduced external unit dimension. Save up to 200mm compared to our competitors)

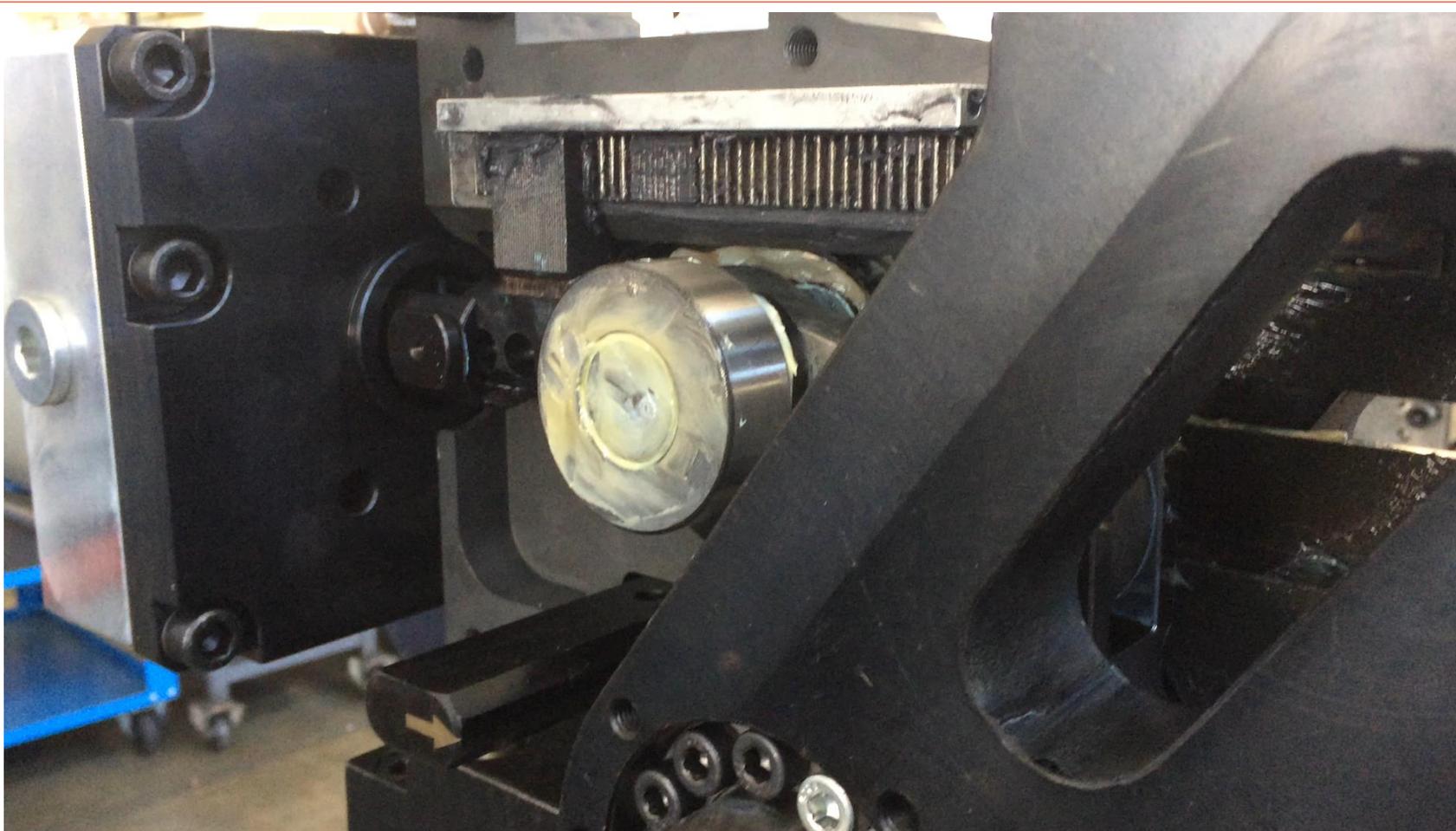


Double Air Connections for the SBI Lock System

SBI Lock System Inductive Sensor (M12 Connection)

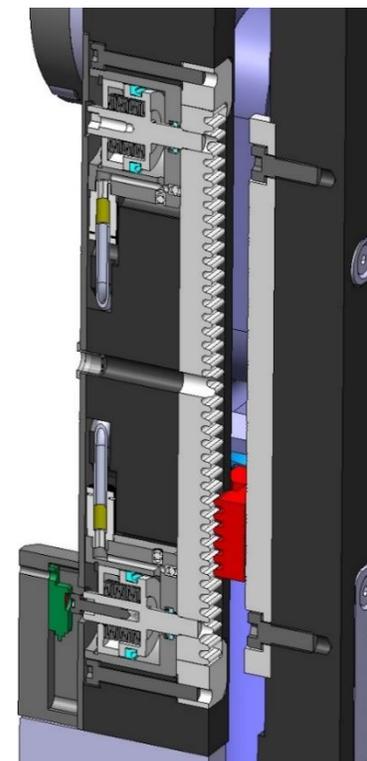


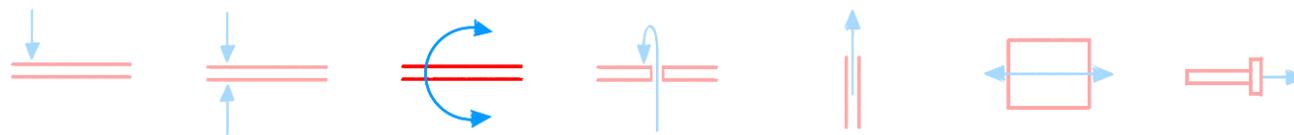
## 1. SBI Lock System integrated into the mechanical head (RFM-RF)



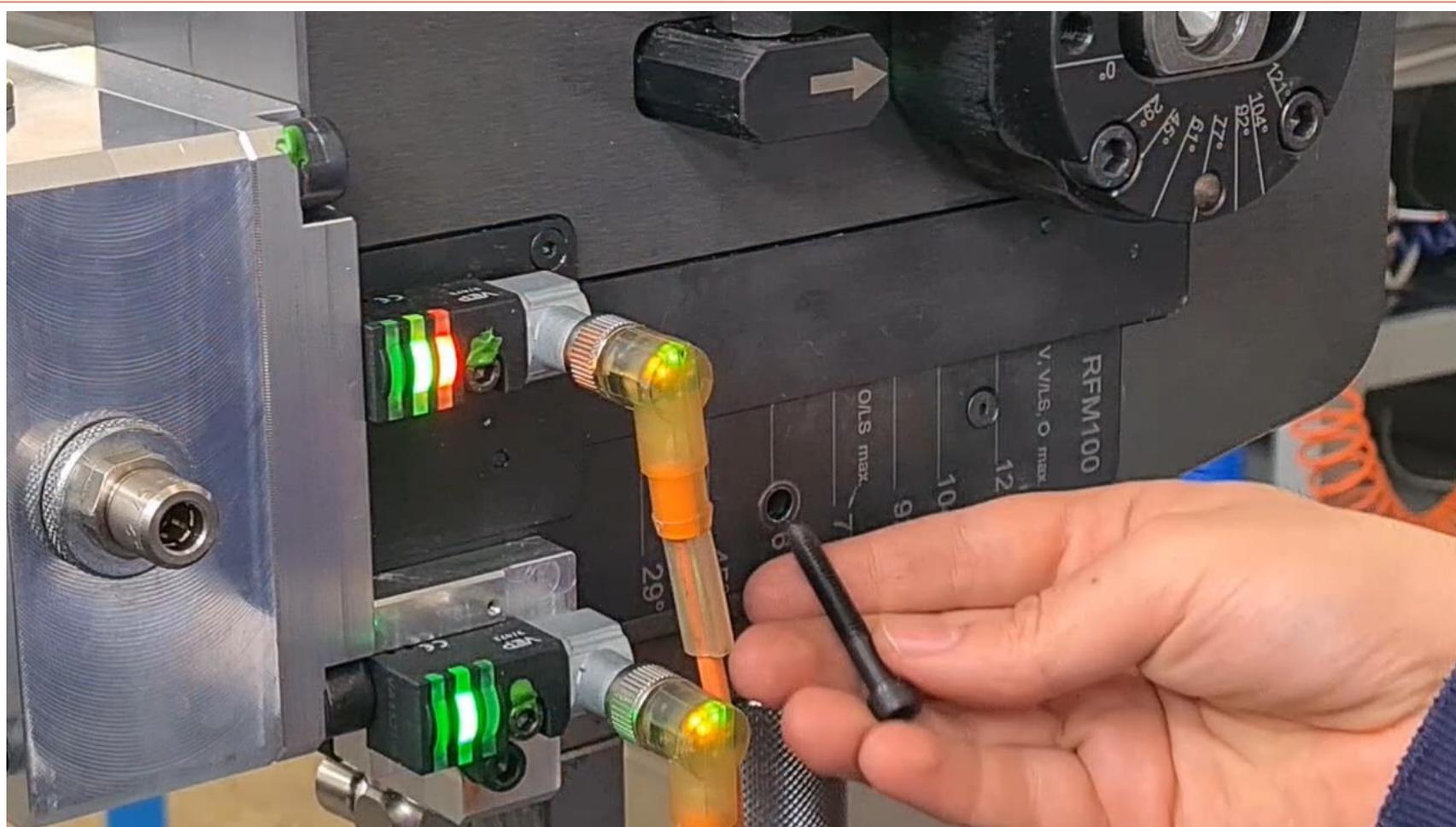
[Link to WebVideo](#)

Operating principle of the:  
Mechanical Teeth Bar Rack  
Locking System (SBI)



