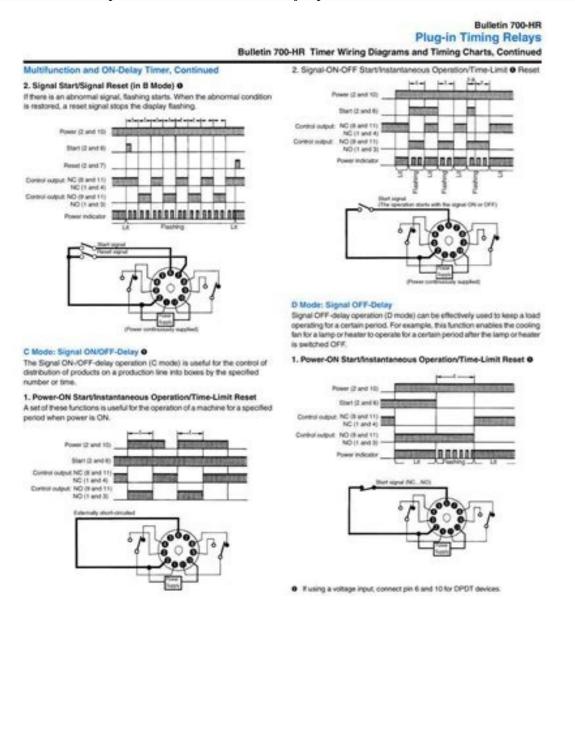
| I'm not robot | |
|---------------|-----------|
| | reCAPTCHA |
| | reCAPTCF |

I'm not robot!

How does an allen bradley safety relay work

Guardmaster Safety Relays Our Guardmaster® single-function safety relays are designed to meet functional safety standards, such as ISO 13849-1 or IEC 62061, and they offer key functions to simplify installation and system complexity. Intermediate Allen-Bradley's (AB) remote PointIO offers robust flexibility for control systems. With a small physical footprint, PointIO provides interconnection for automated areas that communicate over Ethernet/IP, DeviceNet, and ControlNet. A big asset to PointIO is its safety modules, such as 1734-IB8S and OB8S, provide a direct wire, safety-rated contact for devices such as emergency stops, pull-cords, and light curtains. Having these devices directly on the PLC network allows you to utilize them in the safety routines of Studio5000 programs, provides visual feedback for engineers and maintenance technicians within the program, and helps eliminate those pesky safety relays. In this tutorial, we will be discussing the 1734-IB8S & OB8S safety PointIO modules and will learn how to configure and program them in Studio5000.Diagram 1.1-Allen Bradley 1734-IB8S moduleSafety PointIO Hardware Overview & WiringThe 1734-IB8S and OB8S are 8-point modules for their respective inputs or outputs. Looking at these modules we notice they have 16 channels available with similar wiring schemes. However, the difference is in the test points on the 1734-IB8S safety input module. The 1734-IB8S first channel is input 0 or labeled as I0 on diagram 1.2. Both of the noted safety modules require two terminal bases, 1734-TOP.



That is why the terminal layout below is documented with two channels as 0 (highlighted in diagram 1.2). Channels four and five are supply commons. Channels two, three, six, and seven are important for wiring up safety devices and configuring the modules within Studio5000. The noted channels are test points, specifically test outputs. We will go into further detail on configuring inputs and test outputs later in the tutorial. Diagram 1.2-1734-IB8S terminal layout diagramIn this tutorial, we will learn how to wire an emergency stop is dual channel, normally closed. This means that for wiring and programming it, we will need two channels – channel A and channel B. Input 00 will be estop channel A and input 01 channel B. Channel A will be wired so that test point 00, channel 6 (highlighted on diagram 1.2) will be wired to one side of the emergency stop's channel A contact. The other side will have a wire coming back to the 1734-IB8S module and landing on input 00, channel 0. The emergency stop contacts are only passing a voltage through, so which side the wires are landed on does not matter.

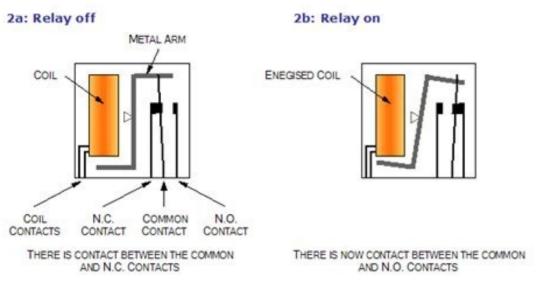
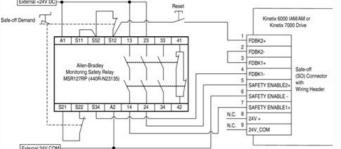


Figure 2: The mechanical operation of a relay

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However, it is good practice to set a standard and follow it. For example, we can make sure that the input going back to the PointIO module is always on one side of the emergency stop contacts and the corresponding test point on the other. Below is an AutoCAD wiring diagram where we can see channels 10 and 11 test output channels T0 and T1 on diagram 1.3-Emergency stop button wiring within AutoCADWith the emergency stop button wiring within AutoCADWith the emergency stop button wiring the safety routine that will enable systems safety circuit and empower a variable frequency drive's (VFD) safety torque off (STO) signal.Configuring the Safety PointIO Modules in RSLogix/Studio 5000In diagram 1.4, you can see that we created a controller tree with our PointIO modules utilizing the 1734-AENT PointIO



