President, Motor Protection Electronics John A. Evans

Level Control Methods and **Explanations for Common Electrical Control terms** 

8



### A Quick Florida Joke!



#### ULTRASONIC TRANSDUCERS PRESSURE TRANSDUCERS BUBBLER SYSTEMS LEVEL PROBES FLOAT SWITCHES Level Sensing Options R

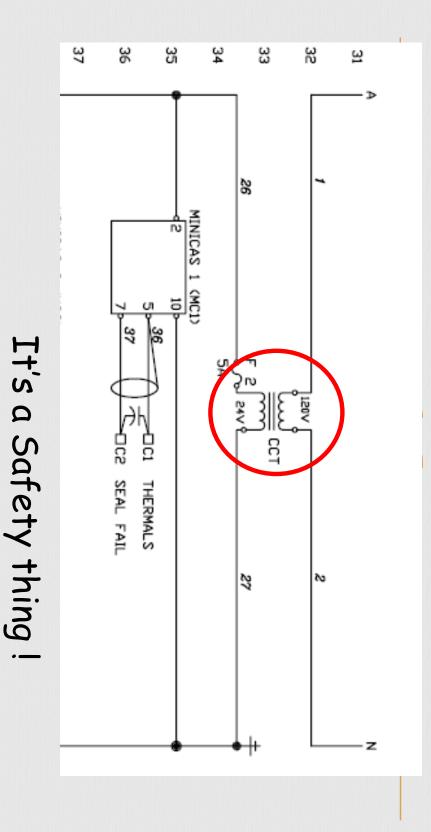
### Float Switches

R



- Simplest operation
- Normally open or Normally closed
- Reliable
- Durable

### Control Transformer



### **24V Transformer for Floats**

- Skin Resistance varies from 100k to if wet or sweaty 1M Ohms when dry, to 1k Ohm or less
- Skin resistance varies with cleanliness, dampness, grip
- A wire held by hand would see 15k to 50k Ohms dry, and 3k to 5k Ohms wet

### **24V Transformer for Floats**

- 120V / 3k Ohms = 40 mA 120V / 15k Ohms = 8 mA
- 24V / 3k Ohms = 8 mA 24V / 15k Ohms = 1.6 mA
- 24V is definitley better, but could still hurt you.

### Current vs. Reaction

- 1mA You can feel the current
- 5mA Typical GFI Operation
- 5mA to 10mA hurts
- 16mA A 175 lb. person can't let go
- 65mA Heart Fibrillation that could You be fatal if no one is there to help

#### Advantages of Float **Relay Logic**

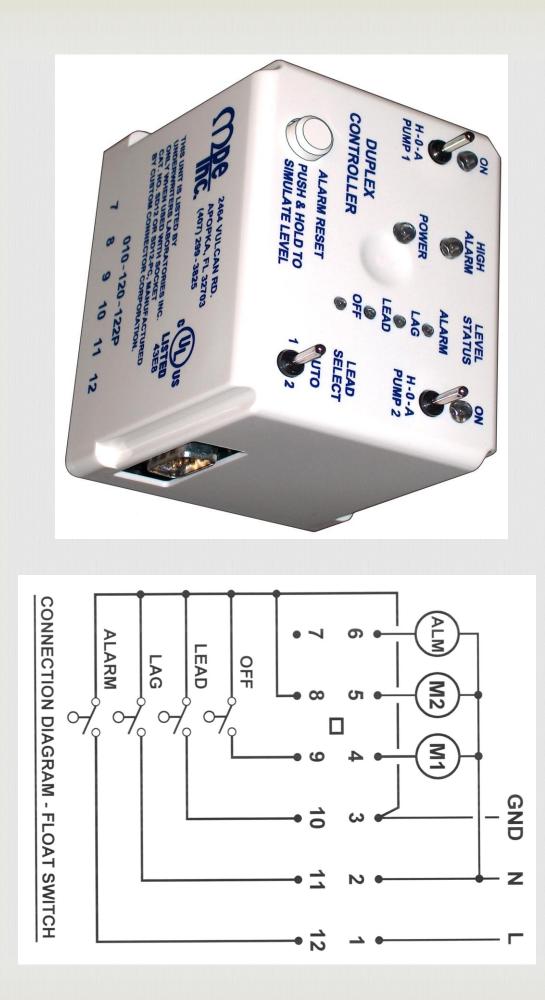
- Simple and rugged
- Allows for "shotgun approach" to troubleshooting
- Easy to implement pump delay by Relays replacing Relays with Time Delay

#### **Disadvantages of Float** Level Control

- Floats can get tangled
- Floats can become grease balls
- Disposal of Mercury floats (for areas still using them)

### Float Controllers

- "Practically a panel" without the power train
- Most panel features included
- Remove and Replace if ever needed
- Simplest way to move a (small)
- Municipality to SCADA readiness



-logt Controller

407) 299-3825 -@[ -@-POWER SIMULATE LEVEL ALARM RESET SEQUENCE ALARM ALARM INTRINSICALLY SAFE DUPLEXER STATUS •5 ● AG ● HIGH off 🔊 H-0-A PUMP 2 SELECT C 2 AUTO 0 BBTRE IVET Low O LEAD Онон Q Q 0 Q 0 마 **P**2 S C BG N ω 4 -LOW OFF LEAD HIGH LAG COMMON BARRIER GND CHASSIS GND ηЧ ηЧ μЧ ηЧ 1 œ P3 7 G Z ω S σ 4 N PUMP 2 HIGH ALARM PUMP 1 ) LOM **ALARM** - NEUTRAL -120 VAC

### -loat Controller



2

the water column Pressure exerted on the liquid level is related to the depth of

### **Bubbler Systems**

- Not too much middle ground people either love Bubblers or hate them
- Can be simple fish tank aquarium pump and pressure switches
- Can operate as a level transducer and provide a 4-20mA level signal

