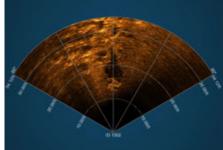


SARbot® (Search & Recovery Robotic System) is a highly capable & low-cost tool for searching, locating and identifying submerged targets in marine environments. Designed from a base ROV platform that has more than 4000 systems in the field, the SARbot® has been optimized to allow the operator to work in low to zero visibility conditions, recover targets and work with an unlimited search time to an operational depth of up to ~650ft.





Integrated Multibeam Imaging Sonar

BASIC SPECIFICATIONS

3 Surface Power Console Options

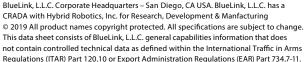
| REACH | 100m (330ft) Standard Depth Rating 300m (984ft) Extended Depth Rating 125m (410ft) or 250m (820ft) Tethers |
|----------------------------|--|
| VIDEO | 1080p HD Video |
| LIGHTING | 6000 Lumens (total) |
| GRIPPER | Large Interlocking Jaws |
| MULTIBEAM IMAGING SONAR | Compatibility: Tritech Gemini, Blueprint Subsea Oculus, Sonoptix ECHO & Teledyne BlueView |
| DIMENSIONS | L 457mm (18"), W 575mm (22.6"), H 254mm (10") |
| ROV WEIGHT | 13.5kg (30lbs) - Typical (Dependent on Payloads) |
| TOPSIDE WEIGHT | 16kg (35lbs) |
| TOPSIDE CONTROL | |
| THRUSTERS | (4) Lateral Vectored Thrusters for Precise Control (4) Vertical Thrusters for Lift & Stablization |
| OPERATING ENVIRONMENT | Zero Visibilty & Up to a 2 Knot Current* |
| SAFETY | Isolated Output, Shielded Tether |

Meets IMCA D 045, R 015 Standard

KEY FEATURES

- Highly Capable & Maneuverable ROV System
- Low Investment & Cost of Ownership
- Full 1080p HD Video
- 1200W or 1800W Vehicle Power Supply
- 6-Axis Control with Stablization
- Direct Load Transfer for Retrieving Submerged Objects
- Effective in Low to Zero Visibility Environments
- Compatible with Most Multibeam Imaging Sonars
- Simple and Designed to be Customer Maintained
- Surfaced Powered (Battery Power Optional)
- Single Person Deployable
- Options: DVLs, USBL Tracking Systems & Scaling Lasers







^{*}Higher current operation possible with experienced operator.