Allen-Bradley

If you need a refresher on the controller organizer window or Studio5000 in general, read this programming RS5000 tutorial. Diagram 1.4-Controller organizer tree within Studio5000, V33Next, either double-click on the IB8S module or right-click and select Properties (Alt+Enter). Diagram 1.5a shows the safety input module's default configuration. For the emergency stop button, we will change the Point Operation - Type to Equivalent. This means that both points, 00 and 01, will be evaluated as a pair, based on the discrepancy time. The discrepancy time has been changed to 150ms, which allows for a small buffer for the PLC to recognize which state both channels A and B, or points 00 and 01 respectively, signals are in. The point mode should be set to Safety Pulse Test, configuring the module so that the input participates in safety evaluation and has a dependency on the test output pulse - noted with a green square in Diagram 1.5b. The Test Source configuration values range from 0-3. Our selection for this project is 0 and 1 which correlates to T0 and T1 in the terminal layout diagram. Diagram 1.5b-Revised input configuration of the 1734-IB8S moduleThe next tab, Test Output, is where we will make our final changes for configuring the IB8S module. The default values are set to Not Used, but we want to select Pulse Test. After changing Points 0 and 1 to Pulse Test apply the changes. Note that this configuration of the 1734-IB8S module Diagram 1.6b-Revised est output configuration of the 1734-IB8S module Diagram 1.6b-Revised test output configuration of the 1734-IB8S module Diagram 1.6b-Revised test output configuration tab. The default Point Operation - Type and Point Mode setting for our OB8S module are Dual and Not Used. If the default configuration is not changed then the result is that if an OTE bit goes high for output 00 the OB8S module will never energize that point.



Therefore, we will change the Point Mode of 00 and 01 to Safety. The Pointer Operation – Type could be changed to Single here, but since both of the outputs are going to the same VFD they can be left in Dual for this instance. We will use these points for a VFD's dual-channel STO signals later in the program. Make sure to apply the changes before moving on. Diagram 1.7a-Default output configuration of the 1734-OB8S module Program within our Studio 5000 After the modules are configured, we can add two routines underneath the default Safety Program within our Studio 5000 program. One will be named Emergency_Stops and the other VFD_Safety. Will begin programming within the Emergency stop button. The ladder element ESTOP. This presents a programming block to utilize for our dual-channel emergency stop button. The ladder element's ESTOP operand tag is significant to that singular ladder element and should not be used anywhere else unless calling one of its sub-operands (such as Estop Button 1.FP). The Reset Type available is Manual and Automatic. The manual reset type corresponds to a 'hard' reset that must occur – coming from within the PLC.



This can be a pushbutton reset to the PLC or an internal PLC reset within the logic, at the discretion of the programmer and the application in question. The automatic reset instantly resets the ESTOP ladder elements Channel A and B are satisfactory. ESTOP ladder elements Channel A and Channel B are normally open inputs we've aliased to the IB8S input terminals 00 and 01 respectively. Circuit Reset operand requires a tag, but if the Reset Type is automatic, it is visual-only and not applied for resetting the ladder element. If the Reset Type is automatic, it is visual-only and not applied for resetting the lement for resetting the ladder element. If the Reset Type is automatic, it is visual-only and not applied for resetting the ladder element for resetting the ESTOP ladder element for months bit will reset the ESTOP ladder element for resetting the inputs described in the ISTOP ladder element for resetting the inputs be set to ESTOP between the ESTOP ladder element for on. Diagram 1.8-ESTOP ladder element

The last XIO is a Boolean bit that is monitoring a flash-timer add-on instruction (AOI) for when its OTE is high. This is being utilized to always fault reset the ladder element when a fault is actively present and both emergency stop channels are okay. If you want to learn more about add-on instructions, you can read this introductory tutorial. Next, we will add another rung, rung 3. On this rung, we will generate a safety circuit for the product for our control system. On rung 3 we have the following ladder elements output. The first XIO will reference the following ladder rung. The first XIO will reference the following ladder rung. The first XIO will reference the following ladder rung. The first XIO will reference the following ladder rung. The first XIO will reference the following ladder rung. The first XIO will reference the following ladder rung. The first XIO will reference the following ladder rung. The first XIO will reference the following ladder our rung as feety for the work of the will pass the rung circuit through to the OTE. This sets the OTE, the modules are clear of faults and actively running the not XIC will pass the rung circuit through to the OTE. This sets the OTE, the modules are clear of faults and actively running the not XIC will pass the rung circuit through the four faults are clear of faults and actively running the not XIC will pass the rung circuit through the other XIC will pass the rung circuit through the other XIC will pass the rung circuit through the four faults are clear of faults and actively running the not XIC will pass the rung circuit through the four faults are clear of faults and actively running the not XIC will pass the rung circuit through the four faults are clear of faults and actively running the not XIC will pass the rung circuit through the OTE. This set the OTE, the fault is to perate the fault of the rung circuit through the fault is to perate the fault of the rung circuit through the fault of the rung circuit through the fault is to perate the fault wil