

KINK-EQUIVALENCE OF MATRICES , SPANNING SURFACES 4-MANIFOLDS, & QUADRATIC FORMS

THOMAS KINDRED

WAKE FOREST UNIV.

BASED ON JOINT WORK WITH:

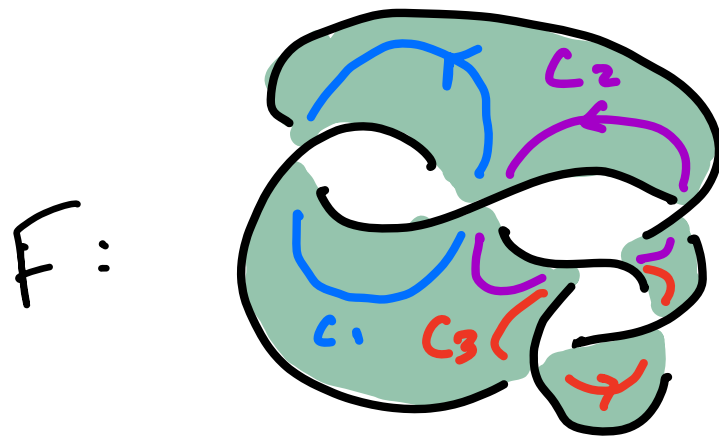
HUGH HOWARDS,

FRANK MOORE,

* JOHN TOLBERT *

A **GOERITZ MATRIX** G of a spanning surface F measures how much F twists:

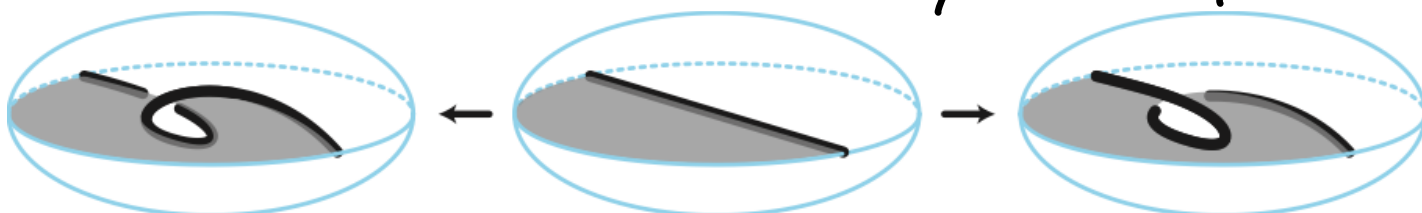
EX:



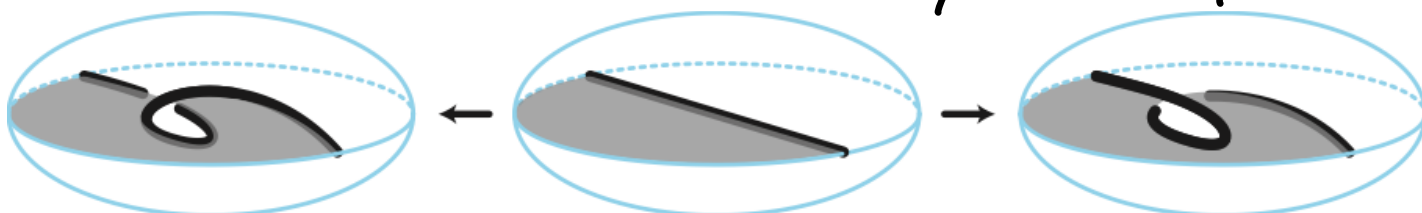
$$G: \begin{bmatrix} 2 & -1 & 0 \\ -1 & 3 & -1 \\ 0 & -1 & 3 \end{bmatrix}$$

THM (GREENE): A KNOT IS **ALTERNATING** IFF IT HAS SPANNING SURFACES WHOSE GOERITZ MATRICES ARE POSITIVE- AND NEGATIVE-DEFINITE.

