TRACTION CONTROLLER SURVEY

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Company:							Purch	ase Order #:					
Address:								Date:					
								Job Name:					
Attn.:													
Phone:							Je	ob Location:					
Fax:								tallation By:					
Email:							Num	ber of Cars:					
Ship To:								Contact:					
Address:								Phone:					
	-						Lift	Gate Truck:		es □ No			
Req. Ship Date:							Delivery I	Notification:		4 hrs* □ 48 otification l		Freight fees ((applicable)
Certification: UL/CUL Other				Office Prints: ☐ 11"x17" ☐ Submittals									
Service:	☐ Passenger ☐ Freight												
Туре:	□ Geared	d □ Gearles	ss			Machin	e Room:	☐ Overhead [⊐ Bas	ement □N	ИRL		
Controller:	□ Vision	2.0 w/Car T	op Insp	ection Stati	on (seric	al I/O) □ V	/F-3000 (dis	screte-wired)					
	□ GE/Em	nerson RX3i	PLC 🗆	A-B Compa	ctLogix	PLC □ A	-B Control	Logix PLC 🗆 (Other:				
		_											
Building Power: _	V	′(þ	Hz									
				ſ		.	5.1 1.	_					
Car Capacity:	lbs	. Car Speed	J:	трт		Roping	Ratio:	:1					
Drive:	□ Variab	le Freq AC (Open-Loc	on <150FPM)		□ Svnc	hronous P	ermanent Mas	net A	C Drive*	□ Regen	erative	
21100.	ector AC* (Cl				☐ Synchronous Permanent Magnet AC Drive* ☐ Regenerative ☐ SSAC ☐ 2SAC ☐ DC Drive (PLC only)								
					· AC or SE							•	
	_ ruen,	-1100001 (110	.quireu i	or rick vector	710 07 07								_
Landings:	No. of La	andings:		_ Total Tra	vel:	ft.	☐ Short F	loors					
	Front Openings @ stops #:												
	Rear Ope	enings @ sto	ps #: _										
Travel Between L	andings:	1-2:	ft.	2-3:	ft.	3-4:_	ft.	4-5:	ft.	5-6:	ft.	6-7:	ft.
7-8:	ft.	8-9:	ft.	9-10:	ft.	10-11:_	ft.	11-12:	ft.	12-13:	ft.	13-14:	ft.
14-15:	ft.	15-16:	ft.	16-17:	ft.	17-18:_	ft.	18-19:	ft.	19-20:	ft.	20-21:	ft.
21-22:	ft.	22-23:	ft.	23-24:	ft.	24-25:_	ft.	25-26:	ft.	26-27:	ft.	27-28:	ft.
28-29:	ft.	29-30:	ft.	30-31:	ft.	31-32:_	ft.	32-33:	ft.	33-34:	ft.	34-35:	ft.
Color-coded trave	el cable: (Vision 2.0 con	trollers c	nly)									
Length:					ft. (NOT	E: default	length is Tot	tal Travel + 70 ft.	.)				
Type:	☐ Jute Co	ore w/grips (suspend	ed < 200 ft.)	☐ Stee	l Core w/	hangers (s	uspended > 200	ft.)				
								•					
Operation:													
•	ive Collec	tive		☐ Single A	utomat	ic Pushb	utton						
☐ Single	e Button Collective ☐ Constant Press Send ☐ Real Time Dispa					ssure Pushbutton							
□ Call & :													
☐ Simple					۵٬۰۰۰۰								
☐ Group:	·												

