

Methods to represent the interface conditions during austenite to ferrite transformation

John Ågren Dept of Materials Science and Engineering Royal Institute of Technology S-100 44 Stockholm

**Ackowledgement:**

**Joakim Odqvist, Henrik Larsson, Klara Grönhagen Annika Borgenstam, Lars Höglund, Gerhard Inden Mats Hillert**



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## 1. The issue

- We want to predict the rate of phase transformations (e.g. austenite -> ferrite)
- We want to calculate the rate from quantities which are "easily" accesible.
- We want to tackle "real" problems.
- Conditions for rapid transformation?



# The mode of transformation?

- •• Partitional – composition change
	- Partitional for all elements (very slow)
	- Non partitional for substitutional elements (rapid)
- •• Non partitional for all elements
	- Massive (very rapid)
	- Martensitic (very-very rapid)
- •• Change in mode
	- Change in rate
	- Change in morphology



# Rate controlling mechanisms

- Diffusior
	- in bulk
	- along grain boundaries and interfaces
	- across interfaces (trans-interface) solute drag
- Interface migration finite mobility
- •• Mixed mode (bulk-diffusion and interface mobility)



## Modeling of the local state of phase interface

- ¾ Sharp interface no thickness
- $\triangleright$  Finite interface thickness

continuous variation in properties

 $\triangleright$  Diffuse interface

no sharp boundary between interface and bulk (phase-field method)

 $\triangleright$  No interface

Only bulk properties are used, i.e. not even an operating interfacial tieline calculated.



### 2. Sharp interface (Stefan Problem)

Transport equations in each phase solved. In an *N* component system *N* extra conditions are needed at phase interface.

- -- Local equilibriun
- -Para equilibrium
- Interface kinetics



#### Local equilibrium





### Local equilibrium non partitioning (LENP) Ternary system Fe-M-C



"Quasi-paraequilibrium" (LENP)



#### Para equilibrium

 $f^{}_{2} = \mu^{\alpha}_{C}(u^{\alpha}_{C}, u^{\alpha}_{M}, T) - \mu^{\gamma}_{C}(u^{\gamma}_{C}, u^{\gamma}_{M}, T) = 0$  $f_1 = \mu_X^{\alpha}(u_C^{\alpha}, u_M, T) - \mu_X^{\gamma}(u_C^{\gamma}, u_M, T) = 0$  $X = F e_{_{(1-u_M)}} M_{_{u_M}} \Rightarrow \mu_{_X} = (1 - u_{_M}) \mu_{_{Fe}} + u_{_M} \mu_{_M}$  $X - C$  (2 effective components)  $N = 2$  $u_M = u_M^{\cdot \cdot} = u_M^{\cdot \cdot}$  $\mu_C^{\alpha}(u_C^{\alpha},u_M^{\alpha},T)-\mu_C^{\gamma}(u_C^{\gamma},u_M^{\gamma})$  $\mu^{\alpha}_\chi(u^{\alpha}_C,u_{_M},T)$  –  $\mu^{\gamma}_\chi(u^{\gamma}_C)$  $\alpha$   $\alpha$ 







LENP and PARA equilibrium very powerful methods because...

- Only involve bulk thermodynamic properties.
- Thermodynamic extremes. Truth in between?
- No information on interface needed.





From G. Inden 2008



## Transition para to LENP

• Thickness of alloy element spike



- Early stages high growth rate: PARA
- Later stages lower rates change to LENP.





G. Inden 2008



#### Interface kinetics

- The driving force across the interface is consumed by two independent processes:
	- - Transformation of crystalline lattice (finite interface mobility)
	- - Change in composition by transinterface diffusion

The processes are assumed independent and thus each needs a positive driving force.

$$
f_k = \mu_k^{\alpha} - \mu_k^{\gamma} - (\Delta \mu_k^{cryst} + \Delta \mu_k^{trans}) = 0
$$



#### Example: substitutional system *A - B*

Transinterface diffusion and finite interface mobility yields:

$$
\Delta\mu_A = \frac{v}{V_m} \left[ \frac{V_m^2}{M} + \frac{x_B^{\gamma/\alpha}}{L_{BB}} \left( x_B^{\gamma/\alpha} - x_B^{\alpha} \right) \right] > 0
$$

$$
\Delta \mu_B = \frac{v}{V_m} \left[ \frac{V_m^2}{M} - \frac{(1 - x_B^{\gamma/\alpha})}{L_{BB}} \left( x_B^{\gamma/\alpha} - x_B^{\alpha} \right) \right]
$$

 $\varDelta \mu_A$  and  $\varDelta \mu_B$  are functions of the compositior on each side of the interface and may be described by suitable thermodynamic models of the  $\gamma$  and  $\alpha$ phase, respectively.



For a given interface velocity the equations may be solved to yield the composition on each side of interface.





