





Easy to use, low power servo solutions





Servo solutions for continuous and pulse duty applications

Control Techniques' servo solutions provide ultimate performance and flexibility for machinery manufacturers with a wide range of servo drives and motors.

Digitax SF

The Digitax SF servo drive and motor package complements the Control Techniques servo portfolio with a compact, cost effective and easy to use solution for a range of application requirements. Digitax SF offers:

- High performance drives with pulse or analogue interface and serial communication
- A range of light-duty industrial motors available in several inertia levels to meet different application requirements

Digitax HD

The Digitax HD range brings ultimate performance to high dynamic, pulse duty applications, where high peak torque is required for fast acceleration.





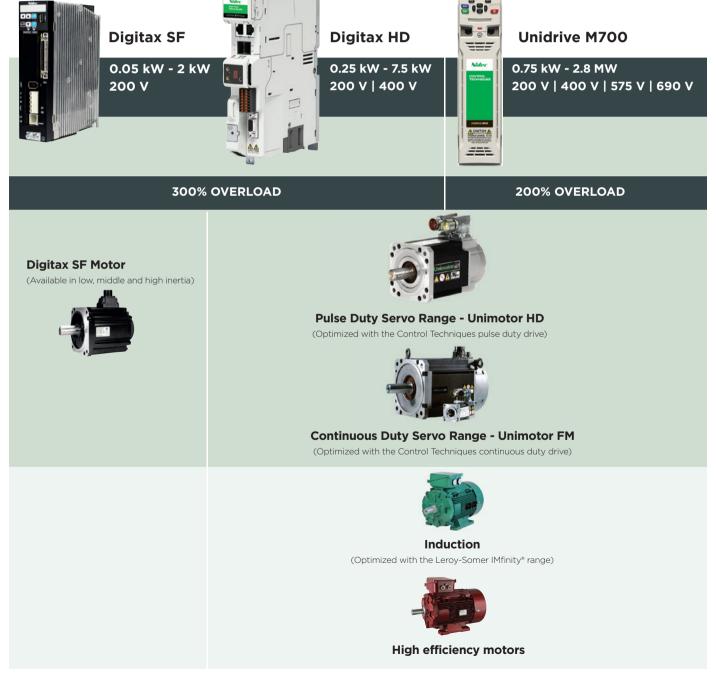
Unidrive M700

Unidrive M700, with high performance and an extensive power range, is the ideal option for continuous duty applications, where precise, continuous torque delivery is required.

Unimotor

Unimotor is a comprehensive family of high performance AC brushless servo motors. With a wide torque and speed range, and a broad selection of feedback options, Unimotor offers the perfect match for Digitax HD and Unidrive M700 to meet any application requirement.

Drive and Motor Compatibility



Digitax SF

Digitax SF responds to the needs of customers requiring low powered precision servo solutions, with a dedicated servo range from 50W to 2 kW.

With 17-bit resolution, robust magnetic encoder technology and pulse or analog control interface, Digitax SF offers a cost-effective servo solution, without compromising on performance.



Versatile analog or pulse interface, offering easy integration with any plc or motion controller

Digitax SF can also operate standalone using the on-board 16-point positioning table

Built-in keypad with 6 digit 7-segment status display for easy startup, parameter setting, and tuning

PC-USB interface for parameter settings, tuning, and status display in the dedicated software Digitax SF Connect

Magnetic encoder technology

- robust in harsh environments
- ultra-low energy consumption for reduced maintenance
- Standardised flange sizes
- IP 65 or 67 motors

Multiple motor inertia levels available, covering a wide range of applications, from semiconductor manufacturing to textile, packaging machines, robotics, extruders, metering and other applications requiring speed, precision and accuracy.

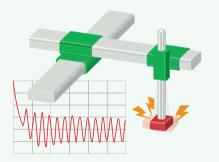
Digitax SF Connect

Digitax SF Connect is a user-friendly PC tool with a familiar Windows interface and intuitive graphical tools for easy parameter setting, tuning and diagnostics. Ease of machine start-up is further facilitated through a positioning table and test run features.