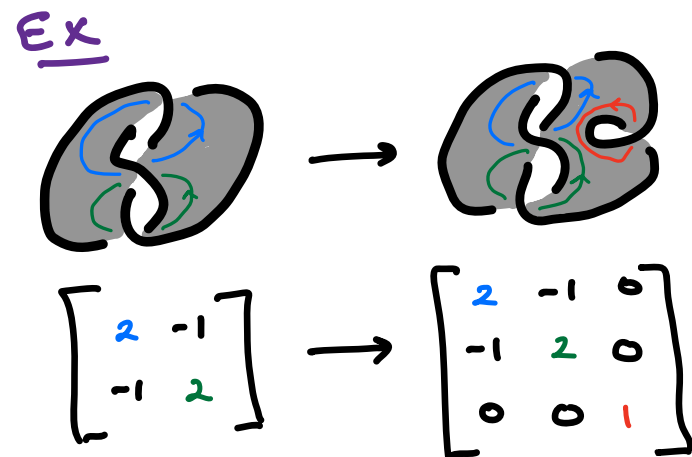
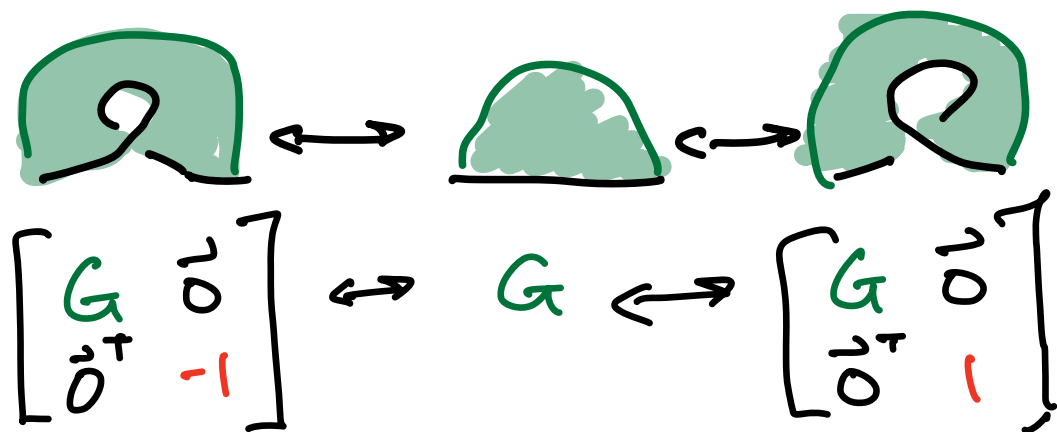
THEOREM (K): ALL CHECKERBOARD (CB) SURFACES
(FOR ALL DIAGRAMS) OF A GIVEN KNOT IN S^3 ARE
"KINK-EQUIVALENT", I.E. RELATED BY ISOTOPY! "KINK" MOVES:



THEOREM (K): ALL CHECKERBOARD (CB) SURFACES (FOR ALL DIAGRAMS) OF A GIVEN KNOT IN S^3 ARE "KINK-EQUIVALENT", I.E. RELATED BY ISOTOPY! "KINK" MOVES:



KINK MOVES CHANGE A GOERITZ MATRIX G LIKE THIS:



DEFN: Two symmetric integer matrices are

KINK-EQUIVALENT if they are related by these moves:

$$G \longleftrightarrow P^T G P$$

(P unimodular)

$$G \longleftrightarrow \begin{bmatrix} G & 0 \\ 0 & \pm 1 \end{bmatrix}$$

Q: How much does kink-equivalence of matrices differ from kink-equivalence of surfaces?

DEFN: Two symmetric integer matrices are KINK-EQUIVALENT IF THEY ARE RELATED BY THESE MOVES:

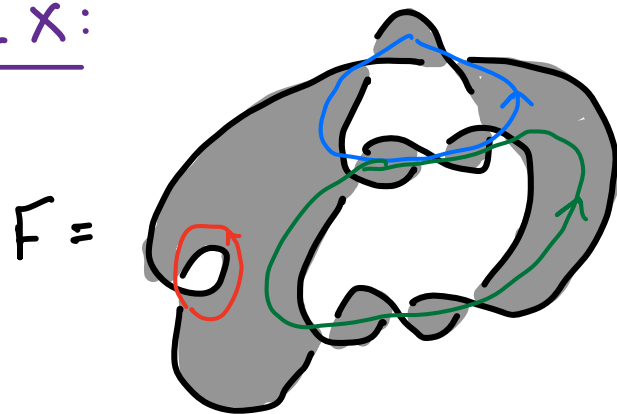
$$G \leftrightarrow P^T G P$$

(P UNIMODULAR)

$$G \leftrightarrow \begin{bmatrix} G & 0 \\ 0 & \pm 1 \end{bmatrix}$$

Q: How much does KINK-EQUIVALENCE OF MATRICES DIFFER FROM KINK-EQUIVALENCE OF SURFACES?

