

Autofinisher: Error Handling Manual

Revision: 01

1.0 Revision History

Rev.	Changes		Date
01	Initial Release		02/14/2019

2.0 Purpose and Scope

The purpose of this document is to provide a list of all the Autofinisher errors, its probable causes and actions. The scope of this document applies to Autofinisher engineers, technicians and operators.

3.0 Personal Protective Equipment

The following Personal Protective Equipment (PPE) is required when using the Autofinisher:

- Closed-toed shoes.
- Latex/Nitrile gloves.
- Safety glasses.







4.0 General Guidelines

Below are some general guidelines, definitions and points to remember for a smooth operation of the Autofinisher at all times.

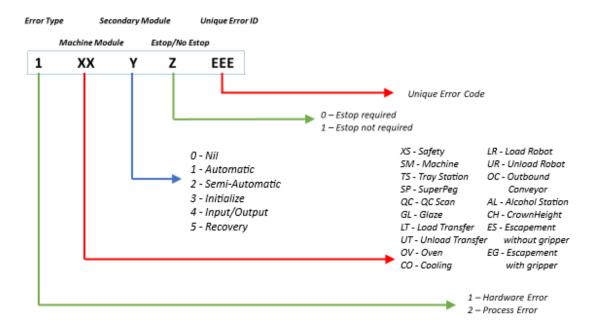
- > Do not remove any trays or fixtures from the machine unless absolutely necessary such as, if the data queue was cleared.
- > If a barcode scanner fails to read the barcode, try again a couple of times by clearing the error before estopping the machine for further troubleshooting.



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5.0 Structure of the Error Code



6.0 Type of Errors

- ➤ Hardware Error A fault that occurred due to the inappropriate functioning or absolute failure of a physical device on the machine or loss of communication, power or air. This always requires the machine to be Estopped and reset.
- Process Error A fault that occurred due to the inappropriate handling of the machine, inaccurate sequence of operation. In most cases this requires, taking the necessary actions as specified in the error table and then clearing the error to bring the machine back to error-free state.

7.0 Machine Module Components

The Autofinisher machine has been divided into 10 modules based on its location and function. Each of these modules work together to successfully complete a job cycle. They do not have the capability to function independently. A complete list of devices under each module is mentioned below and labelled on pictures.

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8.0 Error Description

Error Code	Description	Possible Causes	Solution
1XS00 001	Safety failed to recover in time. Try again or please reset PLC.	Problem with PLC wiring or the safety configuration was changed.	Try again by clearing error. If error persists, Estop the machine, reset PLC, press reset button and try again. Call support if error persists.
1XM00 002	Severe Error! Needs machine reset from Estop.	Machine was Estopped.	Release all the depressed Estops. Press yellow reset button. Then click stop — reset - start buttons on GUI in the same order.
1XM00 003	Error! EtherCAT slave missing.	An EtherCAT device must have got disconnected.	Check the EtherCAT network. Make sure there is no discontinuity. All the cables should be connected then restart the machine.
1XM00 004	Ethercat/Power: Communication Down.	An EtherCAT device must have got disconnected.	Check the EtherCAT network. Make sure there is no discontinuity. All the cables should be connected then restart the machine.
1XM00 005	Error! Problem with EtherCAT network. Please check cables and configuration.	An EtherCAT device must have got disconnected or a new device was added without scanning it into the PLC.	Check the EtherCAT network. Make sure there is no discontinuity. All the cables should be connected then restart the machine If a new device was added, call support/engineer.
1XM00 006	Error! Machine Air!	Main Air Line not connected or the valve is out of order.	Connect main air line and then restart the machine. If problem still persists, call support.