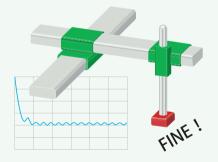




Straightforward to setup and tune, Digitax SF offers high servo performance at the click of a button. For demanding applications, a rich selection of filters to dampen mechanical resonances and suppress tip vibration can be easily configured within Digitax SF Connect with the aid of FFT frequency analysis



No damping filter used



Damping filter used



Drive Set-Up

Quickly find everything you need for quick and easy installation of your drives.

Visit: www.drive-setup.com





Diagnostics tool

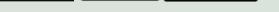
Quickly solve any error codes that the drive may show.

You can download our
Diagnostics Tool app at:
www.controltechniques.com/mobile-applications

Microsoft





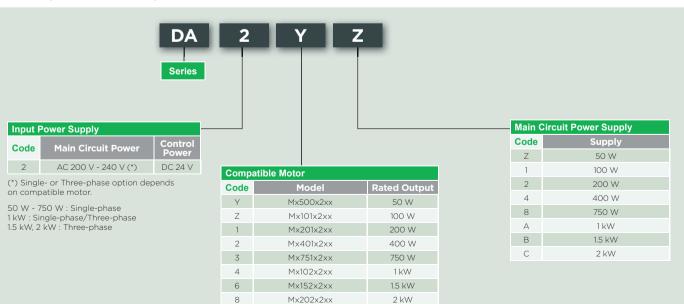


Motor and drive combinations

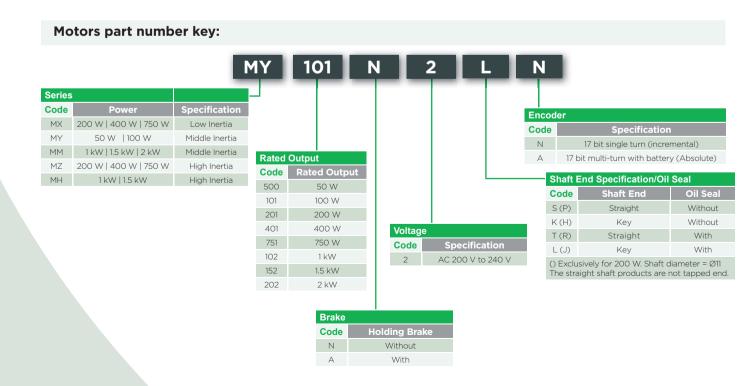
			MOTOR INERTIA LEVEL
	_	Low Inertia	Middle Inertia
MOTOR FLANGE SIZES	40 mm		50 W 100 W 3000 rpm rated 6000 rpm maximum IP65
	60 mm	200 W 400 W 3000 rpm rated 6000 rpm maximum IP65	
MOTOR FL/	80 mm	750 W 3000 rpm rated 6000 rpm maximum IP65	
	130 mm		1 kW 1.5 kW 2 kW 2000 rpm rated 3000 rpm maximum IP67

Digitax SF ordering information

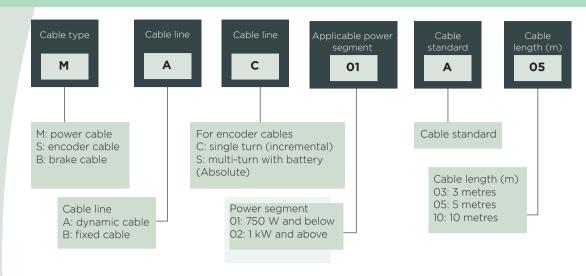
Drives part number key:



High Inertia	Drive Compatibility
	50 W 100 W
200 W 400 W 3000 rpm rated 6000 rpm maximum IP65	200 W 400 W
750 W 3000 rpm rated 6000 rpm maximum IP65	750 W
1 kW 1.5 kW 2000 rpm rated 3000 rpm maximum IP67	1 kW 2 kW



Motor cables part number key:



Accessories	Accessories						
Order code	Phases	Accessory	Description				
2490-2754	1						
2490-0004	3	Surge absorber/ protector	Quick response protection against power supply surges from mains supply to the Digitax SF drive.				
4200-0056	1		EMC noise filters prevent ingress of external noise from the power supply line. To ensure compliance with EMC, use the recommended EMC noise filter				
4200-3106	3	EMC Filter	Rated Voltage (V): 250 Vac Rated Current (A): Single phase: 5 A Three Phase: 10 A				
2216-0211	All	Input / Output (I/O) terminal block and cable assembly	Digitax SF drives are equipped with a 50 pin high-density I/O port. For ease of wiring, a pre-assembled cable and DIN rail mountable terminal block with screw-terminals is available to easily connect the drive I/O.				