EX:



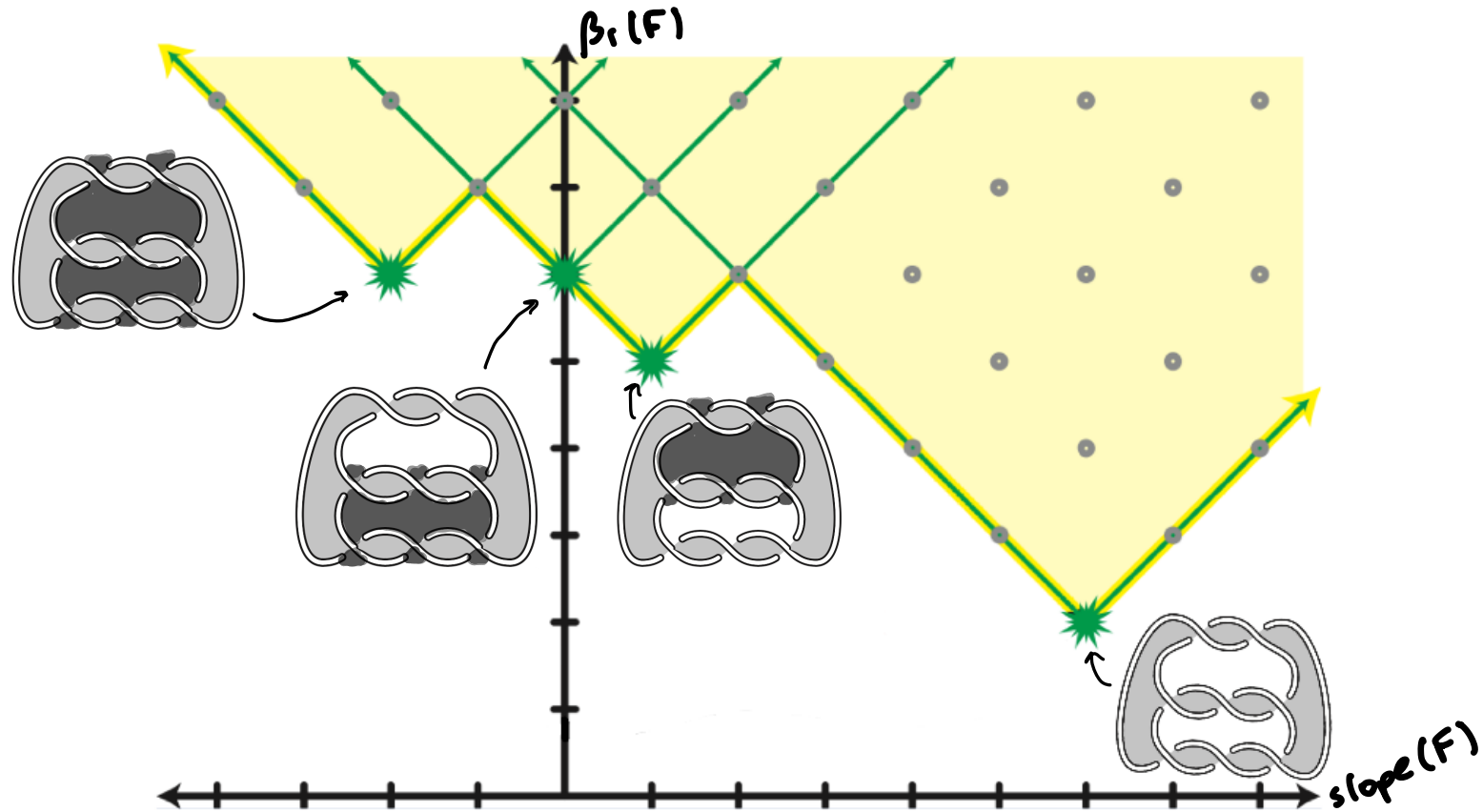
HAS GOERITZ MATRICES

$$G_1 = \begin{bmatrix} 5 & -3 & 0 \\ -3 & 6 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