# **Bubbler System with 4-20mA Output**



Modular design allows

 easy access to Air
 compressor Assembly,
 Air Tank Assembly,
 Controller, and Solenoid
 Valve Assembly

This type of a Bubbler System acts as Transducer, outputting a 4-20 mA signal

### Advantages of Bubbler Systems

- Simple and cheap to do a basic Bubbler
- Not susceptible to lightning damage from the wetwell - (no metallic path controls.) from the wetwell to the panel

### **Disadvantages of Bubbler** Systems

- Not a good application in cold weather if moisture is present -(Warm air condenses on a cooler
- surface)
- Most preventative maintenance regardless of Bubbler type intensive of level measuring devices 1

### **Disadvantages of Bubbler** Systems

Typical failure modes are air leaks and air blockages

 Not a good application for use in heavy sludges

#### ON THE FLEXIBLE DIAPHRAM INCREASES INCREASES, PRESSURE AS WATER LEVEL



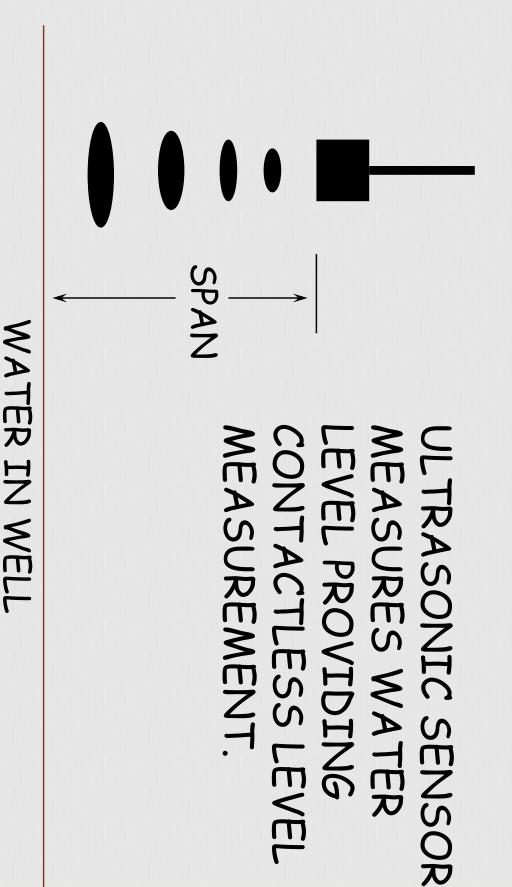
- Most units are vented to Atmosphere
- Non-vented units available as well -(accurate except during a hurricane)
- Worst case atmospheric reading by of 12.6 psi vs the standard 14.7 psi. NOAA was 25.68in-Hg - for a reading

- 14.7 psi 12.6 psi = 2.1 psi
- 2.1 psi x 2.31 ft/psi = 4.85 feet
- The level reading would be low by period of time.) 4.85 feet (for a relatively short

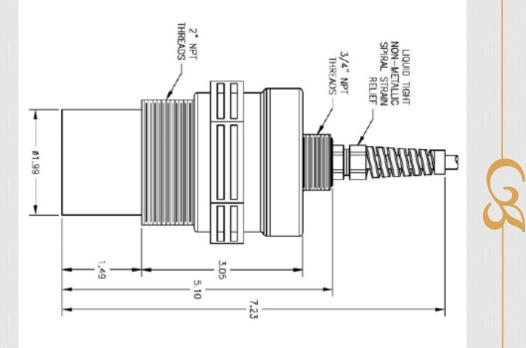
- Advantages:
- Rugged
- Easy to install
- Very Accurate

- Disadvantages
- Units vented to Atmosphere prone vent tube not properly protected) to water intrusion over time (if air
- Desiccant, Dryer, Breather Bag, checked periodically Bellows unit - these need to be

ULTRASONIC TRANSDUCERS



# Ultrasonic Transducer



# Advantages of Ultrasonic Transducers

- Non-contact Level Measurement
- Good for Measuring Level of corrosive chemicals
- Good for Measuring Level in Shallow Applications

#### **Disadvantages of Ultrasonic Transducers** Parameter setup is not intuitive Beam width becomes an issue as Does not measure well in highly Incorrect Readings in high foam and wetwell increases in depth agitated water Grease Build-up applications

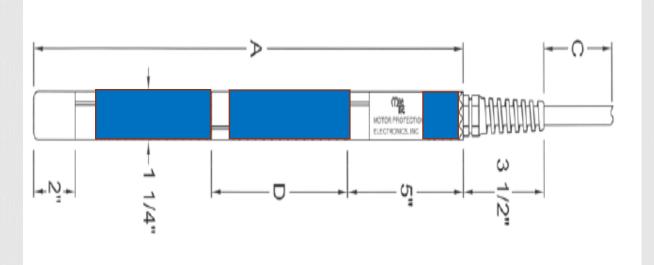
### Level Probes

each point on the Level Probe. supplies a +/- 12V waveform to **Conductance Devices - Controller** 

conducted from the Probe, through the liquid, to ground. submerged, the signal is As the Probe sensor becomes

### Level Probes

- Simple installation
- Excellent in turbulent applications
- Excellent in grease, fat, or heavy sludge
- Low maintenance



Probes available as Single Point, Three to 10. Point, and 10 Point Probes, but can be made with any number of electrodes up

Level Probes



Probes available with 5, 6, 8, 10, and 12 inch spacings between electrodes



# Advantages of Level Probes

- Once installed, should last indefinitely
- Easy to set up using Level Probe **Relays or Controllers**
- Can be used with Barrier to provide an Intrinsically Safe Solution
- Turbulent water actually helps clean probe

# Disadvantages of Level Probes

- Probes do require periodic cleaning
- For VFD applications, the 4-20mA output signal is a "stepped" output
- Not good for clean water and
- Stormwater applications ion count!