Drive E	Basic Specificat	ions							
Item		Specification							
Di	rive model	DA2YZ	DA2Z1	DA212	DA224	DA238	DA24A	DA26B	DA28C
Арр	licable motor	M□500	M□101	M□201	M□401	M□751	M□102	M□152	MM202
D	imensions			(Refer	to dimens	ion chart c	n pages 12-13)		
Drive	e weight (kg)		-).7		0.8	1.0	1.	-
	Main circuit power			se AC 200) % 50/60) V - 240 V) Hz		Three-phase A ±10 %	C 200 V - 50/60 Hz	240 V
	Control power supply				DC	24 V ±10 9			
Input power	Input current	0.8	1.3	2.4	3.6	7.2	Single-phase: 9.7 Three-phase: 5.1	6.1	9.0
	Control power Current		170		210	260	3	350	
	consumption (mA Typ.)	(Inrush current is approx. 1.4 A)							
Co	ontrol type	Three-phase PWM inverter sine-wave driven							
Output	Rated current (A)	0.7	1.0	1.7	2.7	4.3	5.6	9.9	12.2
specifica- tion	Output frequency (Hz)		0 - 500				0 - 250		
Enco	der feedback	17 bit single turn (incremental) (The product can function as a multi-turn absolute type when batteries are added.)							
Control	Input		8-point (24 VDC system, opto-coupler input insulation) inputs whose functions are switched by the control mode						e
signal	Output	8-point (24 VDC system, open-collector output insulation) outputs whose functions are switched by the control mode							
Analogue signal	Input	Single end	led (±10 V) input who	ose function	ns can be s	switched by the co	ntrol mode	!
Pulse	Input	RS-422 di Open-coll							
signal	Output			ulse (A-/B- gh open-co		RS-422 di	fferential output		
Commu	Communication function		USB: connection to PC with Digitax SF Connect installed RS-485: host remote control communication (multi-drop compatible)						
Drive status display function		Normal/E	rror display	y on STATL	JS LED		ent display on Setu Power ON Error, D		ower OFF
Regene	eration function	A braking	resistor m	ay be insta	lled extern	ally			
Coi	ntrol modes	Position c	ontrol, velo	ocity contro	ol, torque c	ontrol			

Drive Env	Drive Environment Specifications						
	Item	Specification					
Ambient	For use	0 - 50 °C					
temperature	For storage	-20 - 65 °C					
Ambient	For use	20 - 85 % RH or less (without condensation)					
humidity	For storage	20 - 65 % RH of less (without condensation)					
Atmosphe	ere for operation and storage	Indoor (no direct sunlight), free from corrosive gas, flammable gas, oil mist, dust, combustibles, abrasives					
	Altitude	≤1000 m					
Vibration		≤ 5.8 m/s² (0.6 G) 10 to 60 Hz (no continuous operation allowed at resonant frequency)					
Dial	ectric strength	AC 1,500 V for one minute across the primary and Ground/Earth FG					
Electric shock protection		Class I (mandatory grounding)					
Overvoltage category							
Installa	ation environment	Pollution degree 2					

