

Line level

- Tool will only be able to work on the desired part or moving area
- Accuracy within 30 to 50cm
- Uses UWB technology to create coordinates
 - Industrial Location Mapping (ILM) Sync Modes









Bolt level

- Tool will only be able to work within the desired bo
- Down to 10mm accuracy
- Different technologies to adapt to different solutions
 - Vision → <u>SpotPoint (ILS)</u>
 - Encoder based → <u>Positioning Arms</u>

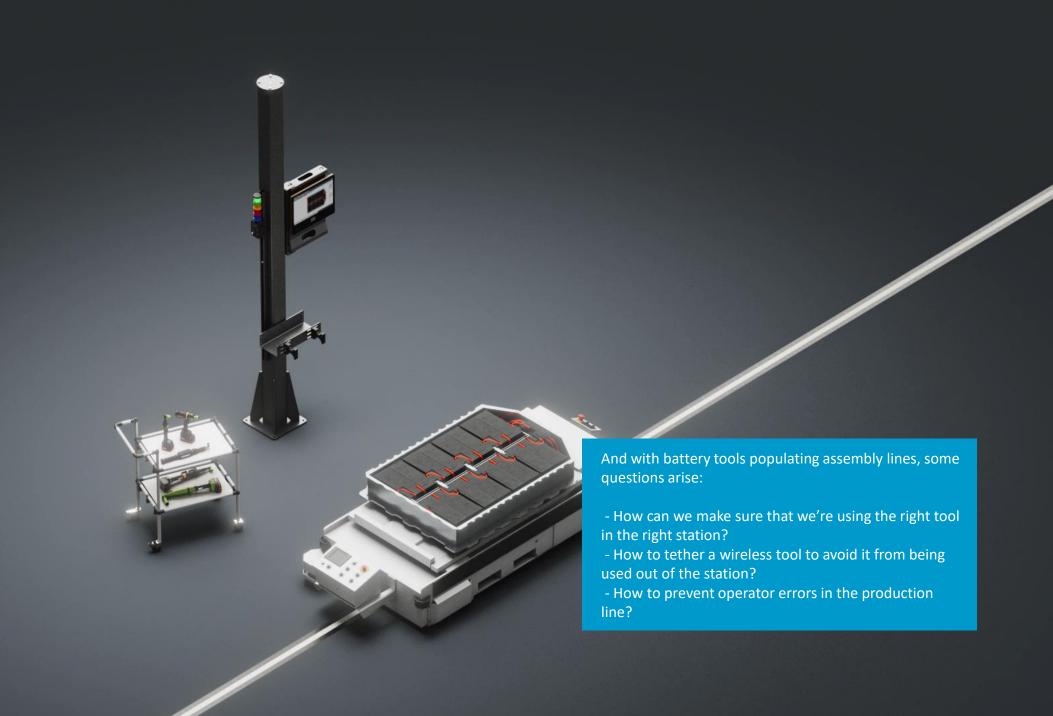


Station level

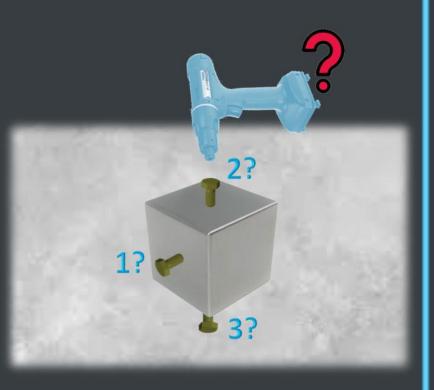
- Tool will only be able to work on the desired area
- Accuracy within 30 to 50cm
- Uses UWB technology to create coordinates
 - Industrial Location Mapping (ILM) Basic & Advanced Modes







How to prevent errors?



Wrong sequence

- How to make sure the operator is following the right sequence?
- How to assure the correct joint seating?



Wrong product

- How to make sure the tools are working in the correct station?
- How to pre prevent tools to work outside the boundaries?



Wrong side

- How to prevent tool of being used in the wrong side?
- What if you have same joint characteristics but different torque parameters?

Location Solutions to envision the future of Industry 4.0

Industrial Location Mapping - ILM







interaction



[Integration]