AND $G_2 = \begin{bmatrix} -3 & 6 & 0 \\ 6 & -5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

BUT F_1 , UNLIKE G_2 , ADMITS NO POSITIVE-UNKINKING MOVE (EVEN AFTER ISOTOPY) \leadsto "fake unkinking move"

Geography Problem: Given a knot K , identify all pairs $(\beta_1(F), \text{slope}(F))$ realized by spanning surfaces F for K .

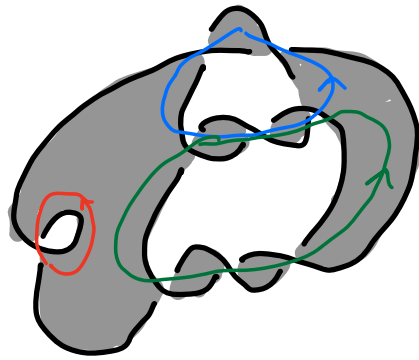


THEOREM (ADAMS-K): Given an alternating diagram D of a knot K the adequate state surfaces from D determine the geography of K as shown above.

EX:

HAS GOERITZ MATRICES

$F =$

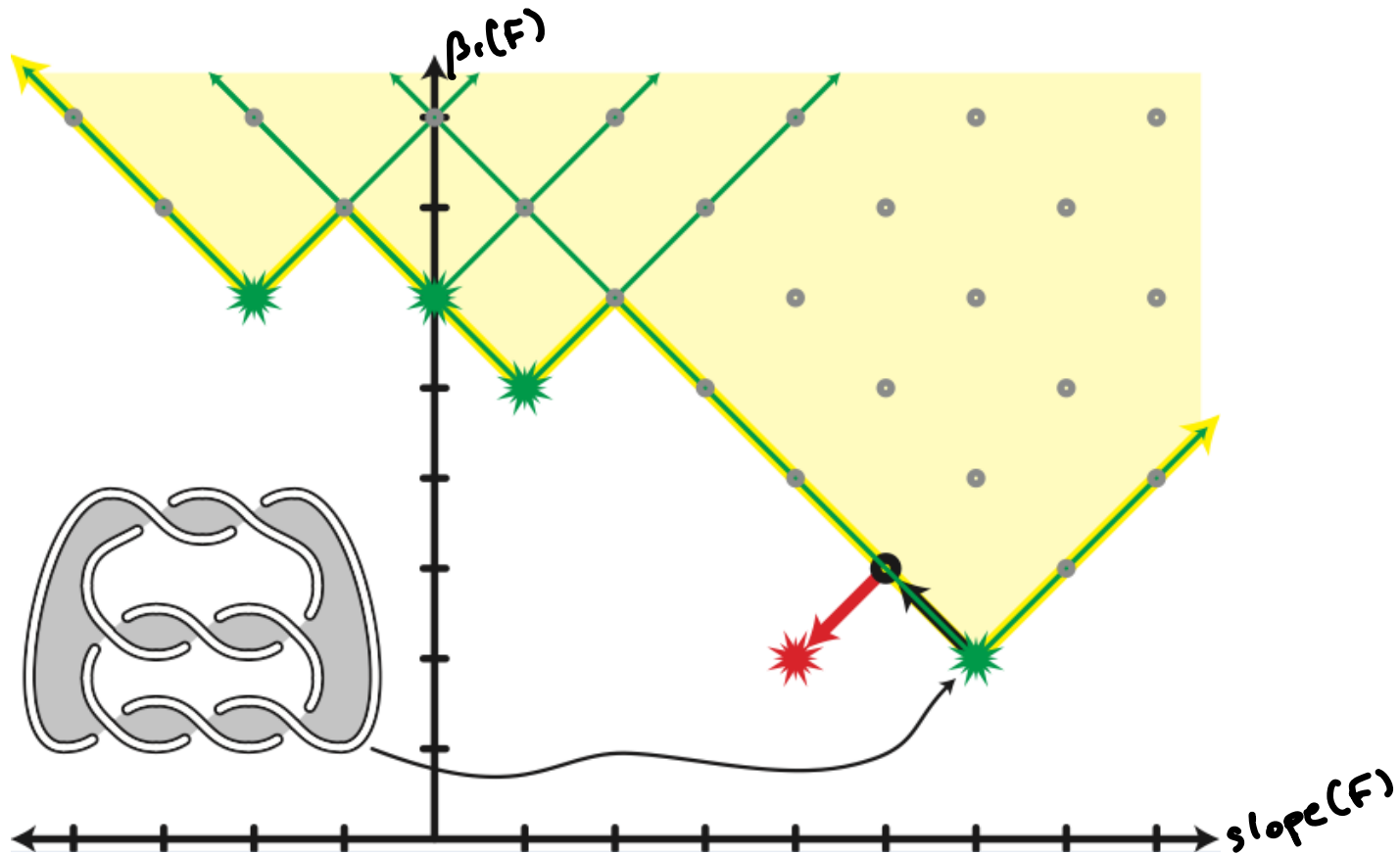


$$G_1 = \begin{bmatrix} 5 & -3 & 0 \\ -3 & 6 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

AND

$$G_2 = \begin{bmatrix} -3 & 6 & 0 \\ 6 & -5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

BUT F , UNLIKE G_2 , ADMITS NO POSITIVE-UNKINKING MOVE (EVEN AFTER ISOTOPY) \leadsto "fake unkinking move"



Q: Which positive-definite integer matrices are
kink-equivalent (\sim) to negative-definite matrices?

Q: Which positive-definite integer matrices are
kink-equivalent (\sim) to negative-definite matrices?

PROP(H-K-M-T): IF G decomposes as $G = I + CC^T = [I \ C] \cdot [I \ C]^T$
then $G \sim -(I + C^T C)$, which is negative-definite.