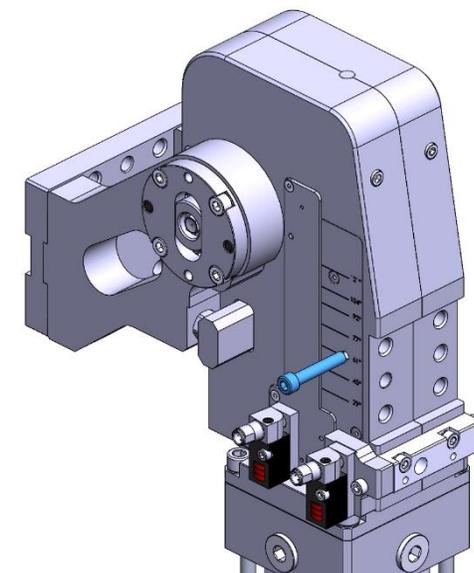


## 1. SBI Lock System integrated into the mechanical head (RFM-RF)

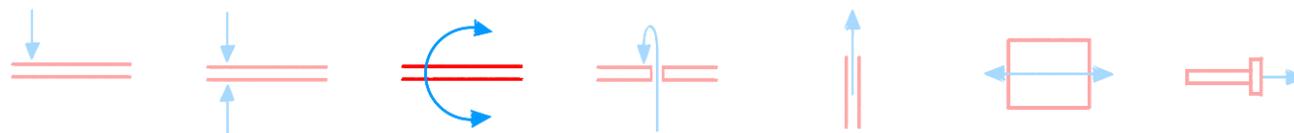


### Manual Release of the SBI Lock System (Brake)

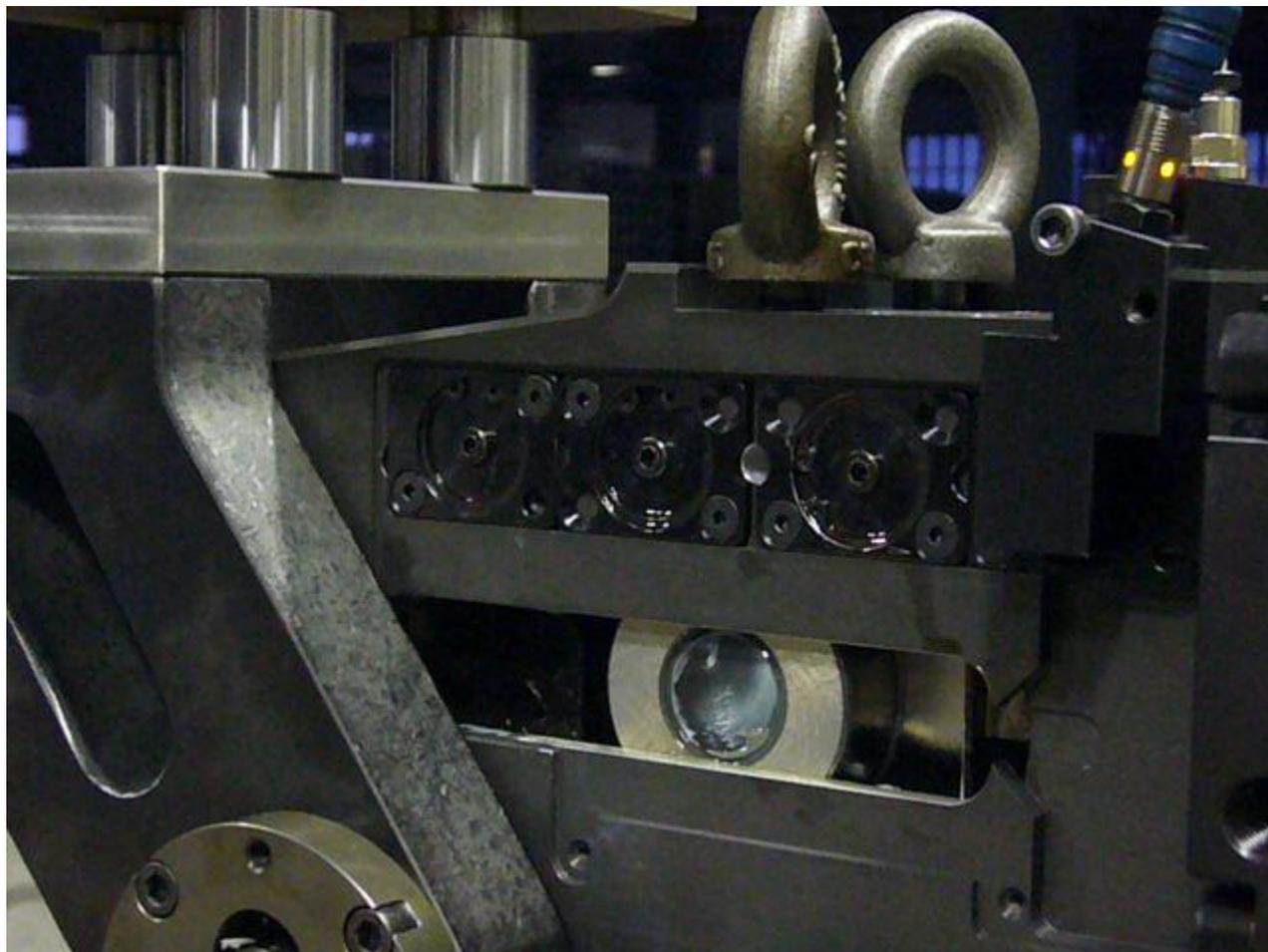
Procedure in case of lack of pressure in the pneumatic system or in case of anomaly  
Needs: Nr.1 M6x40 (D.100) or Nr.1 M8x40 (D.125-160-200)



[Link to WebVideo](#)



## 1. SBI Lock System integrated into the mechanical head (RFM-RF)

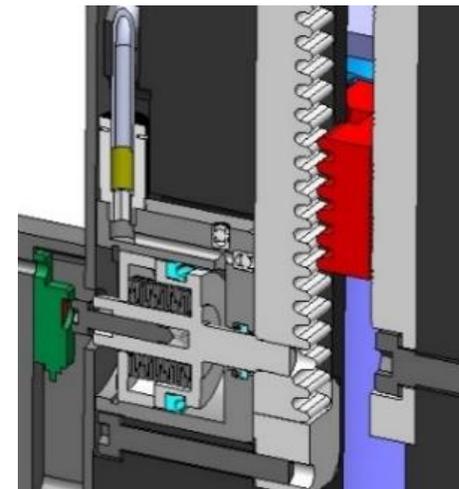


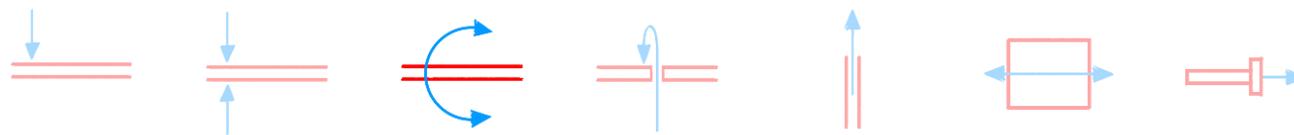
Example of emergency stops with maximum load for the Mechanical Locking System (SBI)

From 10.000 to 25.000 dynamic stops guaranteed at maximum load (B10 value) depending on the size of the Pivot Units

6,000,000 static stop cycles (B10 value) for SBI brake arming/disarming with unit stationary at backward or forward position

«Holding Force» of the rack and pinion SBI system:  
55.000N (D.100)  
65.000N (D125-160-200)





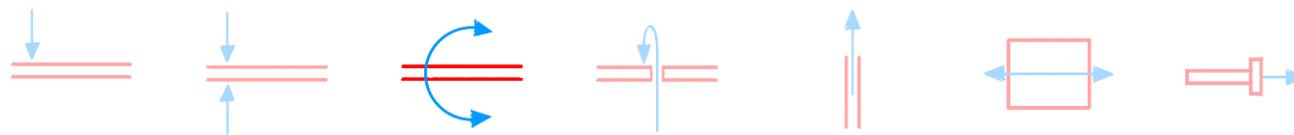
# 1. SBI Lock System integrated into the mechanical head (RFM-RF)

**VEP Automation RFM125.2**      **Competitor KS125.4-BD**

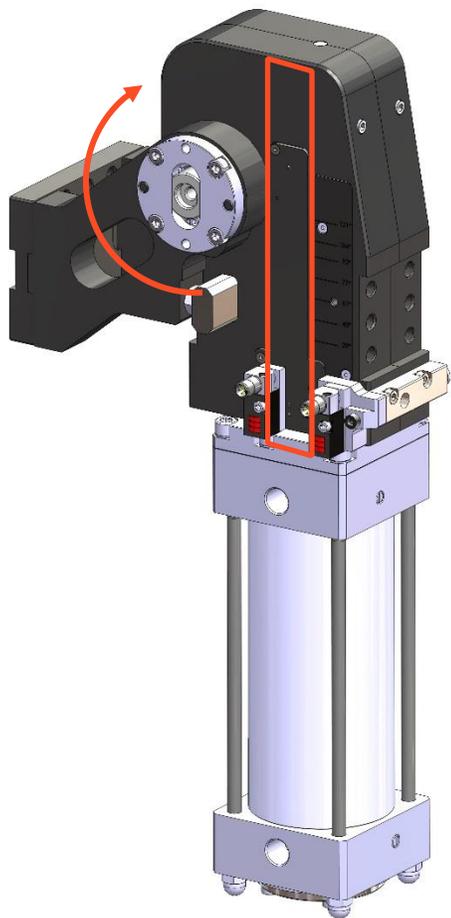
**Example of Dimensional Comparison between: VEP Automation VS Competitor "Dimensional Advantage"**

