

## **TRACTION SURVEY FORM**

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Company	:			Purc	hase Order #				
Address	:				Date:				
					Job Name:				
Attn.	:								
Phone	:				lob Location:				
Fax	:			Nu	mber of Cars				
Email	:								
						T			
Ship To					Contact:				
Address	•				Phone:	<b>5 1 V</b> = 5	[]] N.		
				LIT	t Gate Truck:		[] No		
Poquestor	1				Delivery		rs* [] 48 h	rs≁ Fee Applies	
Requested Ship Date					Notification:	-	ication by V		
Ship Date	•							C	
Certification: Office Prints:	[ ] UL/CUL [✔] 11"x17"			[]C	ther				
Туре:	[] Passenger	[] Freight	[] Overhea	id []B	asement []	] MRL	[]G	eared	[] Gearless
Controller:	[ ] Vision 2.0 w/Ca [ ] PLC (GE RX3i)		-			-	Other		
<b>Building Powe</b>	r:γφ -	·Hz	Car: Ca	pacity:	Sp	beed:		Roping	Ratio::1
	[ ] 2SAC able Freq AC <i>(Open-</i> hronous Permanent	Loop ≤150FP	M) []	Flux Vecto	r AC <sup>*</sup> <i>(Closed-L</i>	oop ≥200	FPM)	[ ] DC	Drive*
Landings:	No. of Landings: _ Front Openings # _								
	Rear Openings #								
Travel Between I	_dgs.: 1						8	9	10
10	_ 11 12	13	14	15	16	17	18	19	20
20	_ 21 22	23	24	25	26	27	28	29	30
Color-Coded T	raveler Cable (Visi	ion 2.0):		_ ft (*Lengt	h Required*)				
Operation:	[] Selective Collective  [] Single Automatic Pushbutton  [] Call & Send    [] Single Button Collective  [] Constant Pressure Pushbutton  [] Real Time Dispa    [] Simplex  [] Duplex  [] Triplex  [] Group  Specify:    [] Operator Interface Unit  [] Machine Room Monitoring  [] Machine Room  [] Monitoring v    Notes:					Dispatching			
[ ] MAC [ ] Man	MOD [] GAL M SS [] MAC S ual: [] Fixed ( [] Retirin er Freight Manuf. &	TD []E Cam	CI:	Bi-parting	_ [] Other: _ Freight []	] Swing D	oor		



## TRACTION SURVEY FORM

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Fire & Safety Co	ode: [] A17 ′19	[]A17′16 []	] A17 ′13 [ ] A17 ′	10 [] A17 (year)			
	[ ] CAN B44	(year) [ ]	] Local Code:	[] Other:			
	[] Fire Service P	hase 1 Only []	] NO FIRE SERVICE				
Main Floor: Landir	ng# Label:	Alternate F	loor: Landing# La	bel:			
Fixtures:		Car / C.O.P.	Hall / Hoistway	[] Pre-Wire Fixtures. Send boards to:			
Fixture Voltage:	Vision 2.0 Standard [ ]	24V DC	24V DC	Company:			
	MH-3000 Standard []	115V AC	115V AC	Contact:			
Other [ ]V [ ] AC [ ] DCV		V [ ] AC [ ] DC	Email:				
Hall I/O Boards: [	] Screw Terminals	[ ] Plug-in (RJ45) Te	rminals	Ship by Date:			
_	_						
	osition Indicator I's @ Non-Main Ldg.	[] Hall Position Indi	-	[] Diverties Amount			
	ectronics PI Driver Board		-	[ ] Direction Arrows [ ] Voice Annunciator			
			(u)				
	[] Call Register LightsV [] AC [] DC [] Car Travel LanternV [] AC [] DC []			d) [] <sup>1</sup> / <sub>2</sub> Stroke Gong Programming by VC			
[] Hall La			[] Serial (from driver board) [] ½ Stroke Gong Programming by VC				
[] Passir							
		[]AC []DC					
[ ] In-Use							
	r Free GongV		=G @ Ldg.#				
			G @ Lug.#				
Features:							
[] Hoistv	way Insp. Access [ ] Top	] Btm [] Rear []_	[] Generator Opera	ation [ ] Auto [ ] Manual [ ] Group			
[ ] In-Cai	r Inspection		[] Governor Set/Reset Circuit				
[] Attend	[] Attendant Service			[] Homing Specify Landing #:			
[] Indep	endent Service		[] Hospital Service "Code Blue"				
[] Door	Nudging with Timed Electr	ic Eye Cutout	[] Load Weighing Bypass (Device Not Included)				
[] Infrar	ed Curtain Unit (Nudge or	Fire Service)	[] Load Weighing Overload (Device Not Included)				
[] Safety	/ Edge with [] Elect	ric Eye	[] Massachusetts EMT Hospital Service				
[] Card F	Reader Provisions		[] Reverse Phase Monitor				
[ ] Key Lo	ockouts in C.O.P. @ Ldgs.		_ [] Emergency Sheave Brake				
[] Car-to	-Lobby Switch		[] Rope Brake				
	Hold Open [ ] Switch [ ]		[] Security Service (code entered via car call buttons)				
	Applied Harmonic Filter (I	EEE 519)	[ ] Seismic (EQ) Specify Device & Code:				
	Isolation Transformer		[] Battery Rescue [] Full Auto [] Brake Pulse [] R&R [] AB				
	gency Terminal Slowdown	Device (ETSD)	[] WiFi Mobile Interface [] Router+Tablet [] Router Only				
	Light Auto K/O		[ ] Other:				
	nking on Fire Service		[ ] Other:				
	on Indicator Cutout Timeo	. ,	[ ] Other:				
[] Other	r:						
	[] Wall Mounted [] Free						
				[ ] Other:			
	[] Special Dimensions:	″ H x″ W x	"D				

