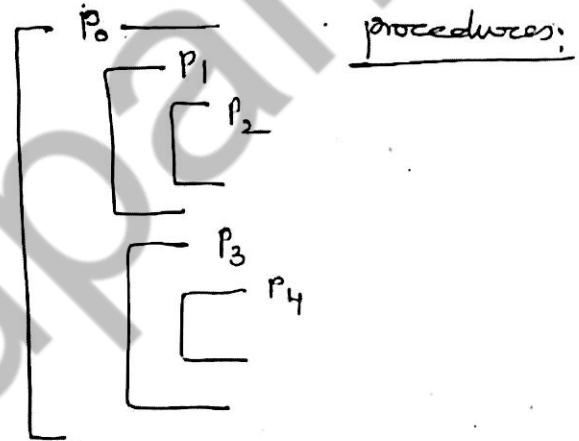
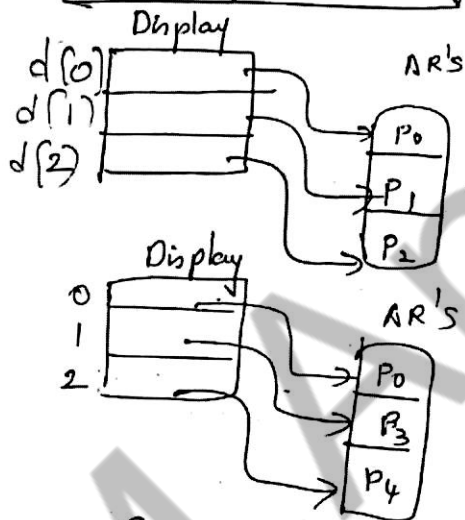


## UNIT IV

Displays: Access to nonlocal data by traversing down of nesting access links every time is expensive when the depth increases. (as we have to follow long chains of links to reach the data we need) So an array of pointers called display  $d[i]$  is maintained.

1. In an display an array of pointers to activation record is maintained. (one pointer for each nesting depth)
2. Array is indexed by nesting level.
3. The pointers point to only accessible activation records.
4. The display changes when a new activation record occurs and it must be reset when control returns from the new activation.

Maintaining a display:



\*  $d[i]$  is a ptr to the highest activation record on the stack for any procedure at nesting depth  $i$ .

Comparison between Access links & displays.

1. Access links take more time to access non local variables especially when non local variables are at many nested levels away.
2. Display is used to generate code efficiently.
3. Display requires more ~~time~~ <sup>space</sup> at runtime than access links.

Type Conversion, Type Equivalence and Type Coercion

(Explain the terms.)

Q) In most languages, even a stack based environment needs some dynamic capabilities in order to handle Heap Allocation: ptr allocation and deallocation. The data structure that handles such allocation is called a heap. If local values of local names must be retained when an activation ends, and a called activation outlives the caller

Stack allocation strategy is not possible. This is because the deallocation of activation records will not occur in a LIFO fashion. So storage cannot be organized as a

Stack. Eg: C++, Java have new to create objects/ptrs which may be passed from procedure to procedure, so they continue to exist after the procedure. So, heap gives out pieces of storage as needed for that created them in go.

activation records or other objects. These pieces can be deallocated at any time and the free space is used by other objects. (A) would:

Heap allocation retains the activation record even after the activation is complete. Later when it is deallocated the free space will be filled up by heap manager by some other objects, whereas in a stack the activation record is deallocated after completion of execution and allocates the next activation record which has started execution. The heap provides two operations allocate & free; eg: new and delete C++ malloc and free C. The size of heap is not fixed. It may grow or shrink interchangeably during the program execution.

The memory manager: 7.4.1 Aho Ullman.