### Summary of Level Controls

- Floats
- Bubbler Systems
- Submersible Pressure Transducers
- Ultrasonic
- Conductance Level Probes
- A few others, but these are the most prevalent

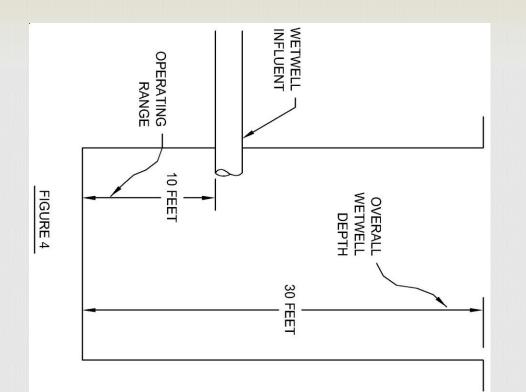
### Summary of Level Controls

- Rule of Thumb -
- While Level Measurement choice is often a matter of preference, one way to go for all applications! type of level control may not be the

#### How to Properly Size a Submersible Pressure Transducer

### Controls Topic #2

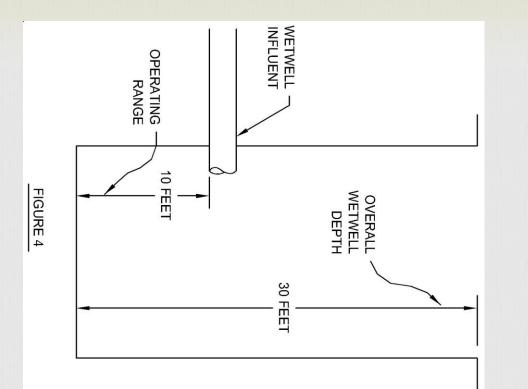
# Sizing a Submersible Transducer



 The operating range of the wetwell is the key piece of information when sizing your transducer.

 If the level exceeds the operating range, you are backfilling your lift station's influent piping.

# Sizing a Submersible Transducer

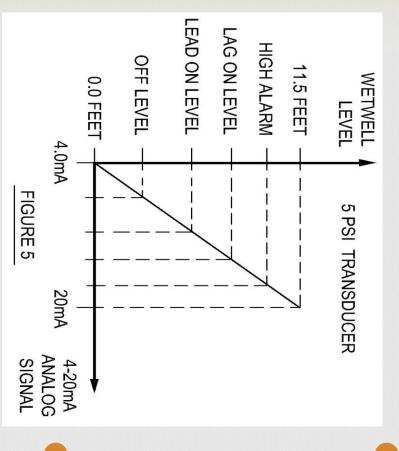


The most common 10psi, and 15psi transducers. transducers are the 5psi,

- 5psi has a range of 0-11.5 feet 10psi has a range of 0-23.1
- 15psi has a range of 0-34.6 feet

feet

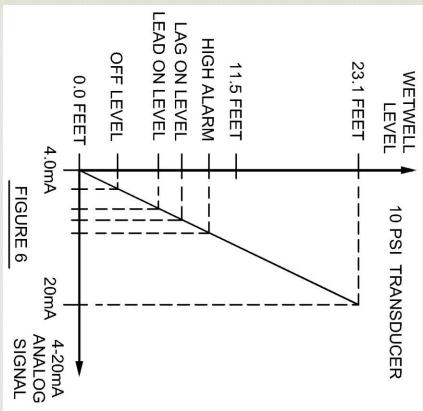




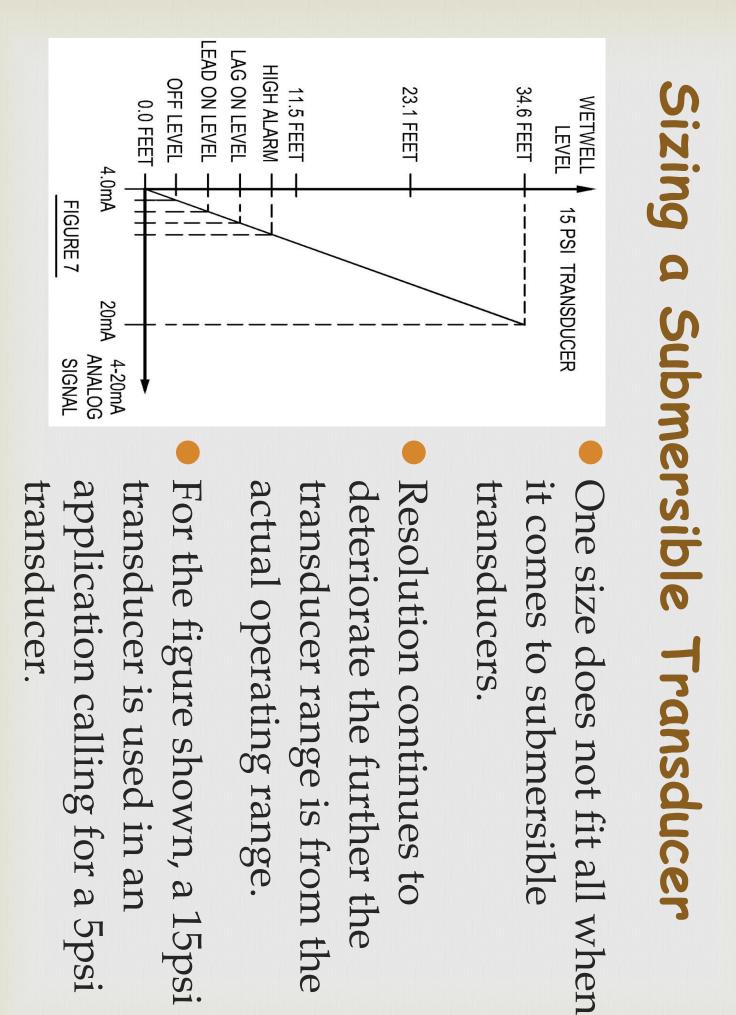
When you select the application. resolution for control of that transducer range to match wetwell, you have the best the operating range of the