Q: For which positive-definite integer matrices G
does there exist an integer matrix C
such that $G = C^T C$?

Q: Which positive-definite integer matrices are
kink-equivalent (\sim) to negative-definite matrices?

PROP(H-K-M-T): IF G decomposes as $G = I + CC^T = [I \ C] \cdot [I \ C]^T$
then $G \sim -(I + C^T C)$, which is negative-definite.

Q: For which positive-definite integer matrices G
does there exist an integer matrix C
such that $G = C^T C$?

A: Not all, e.g. :

$$G = \begin{bmatrix} 2 & 1 & 1 & 1 & 0 & 0 \\ 1 & 2 & 1 & 1 & 1 & 0 \\ 1 & 1 & 2 & 1 & 1 & 1 \\ 1 & 1 & 1 & 2 & 1 & 1 \\ 0 & 1 & 1 & 1 & 2 & 1 \\ 0 & 0 & 1 & 1 & 1 & 2 \end{bmatrix}$$

THM (H. HOWARDS, K., F. MOORE, J. TOLBERT): Given a symmetric integer matrix G , TFAE:

- ① G is kink-equivalent to a positive-definite matrix.
- ② G is kink-equivalent to a negative-definite matrix.
- ③ G is nonsingular.

MOREOVER... [LINEAR BOUND ON THE # OF MOVES NEEDED]
↳ COMES FROM LAGRANGE'S FOUR SQUARES THM

THM (H. HOWARDS, K., F. MOORE, J. TOLBERT): Given a symmetric integer matrix G , TFAE:

- ① G is link-equivalent to a positive-definite matrix.
- ② G is link-equivalent to a negative-definite matrix.
- ③ G is nonsingular.