Drive f	unction s	pecific	ations		
	If	tem		Specification	
		Co	ontrol input	Servo ON, alarm reset, command input inhibit, emergency stop, position error counter clear, 2-stage torque limit inhibit, ABS data demand, homing start	
	Pulse	Со	ntrol output	Alarm status, servo status, servo ready, under torque limit, brake release, positioning complete, motion complete, alarm, emergency stop brake release, ABS data transmitting, homing complete	
	input command		num command se frequency	RS-422 differential: 4 Mpps Open-collector: 200 kpps	
Position		Input p	ulse signal form	Pulse + direction, A-/B-phase quadrature encoder pulse, CW + CCW pulse	
control			and pulse-paired requency	Ratio A/B 1/1,000 < A/B < 1,000 Setting range A: 1 - 65,535 B: 1 - 65,535	
mode	Internal	Сс	ontrol input	Servo ON, alarm reset, position error counter clear, motion start point selection 16, home position sensor input, homing	
	position command	Со	ntrol output	Alarm status, servo status, servo ready, under torque limit, brake release, homing completion, motion complete	
		Оре	eration mode	Point table, communication operation	
	S	moothir	g filter	FIR filter	
	D	amping	control	Enabled	
	Analogue command	Control input		Servo ON, alarm reset, command input inhibit (zero torque command), 2-stage torque limit, CCW/CW run inhibit	
				Alarm status, servo status, servo ready, under torque limit, brake release	
Velocity control		Speed	command input	Input voltage -10V to +10V (maximum speed is reached at ±10 V)	
mode	Internal speed	Co	ontrol input	Servo ON, alarm reset, start 1 (CCW), start 2 (CW), 8-speed setting, 2-stage torque limit	
	command	mmand Control output		Alarm status, servo status, servo ready, under torque limit, brake release	
	S	moothir	g filter	IIR filter, FIR filter	
Т	Analogue -			Servo ON, alarm reset, command input inhibit (zero torque command), 2-stage torque limit, CCW/CW run inhibit	
Torque control	command	Со	ntrol output	Alarm status, servo status, servo ready, under torque limit, brake release	
mode		Torque	command input	Input voltage -10 V to +10 V (maximum torque is reached at ±10 V)	
	S	moothir	g filter	IIR filter	
	S	peed ob	server	Available	
		Auto-tu	ıning	Available	
	Encoder output division/ multiplication			Available	
Common features	Tunir	ng / func	tion setup	Available through the Digitax SF setup software "Digitax SF Connect" Tuning with the setup panel on the drive front side	
	Protect		By hardware	Overvoltage, low voltage, overcurrent, abnormal temperature, overload, encoder error	
	functio	ons	By software	Overspeed, position error too high, parameter errors	
	Alarm log		log	Can be viewed with the setup software Digitax SF Connect	

Safety Standards



5	Specification	Motor	Drive
	Low Voltage Directives (*1)	EN60034-1 EN60034-5	EN61800-5-1
EU/EC Directives	EMC Directives (*2)	EN61000-6-2 EN55011 Class A, Group1	
	Machinery Directives	Not Ap	plicable
UL Standards (*1)		1004-1 1004-6	508C
South Korea Radio Law (KC)		Not applicable KN11 KN61000-6-2	
China Compulsory	Product Certification System (CCC)	Not Ap	plicable

^{*1)} Install the product in the environment that meets the following requirements: • Overvoltage Category II • Class I • Pollution Degree 2 (Circuitry)
*2) Refer to the Digitax SF Instruction Manual for further guidance

Motor General Specification	ons
Item	Specification
Ambient temperature for operation	0 - 40 °C
Ambient humidity for operation	20 - 85 % RH (no condensation)
Ambient temperature for storage	-20 - 65 °C (no condensation) Maximum temperature 80 °C, 72 hours
Ambient humidity for storage	20 - 85 % RH (no condensation)
Atmosphere for operation/storage	Indoor (no direct sunlight), free from corrosive gas, flammable gas, oil mist, dust, combustibles, abrasives
Insulation resistance	≥ 5 M Ω at 1,000 VDC
Dialectric strength	AC 1500 V for one minute across the primary and Ground/Earth FG
Operating altitude	≤1000 m
Vibration class	V15 (JEC 2121)
Vibration resistance	49 m/s² (5 G)
Impact resistance	98 m/s² (10 G)
Protective structure	IP65: 50 W - 750 W IP67: 1 kW - 2 kW
Electric shock protection	Class I (mandatory grounding)
Overvoltage category	II .
Installation environment	Pollution degree 2