**VEP Automation**      **Competitor**

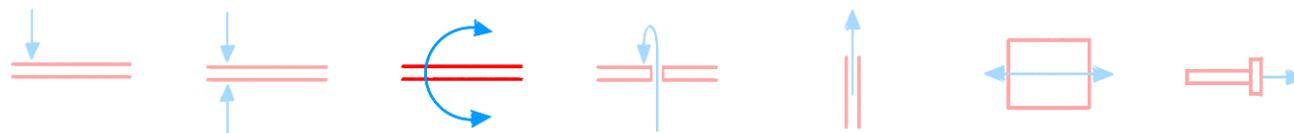
Aprox. 200 mm



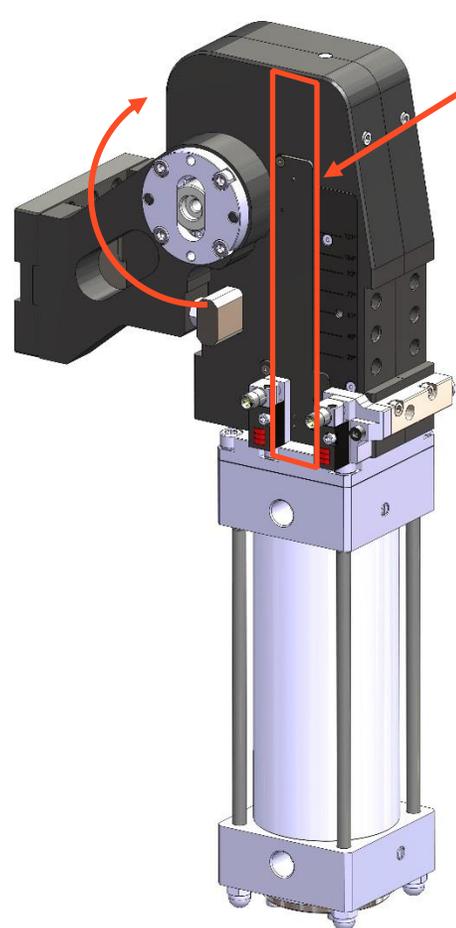
## 2. Opening angles easily adjustable



**2) Opening angles easily adjustable (RFM/RCM)**



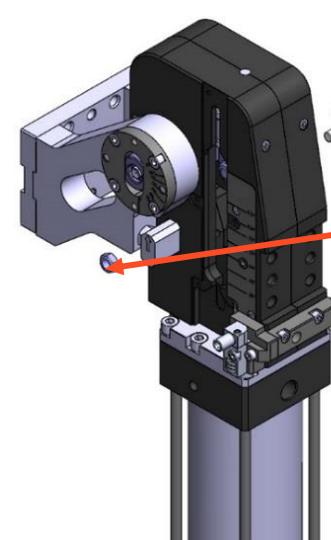
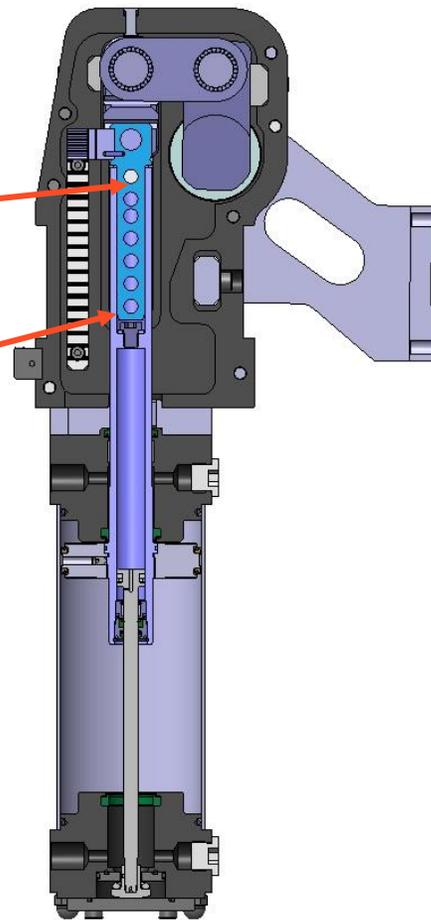
## 2. Opening angles easily adjustable



RFM Opening Angles  
Easily adjustable

Holes for Opening  
Angles Set

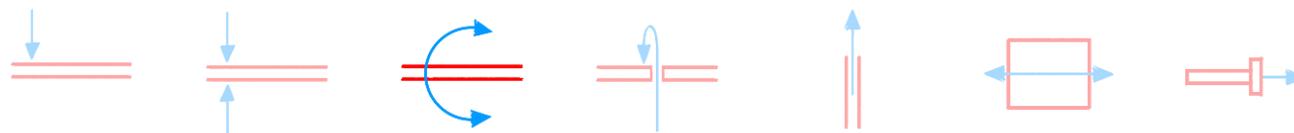
Telescopic Piston Rod  
that allows the angle  
change



Removable Pin and Nut  
for the Opening Angles  
Changing

### **Advantages:**

- Reduction of the amount of spare units needed (up to 50-55%).
- Easy re-use of units on different and future applications and projects
- The customer can change the opening angle himself (no additional parts needed)
- Possible adjustment of the opening angle during the set-up phase of the line in order to optimize cycle times or robot passages



## 2. Opening angles easily adjustable



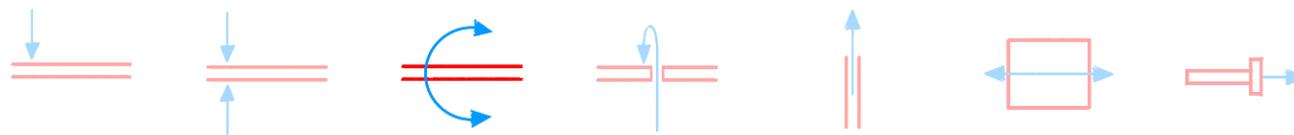
**RFM.2**  
ADJUST THE OPENING ANGLE

### Instructions for Opening Angles Changing

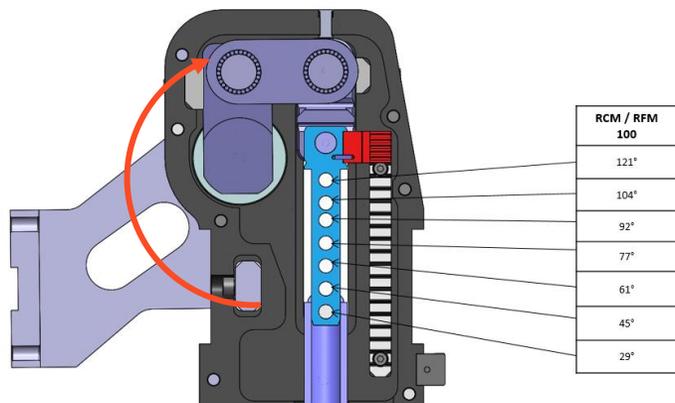
Example of Angle Changing of RFM100.2  
From 121° to 45°

RFM100.2 OPENING ANGLES							
Angles \ Arms	29°	45°	61°	77°	92°	104°	121°
V	•	•	•	•	•	•	•
V/LS	•	•	•	•	•	•	•
O	•	•	•	•	•	•	•
O/LS	•	•	•	•			

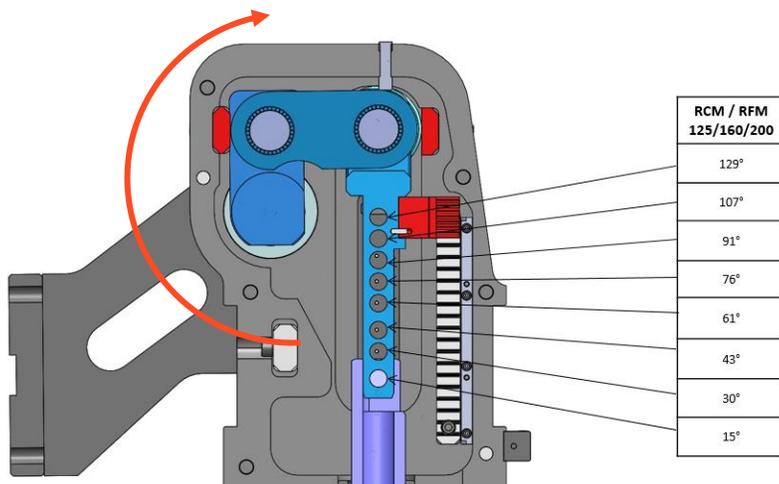
[Link to WebVideo](#)



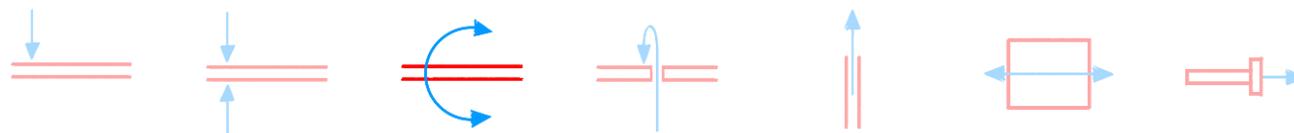
## 2. Opening angles easily adjustable



RFM100.2 OPENING ANGLES							
Angles Arms	29°	45°	61°	77°	92°	104°	121°
V	●	●	●	●	●	●	●
V/LS	●	●	●	●	●	●	●
O	●	●	●	●	●	●	●
O/LS	●	●	●	●			



RFM125-160-200.2 OPENING ANGLES								
Angles Arms	15°	30°	43°	61°	76°	91°	107°	129°
V	●	●	●	●	●	●	●	●
V/LS	●	●	●	●	●	●	●	●
O	●	●	●	●	●	●	●	
O/LS	●	●	●	●	●			



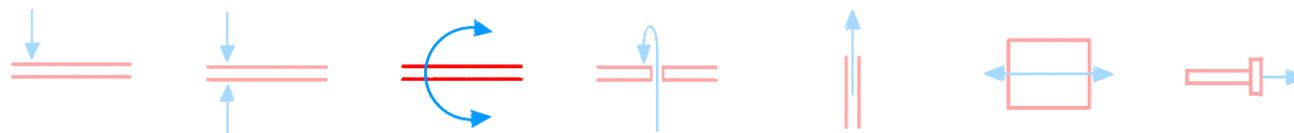
## 2. RF Unit additional Opening angles (Fix, Not Adjustable)

In case of the RFM units available angles are not in according to the application designed by the customer, on request, we can provide the RF unit which allows to have a larger number of available opening angles. Herewith below the complete list of the RF opening angles.

