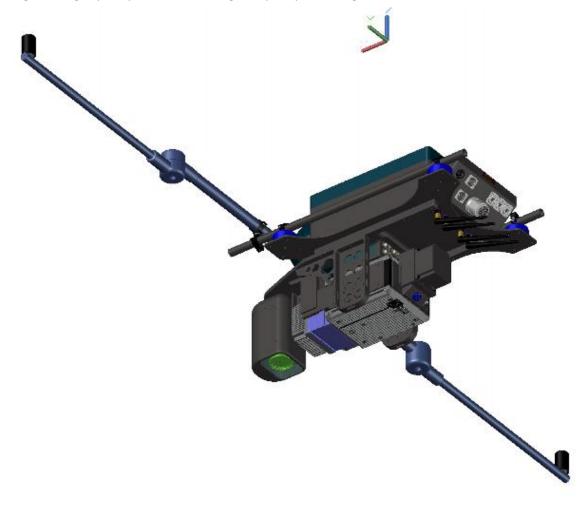




## **High Speed, Long Range UAV Lidar + RGB**

#### **Features**

- Carbon Fiber based molded aerodynamic enclosure.
- o Silicone Elastomer vibration isolation mounts.
- o Integrated fanless industrial grade i7 computer system
- o LAN, 4G and WiFi remote connectivity.
- o Integrated CF Extreme Pro SSD ejectable media.
- o 3D printed mounting system using PEI-CF, FAA-approved for FST applications (Flame/Smoke/Toxicity) and meets FAR 25.853 and OSU 65/65 standards.
- o Integrated 24mp global shutter RGB camera.
- o Dual GNSS antenna on 2m boom for precision real time heading data even while hovering.
- o Integrated tightly coupled IMU for cm grade post processing solution.







# **High Speed, Long Range UAV Lidar + RGB**

| Parameters                              | ■ GS-360-UAV   |                             |         |  |  |  |
|---|--|-----------------------------|---------|--|--|--|
| LASER PULSE REPETITION FREQUENCY (PRF)  |  | 200 kHz                     | 500 kHz |  |  |  |
| Max Range Capacity <sup>1</sup>         |  |                             |         |  |  |  |
| @ 10% target reflectivity               |  | 205 m                       | 130 m   |  |  |  |
| @ 20% target reflectivity               |  | 290 m                       | 185 m   |  |  |  |
| @ 50% target reflectivity               |  | 490 m                       | 250 m   |  |  |  |
| Typical Operating Altitude <sup>2</sup> |  |                             |         |  |  |  |
| @ 10% target reflectivity               |  | 130 m                       | 85 m    |  |  |  |
| @ 20% target reflectivity               |  | 185 m                       | 120 m   |  |  |  |
| @ 50% target reflectivity               |  | 315 m                       | 160 m   |  |  |  |
| Range Accuracy, 1sigma <sup>1</sup>     |  | 5 mm                        | 5 mm    |  |  |  |
| Range Precision, 1sigma <sup>1</sup>    |  | 4 mm                        | 4 mm    |  |  |  |
| LASER                                   |  |                             |         |  |  |  |
| Wavelength                              | 1550   | 350163433                   |         |  |  |  |
| Laser Safety Classification             | 1  |                             |         |  |  |  |
| Beam Divergence (1/e²)                  | 0.3 mrad   |                             |         |  |  |  |
| Beam Footprint at 1/e <sup>2</sup>      | 8.1 mm @ 5 m, 8.5 mm @ 10 m, 11 mm @ 25 m, 17 mm @ 50 m, 31 mm @ 100 m |                             |         |  |  |  |
| RETURNS                                 |  |                             |         |  |  |  |
| Range Measurement Principle             | Time of  | Flight                      |         |  |  |  |
| Sample Collection Rate                  | Up to 2Mhz   |                             |         |  |  |  |
| Intensity Measurement                   | 12bits raw measurement, >16  | 6 bits normalized for range |         |  |  |  |
| Minimum Range                           | 1.5  | m                           |         |  |  |  |
| Number of Returns                       | Up to 4 (first 2   | 2 and last 2)               |         |  |  |  |
| Range Resolution                        | 2 m  | ım                          |         |  |  |  |
| Minimum Target Separation               | 0.7 m (discrete)   |                             |         |  |  |  |
| SCANNER                                 |  |                             |         |  |  |  |
| Field of View                           | 360 degrees possible, typically 80                                     | deg                         |         |  |  |  |
| Scan Speed                              | 100 to 250 lines/second  |                             |         |  |  |  |
| Angular Step Width                      | 0.036 - 1.8 deg  |                             |         |  |  |  |
| Angular Measurement Resolution          | 0.001 deg  |                             |         |  |  |  |
| GENERAL                                 |  |                             |         |  |  |  |
| Input Voltage                           | 11-30  | 6 V                         |         |  |  |  |
| Power (Typical)                         |  | 0.000.0001                  |         |  |  |  |
| @ 100 Hz Scan Speed                     | 30 W   |                             |         |  |  |  |
| @ 15 0 Hz Scan Speed                    | 35 W   |                             |         |  |  |  |
| @ 250 Hz Scan Speed                     | 40   | W                           |         |  |  |  |
| ENVIRONMENTAL                           |  |                             |         |  |  |  |
| Operating Temperature <sup>4</sup>      | -10°C to +40°C   |                             |         |  |  |  |
| Storage Temperature                     | -20°C to +50°C   |                             |         |  |  |  |
| Ingress Protection                      | IP64   |                             |         |  |  |  |
| Vibration                               | DO-160H Section 8, Category S, Curve M                                 |                             |         |  |  |  |
| Shock                                   | DO-160H Section 7, Cate  | egory A, Standard Shock     |         |  |  |  |
| Weight                                  | 7.59   | 9                           |         |  |  |  |
| Dimensions                              | 500mm x 350m   | nm x 220mm                  |         |  |  |  |
| INTERFACES                              |  |                             |         |  |  |  |
| Connector 1                             | Power, PPS, NM   | MEA (\$GPZDA)               |         |  |  |  |
| Connector 2                             | 4G, WiFi, 1 GigE Ethernet for real                                     | 196 W 11 St 14 22           |         |  |  |  |