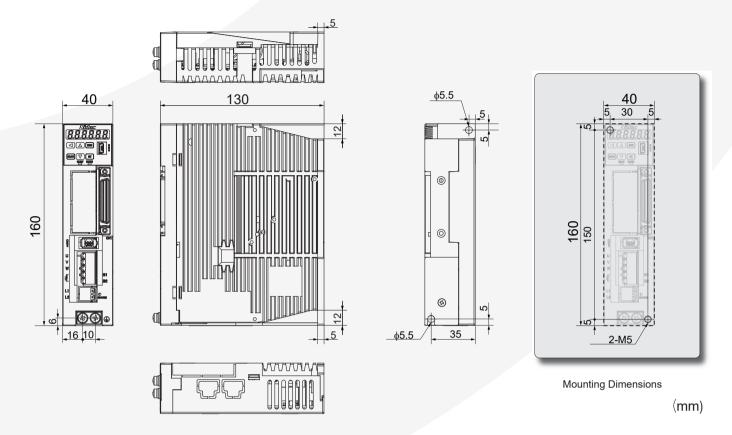
Encoder Basic Specifications							
	Item		Specification				
Motor model			M000020N	M000020A			
	Resolution		Incremental 17 bit	Absolute 17 bit			
Environmental	Ambient ope	rating temperature	0 - 8	35 °C			
requirements	External disturbance magnetic field		±2 mT (20	G) or below			
	Power supply	Voltage	DC 4.5 - 5.5 V (power supply ripple ≤ 5 %)				
		Current consumption	160 mA typ. (not including inrush current)				
	External battery	Voltage		DC 2.4 - 4.2 V			
Electrical		Current consumption	-	10 μA typ. (*1)			
specifications	Multi-turn count		-	65,536 counts			
	Maximum revolving speed		6,000 rpm				
	Count-up direction		CCW (*2)				
	Output/input type		Differential				
Communication	Transmi	ssion method	Half-duplex asynchronous serial communication				
specifications	Commur	nication speed	2.5 Mbps				

 $^{^{*1}}$) Measurement conditions: room temperature, motor not in motion, battery voltage of 3.6 V.

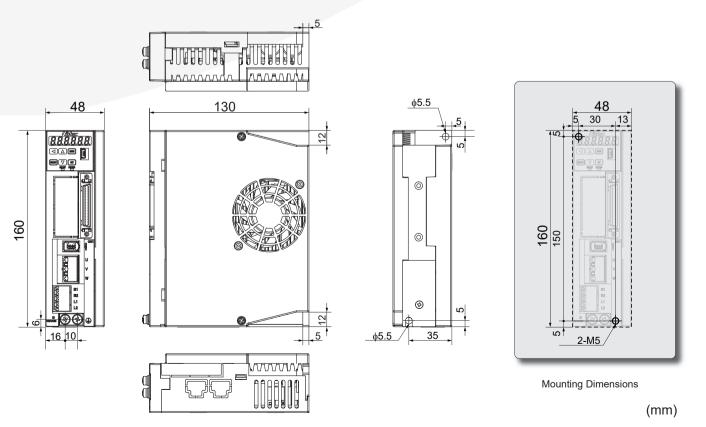
 $^{^{*}}$ 2) CCW when viewed from the load side shaft end.