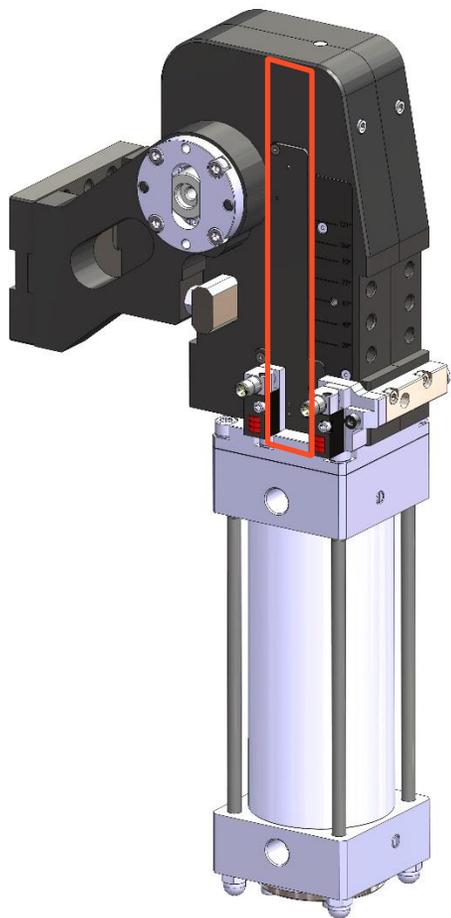
Note: The RF unit doesn't have the opening angle easily adjustable. It's fixed as the old GR/RC. The cylinder length of the RF unit is in according to the opening angle as the unit GR/RC.

RF100.2 OPENING ANGLES (Option on request)																														
Angles Arms	15°	18°	22°	25°	29°	33°	37°	41°	45°	49°	53°	57°	61°	65°	69°	73°	77°	81°	85°	89°	92°	96°	100°	104°	108°	113°	117°	121°	127°	133°
V	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
V/LS	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
O	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
O/LS	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•

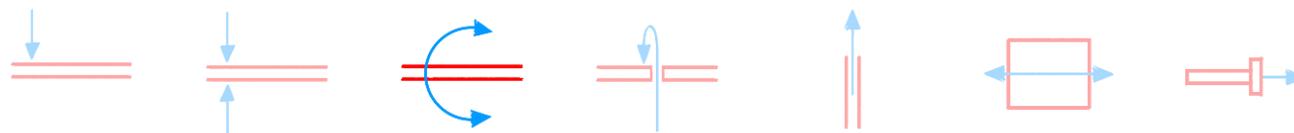
RF125-160-200.2 OPENING ANGLES (Options on request)																															
Angles Arms	15°	18°	21°	24°	27°	30°	33°	36°	40°	43°	47°	50°	54°	58°	61°	65°	69°	72°	76°	80°	83°	87°	91°	95°	99°	103°	107°	112°	116°	122°	129°
V	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
V/LS	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
O	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
O/LS	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•



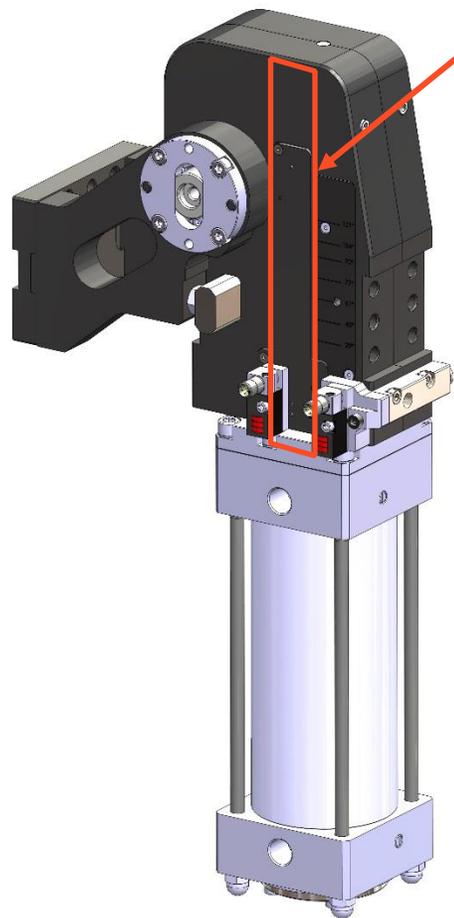
### 3. Detail of New Sensor Kit (Pivot Positioning)



### 3) Sensor kit (Pivot positioning and SBI Brake system)



### 3. Detail of New Sensor Kit (Pivot Positioning)



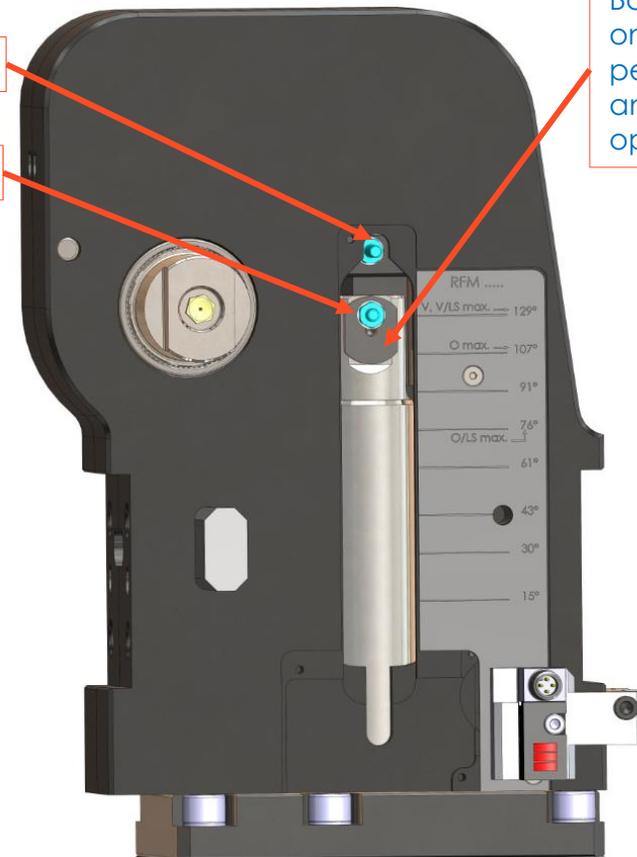
New Sensor Kit  
(Pivot Positioning)

#### **Advantages:**

- The sensor kit permit to have more accuracy on the detection of the unit position
- The sensor kit don't need to be setup or adjust when the customer change the opening angles
- The P&F sensors, divided in two parts (Power Amplifier and Satellite Sensors) permit to replace easily and quickly the Power Amplifier part only
- It's reduced the number of spare parts codes (P&F separable sensors, are in common for all opening angle and Power Amplifier may be in common with other products).