MOREOVER... [LINEAR BOUND ON THE # OF MOVES NEEDED]
 ↳ COMES FROM LAGRANGE'S FOUR SQUARES THM

COR: EVERY KNOT IS "ALTERNATING UP TO FAKE UNKINKING MOVES"

COR: Given a simply-connected closed topological 4-manifold whose intersection pairing is nonsingular w/ n_{\pm} \pm eigenvalues, \exists \pm definite 4-manifolds M_{\pm} and these homeomorphisms:

$$M_+ \#_{i=1}^{n_-} \overline{\mathbb{C}P^2} \cong M \#_{i=1}^{+n_-} \mathbb{C}P^2 \quad \text{AND} \quad M_- \#_{i=1}^{n_+} \overline{\mathbb{C}P^2} \cong M \#_{i=1}^{+n_+} \mathbb{C}P^2$$

DEFN: Two symmetric RATIONAL MATRICES ARE KINK-EQUIVALENT IF THEY ARE RELATED BY THESE MOVES:

$$G \longleftrightarrow P^T G P$$

(P UNIMODULAR)

$$G \longleftrightarrow \begin{bmatrix} G & 0 \\ 0 & \pm 1 \end{bmatrix}$$

THM (H. HOWARDS, K., F. MOORE, J. TOLBERT): Given a symmetric rational integer matrix G , TFAE:

- ① G is kink-equivalent to a positive-definite matrix.
- ② G is kink-equivalent to a negative-definite matrix.
- ③ G is nonsingular.

MOREOVER... [LINEAR BOUND ON THE # OF MOVES NEEDED]

DEFN: Two symmetric RATIONAL MATRICES ARE KINK-EQUIVALENT IF THEY ARE RELATED BY THESE MOVES:

$$G \longleftrightarrow P^T G P$$

(P UNIMODULAR)

$$G \longleftrightarrow \begin{bmatrix} G & 0 \\ 0 & \pm 1 \end{bmatrix}$$

THM (H. HOWARDS, K., F. MOORE, J. TOLBERT): Given a symmetric rational integer matrix G , TFAE:

- ① G is kink-equivalent to a positive-definite matrix.
- ② G is kink-equivalent to a negative-definite matrix.
- ③ G is nonsingular.

MOREOVER... [LINEAR BOUND ON THE # OF MOVES NEEDED]

COR: LET $q: \mathbb{Q}^n \rightarrow \mathbb{Q}$ be a nonsingular quadratic form w/ n_{\pm} \pm eigenvalues. Writing $q_0: x \mapsto x^2$, \exists \pm definite quadratic forms that satisfy these unimodular congruences:

$$q + q_0^{\pm n_-} \approx q_+ \oplus (-q_0)^{n_-} \quad \text{AND} \quad q + (-q_0)^{\pm n_+} \approx q_- \oplus q_0^{n_+}$$

OPEN Q: ARE $[3]$ AND $[-3]$ KINK-EQUIVALENT?

Open Q:

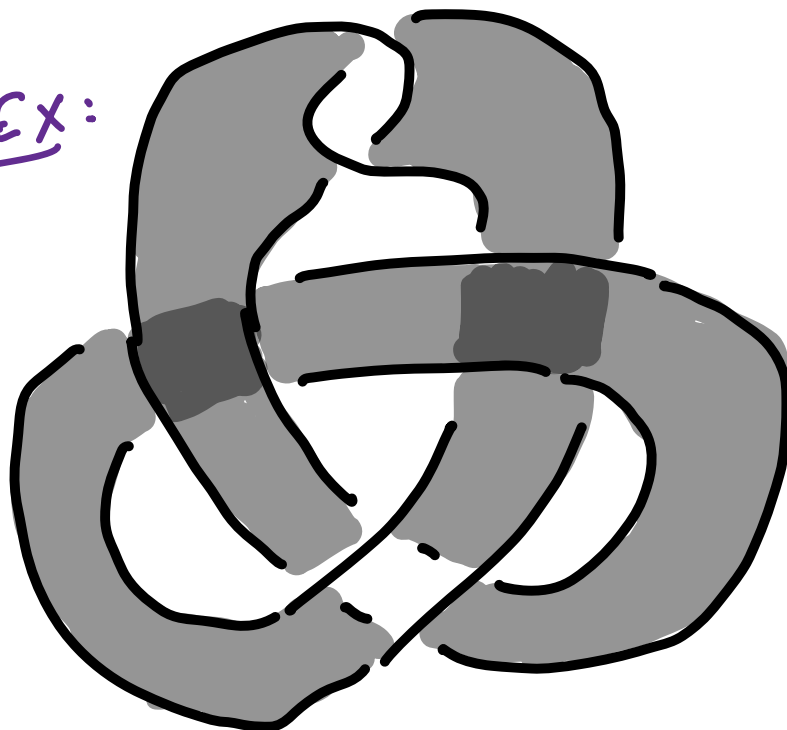
$\left\{ \begin{array}{l} \text{Spanning} \\ \text{Surfaces} \\ \text{in } \mathbb{R}^3 \end{array} \right\}$