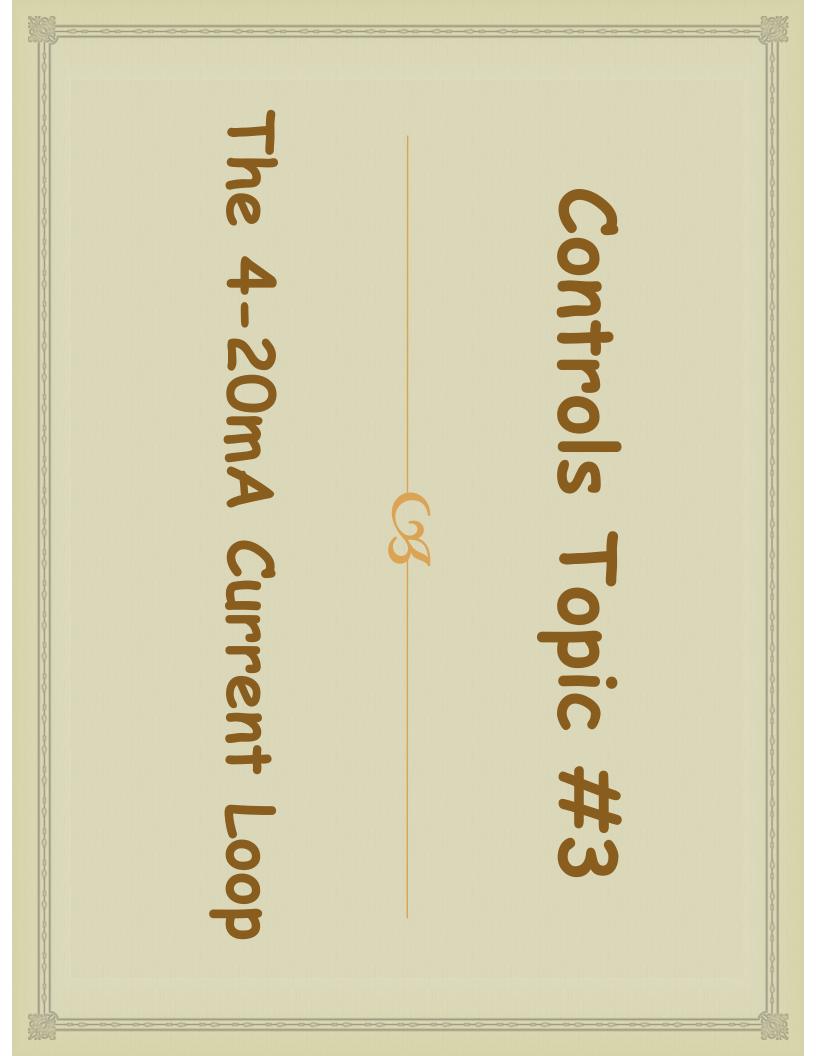
 For the figure shown, the entire 4-20mA range is available for lift station control. (Good Resolution!)  For the figure shown, a 10psi transducer is used in an application calling for a 5psi transducer.

When you select the transducer range that does not match the operating range of the wetwell, you begin to lose resolution for control of the application.



Sizing a Submersible Transducer





- Used to transmit analog data temperature, etc. variables such as level, pressure, flow, representing various process
- Although conceptually simple, the 4troubleshoot. 20mA loop can be tricky to
- calls. Represents a fair % of MPE technical

- If you have a control system with a following: 4-20mA level signal, you need the
- A good meter that reads 4-20mA 200
- A loop calibrator, or adjustable transmitter

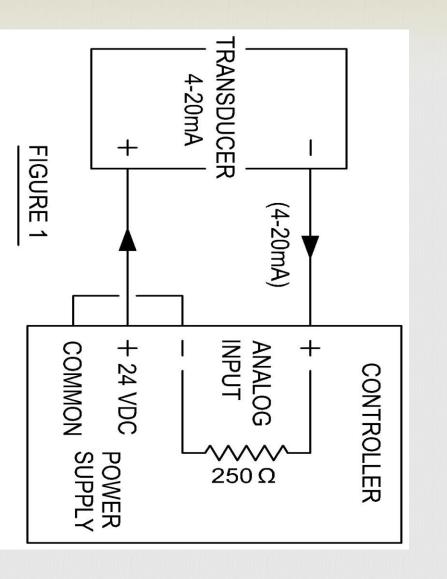
# Loop Calibrator / Adjustable Transmitter



Simulates a 4-20mA signal from field devices while testing control equipment

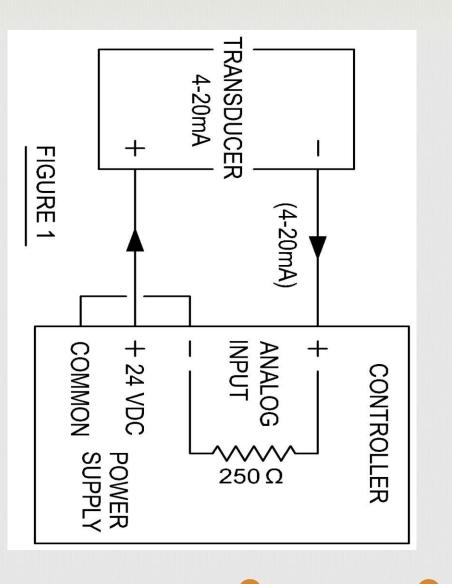
Used to calibrate
 equipment having a 4 20mA analog input