Forward Positioning Pin

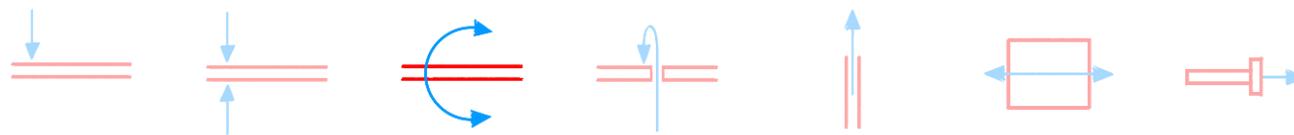
Back Positioning Pin



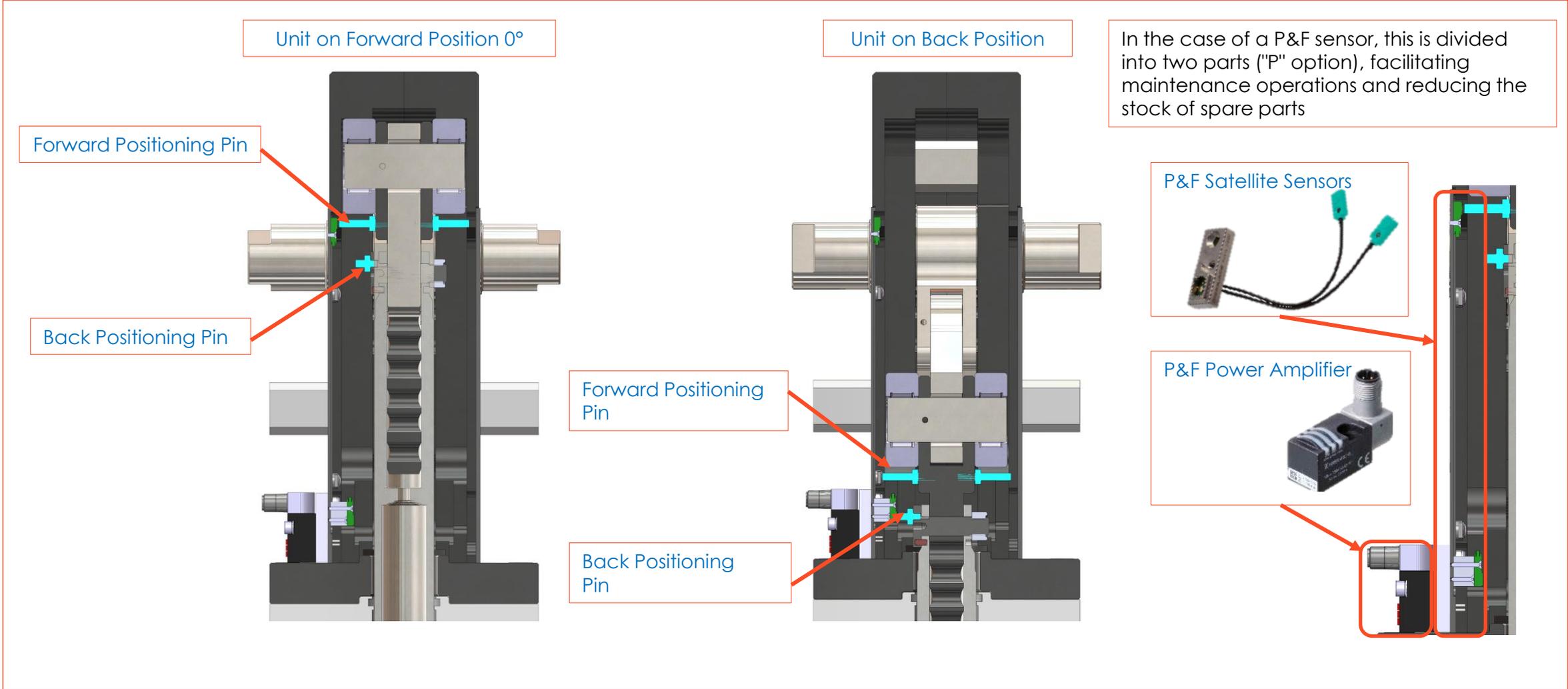
Back Positioning Pin installed on the cylinder rod has permitted to don't setup anything on the sensor during opening angles changing

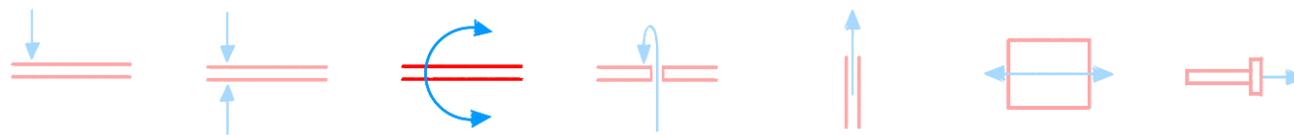
Forward Position Inductive Sensor

Back Position Inductive Sensor

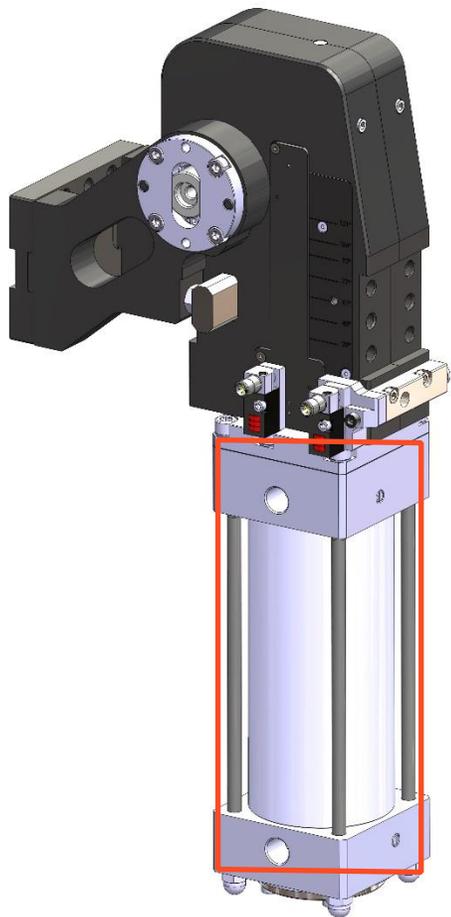


### 3. Detail of New Sensor Kit (Unit Position)

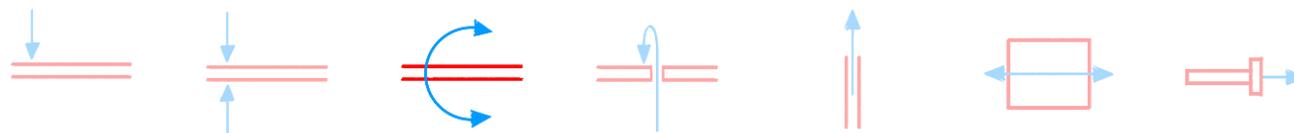




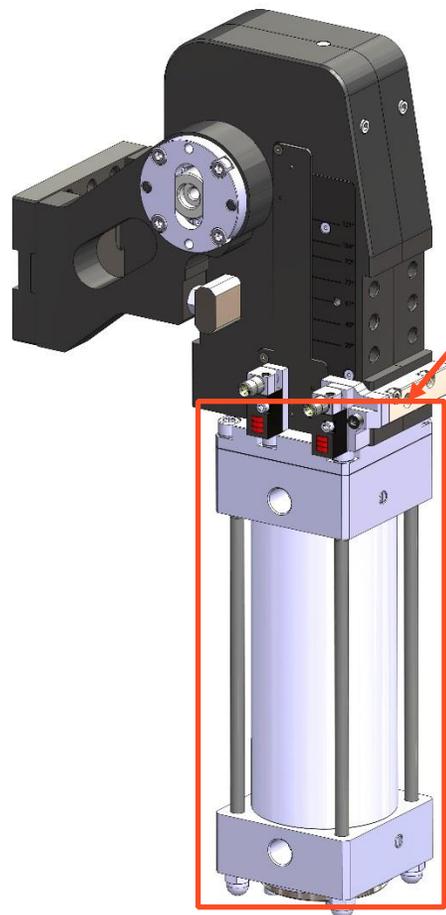
## 4. Pneumo-Hydraulic Motion Control



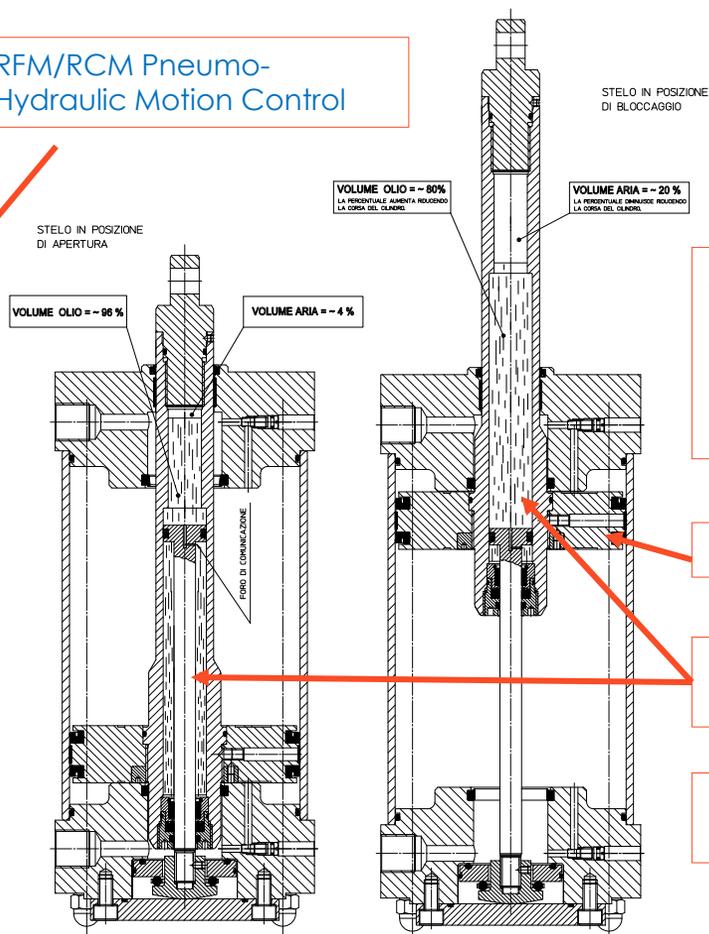
## 4) Pneumo-Hydraulic Motion Control



## 4. Pneumo-Hydraulic Motion Control



RFM/RCM Pneumo-Hydraulic Motion Control



### Advantages:

- Ensures a smooth and regular moving
- Improving of the Cycle Time (up to 2.0 Sec.)
- Avoid using additional shock absorber
- Avoid dangerous extra speed at first cycle (increased safety in manual loading stations)

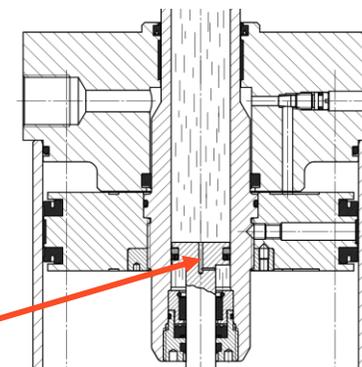
### Functioning description:

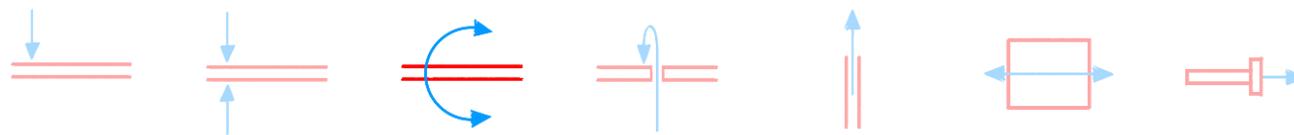
When the piston of the pneumatic cylinder runs, it forces the hydraulic oil, contained in the piston rod, to pass through a calibrated hole controlling the movement of the unit. It helps to avoid the typical over-speeds due to the pneumatic systems and due to the behavior of the loads applied on the pivot unit during the rotation.