Dimensions

50 W to 400 W (DA2YZ | DA2Z1 | DA212 | DA224)

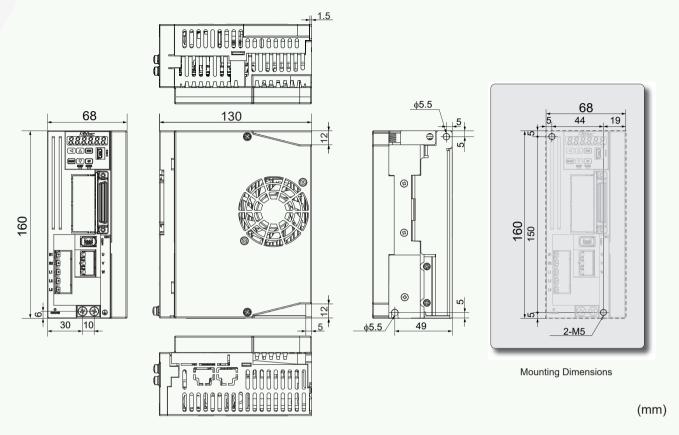


750 W (DA238)

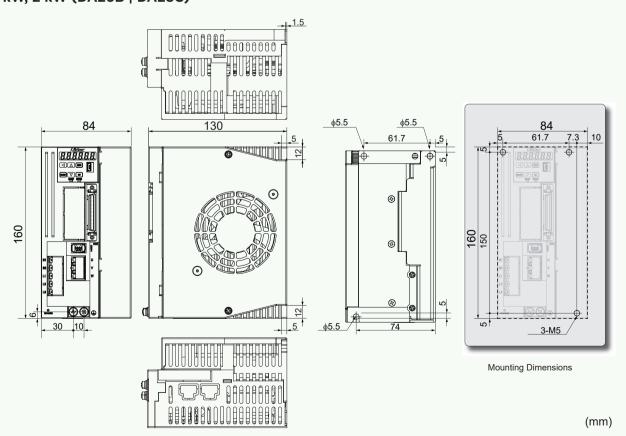


Dimensions

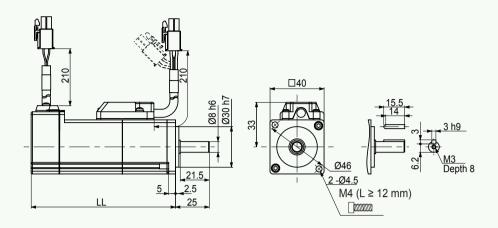
1 kW (DA24A)



1.5 kW, 2 kW (DA26B | DA28C)



Dimensions



The straight shaft products are not tapped end.

Motor Specifications

Motor Specifications	Unit	MY500 🗆 2 🗆 🗆	MY101□2□□
Voltage	V	AC200V-240V	AC200V-240V
Rated output power	kW	0.05	0.1
Rated torque	Nm	0.16	0.32
Instantaneous max. torque	Nm	0.56	1.12
Rotor inertia (with brake)	kg·cm²	0.039	0.061
Rotor inertia (without brake)	kg·cm²	0.047	0.069
Mechanical time constant (without brake)	ms	1.92	1.17
Mechanical time constant (with brake)	ms	2.31	1.32
Electrical time constant	ms	0.74	0.89
Rated speed	rpm	3000	3000
Maximum revolving speed	rpm	6000	6000
Torque constant	Nm/A	0.25	0.35
Induced voltage constant per phase	mV/(rpm)	8.8	12.3
Mass (with brake)	kg	0.4	0.5
Mass (without brake)	kg	0.6	0.8
Permissible radial load	N	68	68
Permissible axial load	N	58	58

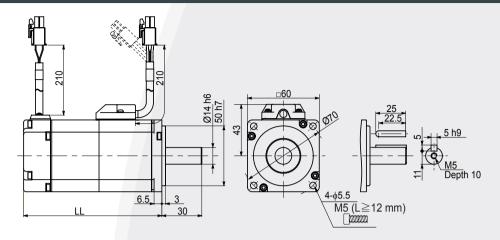
Brake specification

Rated voltage	V	DC24V ±10 %	DC24V ±10 %
Rated current	А	0.25	0.25
Static friction torque	Nm	>0.16	>0.32
Suction time	ms	<35	<35
Release time	ms	<20	<20
Release voltage	V	> DC1V	> DC1V

Motor size LL (mm)

Brake	With	nout	With		
Oil seal	Without	With	Without	With	
MY5000200	66.4	72.0	106.8	112.4	
MY1010200	82.4	88.0	122.8	128.4	

Dimensions



The straight shaft products are not tapped end.