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1XM00 007	Error! Door: X is Open!	Door is Open!	Close door and restart system.
1XM00 008	Machine needs 5 Pallets to start! Add Pallets and run the machine again.	There are less than 5 pallets inside the machine.	However many pallets are short, insert them and then restart the system.
10C40 009	Motor Alarm is ON. Restart machine.	Conveyor Motor is jammed.	Check if there is any obstruction, clear it and restart the system.
20C21 010	Could not read barcode.	Label was not placed correctly on the box,	Take the box out, clear the error, make sure the label
2OC11 012		label size not correct or the box was not sent into the conveyor in the correct orientation.	size is correct, correct the label orientation, box orientation and send it again through the conveyor.
20C21 011 20C11 013	Bad Barcode, no \$R.	Fixture read something other than the barcode.	Make sure the barcode reader didn't read something else other than the box label. Take the box out from the blow out region and clear the error. Put the box back on conveyor. It should scan normally.
20C11 014	Timeout! Part could not escape. Check Blow Nozzle air connection.	The air to the blow nozzle may have got disconnected.	Connect the air- line to the nozzle and clear the error.
1AL10 015	Alcohol Tank & Cartridges are empty.	There is no alcohol in the tank and one or both the	Fill the alcohol tank and restart the machine. The cartridges will
1AL20 021		cartridges are empty. We can't glaze in this situation.	automatically refilling. Do not try to fill them manually.
2AL11 016	Warning! Alcohol Tank is empty. Fill it.	No Alcohol in the tank or the level	Fill the tank with alcohol, close the lid and then clear
2AL21 022		sensor is out of place.	the error. If error still

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			persists, sensor may have to be replaced.
2AL11 017	Warning! Alcohol Tank missing or empty.	The tank drawer is open or there is no	Close the drawer and clear the error. If error still
2AL21 023	missing or empty.	Alcohol in the tank.	persists, make sure there is enough alcohol in the tank and clear error.
2AL41 018	Cartridge 1 Low Level Sensor out of order.	Sensor is out of order or not placed at the correct	Make sure the cartridge is secured appropriately. Check if the sensor still
2AL41 019	Cartridge 2 Low Level Sensor out of order.	sensing position or the cartridge is not secured properly in its correct position.	works, if so adjust it to see the low level of alcohol and then clear the error. If sensor is out of order, call support to replace it.
2AL41 020	Warning! Tank Air Pressure too Low.	Air hose to alcohol tank could have been pinched or disconnected.	Check the hoses and then clear error.
1CO40 024	Work position not reached / Base position not reached.	Cooling Station pinched air hose, air hose disconnection, valve out of order or obstruction by robot.	Check the hoses and restart the system. If there is obstruction by robot due to an earlier crash, robot should recover on its own and move out of the way of the cooling station. To recover the robot, estop and then stop – reset – start the system from GUI.
1CO40 025	Fan is not ON.	Cooling Fan sensor has moved and does not sense the fan moving anymore or the fan is out of order, or the fan cable got disconnected or the	If the fan is ON, then reposition the sensor to make sure it senses the fan moving, if it still doesn't work, the sensor may have to be replaced. If the fan is not ON, make sure the fan is getting power by checking the power cable.

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		fan sensor is out of order.	If fan is still not ON, fan may need to be replaced. Restart the machine after taking care of the issue.
1CO30 027	Tray Presence not working or Fixture Presence false triggered.		
1CO10 028	Tray or Crown Missing!		
10V10 029	Oven is not ON.	Oven is not ON.	Estop, open door, switch on Oven, close the doors and then restart the system.
10V10 030	Pallet missing or Pallet Presence Sensor not working.		
10V10 031 10V20 036	Table not down.	Oven table sensor is not correctly positioned to see the table or the oven table is not completely down. The table has some horizontal play because of which the sensor may not have picked up.	Make sure the table down sensor is able to sense the table for its whole range of horizontal play. If the sensor has gone bad due to heat exposure, change the sensor.
10V10 032 10V20 037	Oven failed to start program.	The oven is not set to run the correct program.	Call support to set the correct program on that oven.
10V10 033 10V20 038	Oven failed to complete program.	Oven table came down after finishing baking but the table down sensor did not see it for some reason and it has been more than 30minutes since bake had started.	If the table is down upon baking, but the table down sensor is not ON, estop, readjust the sensor to see the table and then restart the system. Do not remove the baked pallet.

