

# AI-Robot Development Kit Course Outline

|   | Categories         | Course Resources and Practice Cases  |
|---|--------------------|--|
| 1 | Python programming | <ul style="list-style-type: none"> <li>(1) Number types, conversions, and operations</li> <li>(2) Basic usage of Python operators, built-in functions, sequences</li> <li>(3) Program selection structure experiment</li> <li>(4) Program loop structure experiment</li> <li>(5) List experiments</li> <li>(6) Ensemble experiments</li> <li>(7) Function experiments</li> <li>(8) String experiments</li> <li>(9) The regular expression experiment</li> <li>(10) Visualize the data</li> <li>(11) Data processing in Python</li> <li>(12) Python file operations</li> <li>(13) Python multi-processing</li> <li>(14) Python multi-threading</li> <li>(15) The difference between Python processes and threads</li> <li>(16) Object-oriented Python understanding</li> <li>(17) Using Python classes and instantiating them</li> <li>(18) Using Python to instantiate objects</li> <li>(19) Inheritance with Python classes</li> <li>(20) Serial communication with Python</li> <li>(21) Socket TCP communication based on Python</li> <li>(22) Python based Socket UDP communication</li> <li>(23) Modbus communication with Python</li> <li>(24) PyQt5 environment setup</li> <li>(25) Use of PyQt5</li> <li>(26) Use of Qt Designer and PyUIC</li> </ul> |
| 2 | Machine learning   | <ul style="list-style-type: none"> <li>(1) AdaBoost movie dataset data classification</li> <li>(2) Verification of double coin toss model based on EM inference</li> <li>(3) Classification of unknown data based on K-means algorithm</li> <li>(4) Movie genre recognition based on K-nearest neighbor algorithm</li> <li>(5) Dynamic pedestrian detection based on HOG and support vector machine</li> <li>(6) Decision tree-based diagnosis of breast cancer</li> <li>(7) Naive Bayes-based spam filtering</li> <li>(8) Face recognition based on random forest</li> </ul>  |

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|   |                          | (9) Housing price prediction based on linear regression  |
| 3 | Deep learning            | <p>(1) Linear regression modeling and application: house price prediction experiment</p> <p>(2) Model construction and application of neural network: clothing classification experiment</p> <p>(3) Neural network regularization: clothing classification optimization experiment</p> <p>(4) Neural network parameter optimization: nonlinear function minima finding experiment</p> <p>(5) Model construction and testing experiments based on neural networks</p> <p>(6) Optimization model design based on residual network</p> <p>(7) Neural network optimizer - handwritten digit recognition</p> <p>(8) Text classification - JD shopping classification</p> <p>(9) Design based on LeNet handwritten digit body recognition system</p> <p>(10) Automatic arrangement design of songs based on RNN</p> <p>(11) Image target detection based on YOLOV5</p> |
| 4 | Digital image processing | <p>(1) Algebraic operations between images</p> <p>(2) Coding and decoding of image operations</p> <p>(3) Geometric affine transformation of the image</p> <p>(4) Image airspace filtering</p> <p>(5) Frequency-domain filtering of images</p> <p>(6) Morphology-based detection of rice grains</p> <p>(7) Image cutout based on Canny algorithm</p> <p>(8) Image contour segmentation based on watersheds</p> <p>(9) Based on Hu rectangular shape matching</p> <p>(10) Smooth filtering and morphological processing</p>  |
| 5 | Machine vision           | <p>(1) Visual system cognition</p> <p>(2) Pixel size measurement</p> <p>(3) Object positioning and angle measurement</p> <p>(4) Edge length measurement and area detection</p> <p>(5) Object color and shape recognition</p> <p>(6) Barcode and QR code recognition</p> <p>(7) OCR character segmentation and training</p> <p>(8) OCR character recognition</p> <p>(9) Detection of product surface defects based on morphological treatment</p> <p>(10) Camera checkerboard calibration</p> <p>(11) Vision-based license plate recognition</p> <p>(12) License plate recognition based on OpenCV</p> <p>(13) Electronic product identification based on template matching</p>   |

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|   |                                      | <ul style="list-style-type: none"> <li>(14) Vision-based barcode recognition</li> <li>(15) Vision-based QR code recognition</li> <li>(16) Vision-based object shape and color recognition</li> <li>(17) Visual-based fruit recognition</li> <li>(18) Image-based NanoDet object detection model practice</li> </ul>   |
| 6 | Depth vision                         | <ul style="list-style-type: none"> <li>(1) Face detection and ranging</li> <li>(2) Face detection and gimbals following</li> <li>(3) Face detection and recognition</li> <li>(4) Mask testing</li> <li>(5) Dynamic pedestrian detection</li> </ul>  |
| 7 | Embedded Systems and applications    | <ul style="list-style-type: none"> <li>(1) Intelligent sensing system cognition</li> <li>(2) The construction of the Arduino programming environment</li> <li>(3) OLED display experiment</li> <li>(4) Human radar detection experiment</li> <li>(5) Illuminance detection experiment</li> <li>(6) Heart rate detector experiment</li> <li>(7) Ultrasonic rangefinder experiment</li> <li>(8) Intelligent traffic light control experiment</li> <li>(9) Fan speed control experiment</li> <li>(10) Gyroscope-based attitude somatosensory gimbals control</li> <li>(11) Bluetooth-based intelligent security system design</li> </ul> |
| 8 | Speech Processing and Sensor Control | <ul style="list-style-type: none"> <li>(1) Cognition of speech processing module</li> <li>(2) LED light control</li> <li>(3) Lamp ring control based on SPI</li> <li>(4) Sound source localization</li> <li>(5) Voice control lighting</li> <li>(6) Voice control to play music</li> <li>(7) Speech recognition and response</li> <li>(8) Voice-controlled robotic arm visual grabbing</li> <li>(9) Voice-based intelligent sensor control</li> <li>(10) Object classification of robotic arm based on vision and speech</li> </ul>   |
| 9 | Vision-based Robotics Applications   | <ul style="list-style-type: none"> <li>(1) Robotic arm cognition and basic operation</li> <li>(2) Robotic arm teaching and motion control</li> <li>(3) Calibration of robotic arm and vision system</li> <li>(4) Vision-based object classification of robotic arms</li> <li>(5) Vision-based robotic arm object palletizing</li> <li>(6) Vision-based numerical sequencing of robotic arms</li> <li>(7) Object classification of robotic arms based on vision and speech</li> <li>(8) Vision-based robotic arm fruit sorting</li> </ul>  |