

Kinetix 6500 fault codes s55

Looking for Technical Documentation? Visit the Technical Documentation Center to find product specifications, installation guides, user manuals, product certifications and more. For information on troubleshooting SAFE FLT fault codes, refer to the Kinetix 6200 and Kinetix 6500 Safe Speed Monitoring Safety Reference Manual, publication 2094-RM001. Table 80 - Fault Code Summary Fault Code Type Description FLT Sxx Standard runtime anomalies. FLT Mxx INIT FLT Sxx Anomalies that prevent normal operation and occur during the initialization process. INIT FLT Mxx NODE FLTxx Anomalies that prevent normal operation of all drives on the power rail. NODE ALARM xx Anomalies that prevent normal operation of all drives on the power rail, but do not result in any action other than reporting the alarm to the controller. ALARM SxxALARM Mxx Warnings of conditions that may affect normal operation, but do not result in any action other than reporting the alarm to the controller. TIP Fault codes triggered by conditions that fall outside factory set limits are identified by FL at the end of the display message. <u>healthrider softstrider le treadmill</u> For example, FLT S03...MTR OVERSPEED FL. Fault codes triggered by conditions that fall outside user set limits are identified by UL at the end of the display message. For example, FLT S04...MTR OVERSPEED FL S04

Chapter 8 Insubleshooting the Kinetix 6200 and Kinetix 6500 Drive System

Four-character Display Message	RSLogix S000 Fault Message	Problem or Symptom	Potential Cause	Possible Resolution
FUT M12POWER CYCLE FL	Pre-charge Overload	The converter estimates that the pre- charge circuit has exceeded its limit due to excessive power cycling.	The DC bus power has been cycled too frequently.	Limit power cycles to two per minute maximum.
FLT M13 POWER CYCLE UL (Kinetix 6500 drives only)	Pre-charge Overload	The converter estimates that the pre- charge circuit is approaching its user- defined limit due to excessive power cycling.		
FUT M14CURR FDBX OFFSET	Excessive Current Feedback Offset	Current feedback hardware fault detected.		Replace the power module.
FLT M15REGEN PWIR SUPPLY	Regenerative Power Supply Fault	The hardware Regeneration DK input was deactivated while the drive was enabled.	Regen unit faulted.	Reset faulted regen unit.
FUT M19DC BUS LIMIT	DC Bus Limited Position Error	During a DC bus limit condition, the position error exceeded a user limit for a programmable period of time.	Excessive load drawn from DC bus by application.	Modify application to reduce loading on DC Bus. Increase converter size to provide additional bus capacity.
FLT M25COMMON BUS	DC Common Bus Fault	AC Power was detected by the drive while configured for Common Bus Follower operation.	Improper configuration or connection.	Check IAM power configuration and wire accordingly.
FUT M26RUNTIME ERROR	Runtime Drive Error	The drive firmware encountered an unrecoverable runtime error.		Cycle control power. Replace Module
FUI M27BACKPLANE COMM	Backplane COM	Communication over the backplane detected a problem.	Electrical Noise.	Cycle control power.
			Poor module connection.	With power off, reseat power module in rail and control module in power module.
			Faulty module.	Replace module.
FUT M28SAFETY COMM	Internal Safety Communication	Communication with the safety hardware within the drive mailfunctioned.		Cycle control power. Replace module.
FLT IM64SENSOR ASSIGNMENT	No Quick View message	The Rivne, Registration 1, or Registration 2 digital input function has been requested but is not assigned to an input. Multiple inputs have been assigned the same function.		Assign proper function to the four available digital inputs.
FLT MG8IPIM	IPM Module Fault	A fault has occurred in one or more IPDM modules on the power rail.		Refer to the troubleshooting chapter in the Kinetix 6000M Integrated Drive-Motor System User Manual, publication 2014- 14003.

204 Rockwell Automation Publication 2014-UM002E-EN-P - May 2012

Check cables for noise.
Check tuning. FLT S04...MTR OVERSPEED UL(Kinetix 6500 drives only) Motor Overspeed Motor speed has exceeded user velocity limits. FLT S05...MTR OVERTEMP FL nn Motor Overtemperature The motor thermistor, or encoder temperature sensor indicates that the motor factory temperature limit has been exceeded. <u>bapedakikarikubizew.pdf</u> The nn sub-code is defined as follows: High motor ambient temperature and/or Excessive Current.
Operate within (not above) the continuous torque rating for the ambient temperature.



• Lower ambient temperature or increase motor cooling. 01: Motor Thermostat or Thermistor. Motor wiring error. Check motor wiring at motor feedback (MF) connector. 02: Encoder Temperature Sensor. Incorrect motor selection. Verify the proper motor has been selected. This manual is related to the following products: Login Required to View Full Answer Content Please use the 'Sign In' button above Scan this QR code to download the app now Or check it out in the app stores System Design for the Control of Electrical Noise Kinetix Rotary and Linear Motion Cable Specifications Low-profile Connector Kits Installation Low-profile Connector Kit for I/O, Safety, and Auxiliary Feedback Installation Low-profile Connector Kit for Cascading Safe Torque-off Signals Installation Integrated Motion on the EtherNet/IP Network Reference Manual