 Should be part of everyone's tool box



- This is a series connected loop, and current flow is in the same direction throughout the loop.
- Controller shown has an internal power supply
- 250Ω represents the Controller input resistance

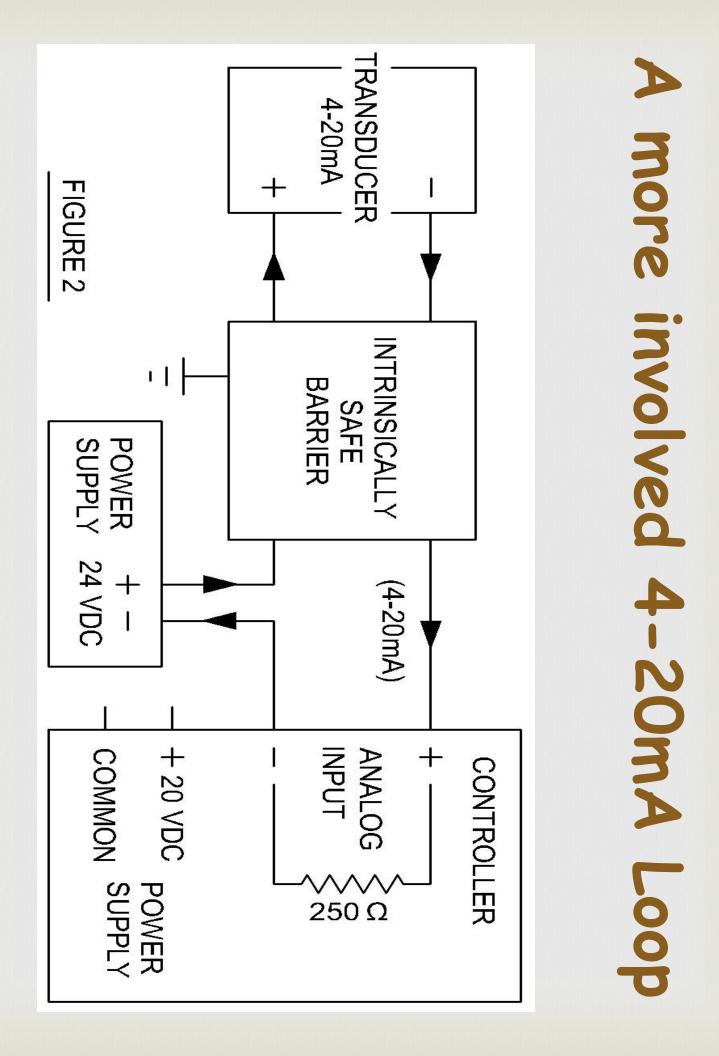




 Rule of thumb for connection within the loop:

Start with connecting the positive lead of the power supply to the positive lead of the transducer.

- There are two types of instruments used in a current loop:
- Loop powered instruments are placed within the loop. powered by the DC power supply
- Non-loop powered devices require a instrument to be used in the loop. separate voltage source for the



- Care must be taken to ensure that the 20mA to flow in the loop. the loop DC Voltage allows for a full impedance of the loop instruments, and
- A quick check to ensure your loop will operate properly is to add the voltage Voltage supply powering the loop. drop across each device in the loop, and make sure this does not exceed the DC

- Why is the 4-20mA current loop preferred over voltage control?
- DC voltage control circuits are affected by noise - it adds to the DC voltage and causes error.
- Convenience of looping items together

- Why is the 4-20mA current loop preferred over voltage control?
- Each loop impedance drops a certain amount of the loop voltage, but the impedance of the transducer changes current remains constant. (Only the to vary the loop current.)
  - oltage control?

- Two of the most common problems encountered when designing a 4-20mA loop are:
- Enough voltage
- Too much voltage

- Two of the most common obstacles encountered when working with a 4-20mA loop are:
- Polarity
- Unintentional grounding

#### Isolated vs. Non-Isolated This gets a little tricky! Analog Level Inputs

### Controls Topic #4

2

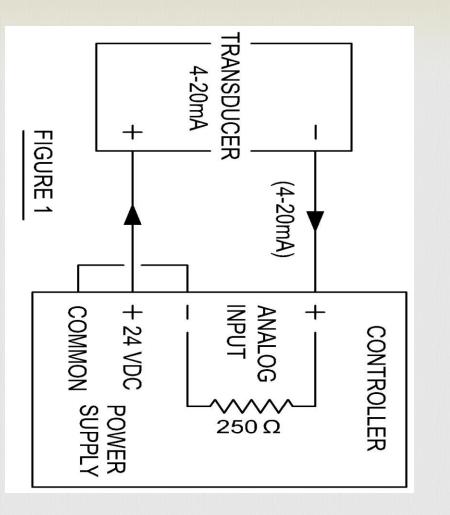
# **Isolated vs Non-Isolated Analog Level Inputs**

which is typically connected to connected to the Controller's controller's analog level input has control panel ground. (Quite a mouthful!) internal power supply common, Analog Input (-) common is to do with whether or not the Isolation with regard to a