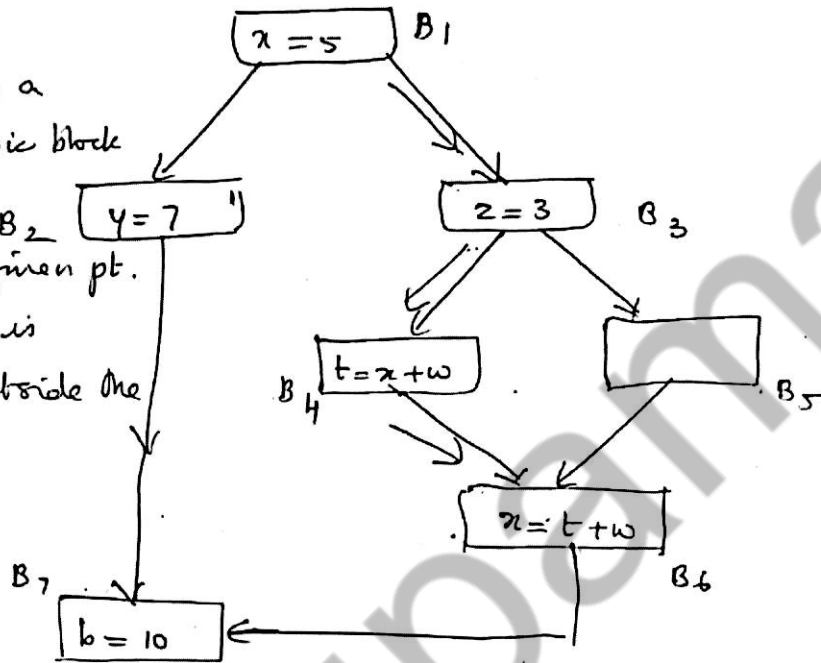
Garbage Collection: It is the process of finding spaces within the heap that are no longer used by the program, and can therefore be reallocated for other data items. Eg: In Java the garbage collector deallocates memory. Automatic garbage collection deallocates unreachable data.

7.5.1 and 7.5.2 Aho Ullman Design goals for garbage collectors, performance metrics and Reachability.



Live Variables: A variable  $x$  is live at some pt.  $p$  if there is a path from  $p$  to the exit, along which the value of  $x$  is used before it is redefined. Otherwise the variable is said to be dead at that point.

In other words a variable name in a basic block is said to be alive at a given pt. if its value is required outside the block.

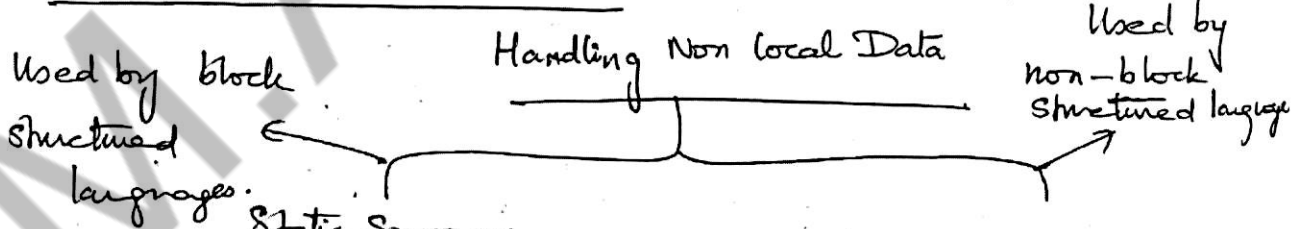


$x$  is live at block  $B_1, B_3, B_4$  but killed at  $B_6$ .

live variables are useful in register allocation.

live variables are useful for dead code elimination.

Access to Non local Data: Variables not local to a procedure are called non-local variables.



Static Scope or lexical Scope

Dynamic Scope

Access link

Deep Access

Display

P.T.O ( )

Shallow Access.

Static Scope Rule: Also called as lexical scope.

The scope is determined by examining the program text.

Eg: Pascal, C. These languages are called block structured languages.  
Dynamic Scope: Non block structured languages Lisp, Snobol.

(It determines the scope of declaration of the names at runtime by considering the current activation.)

The use of a non local variable refers to the non local data declared in most recently called and still active procedure. Therefore each time new bindings are set up for local names called procedure. Symbol tables can be required at run time.

(In dynamic scoping the question of which non local variables to use is determined at runtime.)

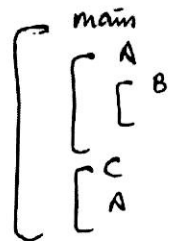
There are two ways to implement non local accessing under dynamic scoping.

1. Deep Access
2. Shallow Access.

Static Scope Rule: Block Structured languages.

The blocks can be in nested fashion that is  $B_2$  completely inside  $B_1$ . (The scope of declaration in a block structured language is given by most closely nested loop or static rule. Block structure storage allocation can be done by stack.)

Nested procedures: Nested procedure is a procedure that can be declared within another procedure.



(Static/lexical scope can be implemented using access link and displays.)