## **Traction SURVEY FORM**



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Positioning/Leveling System: [] ELGO Absolu	te Positioning System (Visio	n 2.0 Controllers ONLY)			
[]IP-8300 []IP-8700 []NE	[] IP-8300 [] IP-8700 [] NEMA 1 w/Steel Tape				
[] Landing/Leveling by Others: [] Ou	tput/Floor	[] Pulsing			
Brake: Provide Manufacturer's Data / Nai	•				
[] Hollister/Whitney [] Other:		Economy Switch: [ ] Yes [ ] No			
[ ] AC:V @ Amps	[] DC: Pull-In_	V HoldVΩ			
-		rmation as available			
about the mot	or you want the proj	ject to be based on.			
1 or 2 Speed AC & Variable Frequency:	Provide Manufacturer's Da	ata / Nameplate Data			
[] Existing or New by You	Matau V 2 COLL				
Manuf.:		HP Ratio::1			
Fast:ARPM	Slow:AI	RPM No Load (Mag): A			
[] New by VCI					
[] Foot Mounted	Required Motor F	RPM:			
[] Flange Mounted:					
Machine Manur.:	Machine No.:	Frame Size:	-		
Synchronous Permanent Magnet AC:	Provida Manufacturar's D	ata / Namonlato Data			
		cy:% Sheave Dia.:in.			
Motor:V-36Hz/					
·	•				
		nDat Interface) Compensation: [] Cable			
		[ ] None			
Motor-Generator: Provide Manufa	cturer's Data / Namenlate Di	Pata			
Manuf.:					
		PM [] Wye-Delta [] Across-the-line			
[] Other:					
	PlateVDC Name P	Plate A	-		
	allel <i>(Provide Sketch)</i>				
Shunt Field Resistance (Measured)					
Shunt Field Volt @ Level Speed: Up		Level Speed: UpFPM DownFPM	4		
Shunt Field Volt @ High Speed: Up			•		
		suicide & hoist motor loop with "wire markings".			
	5 5	, 2			
DC Hoist Motor: Provide Manufacturer's D	Data / Nameplate Data				
Manuf.: [] Nev					
HPRPM Name		Plate A			
Field: [] Series [] Parallel	(Provide Sketch)				
Field Voltage @ High Speed: V		eed:V Field Voltage @ Standing:	_v		
Field Resistance (Hot): $\Omega$		Up FPM Down FPM	-		
Arm. Volts @ High Speed: UpV		mps @ High Speed: UpA DownA			
<u> </u>					
Special Notes:					