Pneumatic Unit Piston

Hydraulic Oil into the Pneumatic Unit Rod

Calibrate Hole Control Movement





## 4. Pneumo-Hydraulic Motion Control

RFM/RCM **WITHOUT** Pneumo-Hydraulic motion control

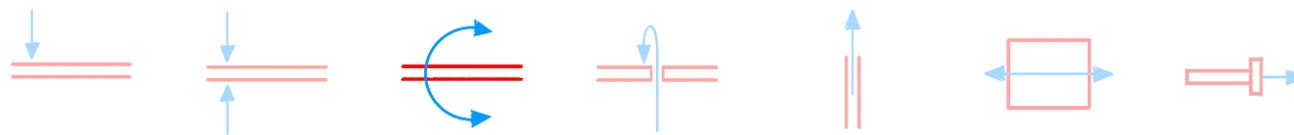


[Link to WebVideo](#)

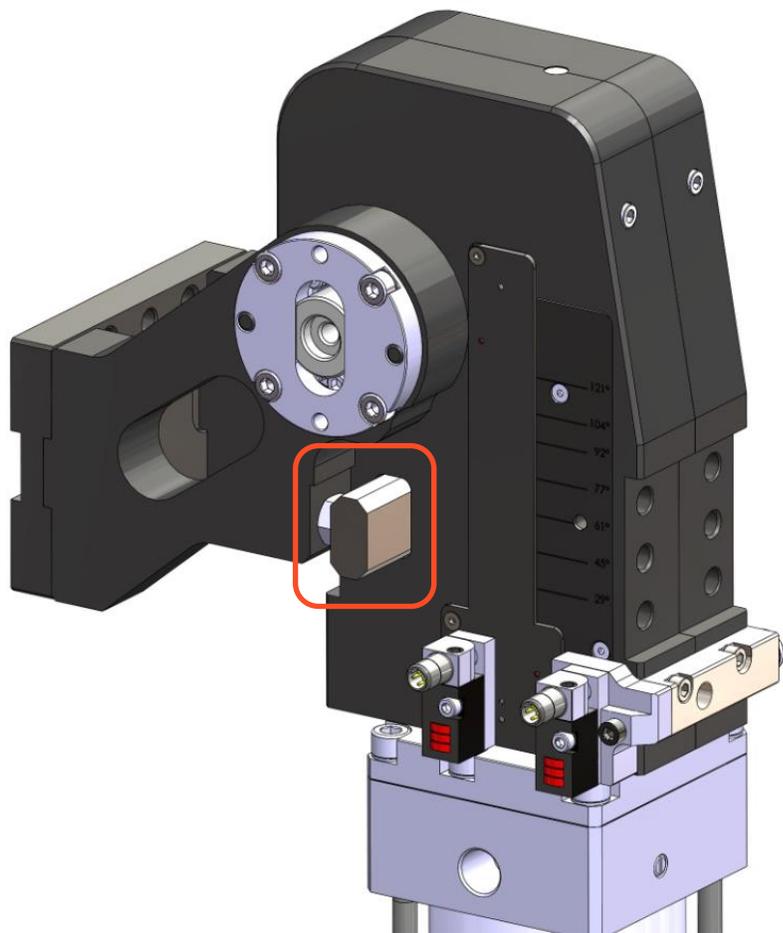
RFM/RCM **WITH** Pneumo-Hydraulic motion control



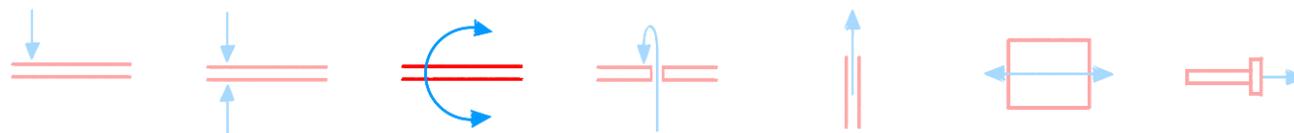
[Link to WebVideo](#)



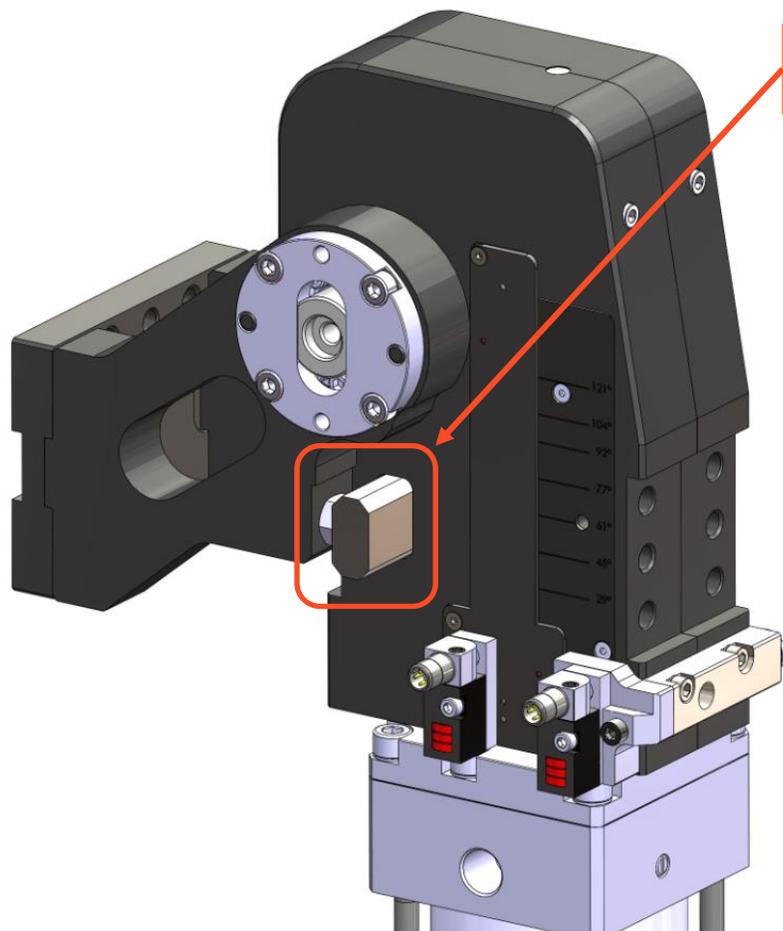
## 5. External Arms Hard Stop



## 5) External Arms Hard Stop



## 5. External Arm Hard Stop



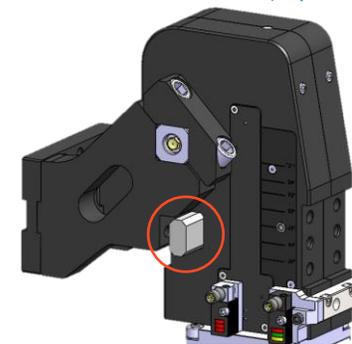
RFM External Arms Stop

### Advantages:

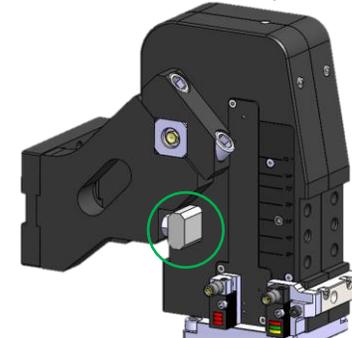
- With the external arms hard stop is being increased the repeatability and accuracy of the arms position
- With the external arms stop it can be easily verified the reached of forward position 0°
- The external arms hard stop are integrated into the heads (no additional external dimensions)
- The external arms hard stop are included into the basical unit price (no additional costs)
- Available several Arms Options in according to Customers specifications

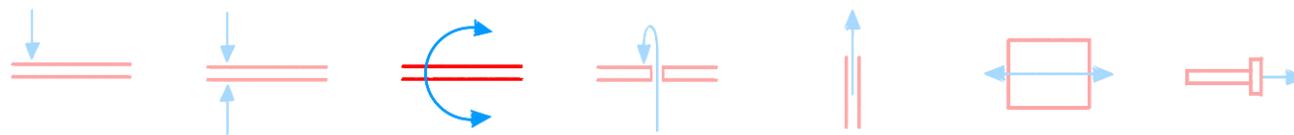
### Arm Fix options and External Arms Hard Stop

Assembly of lever arms "square" and WITHOUT arms hard stop (RFMA.2)

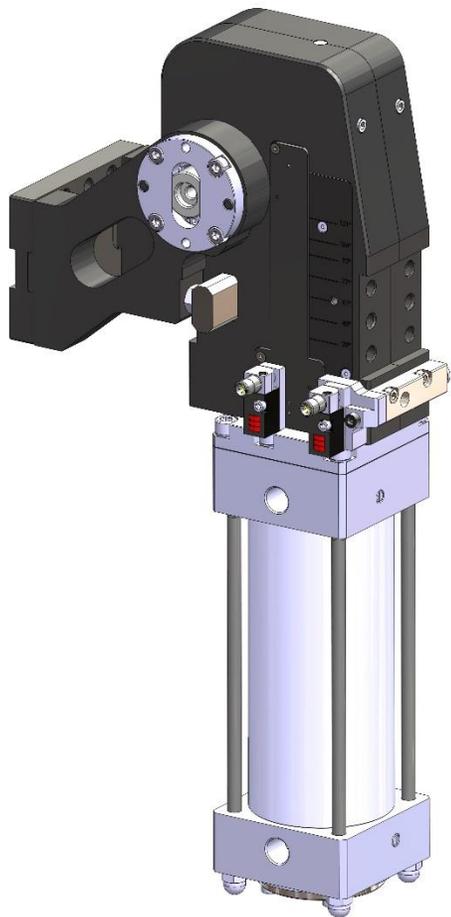


Assembly of lever arms "square" and WITH arms hard stop (RFMB.2)