# **Isolated vs Non-Isolated Analog Level Inputs**

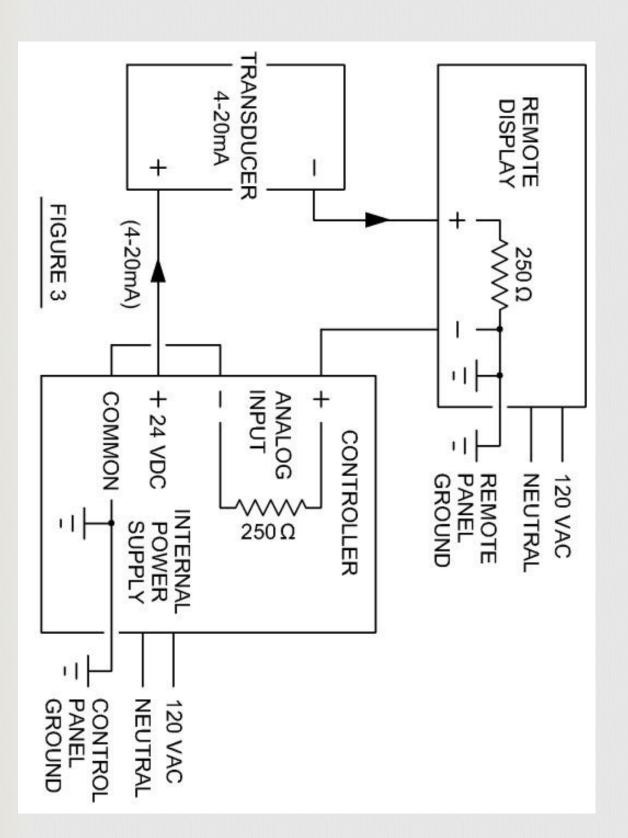
- An isolated Analog Level Input (-) ground. common will be free from any connection to control panel
- It will also be free from any other analog loop. connection to the common ot any

# **Isolated vs Non-Isolated Analog Level Inputs**



 For the majority of analog level input applications, isolation for the level input is not required.

 Here the loop powered transducer has no ground connection, so no isolation is required.



## **Isolated vs Non-Isolated Analog Inputs**

### Controls Topic #5

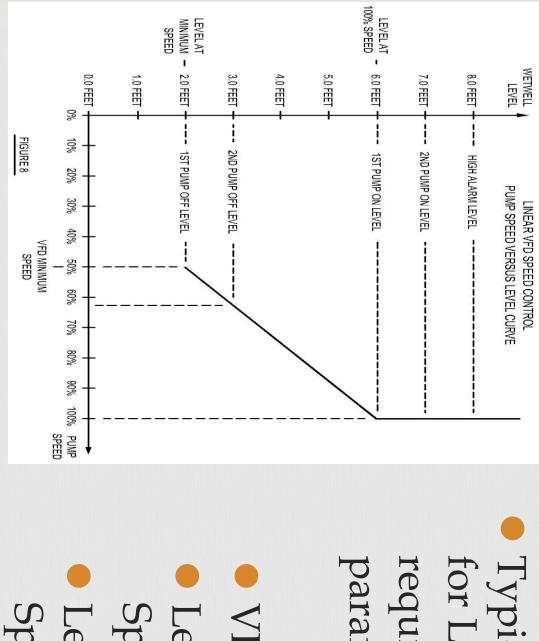
- There are two types of Level Control:
- Linear Level Control, also known as Proportional Control
- PID (Proportional-Integral-Derivative)

- Linear Level Control is used variable speed applications. for both constant speed and
- PID Control is used only in
- variable speed applications.

- For most lift station control and desirable for simplicity. applications, proportional control (Linear Level Control) is sufficient,
- A typical Linear Level Control point, lead pump-on point, lag pump-on point, and the high level point. application would include an pump-off

- For Linear Level Control, the the pumps is proportional. the wetwell, and the control of relationship between the level in
- In other words, if the level calls reached. to run until the off point is for a pump to run, a pump is called

- Advantages to Linear Level Control:
- Simplicity in setup
- Lower equipment cost
- No "sludge ring" in the wetwell, as the level does not stay in one place tor any length of time.



 Typical VFD setup for Level Control requires three parameters Linear Level Control vs. PID Control

VFD Min Speed
Level at Min Speed
Level at 100% Speed

When a VFD Linear Level Control adjustments to the pump speed as application is set up correctly, the speed, and continually make into the lift station. needed to keep up with the flow between minimum speed and 100% more pumps at some speed control system will run one or

- PID Control is also known as setpoint control.
- PID Control is used to maintain a or pressure. such as level, flow, temperature, setpoint for a process variable

As the process variable begins to move away from the setpoint, the difference, between the setpoint and makes a change to the speed reference Proportional part of the PID Control that is proportional to the error, or the process variable being controlled.

setpoint. speed reference is being The Integral part of the PID changed to move the process variable back to the desired loop determines how fast the

The Derivative part of the "overshoot" effect of the signal to reduce the change of the speed reference PID loop slows the rate of control. Integral part of the PID

- PID Control requires that the adjusted for the best performance of the control system. control system be "tuned", or
- PID Control is only necessary where for the application. tight (accurate) control is required

- PID examples:
- Controlling flow into a treatment plant
- A booster system for pressure maintaining building water

#### VFD's vs. Single Phase Modules (For Single Phase to Three Phase Conversion)

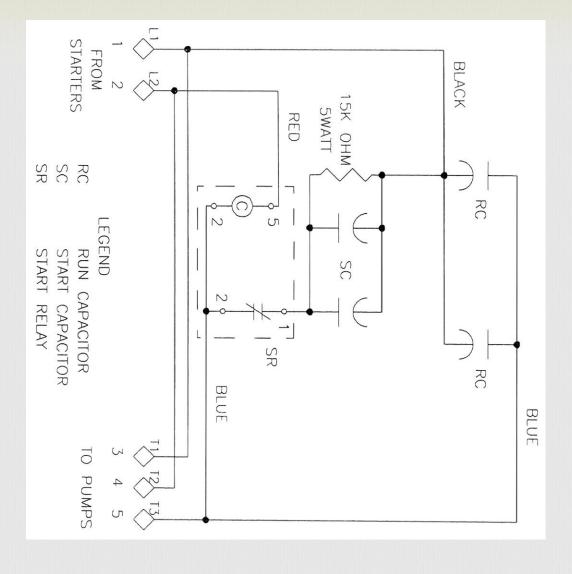
## Controls Topic #6

2

# VFD's vs Single Phase Modules

phase conversion as much as in Capacitors. function of Start and Run the past, but the concept here using Single Phase Modules for We don't see the application is good for explaining the





