







Offshore Aviation OA-4
3D Mapping • Photogrammetry
OA-8B Flight Training Platform • OA-8B Route Rehearsal



## Aircraft Limitations

Aircraft Model: OA-4

Max takeoff weight = 34lbs

Center of Gravity = Max within 80mm, recommended within 30mm

Max wind = 15mph

Precipitation = None

Operating Temps = 32 - 95 degrees F (recommended)

Max altitude = 5,000ft MSL

Max speed = 30mph

Max flight time = 21 min



OA-4 Quadcopter

## Specifications:

MODEL: OA-4 Quadcopter

MANUFACTURER: Offshore Aviation LLC

TYPE: Multi-rotor: Quadcopter FRAME DIAMETER: 960mm

READY-TO-FLY WEIGHT: 12lbs 13oz

RADIO: 6 channel minimum, 8+ channels recommended

BATTERY: 22.2v 6s 8000-10000Mah 15c (two of each in parallel)

FLIGHT TIME: 21 minutes

#### Gear Installed:

-Radio: Futaba 14SG, Futaba 7008SB 8ch rx

-Motor: (4) KDE 4014XF 380Kv Brushless Outrunner,

-ESC: (4) KDE 55A HV OPTO

-Propeller: (4) KDE 15.5x5.3 Folding Carbon Fiber -Battery: (2) Turnigy Graphene 6s 8000mAh 15C