→ Easy rebalancing

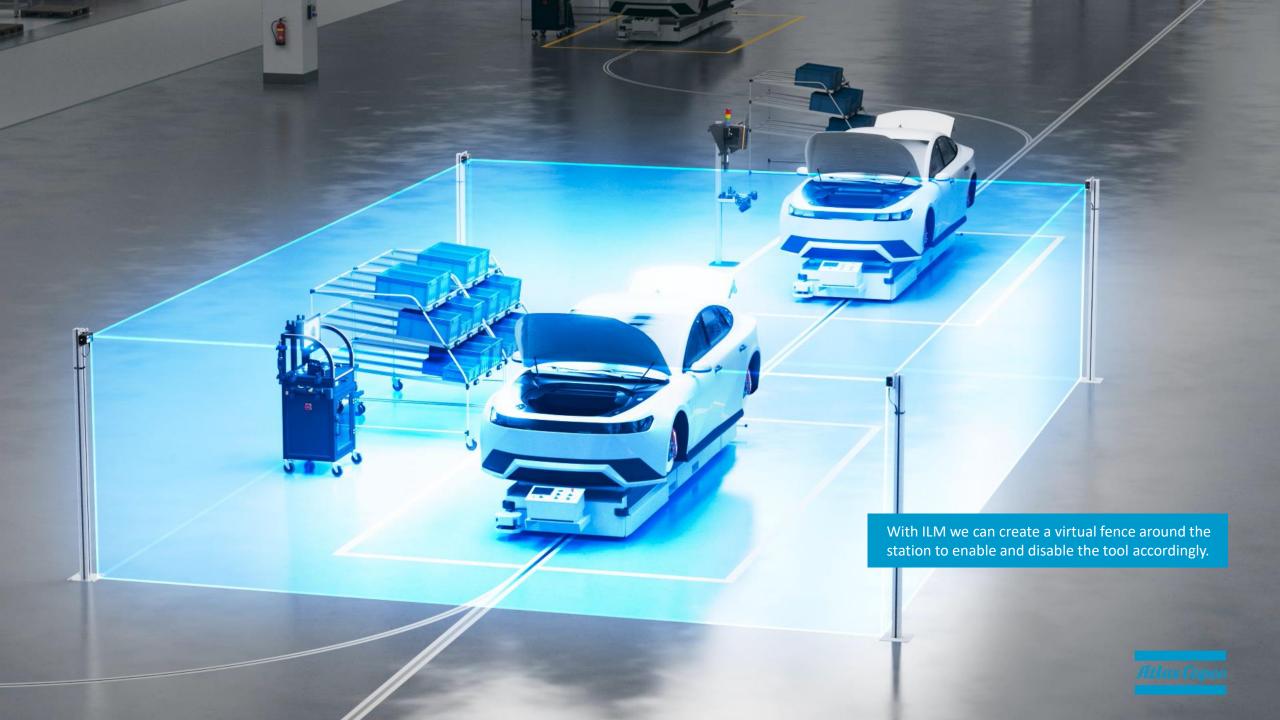
[Quality]