L1 connected to T1

L2 connected to T2

 L1 also goes through Start Cap SC, and Slave Relay SR, to get to T3

After SR opens, the current flow for T3 comes through the Run Cap, RC

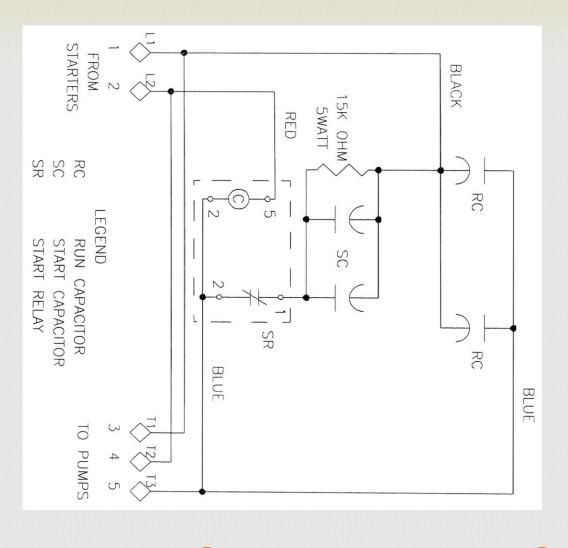
## VFD's vs. Single Phase Modules

- How do you tell the Start Cap from the Run Cap?
- Cap. Start Cap has greater Capacitance value than Run
- $X_c = 1/[2(TT)(f)(c)]$
- A larger value of "C" gives a lower value of Impedance, X<sub>c</sub>

#### **Bonus Thought**

- Line Reactors are Inductive
- The Impedance, X<sub>L</sub>, increases as the frequency increases.
- $X_{L} = 2(\Pi)(f)(L)$
- Harmonics, which are multiples of the Base frequency 60Hz, are effectively blocked by the increase in Impedance, X<sub>L</sub>.





 The Start Caps, SC, have a lower
 impedance so current flows through this path first, giving the motor a "Starting boost"

 Once the motor is running, current flow is changed through the Run Caps, RC

## VFD's vs. Single Phase Modules

- For many years now, there has conversion from single-phase to the Single Phase Modules to using been a movement away from using three-phase voltage. Variable Frequency Drives for
- Why is this?

## VFD's vs. Single Phase Modules

- Problems with SPM's:
- 3-Phase voltage not balanced
- Low starting torque
- Nuisance tripping if start relay goes bad
- Start and Run caps need to
- builder's UL file/procedure be described in the panel

# VFD's vs Single Phase Modules

- VFD's can be used as a "Phase Converter" by de-rating for Single Phase application
- Output is balanced, true Three-Phase
- 100% Torque available
- Proven technology



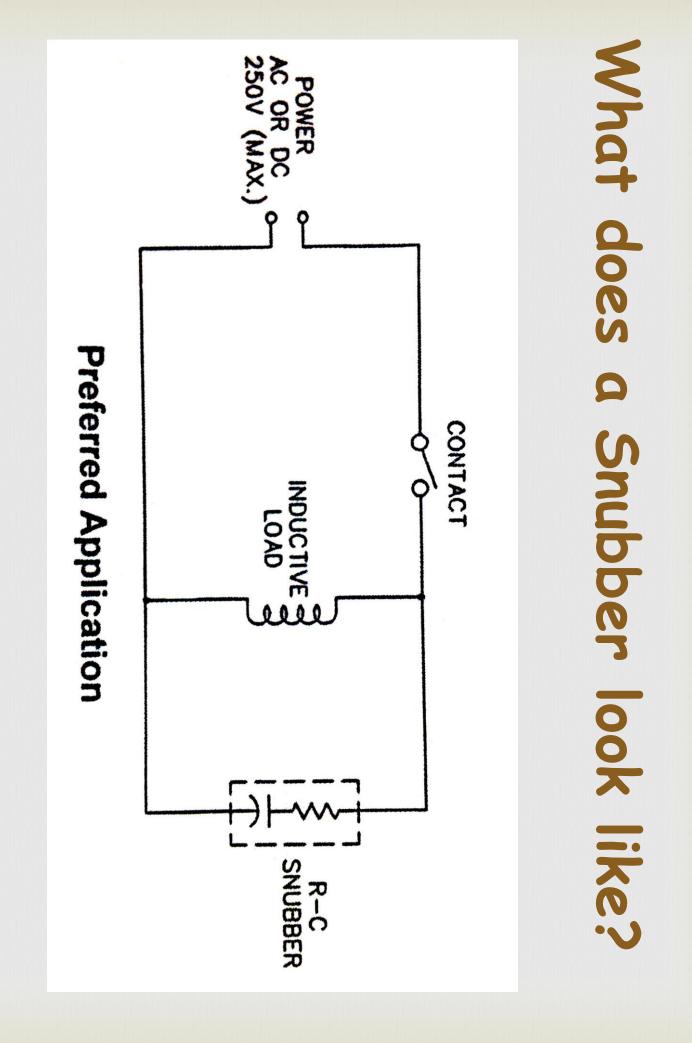
#### What is a Snubber, and how does it work?