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Doors:	☐ GAL MOVFR	☐ GAL Other:			UC MODSS Door Controller					
	☐ MAC SS	☐ MAC STD	☐ ECI:		Swing Door					
	☐ Other:									
	□ Manual: □ Fixed Cam □ Retiring Cam: □ AC:									
	☐ Power Freight:	: Manuf. & Model:	☐ Courion ☐ EM	S □ Peelle □ Auto	o-open □ Auto-close					
Fire & S	afety Code:									
	□ A17 '19	□ A17 '16	□ A17 '13	□ A17 '10	☐ A17 Other Year (('98 or later):				
	☐ CAN B44	(year) □ Local Code:	:						
	☐ Fire Service Ph	ase 1 Only	☐ NO FIRE SE	RVICE						
Main Fi	re Landing: Landir	ng#: Labe	el:	Alternate Fire	e Landing: Landing#:	Label:				
Fixture	Interfaces:									
	☐ Pre-Wire Fixt	ures: Ship boards to	o:			_ Ship by Date:				
	Fixture Voltages	s: (MH-3000 standard	is 120VAC, Vision 2.0	standard is 24VDC) C	Car/COP:	_V Hall/Hoistway:V				
	Hall I/O Boards: [□ Screw Terminal C	Connections (CAN	bus cable by Virginia C	Controls) \square Plug-In (RJ45)	Connections (CAT5 cable by Installer)				
	☐ Car Position In	idicator: 🗆 Digit	al □ Multi-light							
	☐ Hall Position I	ndicator: 🗆 Digit	al □ Multi-light	☐ Hall PI's @ I	Non-Main Landing					
	☐ C.E. Electronic	s Micro-Comm PI D	river Board <i>(Floor</i>	Labels Required)	☐ Voice Annunciat	tor				
	☐ Passing Gong		$V \square AC \square DC$							
	☐ Car Travel Lan	tern	V □ AC □ DC □] Serial (from driver b	oard) □ ½ Stroke Gong	Programming by VC				
	☐ Hall Lanterns		V □ AC □ DC □	☐ AC ☐ DC ☐ Serial (from driver board) ☐ ½ Stroke Gong Programming by VC						
	☐ Door Open Bel	Il	$V \square AC \square DC$							
	☐ In-Use Lights		$V \square AC \square DC$							
☐ Barrier Free Gong V☐ AC☐ DC Barrier Free Go					Landings"#					
Feature	Interfaces:									
	☐ Hoistway Insp	ection Access: 🗆 To	op □ Bottom □	Other	☐ Drive Applied Har	monic Filter (IEEE 519)				
	☐ In-Car Inspecti	ion (if Hoistway is che	cked do not select t	his)	☐ Drive Isolation Transformer					
	☐ Independent Service				☐ Emergency Terminal Slowdown Device (ETSD)					
	☐ Generator Ope	eration: 🗆 Auto 🗆 I	Manual □ Group		☐ Fan & Light Auto K/O					
	☐ Battery Rescue Services: ☐ Full Auto ☐ Brake Pulse				☐ Governor Set/Reset Circuit					
	☐ Door Nudging	with Timed Electric	Eye Cutout		☐ Homing: Specify Landing#: ☐ Load Weighing Bypass (Device not included)					
	☐ Infrared Curtai	in Unit (Nudge on Fire	e Service)							
	☐ Safety Edge: ☐	l Electric Eye			☐ Load Weighing Overload (Device not included)					
	☐ Hospital Servi	ce ("Code Blue")			☐ Reverse Phase Monitor					
	☐ Massachusetts	EMT Hospital Serv	ice		☐ Seismic (EQ): Device & Code:					
	☐ Anti-Nuisance				☐ Machine Room Monitoring (Vision 2.0 only): ☐ Local ☐ Rer					
	☐ Key or Card Lo	ckout in C.O.P. @ L	dg.#'s:		☐ Wifi Interface (Vision 2.0 only): ☐ Router+Tablet ☐ Router C					
	☐ Security Service	ce (Code entered via c	ar call buttons)		☐ Other:					
	☐ Car-to-Lobby S	Switch			☐ Other:					
	☐ Door Hold Ope	en: 🗆 Switch 🗆 But	ton		☐ Other:					
Enclosu	ires:									
	☐ Wall Mounted	☐ Free Standing	☐ Back Panel	Only □ Hinged Enc	losure					
	□ NEMA 1	□ NEMA 12	□ NEMA 4	□ NEMA 4x	☐ Other:					
	☐ Special Dimen	sions:" H	x"W x_	"D	☐ Cooling:					



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Positio	ning/Leveling Sys	tem:			
	☐ ELGO Absolute	e Positioning Syste	em (Vision 2.0 Controllers ONLY)	
	□ IP-8300	☐ IP-8700	☐ NEMA 1 w/Steel Tape	e □ NEMA 12/4/4X w/Pol	y-coated Tape
	☐ Landing/Level	ling by Others:	☐ Output/Floor	☐ Pulsing	
Brake:	(Provide Manufacti	urer's Data / Nameplo	ate Data)		
	☐ Hollister/Whit	ney □ Oth	er	Eco	nomy Switch: ☐ Yes ☐ No
	□ AC:V	φ @An	nps 🗆 DC: Pull-In:V	Hold:VΩ	
	☐ Emergency Sh	eave Brake	☐ Rope Brake		
1 or 2 S	peed AC & Variabl	le Frequency:			
	Manufacturer:				
	Motor:V - 3¢	o - <u>60</u> Hz	HP Ratio::1		
	Machine No.:		Fram	ne Size:	
	Fast:Ar	mpsRPM	Slow:Amps _	RPM No Load (Mag,	:Amps
Synchr	onous Permanen	t Magnet AC:			
	Machine Manufa	acturer:	Мас	chine Efficiency:%	Sheave Dia.: ir
	Motor:V - 30	фHz	kW	RPM	Rated Torque:
	Abs. Encoder:	☐ Stegmann (H	$iperface$ $Interface) \square Heideh$	ain (EnDat Interface) \Box Other:	
	Compensation:	□ Cable □ Nor	ne		
DC Hois	st Motor: (NOTE: DO	traction jobs require	GE or A-B PLC; no VF-3000 or V	ision 2.0.)	
	HP	RPM	Name Plate	V Name Plate	A
	Field: ☐ Series	□ Parallel <i>(Provide</i>	Sketch)		
	Field Voltage @	High Speed:	V Field Voltage @ Level S	Speed:V Field Voltage	e @ Standing:V
	Field Resistance	(Hot):Ω	Hig	h Speed (Tached): Up:	FPM Down:FPM
	Arm. Volts @ Hig	gh Speed: Up:	V Down:V Arn	n. Amps @ High Speed: Up: _	A Down:A
Snecial	Notes:				
opecial					
					_
					_
					_



Floor labels:

(for programming CE PI Driver board)

	Front	Rear
35		
34		
33		
32		
31		
30		
29		
28		
27		
26		
25		
24		
23		
22		
21		
20		
19		
18		
17		
16		
15		
14		
13		
12		
11		
10		
9		
8		
7		
6		
5		
4		
3		
2		
1		
	Front	Rear

EMAIL FORM