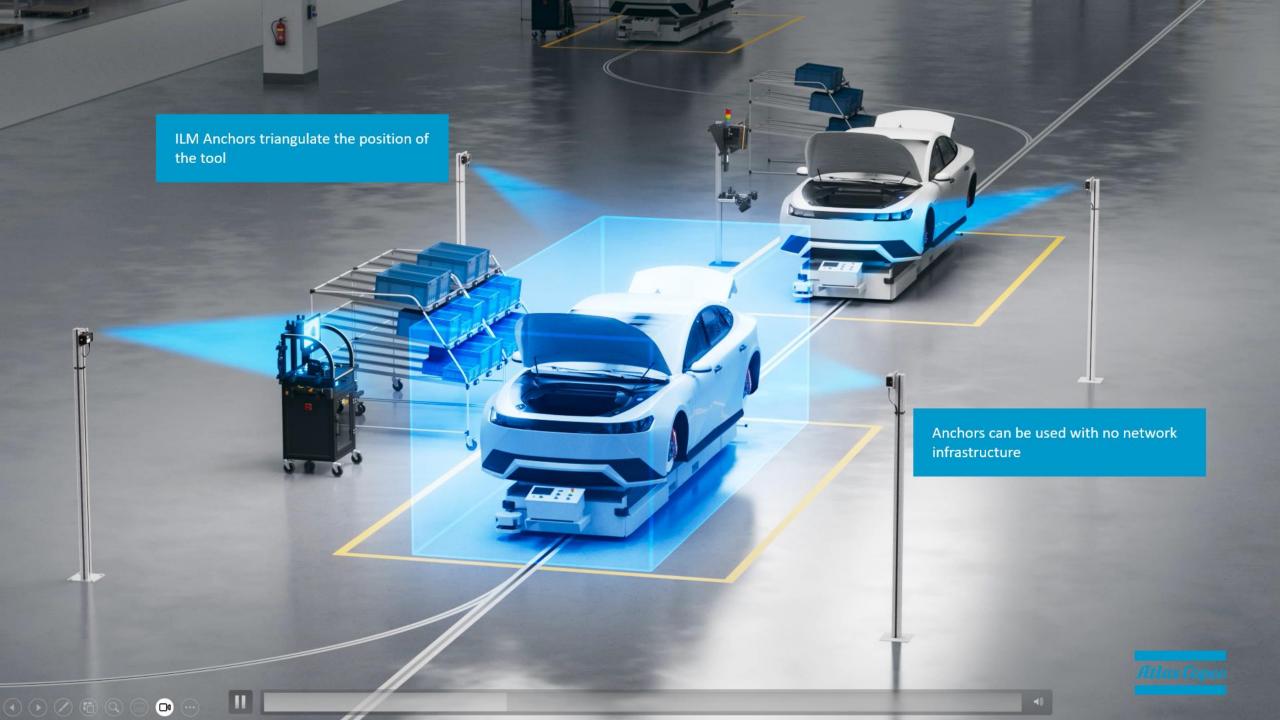
→ Right first time

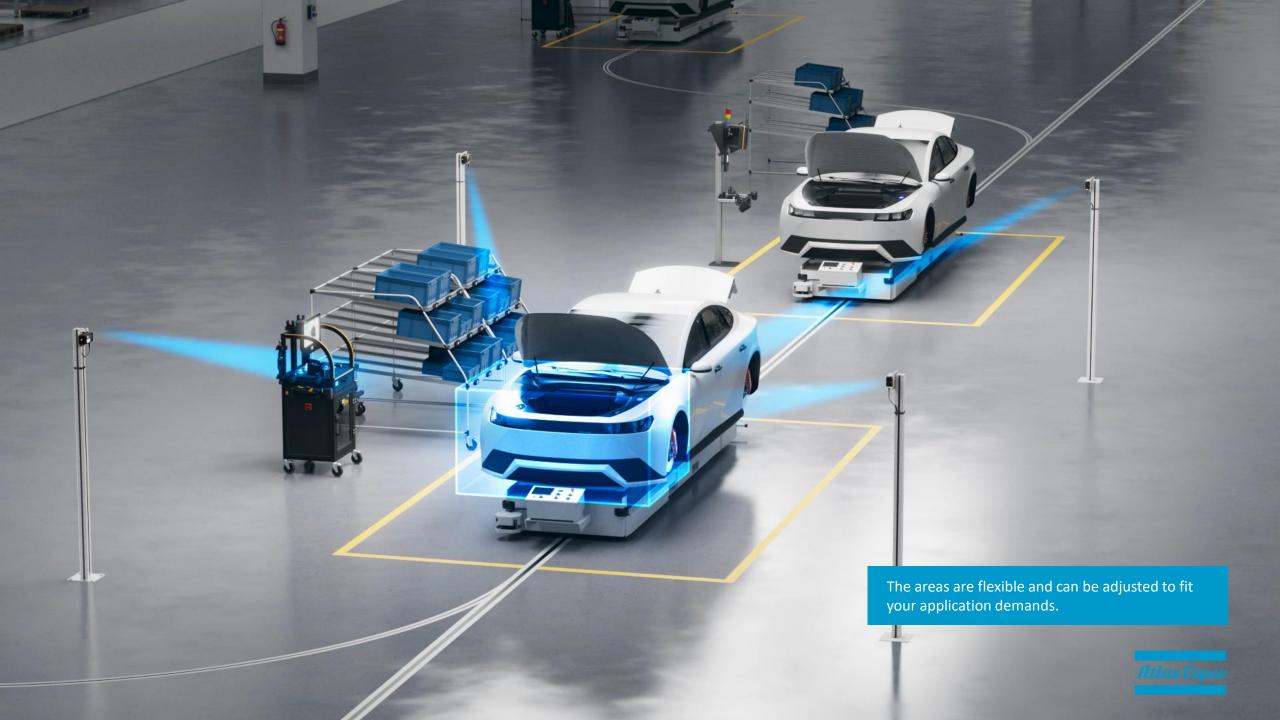
[Flexibility]