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20V10 034	Waking up or Table down		
	sensor not working		
	correctly!		
10V20 035	Pallet not present.		
1CH30 039	Glaze Height Adjust		
	Motor Initialize Error:		
1CH40 040	Axis actual position error.		
1CH40 041	Glaze Height Motor Error:		
1CH60 042	nCommPos out of range.		
	Start machine to try		
	again.		
2CH11 043	Invalid DSM ID. Clear		
	Error to try again.		
1CH20 044	Invalid DSM ID.		
2QC11 045	DSM software not		
1QC20 059	running or not Ready.		
1QC10 046	Barcode scanner	Barcode reader	Reconnect the cables and
	connection timeout.	power or Ethernet	clear error.
		cable disconnected.	
2QC11 047	Could not read barcode.		
2QC21 055			
1QC10 048	Could not read barcode		
	after 3 Attempts.		
1QC10 049	Barcode Out of Range.	Barcode on the	If it is a valid fixture with a
1QC20 056		fixture is out of the	barcode range out of the
		fixture ID range set	set range, call
		as 400 to 200.	engineer/support to modify
			fixture ID range setting
			through the config page.
2QC11 050	Connection/Data	Barcode reader	Reconnect the cables and
2QC21 057	Transmission Error.	power or Ethernet	clear error.
		cable disconnected	
		while reading the	
		part.	
		Parti	

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2QC11 051 2QC21 060	Timeout - QC Scan did not start.	Cloud issue, Cloud server down/crash	Relaunch the DSM software and clear the error.
2QC11 052			
2QC11 053	Timeout: DSM Scan could	Cloud issue, Cloud	Relaunch the DSM
2QC21 062	not complete or result	server down/crash	software and clear the
	not valid.		error.
1QC11 054	DSM Scanner failed to		
	reset!		
2QC21 058			
2QC21 061			
2QC21 063			
1GL40 064	Glaze Mix Level too low!		
	Please Refill and restart		
	machine.		
1GL40 065	Tilt axis actual position		
	error.		
1GL40 066	Spin axis actual position		
	error.		
1GL40 067	Shuttle axis actual		
	position error.		
1GL40 068	Mixer Motor 1 not	Motor power got	Check the power cable dis-
	running	disconnected or	connector of the motor.
		motor is out of	
		order.	
1GL40 069	Mixer Motor 2 not	Motor power got	Check the power cable dis-
	running.	disconnected or	connector of the motor.
		motor is out of	
		order.	
1GL40 070	Glaze Shuttle Motor		
101 10 071	Error:		
1GL40 071	Glaze Tilt Motor Error:		
1GL40 072	Glaze Spin Motor Error:		
1GL40 073	Shutle in Crash Zone!		
1GL40 074	Funnel1Cylinder:		
1GL40 075	Funnel2Cylinder:		
1GL40 076	GlazeShieldCylinder:		
1GL40 077	VacuumDivertingCylinder:		

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1GL40 078	PurgeValve1:	
1GL40 079	PurgeValve2:	
1GL40 080	fbSpool1:	
1GL40 081	fbSpool2:	
1GL10 082	Glaze Mix Tank 1 is	
1GL20 108	empty! Please Refill and	
	restart machine.	
2GL10 083	Glaze Mix Tank 1 is Low	
2GL20 109	on Spray Solution.	
1GL10 084	Mixer 1 Low Level sensor	
1GL20 110	out of order.	
1GL10 085	Glaze Mix Tank 2 is	
1GL20 111	empty! Please Refill and	
	restart machine.	
2GL10 086	Glaze Mix Tank 2 is Low	
2GL20 112	on Spray Solution.	
1GL10 087	Mixer 2 Low Level sensor	
1GL20 113	out of order.	
10110.000	(5)	
1GL10 088	Unknown/Partially glazed	
	crown in glaze station.	
1GL10 089	Remove and try again. Barcode scanner	
1GL10 089		
2GL10 090	connection timeout. Could not read barcode.	
2GL10 090 2GL20 114	Could flot read barcode.	
2GL2U 114		
1GL10 091	Could not read barcode	
1GL10 031	after 3 Attempts.	
10220 113	dici 5 /ttcilipts	
1GL10 092	Fixture scanned at Glaze	
	station does not match	
	data requested to cloud.	
1GL10 093	Barcode Out of Range.	
1GL20 116		

