DEMOS

Table	First Name	Last Name	Affiliation	TITLE
D-1	**Aaron**	**Becker**	University of Houston	Blood clot removing catheter competition! (Robotics Outreach)
D-2	**Kevin**	**Best**	University of Michigan	NRI: INT: Collaborative Research: An Open-Source Framework for Continuous Torque Control of Intuitive Robotic Prosthetic Legs
D-3	**Yu**	**Gu**	West Virginia University	Stickbug, a six armed robotic pollinator
D-4	**Kaushik**	**Jayaram**	University of Colorado Boulder	Towards Shape-shifting Locomotion in Confined Environments with Insect-scale Robots
D-5	**Idris**	**Jeelani**	University of Florida	Investigating the Safety Challenges of Co-drones in Future Construction Workplaces
D-6	**Rui**	**Liu**	Kent State University	Meta preference learning for customized human-multi-robot coordination
D-7	**Giuseppe**	**Loianno**	New York University	CAREER: Re-Thinking the Perception-Action Paradigm for Agile Autonomous Robots
D-8	**Andreas**	**Malikopoulos**	Cornell University	A Virtual Reality Platform for Studying the Interactions between Human-Driven Vehicles and Autonomous Vehicles
D-9	**Yichen**	**Zhai**	University of California San Diego	Monolithic Printing of Soft Robots with Embodied Control
D-10	**Harry**	**Asada**	MIT	**DEMO at Poster #38 Handle Anywhere**
D-11	**Joshua**	**Smith**	University of Washington	**DEMO at Poster #61 NRI:FND: Multi-Manipulator Extensible Robotic Platforms**
D-12	**Zeynep**	**Temel**	Carnegie Mellon University	**DEMO at Poster #17 | NRI: INT Dexterous Manipulation using Delta Arrays**