$\subsetneq \left\{ \begin{array}{l} \text{FREE} \\ \text{Spanning} \\ \text{Surfaces} \\ \text{in } \mathbb{R}^3 \end{array} \right\}$

$\subsetneq \left\{ \begin{array}{l} \text{unkinked} \\ \text{Checkerboard} \\ \text{Surfaces} \\ \text{in } \mathbb{R}^3 \end{array} \right\}$

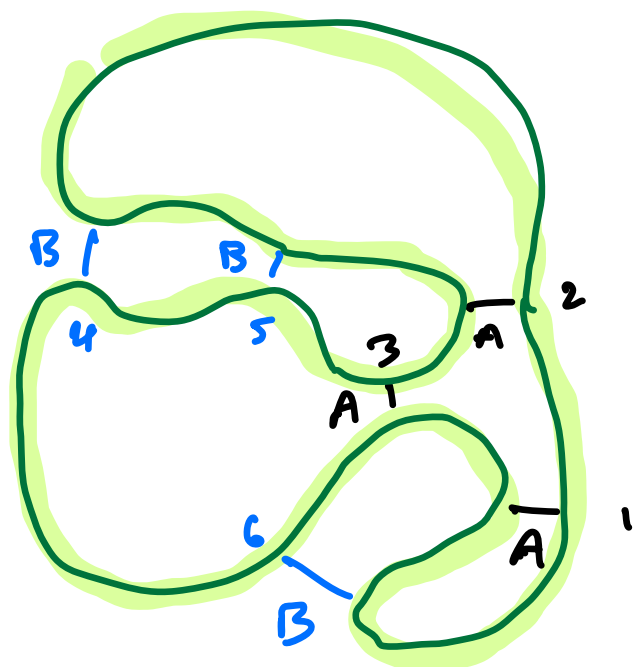
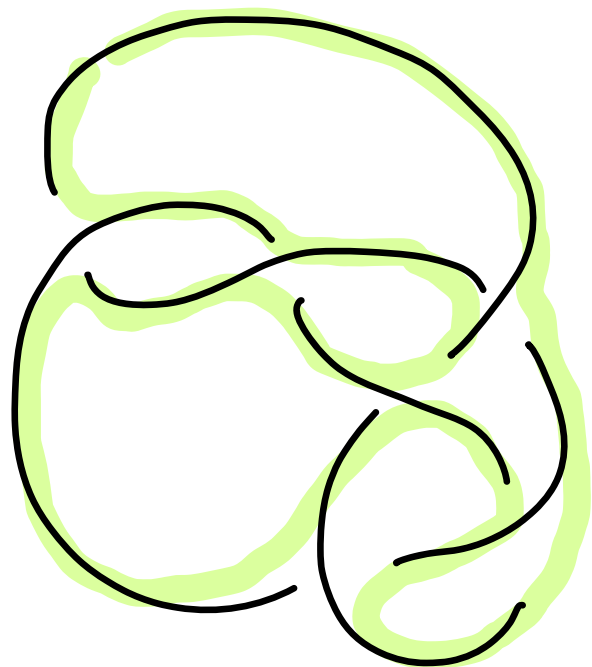
$\subsetneq \left\{ \begin{array}{l} \text{Checkerboard} \\ \text{Surfaces} \\ \text{in } \mathbb{R}^3 \end{array} \right\}$

EX:



THANK

You!



$$\begin{bmatrix} -1 & 0 & 0 & 0 & 0 & 1 \\ 0 & -1 & 0 & 1 & 1 & 0 \\ 0 & 0 & -1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$\left[\begin{array}{cc|cc} I & 0 & & A \\ 0 & -I & & \\ \hdashline & & I & 0 \\ A^T & & 0 & -I \end{array} \right]$$