Motor Specifications

Motor Specifications	Unit	MX2010200	MZ2010200	MX4010200	MZ4010200
Voltage	V	AC200V-240V	AC200V-240V	AC200V-240V	AC200V-240V
Rated output power	kW	0.2	0.2	0.4	0.4
Rated torque	Nm	0.64	0.64	1.27	1.27
Instantaneous max. torque	Nm	1.91	1.91	3.82	3.82
Rotor inertia (with brake)	kg·cm²	0.14	0.44	0.23	0.71
Rotor inertia (without brake)	kg·cm²	0.17	0.47	0.26	0.73
Mechanical time constant (without brake)	ms	0.72	2.23	0.47	1.42
Mechanical time constant (with brake)	ms	0.87	2.38	0.53	1.47
Electrical time constant	ms	2.53	2.53	2.92	2.92
Rated speed	rpm	3000	3000	3000	3000
Maximum revolving speed	rpm	6000	6000	6000	6000
Torque constant	Nm/A	0.41	0.41	0.49	0.49
Induced voltage constant per phase	mV/(rpm)	14.3	14.3	17.1	17.1
Mass (with brake)	kg	0.8	1.0	1.3	1.5
Mass (without brake)	kg	1.3	1.5	1.8	2.0
Permissible radial load	N	245	245	245	245
Permissible axial load	N	98	98	98	98

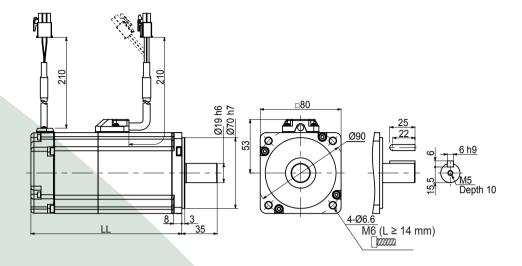
Brake specification

Rated voltage	V	DC24V ±10 %
Rated current	А	0.3
Static friction torque	Nm	>1.27
Suction time	ms	<50
Release time	ms	<15
Release voltage	V	> DC1V

Motor size II (mm)

Brake	Without	With
MX2010200	76.5	113.0
MZ2010200	93.5	130.0
MX4010200	93.5	130.0
MZ4010200	110.5	147.0

Dimensions



The straight shaft products are not tapped end.

Motor Specifications

Motor Specifications	Unit	MX7510200	MZ751□2□□
Voltage	V	AC200V-240V	AC200V-240V
Rated output power	kW	0.75	0.75
Rated torque	Nm	2.39	2.39
Instantaneous max. torque	Nm	7.1	7.1
Rotor inertia (with brake)	kg·cm²	0.74	1.61
Rotor inertia (without brake)	kg·cm²	0.94	1.81
Mechanical time constant (without brake)	ms	0.40	0.86
Mechanical time constant (with brake)	ms	0.50	0.96
Electrical time constant	ms	4.60	4.60
Rated speed	rpm	3000	3000
Maximum revolving speed	rpm	6000	6000
Torque constant	Nm/A	0.63	0.63
Induced voltage constant per phase	mV/(rpm)	21.9	21.9
Mass (with brake)	kg	2.2	2.5
Mass (without brake)	kg	3.0	3.3
Permissible radial load	N	392	392
Permissible axial load	N	147	147

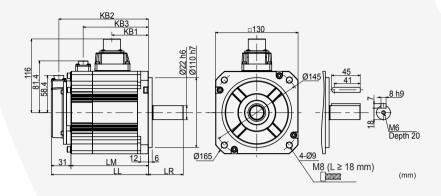
Brake specification

Rated voltage	V	DC24V ±10 %
Rated current	А	0.4
Static friction torque	Nm	>2.39
Suction time	ms	<70
Release time	ms	<20
Release voltage	V	> DC1V

Motor size LL (mm)

Brake	Without	With
MX7510200	107.3	144.3
MZ7510200	122.3	159.3

Dimensions



The straight shaft products are not tapped end.