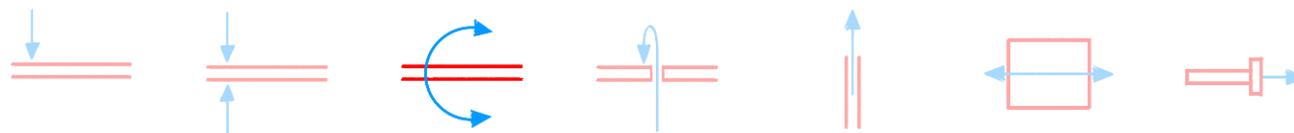




## 6. Patent, Parts List, Production



## 6) Patent, Parts List, Production

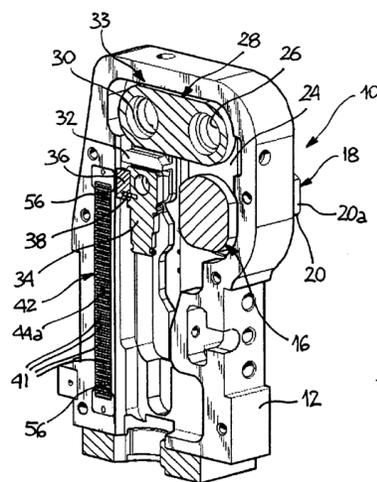


## 6. Patent, Parts List, Production

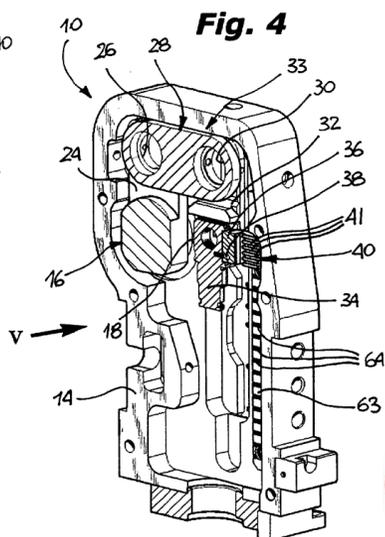
(54) **Device for stopping the oscillation of the arm of a handling equipment of the swingable lever type**

(57) A handling equipment of the swingable lever type comprises an arm rotationally connected to a shaft (18) that extends from a body (10) of the equipment, and a toggle mechanism (33) interposed between the shaft (18) and one end of an axially slidable stem (34). The sliding of the stem (34) is controlled by pressurized fluid control means so as to cause an angular oscillation of the arm between two predetermined end-of-stroke angular positions. The equipment further comprises a de-

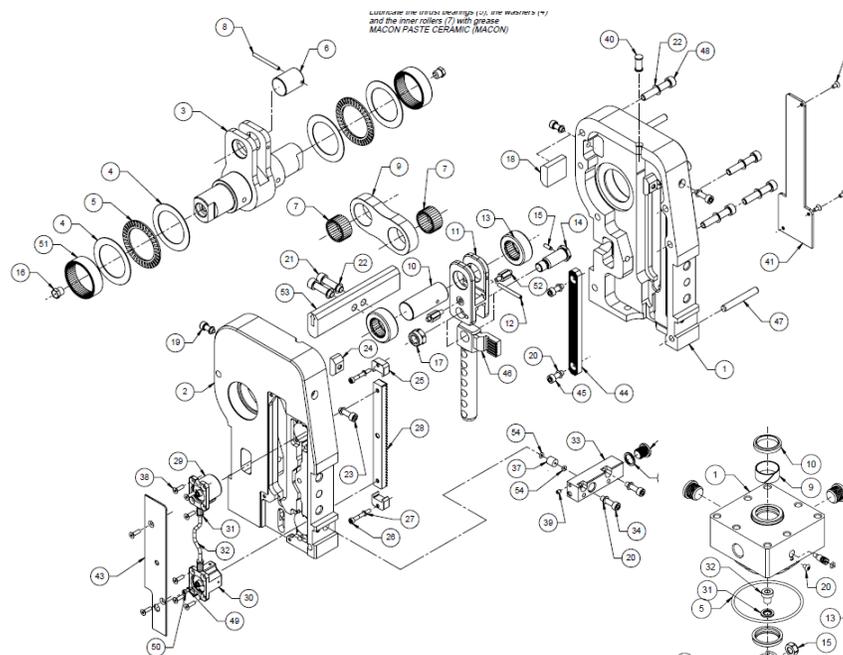
vice for stopping the oscillation of the arm, including a first engagement member (42, 40) fixed to the body (10) and a second engagement member (40) movable together with the stem (the 34), which members (40, 42) have respective reciprocally facing active surfaces adapted to reach a frontal engagement condition as a result of the transverse movement of one of them with respect to the stem (34), when a pressure drop of the fluid fed to said control means takes place, with the aim of stopping the movement of the stem (34).



**Fig. 3**

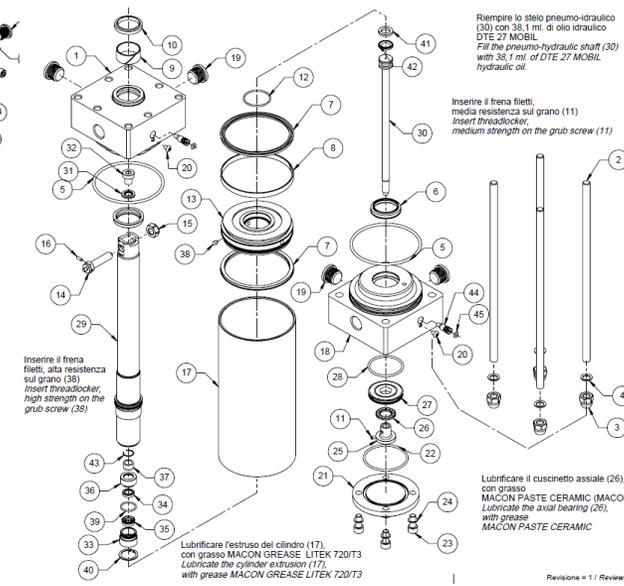


**Fig. 4**

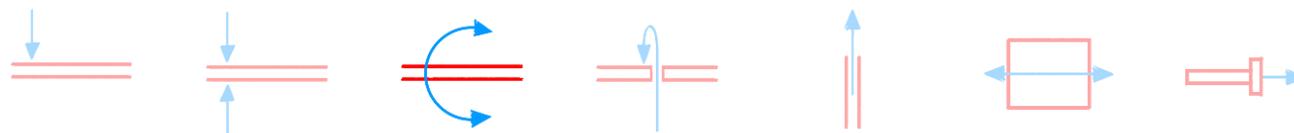


**Part List RFM:**  
More than 200 pcs  
between  
manufactured and  
commercial parts

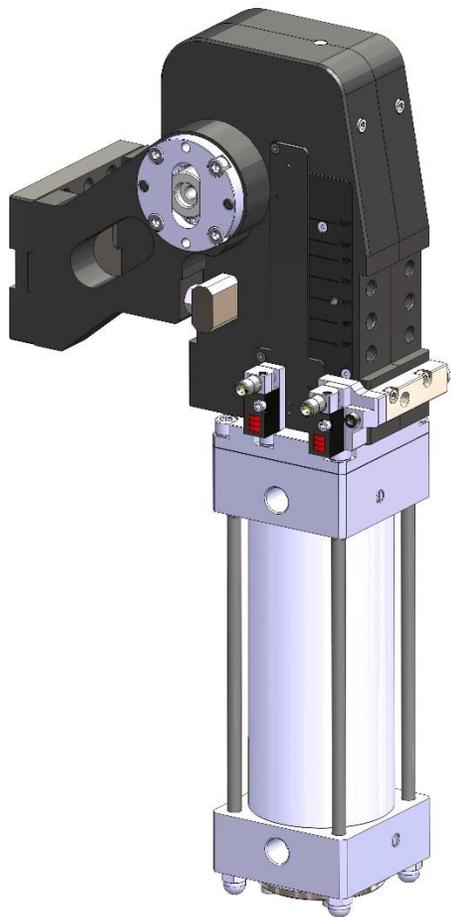
**Production Volumes:**  
More than 20,000 pcs.  
sold from 2009 to 2022/06



EP 2 177 319 A1



## 7. Code to Order (RFM/RF – RCM/RC)



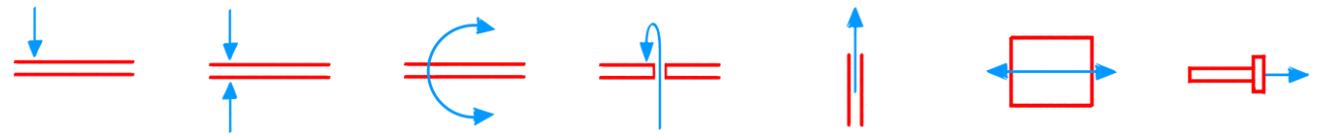
### 7) Code to Order RFM/RF e RCM/RC

RFM: With Lock System and Opening Angle Changeable

RF: With Lock System and Opening Angle Fixed

RCM: Without Lock System and with Opening Angle Changeable

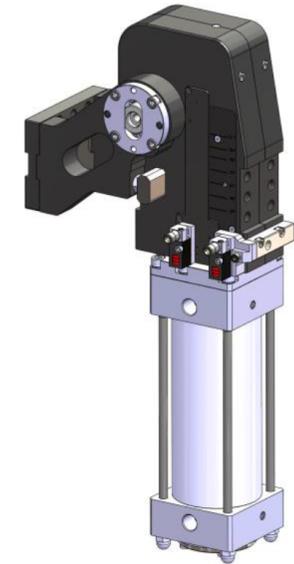
RC: Without Lock System and with Opening Angle Fixed



## Ribaltatore pneumo-idraulico RFM/RF.2 Pneumo-hydraulic swivel unit RFM/RF.2

### Caratteristiche principali:

- Blocco (SBI) integrato nella meccanica (brevettato)
- Sistema di cambio angolo facilitato (RFM)
- Versione (RF) con angolo d'apertura fisso
- Fianchetti in alluminio
- Dispositivo a ginocchiera interno
- Bracci leva in acciaio ed arresto bracci leva esterno
- 2 possibilità di staffaggio (fronte e retro)
- 6 fori di connessione (GAS o NPT)
- 2 smorzatori di finecorsa pneumatici regolabili
- Nuovo finecorsa induttivo (connessione M12x1)
- Controllo idraulico della movimentazione integrato nel cilindro pn.