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1GL10 094	Waiting for Crown data timeout.	
1GL10 095 1GL20 117	Both spool Valves Stuck	
1GL10 096 1GL20 118	Spool Valve 1 Stuck.	
1GL10 097 1GL20 119	Spool Valve 2 Stuck.	
1GL10 098 1GL20 120	Spool valve (1) stuck timed out.	
1GL10 099 1GL20 121	Spool valve (2) stuck timed out.	
1GL10 100 1GL20 122	Spool valve (both) stuck timed out.	
2GL10 101	Glaze Purge timeout error as Alcohol Station is not Ready.	
1GL10 102	Alcohol Station not ready after 3 Attempts.	
1GL30 103	Glaze Shuttle Motor Homing/Initialization Error:	
1GL30 104	Glaze Tilt Motor Set Pos Error:	
1GL30 105	Glaze Spin Motor Set Pos Error:	
1GL30 106		
1GL30 107	Initialize Time out.	
1GL20 123	Spool2 did not reach Work Position.	
1GL20 124	Spool2 did not reach Base Position.	

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2GL21 125	Glaze Purge timeout error		
	as Alcohol Station is not		
	Ready.		
1GL20 126	Alcohol Station not ready		
	after 3 Attempts.		
1OR30 127	Both robots in overlap		
	zone. Jog one robot out		
	of overlap zone.		
1OR30 128	Initialize Timeout.		
1OR30 129	Denso Robot state error.		
1OR50 130	Robot recovery failed. Do		
	not know destination.		
1OR50 131	Robot recovery failed.		
	Timed out.		
2OR51 132	Tray present at Load	N/A	
	Transfer station.		
2OR51 133	Oven 1 not ready.		
20R51 134	Oven 2 not ready.		
2OR51 135	Oven 3 not ready.		
2OR51 136	Oven 4 not ready.		
2OR51 137	Oven 5 not ready.		
1OR50 138	Cooling 1 not ready.		
1OR50 139	Cooling 2 not ready.		
1OR50 140	Cooling 3 not ready.		
10R50 141	Cooling 4 not ready.		
1OR50 142	Cooling 5 not ready.		
1OR50 143	Tray present at Unload		
	Transfer station.		
10R50 144	Robot recovery failed.		
	Location cannot be a		
	destination.		
1LR30 145	Both robots in overlap		
	zone. Jog one robot out		
	of overlap zone.		
1LR30 146	Initialize Timeout.		
1LR30 147	Denso Robot state error.		
2LR10 148	Fixture not placed		
	correctly in Oven Unload		

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	T	T	1
	Transfer station. Call		
	Support!		
2LR10 149	Fixture not placed		
	correctly in Oven Load		
	Transfer station. Call		
	Support!		
2LR10 150	Part not placed correctly		
	in glaze station. Call		
	Support!		
2LR10 151	Fixture not placed		
	correctly in Oven Load		
	Transfer Station. Call		
	Support!		
1LR60 152	Crown Missing during		
	drop off.		
1LR50 153	Robot recovery failed. Do		
	not know destination		
1LR50 154	Robot recovery failed.		
	Timed out.		
1LR50 155	Robot recovery failed.		
	Safe location cannot be a		
	destination.		
2LR51 156	Load robot needs peg for	N/A	N/A
	recovery, Please load		
	Empty Peg.		
2LR51 157	DSM1 Not Ready.	Robot was going to	Make sure the part at
		DSM1 with a part	DSM1 is not a valid case
		when an unexpected	and was placed manually
		machine abort	by someone for DSM
		happened. Robot is	manual testing and then
		trying to recover on	remove the part and
		machine restart but	restart the machine.
		someone placed a	
		random fixture at	
		the DSM1 manually	
		before restarting the	
		machine because of	
		which DSM1 is not in	