Motor Specifications

Motor Specifications	Unit	MM1020200	MH1020200	MM1520200	MH152□2□□	MM2020200
Voltage	V	AC200V-240V	AC200V-240V	AC200V-240V	AC200V-240V	AC200V-240V
Rated output power	kW	1.0	1.0	1.5	1.5	2.0
Rated torque	Nm	4.77	4.77	7.16	7.16	9.55
Instantaneous max. torque	Nm	14.3	14.3	21.5	21.5	28.6
Rotor inertia (with brake)	kg·cm²	4.56	24.9	6.67	37.12	8.70
Rotor inertia (without brake)	kg·cm²	6.24	26.4	8.35	38.65	10.38
Mechanical time constant (without brake)	ms	0.76	4.17	0.60	3.32	0.58
Mechanical time constant (with brake)	ms	1.05	4.43	0.75	3.46	0.69
Electrical time constant	ms	10.1	10.1	12.2	12.2	12.2
Rated speed	rpm	2000	2000	2000	2000	2000
Maximum revolving speed	rpm	3000	3000	3000	3000	3000
Torque constant	Nm/A	0.88	0.88	0.81	0.81	0.85
Induced voltage constant per phase	mV/(rpm)	30.9	30.9	28.4	28.4	29.6
Mass (with brake)	kg	5.6	7.6	7.0	9.0	8.4
Mass (without brake)	kg	7.0	9.0	8.4	10.4	9.8
Permissible radial load	N	490	490	490	490	490
Permissible axial load	Ν	196	196	196	196	196

Brake specification

Rated voltage	V	DC24V ±10 %
Rated current	А	1.0
Static friction torque	Nm	>9.55
Suction time	ms	<120
Release time	ms	<30
Release voltage	V	> DC1V

Motor size (mm)

	Brake	LL	LM	LR	KB1	KB2	KB3
MM1020200	Without	128.0	97.0	55.0	57.5	116.0	1
1411411020200	With	153.0	122.0	55.0	57.5	141.0	102.8
MH1020200	Without	163.0	132.0	70.0	92.5	151.0	1
1411 1102 112 1111	With	188.0	157.0	70.0	92.5	176.0	137.8
MM1520200	Without	145.5	114.5	55.0	75.0	133.5	-
	With	170.5	139.5	55.0	75.0	158.5	120.3
MH1520200	Without	180.5	149.5	70.0	110.0	168.5	1
1411 1132 112 1111	With	205.5	174.5	70.0	110.0	193.5	155.3
MM2020200	Without	163.0	132.0	55.0	92.5	151.0	-
11111202020	With	188.0	157.0	55.0	92.5	176.0	137.8



#1 for advanced motor and drive technology

Nidec Corporation is a global manufacturer of electric motors and drives. Founded in 1973, Nidec has worldwide operations and a workforce of more than 110,000 who develop, manufacture and install motors, drives and control systems in industrial plants, automobiles, home appliances, office equipment and information technology.



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CONTROL TECHNIQUES

DRIVE SPECIALISTS SINCE 1973

Drives: they're what we do. Whether you're designing a new machine or installing a replacement, we know you need quick delivery and an easy set up, with the confidence that your drive's going to keep on performing with accurate control.

So leave it to the specialists. We've dedicated ourselves to designing and manufacturing variable speed drives since 1973. This means quick set up, high reliability, maximum motor control and fast, efficient service.



1,000+ OEM CUSTOMERS



5M+
INSTALLED
DRIVES



1,500+
EMPLOYEES
WORLDWIDE



70 COUNTRIES



Outstanding performance

The outstanding performance of our drives is the fruit of over 45 years of engineering experience in drive design.



Technology you can rely on

Robust design and the highest build quality ensure the enduring reliability of the millions of drives installed around the world.



Open design architecture

Based on open design architecture, our drives integrate with all primary communication protocols.

Global reach, local support

Highly experienced, locally based Application Engineers design and support drive technology to provide maximum value, wherever you are in the world.



Embedded intelligence

Precision motor control is combined with the highest embedded intelligence, ensuring maximum productivity and efficiency of your machinery.

A part of the Nidec Group

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Control Techniques is your global drives specialist.

With operations in over 70 countries, we're open for business wherever you are in the world.

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www.controltechniques.com



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