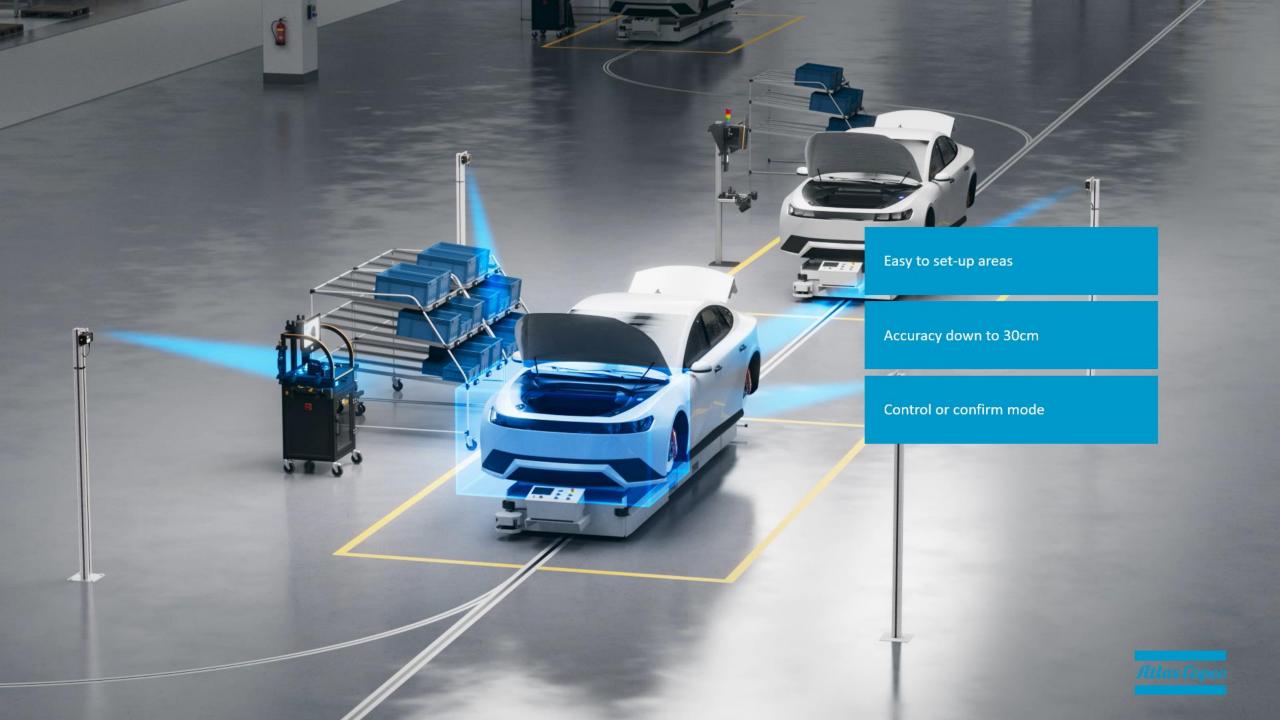
→ Battery as a trend

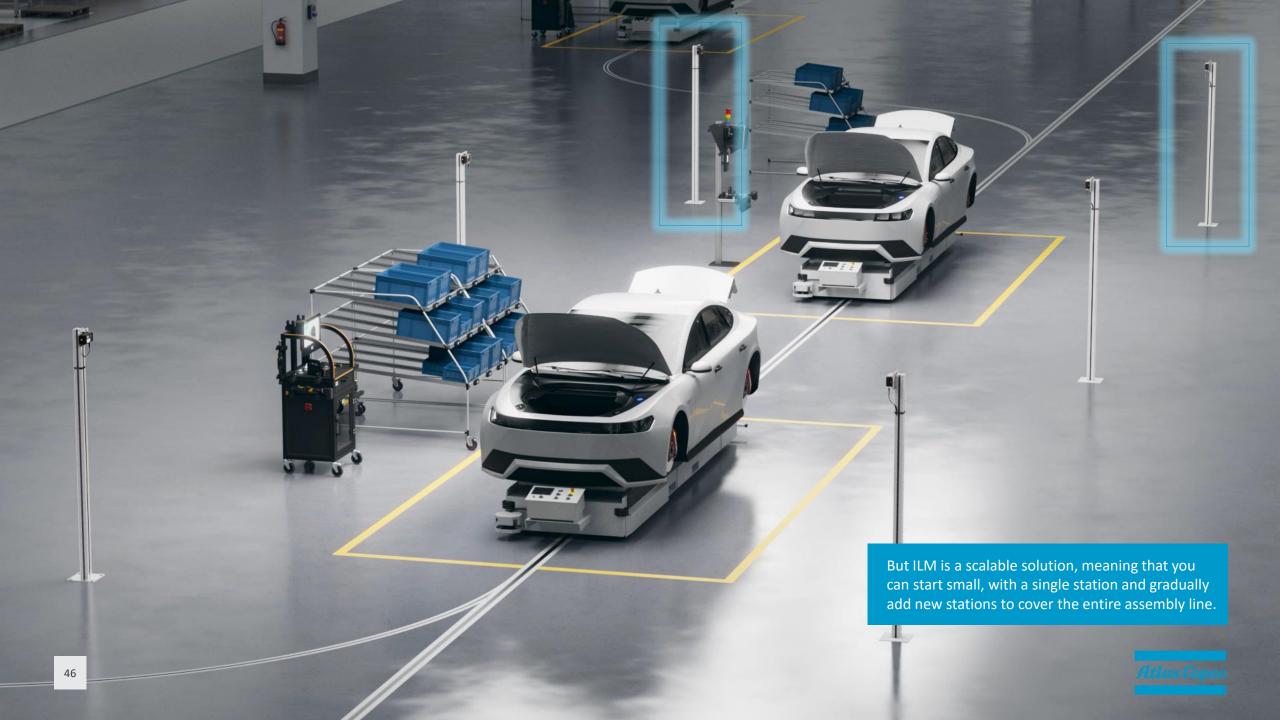














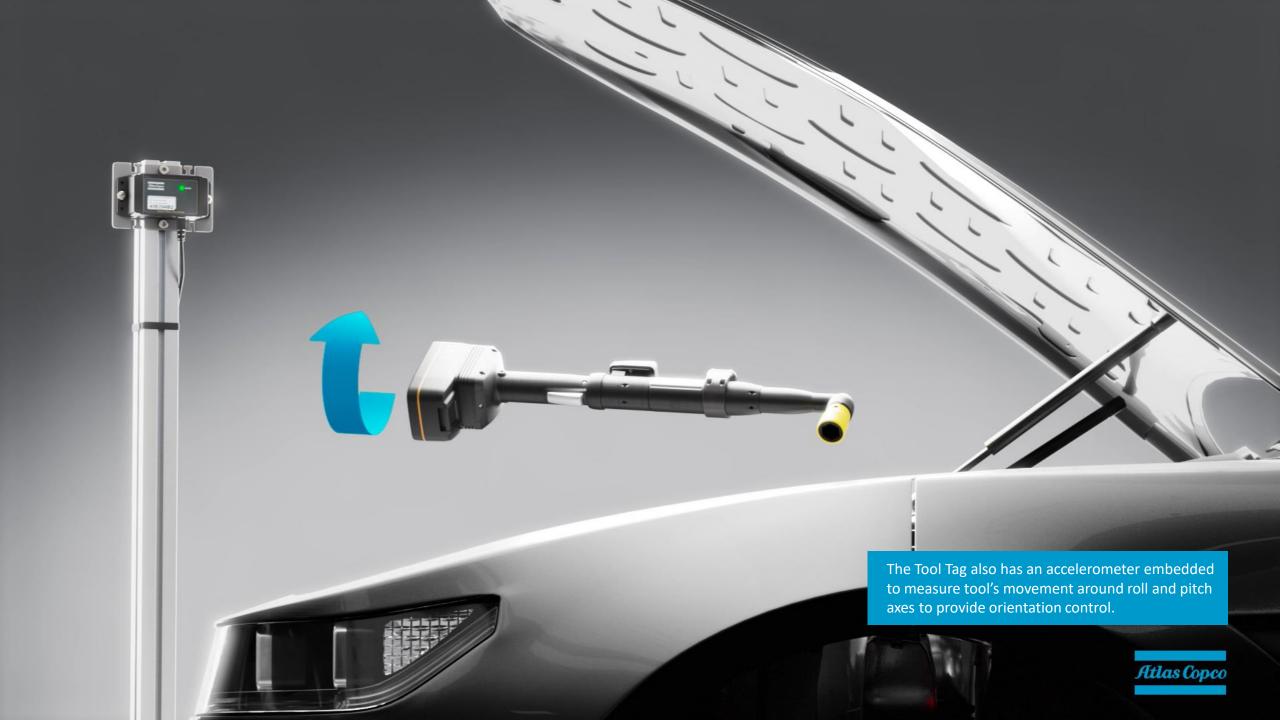
To do so it's simple: you need to connect just one ILM Anchor to the network