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		ready state after	
		machine initialize.	
2LR51 158	DSM2 Not Ready.	Robot was going to DSM2 with a part when an unexpected machine abort happened. Robot is trying to recover on machine restart but someone placed a random fixture at the DSM1 manually before restarting the machine because of which DSM1 is not in ready state after machine initialize.	Make sure the part at DSM2 is not a valid case and was placed manually by someone for DSM manual testing and then remove the part and restart the machine.
2LR51 159	Glaze Not Ready.		
2LR51 160 2LR51 161 2LR51 162 2LR51 163 2LR51 163 2LR51 164 2LR51 165	Cannot go to Load Position X - 1/2/3//5/6.	The Load transfer station position the robot was trying to go on recovery is not available anymore. It could be because someone placed a part manually at that position after the machine got aborted or the position sensor is getting triggered falsely.	Clear the error and see if the robot is able to go to the position. If it can't, machine will timeout in few seconds. Follow the steps for that error and restart the machine. If there is a non-production fixture at the referred position, take it out and then estop and stop - reset - start from GUI. If robot is still not able to go to the desired position, estop and take the part out manually from robot's gripper and restart the system. Send the case back into the conveyor after cleaning up the glaze.

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2LR51 166 2LR51 167 2LR51 168 2LR51 169 2LR51 170 2LR51 171	Cannot go to Unload Position X – 1/2/3/4/5/6.	The Unload transfer station position the robot was trying to go on recovery is not available anymore. It could be because someone placed a part manually at that position after the machine got aborted or the position sensor is getting triggered falsely.	Clear the error and see if the robot is able to go to the position. If it can't, machine will timeout in few seconds. Follow the steps for that error and restart the machine. If there is a non-production fixture at the referred position, take it out and then estop and stop - reset - start from GUI. If robot is still not able to go to the desired position, estop and take the part out manually from robot's gripper and restart the system. Unload the part manually by placing it on the inbound escapement and scanning it using the unload GUI.
2LR51 172	Reject station Not available/Ready.	N/A	N/A
1SP30 173	Motor Initialize Error:		
1SP30 174	Dispense Valve:		
1SP40 182	Base/Work position not reached.		
1SP40 175	Motor Error:		
2SP11 176	Cartridge Cap Not Locked!	Cartridge cap not locked/ cap sensor	Make sure the cap is locked/cap sensor cable is
2SP21 179		cable disconnected/ cap sensor not in correct position/ cap sensor not working.	not disconnected/mount the sensor in correct position/replace the sensor if it is out of order. Clear error.
2SP11 177	Cannot refill, Cartridge Cap Not Locked!	Cartridge cap not locked/ cap sensor	Make sure the cap is locked/cap sensor cable is

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2SP21 180		cable disconnected/ cap sensor not in correct position/ cap sensor not working.	not disconnected/mount the sensor in correct position/replace the sensor if it is out of order. Clear error.
1SP10 178 1SP20 181	Super Peg Dispenser could not refill.	Refill timed out – If the dispenser was refilled in reality, the syringe Full sensor must be out of order or its cable got disconnected or it is no longer mounted in the correct position or if there was no refill, then motor did not move because it is jammed or its cable got disconnected or an encoder issue.	

9.0 Approval

This document is reviewed annually and approved by the following individuals:

Reviewer and Title	Signature and Date
Mishka Banerjee Electrical & Controls Engineer, E&T	
Fernando Vera Electrical Manager, E&T	
Anita Mendoza Project Manager, E&T	

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Reviewer and Title	Signature and Date
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David Leeson <i>Vice President of Engineering</i>	

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