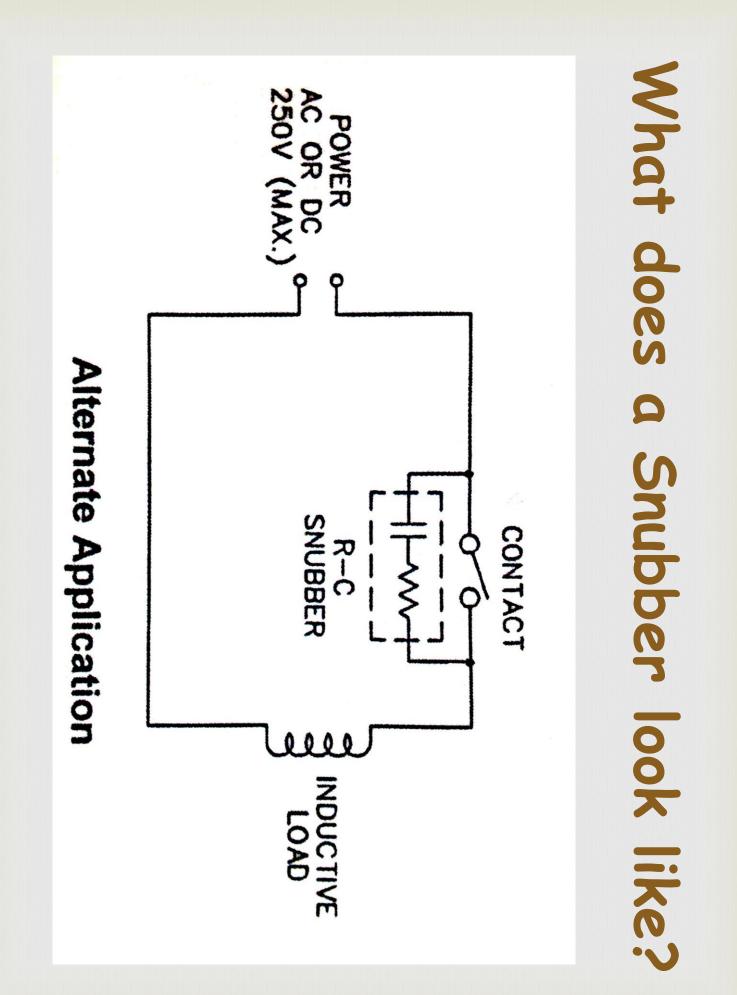
## Controls Topic #7

R

#### voltage transient. Capacitor, placed across an connected Resistor and inductive load, to reduce a A Snubber is a series

What is a Snubber?





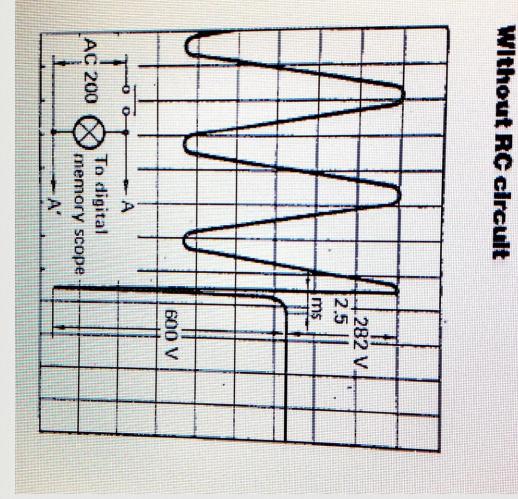
### **Transient Explanation**

- When the voltage to the coil of a collapses. develop across the coil as the field quickly, a large voltage spike can motor starter or a relay is removed
- duration, but may be quite high in voltage. The voltage spike is of very short

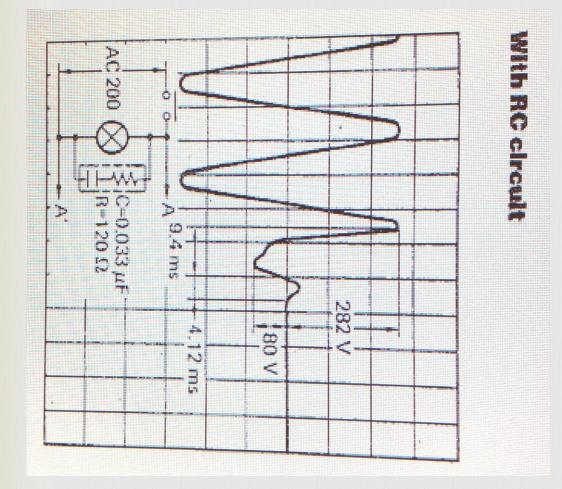
### Transient Explanation

- The formula for this phenomena is: V = L di/dt, where:
- V = Transient Voltage developed across the coil
- L = Inductance of the coil
- di/dt = Change in current with respect to time

#### with no Snubber across the coil What the transient looks like



#### with a Snubber across the coil What the transient looks like



## Snubber Explanation

- A Snubber, consisting of a resistor and of the rise time of the transient. capacitor in series, changes the slope
- that absorbs the very fast rise time, The resistor and capacitor form a filter and shifts the slope of the transient so that it becomes a non-issue.

# Selecting a Snubber

- Values for R and C are chosen so that they equal or come close to the rise time of the transient.
- (R \* C) = time constant
- Set time constant equal to rise oscilloscope. time measurement from

# Selecting a Snubber

- A resistor value of 100 Ohms is fairly the value of the capacitor. common, which leaves us to solve for
- In 120VAC circuits, a rise time of 10uS is fairly common.
- You don't have to be exact if you're result of removing the transient. close, you will achieve the desired

#### Rule of Thumb

- It would be good design practice to put a Snubber across the coils of size three and size four motor starters.
- Several companies offer a multitude of wiring duct work. to be tucked away in your control panel Snubbers which have leads long enough

#### Question Time!

# Thanks for listening to me!