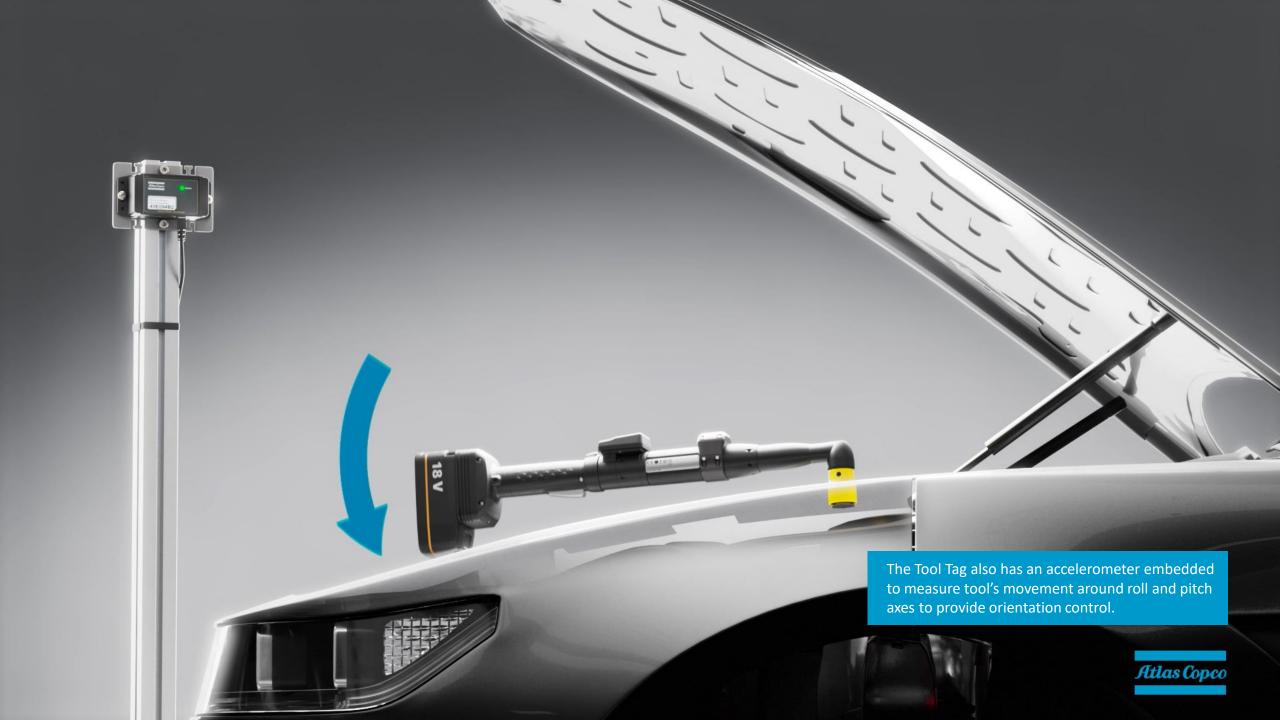




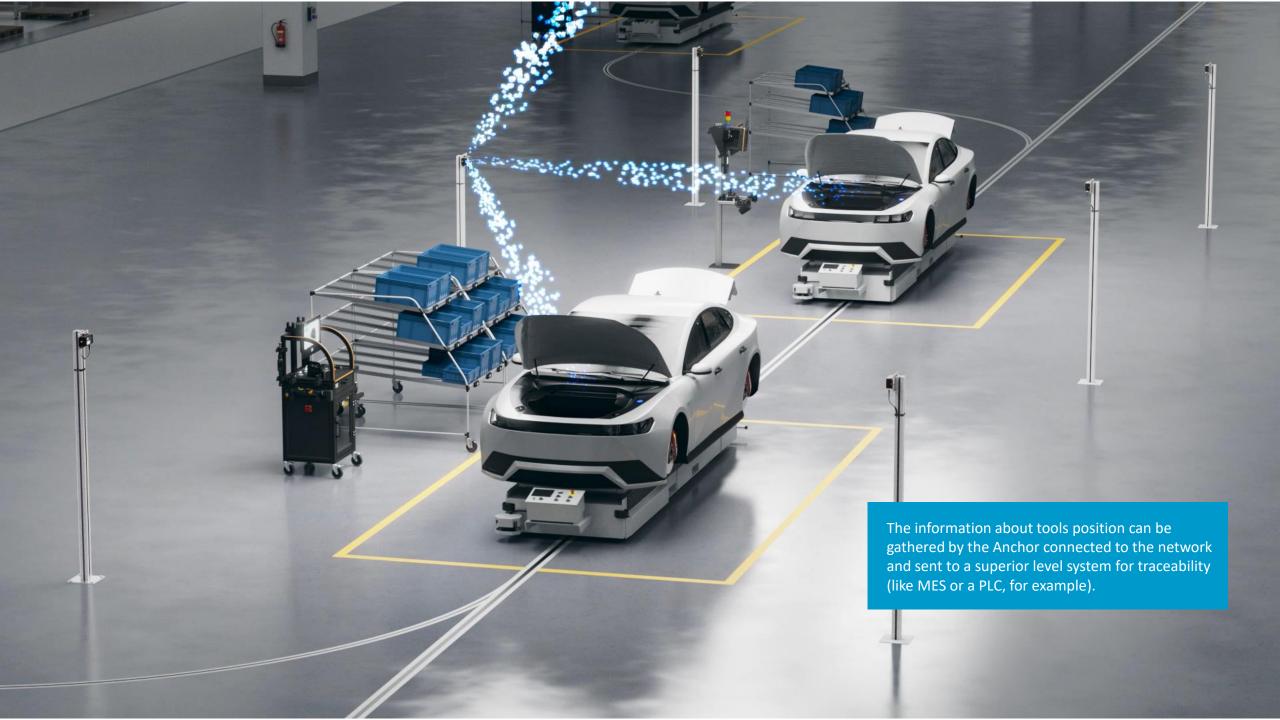


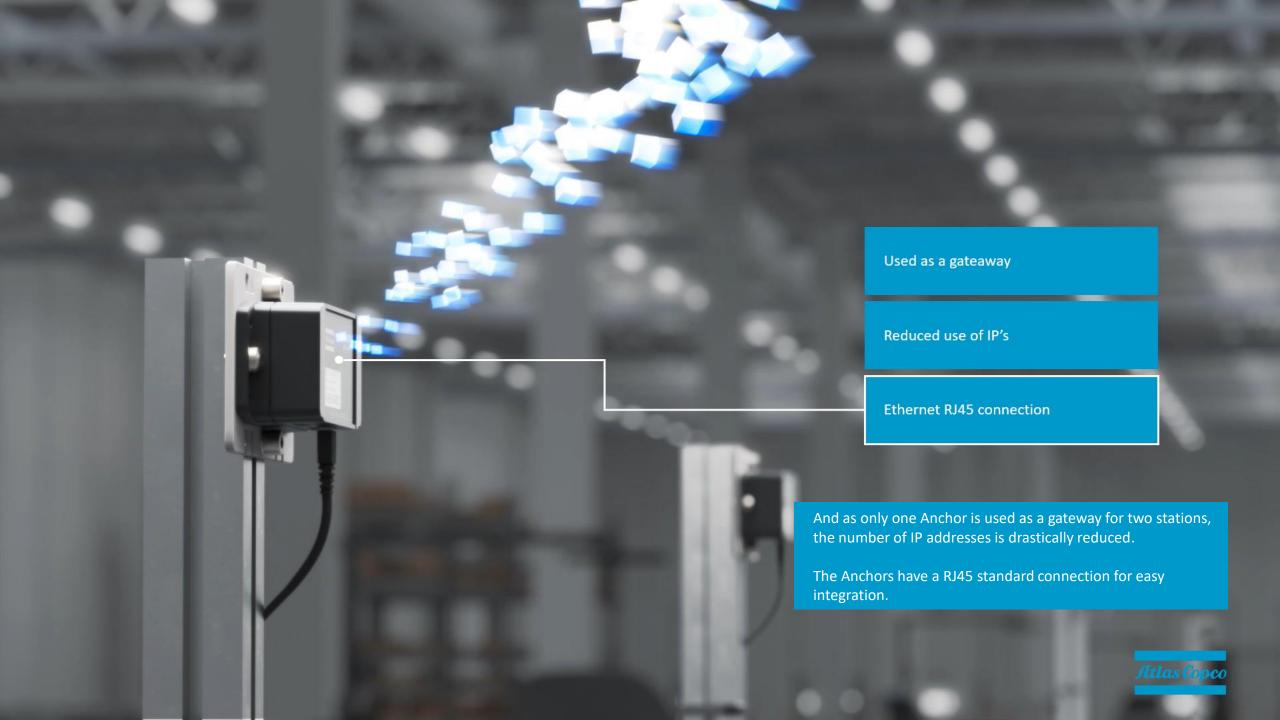


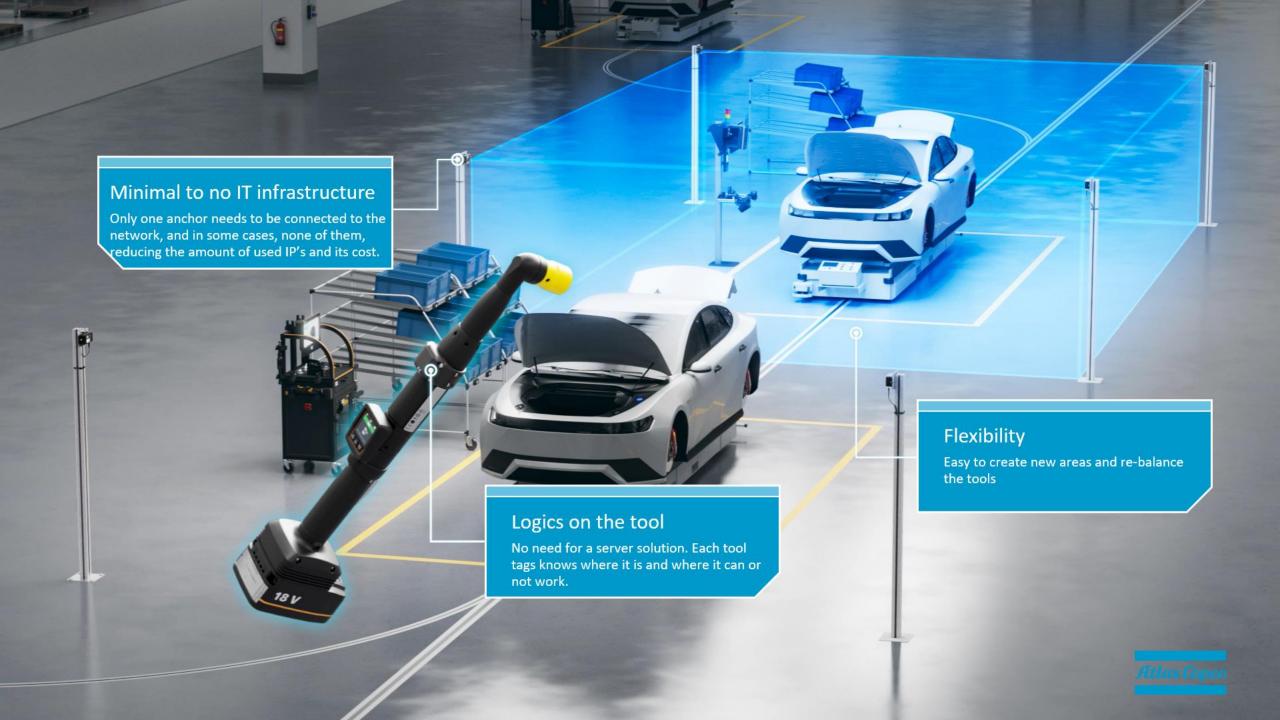




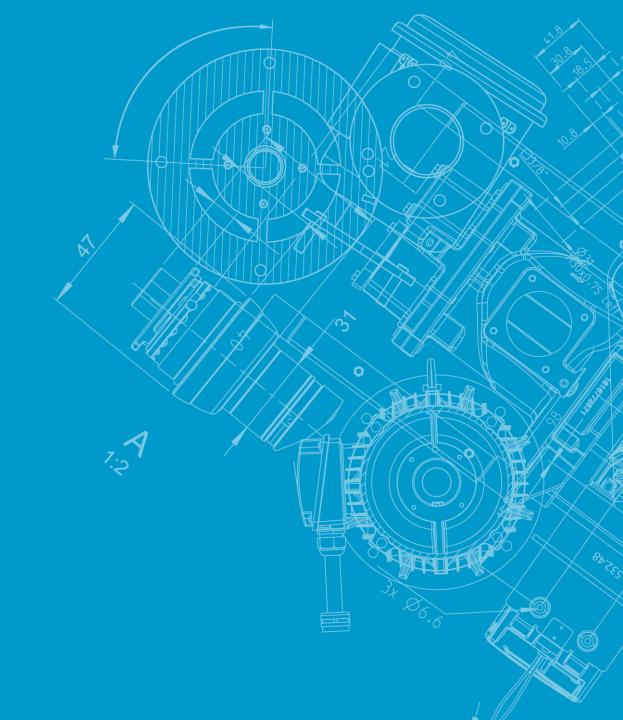








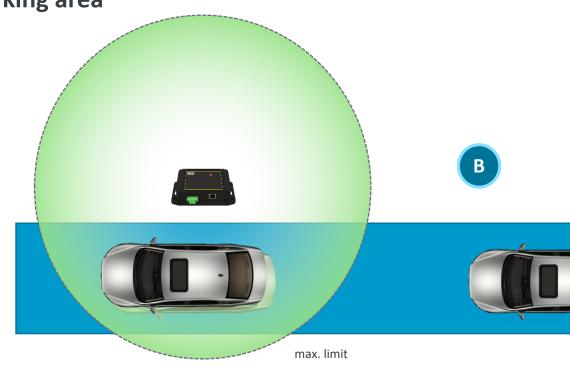
ILM Modes



ILM – Basic mode – 1x anchor

The best solution for simple stop-and-go lines or fixed working area

- Plug and play solution without measuring the infrastructure
 - No anchor configuration needed
- Minimal installation effort
 - Only power needed for ILM anchors (12-24V)
 - No additional data or timing cables
- Creates a circular area (dome shaped volume)
- Up to 50 cm tolerance + orientation detection of the tool





ILM – Basic mode – 4x anchors

The best solution for simple stop-and-go lines or fixed working area

- Plug and play solution without measuring the infrastructure
 - No anchor configuration needed
- Minimal installation effort
 - Only power needed for ILM anchors (12-24V)
 - No additional data or timing cables
- Creates a rectangular area (fenced box volume)
- Up to 50 cm tolerance + orientation detection of the tool





ILM – Advanced mode

The best solution for complex stop-and-go lines or fixed working area

SEGMENTATION OF THE CAR / AREA

- More accurate tool enable / disable areas
- Up to 30 cm accuracy + orientation detection
- Same installation effort as Basic mode + measurement
- Cable less configuration with ILM Configurator stick
- Same data and tool controller interfaces as Basic mode
- Real time visualization of tag position on configurator