-Autopilot: PixHawk 2.1, Here GNSS GPS

-Telemetry: HolyBro 915Mhz 100mW radio

-FPV system: ImmersionRC 5.8GHz 600mW video tx, RunCam Eagle 800TVL camera,

MinimOSD

-Lighting: Vulcan Day Bright LED Navigation lights

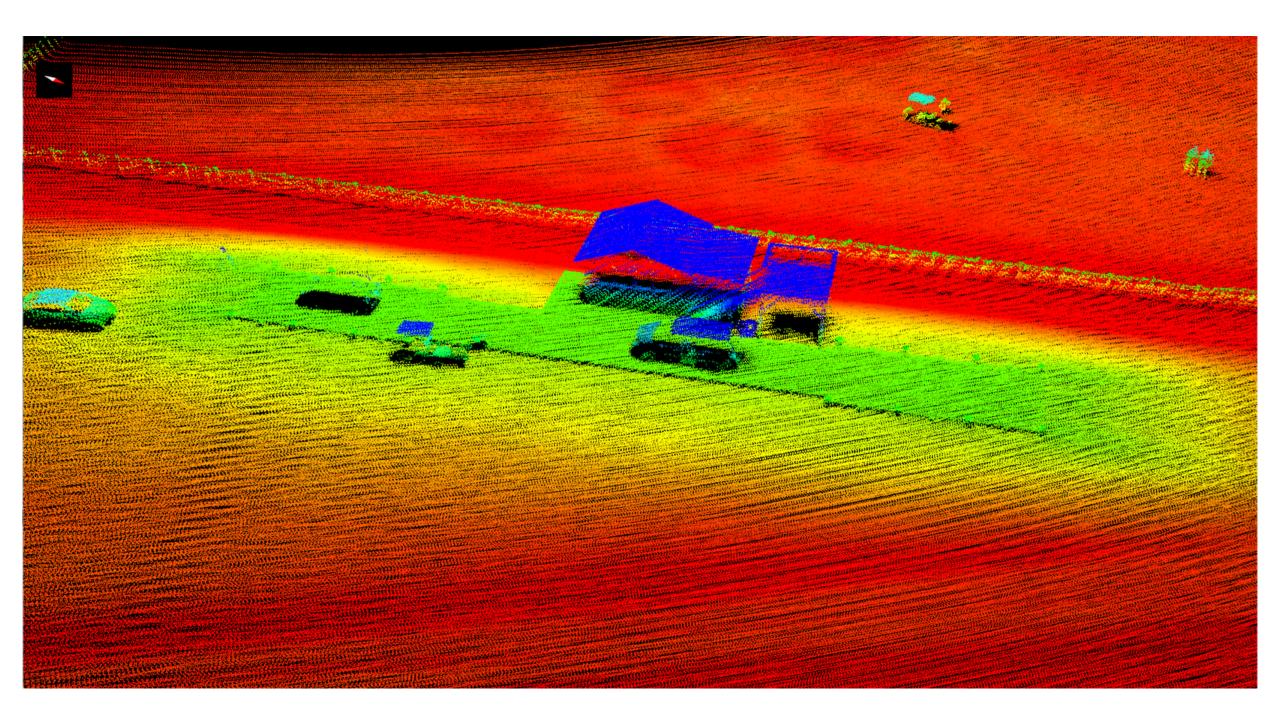


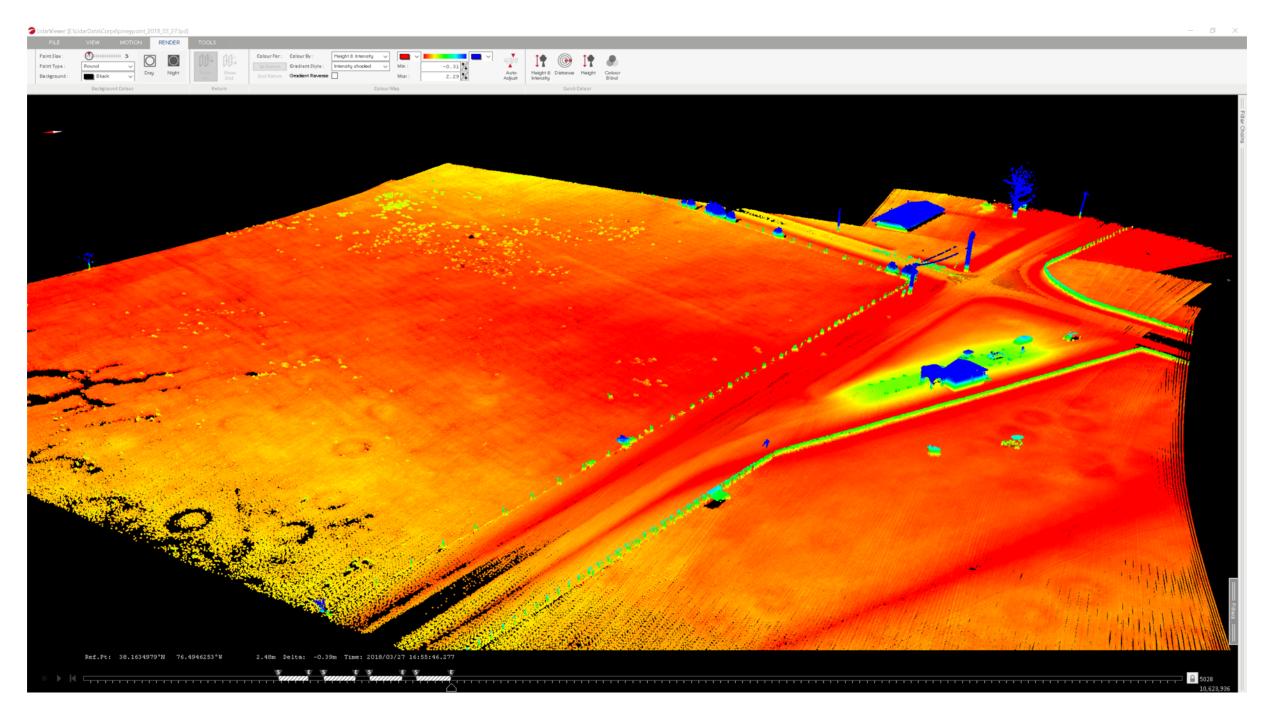


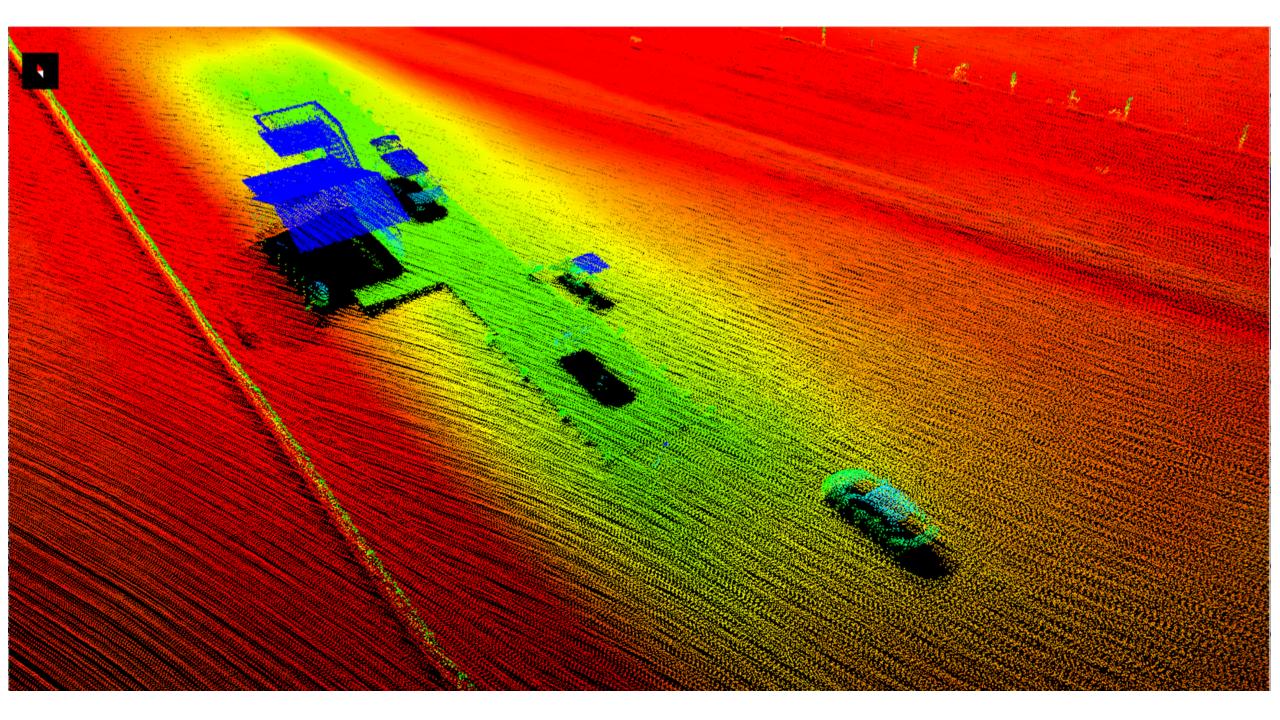


















### **Aircraft Limitations**

Aircraft Model: OA-8B

Max takeoff weight = 59.5lbs

Center of Gravity = Max within 100mm, recommended within 40mm

Max wind = 25mph

Precipitation = Dry

Operating Temps = 32 - 95 degrees F (recommended)

Max altitude = 6,000ft MSL

Max flight speed = 40mph

Max flight time (with Lidar Pod) = 25 min



# OA-8B Lidar Octocopter

## Specifications:

MODEL: OA-8B Lidar Octocopter

MANUFACTURER: Offshore Aviation LLC

TYPE: Multi-rotor: Octocopter FRAME DIAMETER: 1150mm

READY-TO-FLY WEIGHT: 36.3lbs, 43.2lbs (w/ lidar pod) RADIO: 6 channel minimum, 8+ channels recommended

BATTERY: 29.6v 8s 16000-22000Mah 15c (two of each in parallel)

FLIGHT TIME: 30 minutes (25 min w/ lidar pod)

## Gear Installed:

-Radio: Futaba 14SG, Futaba r7008SB 8ch rx

-Motor: (8) KDE 6213XF 185Kv Brushless Outrunner, (8) KDE 95A HVC OPTO ESC

-Propeller: (8) KDE 24.5x8.1 Folding Carbon Fiber

-Battery: (2) Tattu 8s 22000mAh 15C

-Autopilot: PixHawk 2.1, Here GNSS GPS

-Telemetry: RFDesign RFD900 915Mhz 1W radio

-FPV system: Foxeer 5.8GHz 600mW vtx, Foxeer 1200TVL camera, XLRS XOSD

-Lighting: Vulcan Day Bright LED Navigation lights

-UAVionix PingRX ADS-B transceiver