### Main characteristics:

- Lock system (SBI) integrated into the head (patented)
- Opening angle easily adjustable (RFM)
- (RF) version with fixed opening angle
- Aluminum flanks
- Toggle action mechanism
- Steel arms and external arms stop
- 2 mounting areas (front and back)
- 6 feeding ports (GAS or NPT)
- 2 end strokes pneumatic cushioning adjustable
- New inductive proximity switch (connection M12x1)
- Hydraulic motion control integrated into pneumatic cylinder



[PDF](#)



[3D Step](#)



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RFM125.2 - 91 - V - PX - P - G - X

**RFM100.2**  
alesaggio Ø100mm  
cylinder bore Ø100mm

**RFM125.2**  
alesaggio Ø125mm  
cylinder bore Ø125mm

**RFM160.2**  
alesaggio Ø160mm  
cylinder bore Ø160mm

**RFM200.2**  
alesaggio Ø200mm  
cylinder bore Ø200mm

**RFMA (optional)**

**RFMB (optional)**

**Tipologia fori d'alimentazione:**  
**Feeding ports type:**  
G: fori tipo G...\*  
ports type G...\*  
N: fori tipo ...\*NPT  
ports type ...\*NPT

**Tipo sensore induttivo:**  
**Inductive sensor type:**  
P: Pepper+Fuchs con LED rosso  
Pepper+Fuchs with red LED

**Angolo d'apertura**  
**Opening angle**

RFM100.2								
O	---	29°	45°	61°	77°	92°	104°	121°
O/LS	---	29°	45°	61°	77°	---	---	---
V	---	29°	45°	61°	77°	92°	104°	121°
V/LS	---	29°	45°	61°	77°	92°	104°	121°
RFM125.2 / 160.2 / 200.2								
O	15°	30°	43°	61°	76°	91°	107°	---
O/LS	15°	30°	43°	61°	76°	---	---	---
V	15°	30°	43°	61°	76°	91°	107°	129°
V/LS	15°	30°	43°	61°	76°	91°	107°	129°

Angoli d'apertura aggiuntivi sono disponibili su richiesta con l'unità **RF.2** (vedi pagina 26 - 27)  
On request are available additional opening angles with the **RF.2** (see page 26 - 27)

**Tipologia braccio leva (vedere pagine dimensionali):**  
**Swivel arm type (see dimensional pages):**  
O: braccio leva orizzontale  
horizontal arm  
V: braccio leva verticale  
vertical arm  
O/LS: braccio leva orizzontale simmetrico  
symmetric horizontal arm  
V/LS: braccio leva verticale simmetrico  
symmetric vertical arm

**Posizione sensore induttivo (vedere pag. 23):**  
**Inductive sensor position (see page 23):**  
PO: senza  
without  
PX: sul lato X  
on the X side  
PY: sul lato Y  
on the Y side

**Posizione fori d'alimentazione e smorzatore di finecorsa:**  
**Feeding ports position and cushion adjustment:**

X: sul lato X (sx)  
on the X side (left)

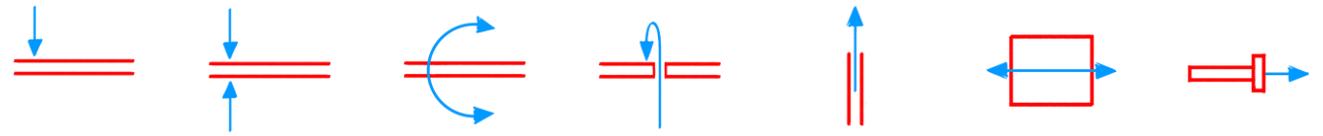
Y: sul lato Y (dx)  
on the Y side (right)

W: sul lato W (ant.)  
on the W side (front)

Z: sul lato Z (post.)  
on the Z side (rear)

→ connessione aria air connection  
→ connessione aria con tappo air connection with plug  
→ smorzatore di finecorsa cushion adjustment

**N.B.**  
Il sensore del blocco integrato (SBI) si trova sempre sul lato sinistro (PX)  
**Note:**  
SBI lock system sensor is always on the left side (PX)



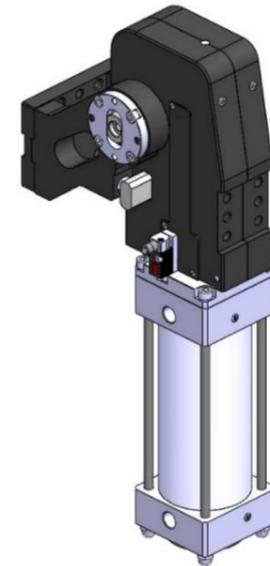
## Ribaltatore pneumo-idraulico RCM/RC.2 Pneumo-hydraulic swivel unit RCM/RC.2

### Caratteristiche principali:

- Sistema di cambio angolo facilitato (RCM)
- Versione (RC) con angolo d'apertura fisso
- Controllo idraulico della movimentazione integrato nel cilindro pneumatico
- Fianchetti in alluminio
- Dispositivo a ginocchiera interno
- Bracci leva in acciaio
- Arresto bracci leva esterno
- 2 possibilità di staffaggio (fronte e retro)
- Alesaggio del cilindro pneumatico: 100/125/160/200 mm
- 6 fori di connessione (GAS o NPT)
- 2 smorzatori di finecorsa pneumatici regolabili
- Nuovo finecorsa induttivo (connessione M12x1)

### Main characteristics:

- Opening angle easily adjustable (RCM)
- (RC) version with fixed opening angle
- Hydraulic motion control integrated into the pneumatic cylinder
- Aluminum flanks
- Toggle action mechanism
- Steel arms
- External arms stop
- 2 mounting areas (front and back)
- 4 Pneumatic cylinder bore: 100/125/160/200 mm
- 6 feeding ports (GAS or NPT)
- 2 end strokes pneumatic cushioning adjustable
- Inductive proximity switch (connection M12x1)



[PDF](#)



[3D Step](#)



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RCM125.2 - 91 - V - PX - P - G - X

**RCM100.2**  
alesaggio Ø100mm  
cylinder bore Ø100mm

**RCM125.2**  
alesaggio Ø125mm  
cylinder bore Ø125mm

**RCM160.2**  
alesaggio Ø160mm  
cylinder bore Ø160mm

**RCM200.2**  
alesaggio Ø200mm  
cylinder bore Ø200mm

**RCMA (optional)**

**RCMB (optional)**

**Tipologia fori d'alimentazione:**  
**Feeding ports type:**  
G: fori tipo G...\*  
ports type G...\*  
N: fori tipo ...\*NPT  
ports type ...\*NPT

**Tipo sensore induttivo:**  
**Inductive sensor type:**  
P: Pepper+Fuchs con LED rosso  
Pepper+Fuchs with red LED

**Angolo d'apertura**  
**Opening angle**

RCM100.2								
	---	29°	45°	61°	77°	92°	104°	121°
O	---	29°	45°	61°	77°	---	---	---
O/LS	---	29°	45°	61°	77°	---	---	---
V	---	29°	45°	61°	77°	92°	104°	121°
V/LS	---	29°	45°	61°	77°	92°	104°	121°
RCM125.2 / 160.2 / 200.2								
	15°	30°	43°	61°	76°	91°	107°	---
O	15°	30°	43°	61°	76°	---	---	---
O/LS	15°	30°	43°	61°	76°	---	---	---
V	15°	30°	43°	61°	76°	91°	107°	129°
V/LS	15°	30°	43°	61°	76°	91°	107°	129°

Angoli d'apertura aggiuntivi sono disponibili su richiesta con l'unità **RC.2**. (vedi pagina 25)  
On request are available additional opening angles with **RC.2** units. (see page 25)

**Tipologia braccio leva (vedere pagine dimensionali):**  
**Swivel arm type (see dimensional pages):**  
O: braccio leva orizzontale  
horizontal arm  
V: braccio leva verticale  
vertical arm  
O/LS: braccio leva orizzontale simmetrico  
symmetric horizontal arm  
V/LS: braccio leva verticale simmetrico  
symmetric vertical arm

**Posizione sensore induttivo (vedere pag. 23):**  
**Inductive sensor position (see page 23):**  
PO: senza  
without  
PX: sul lato X  
on the X side  
PY: sul lato Y  
on the Y side

**Posizione fori d'alimentazione e smorzatore di finecorsa:**  
**Feeding ports position and cushion adjustment:**

X: sul lato X (sx)  
on the X side (left)

Y: sul lato Y (dx)  
on the Y side (right)

W: sul lato W (ant.)  
on the W side (front)

Z: sul lato Z (post.)  
on the Z side (rear)

→ connessione aria air connection  
→ connessione aria con tappo air connection with plug  
→ smorzatore di finecorsa cushion adjustment

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