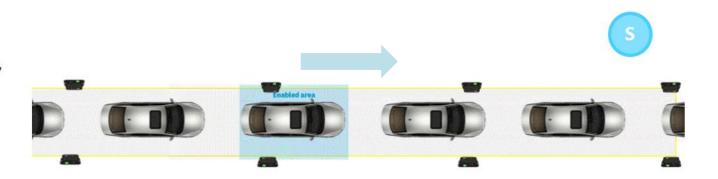


ILM – Sync mode

The best solution for moving lines → Needs integration with customer PLC

Enabling area moving together with the part

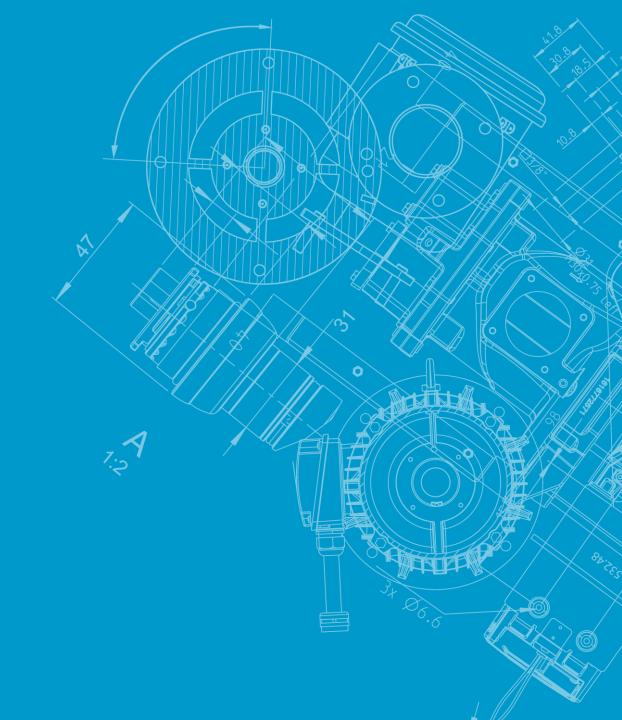
- Up to 30 cm accuracy + orientation detection
- Same installation effort as Advanced mode
- Location system will send the position of the tool (x, y, z), and tool orientation to Master PC / Interface
- Need of external SW to synchronize Tool Coordinates with car coodinates: ILM Server / ILM Adapter* / Customer specifics (SJC/AklanS...)
- Best solution for moving production lines / moving areas
- Need's project or APC to integrate with customers car position data







Summing it up



ILM

Hardware

ILM Anchor



- Reference point for UWB-based localization
- Power Supply via 24 V or PoE
- Built-in movement detection protects against manipulation
- Connection with external systems via network possible
- LED indicates status and working mode





- Power supply directly from the tool
- Built-in orientation detection
- Power-LED indicates when turned on
- Status-LED illuminates when in enable area
- For easy integration the ILM Tag can simulate a second-starttrigger. No software interfaces required!

ILM Configurator stick



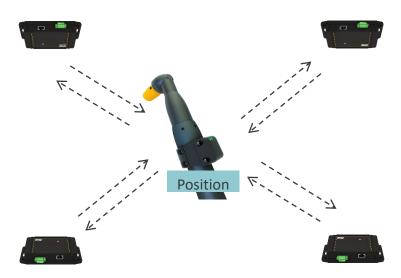
- For configuration and system setup over UWB radio
- Updating configuration of tool tag/anchor
- Updating SW over-the-air
- LED indicates status and working mode

ILM

Distance measurement concept

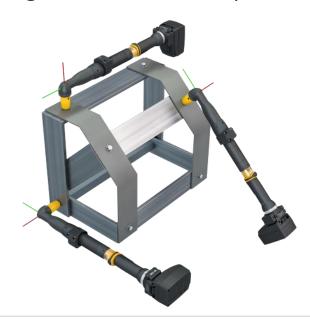
Wireless Distance measurement technology

- Monitors the distance between the ILM Tag and the ILM Anchors.
- Users can easily define criteria with a maximum and minimum allowed distance around the ILM Tag.



Tool Orientation detection

- An accelerometer in the ILM Tag continuously monitors the tool orientation.
- Users can define criteria with minimum and maximum angles for both roll and pitch.



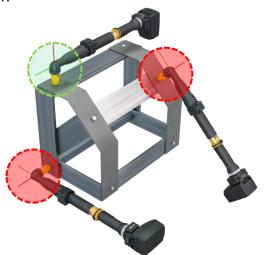
Confirm Mode / Control Mode

PSet selection management feature

Confirm Mode

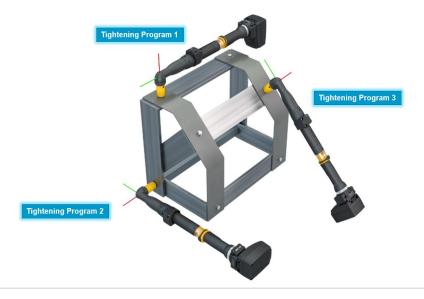
The controller (which in turn can receive process information from an overhead system) selects the tightening program to be used.

The ILM system confirms that the user defined area and or orientation for that tightening program is correct and enables the tool.



Control Mode

In Control mode, the ILM system tells the controller which tightening program to use based on tool distance and / or orientation.





ILM – Short facts

- Ultra wideband radio technology (UWB)
- Works with metal interference → No need of line of sight
- Tool tag accessories available for ST, STB, STR, TBP, ITB-A and ITB-P.
- Tool tag accessory combinations available:
 - 2in1 (location + 2D scanner)
 - 3in1 (location + 2D scanner + E-HMI)
- Recommended max. distance between anchors: 7 m.
- Accuracy level: 0,3 m (Advanced mode) / 0,5 (Basic mode)
- Pitch and roll accuracy: 5 degrees.
- Communication via Open Protocol to PF4000, PF6000 & PF8 controllers and ITB





Atlas Copco