# **High Speed, Long Range UAV Lidar + RGB**

Long Range digital communications systems of the MAP1600 support real-time control of the GS-360-UAV Lidar



### **System Options**

#### Range:

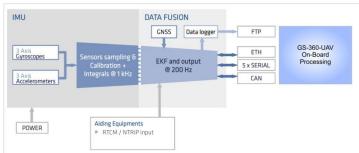
- >4km standard
- >15km extender
- >100km BVLOS Grade

#### Controller:

Single screen single operator Dual screen single operator Dual screen + Lidar manager

#### Power supplies:

- 1 x battery set standard
- 2 x or more battery sets optional
- 1 x 4-ch charger standard
- 2 x charger or 8-ch charger opt.



| Positioning Mode | Position Accuracy |          | Velocity Accuracy |          | Attitude Accuracy (*) |                                   |
|------------------|-------------------|----------|-------------------|----------|-----------------------|-----------------------------------|
|                  | Horizontal        | Vertical | Horizontal        | Vertical | Roll / Pitch          | Heading                           |
| SP               | 1.2 m             | 1.5 m    | 0.03 m/s          | 0.02 m/s | 0.05 *                | 0.5 single ant. / baseline > 0.3m |
| RTK              | 0.01 m            | 0.03 m   | 0.02 m/s          | 0.01 m/s | 0.03 *                | 0.2 ° (baseline > 1m)             |
| PPK              | 0.01 m            | 0.02 m   | 0.01 m/s          | 0.01 m/s | 0.025 *               | 0.08 ° (baseline >2m)             |

| Positioning Mode | Position Accu | Position Accuracy |            | Velocity Accuracy |              | Attitude Accuracy (*)             |  |
|------------------|---------------|-------------------|------------|-------------------|--------------|-----------------------------------|--|
|                  | Horizontal    | Vertical          | Horizontal | Vertical          | Roll / Pitch | Heading                           |  |
| SP               | 1.0           | 1.0               | 0.02       | 0.01              | 0.01         | 0.1 single ant. / baseline > 0.5m |  |
| RTK              | 0.01          | 0.03              | 0.01       | 0.01              | 0.008        | 0.06 ° (baseline > 1m)            |  |
| PPK              | 0.01          | 0.02              | 0.01       | 0.01              | 0.005        | 0.025 (baseline >2m)              |  |





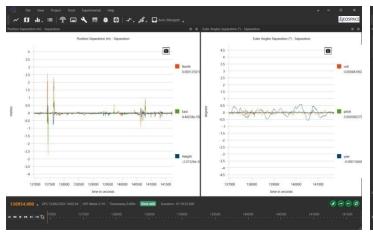
## High Speed, Long Range UAV Lidar + RGB

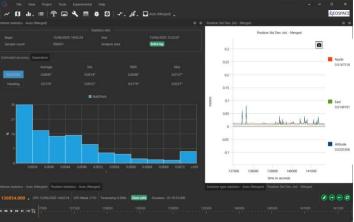
### **Sophisticated Post processing software solution**

Precision data alignment from post processing of the IMU trajectory, GNSS recordings and data from associated GNSS Base stations, with multiple Base references able to be drawn into a single process in order to allow for extremely long or remote scan runs where required.



Detailed Dynamic data analysis to provide assurance of data quality









## **High Speed, Long Range UAV Lidar + RGB**

### **Forestry Application**

High density points when the scanner is mounted at +15 degrees forward inclination, combined with cross path scan angles provide a superior points density on the surfaces all standing timber and branching.

The points are distributed the full height of each trunk and typically on up to 50% of the circumference, providing exceptional detail for post process analysis of diameter, sweep and branching.

### **Geospace Tree Attribute Profiler**

Proprietary 3D stem processing software enabled by the GS-360-UAV data point density and accuracy