## Aziz model (1982)

Similar as the previous sharp interface models but:

$$
-J_A^t = J_B^t = -\frac{D^i}{V_m f^\alpha} (a_B^{\gamma/\alpha} - a_B^\alpha)/\lambda
$$

where

 $\lambda$  : Thickness of interface  $\alpha$  $a_{B}^{\gamma/\alpha}$  and  $a_{B}^{\alpha}$  : B activity on  $\gamma$  and  $\alpha$  side of interface  $^\alpha$  : activity coefficient in  $\alpha,\,D^\iota$  :  $f^\alpha$  : activity coefficient in  $\alpha,$   $D^i$  : diffusivity in interface

Assuming activity coefficients constant one finds:

$$
k_B^{\alpha/\gamma} = \frac{\beta + {}^{eq}k_B^{\alpha/\gamma}}{\beta+1} \quad \beta = \frac{\nu}{D^i / \lambda}
$$



"Sharp" interface with with representative composition (Ågren 1989)

$$
-J_A^{trans} = J_B^{trans} = -L_{BB}\Delta(\mu_B - \mu_A) = \frac{v}{V_m} (x_B^i - x_B^\alpha)
$$
  
\n
$$
\Rightarrow \Delta G_m^{trans} = -\left(x_B^i - x_B^\alpha\right)\Delta(\mu_B - \mu_A)
$$
  
\n
$$
\Delta G_m^{cryst} = x_A^i \Delta \mu_A + x_B^i \Delta \mu_B
$$
  
\n
$$
\Delta \mu_A = \frac{v}{V_m} \left[ \frac{V_m^2}{M} + \frac{x_B^i}{L_{BB}} \left( x_B^i - x_B^\alpha \right) \right]
$$

$$
\Delta \mu_B = \frac{v}{V_m} \left[ \frac{V_m^2}{M} - \frac{(1 - x_B^i)}{L_{BB}} \left( x_B^i - x_B^\alpha \right) \right]
$$

*BB*

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α *B*



#### Limit for partitionless transformation



Jönsson and Ågren 1990

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### 3. Finite interface thickness

Diffusion inside the interface  $\rightarrow$  solute drag Property



 **Solute drag theory** (Cahn, Hillert and Sundman, Brechet and Purdy)

Distance *y*



 $\bullet$ Solution of steady state equation inside interface.

$$
-J_A^t = J_B^t = -L_{BB} \frac{\partial(\mu_B - \mu_A)}{\partial y} = \frac{v}{V_m} (x_B - x_B^{\alpha})
$$

 $x_B^{\alpha}(y)$ . A specific model yields  $(\mu_B - \mu_A) = f(y, x_B)$ .  $\nu$  and  $x_B^$ α For given  $v$  and  $x^{\alpha}_{\scriptscriptstyle{B}}$  we may thus calculate

•Integration of dissipation over interface:

$$
\Delta G_m = -\frac{V_m}{v} \int_{\delta} J_B^t \frac{d(\mu_B - \mu_A)}{dy} dy + \frac{v}{M} V_m
$$

 $\bullet$ Total driving force

$$
\Delta G_m^{tot} = \sum_{k=1}^n x_k^{int} (\mu_k^{\gamma} - \mu_k^{\alpha})
$$



#### Driving force = Dissipation:



The compositions on each side of the phase interface depend on interface velocity and they approach each other.

$$
u_B^{\alpha} = f(T, v) \to u_B^{\alpha eq} \text{ as } v \to 0
$$
  

$$
u_B^{\gamma} = g(T, v) \to u_B^{\gamma eq} \text{ as } v \to 0
$$

Above a critical velocity trans formation turns partitionless.





Maximum possible growth rate for alloy 1



#### Fe-Ni-CThe interfacial tieline depends on the growth rate. (Odqvist et al. 2002)



- At high growth rates the state is close to paraequilibrium.
- At slower rates there is a gradual change towards NPLE.
- For each alloy composition there is a maximum size which can be reached under non-partitioning conditions.
- This size may be reached before there is carbon impingement. See also Srolovitz 2002.



#### Ferrite formation under "practical" conditions in Fe-Ni-C (Oi et al. 2000)1200°C - 5min

Thickness of M spike in  $\gamma$ :

*DM / v.*

Local equilibrium, i.e. quasi paraequilibrium impossible if *DM / v <* atomic dimensions.

$$
\begin{array}{|c|c|}\n\hline\nv = 4.8 \, 10^{-7} \, \text{ms}^{-1} \\
\hline\nD_M / v = 3.5 \, 10^{-14} \, \text{m}\n\end{array}
$$







Calculated limit of the massive transformation in Fe-Ni alloys (dashed lines) calculated for two different assumptions on properties of interface.

(Odqvist et al. 2002)

Exp: Borgenstam and Hillert 2000











- Larsson and Borgenstam analyzed the critical limit for the massive transformation in Fe-Ni and found
	- high diffusivity across phase interface displaces critical limit towards onephase field.
	- High interface mobility displaces critical limit towards To.

These results are in agreement with Jönssons analysis.





# 4. Diffuse interfaces – phase-field method

- •Some properties of interface modelled.
- Solution of a diffusion equation to obtain concentreation profile.
- Cahn-Allen equation plays a similar role as the equation for interfacial friction.

But: Thickness of interface must be treated not only as a numerical parameter but as a physical quatity.



### Example: Formation of WS-ferrite in steels



#### Loginova et al. 2004

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Loginova et al. 2004



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## 5. No Interface at all

Svoboda et al. 2004 (by Onsager extremum principle) Ågren et al. 1997 (from other principles)

$$
\frac{d\Re}{dt} = \frac{1}{\Re} M_{\text{eff}} \left( \sum_{i=1}^{C} x_i^{\beta} \mu_i^{\alpha} - G_m^{\beta} \frac{2 \sigma V_m^{\beta}}{\Re} - \frac{\dot{\Re}}{M} V_m \right)
$$

where

$$
M_{\text{eff}} = \frac{1}{\sum_{i=1}^{C} (x_i^{\beta} - x_i^{\alpha})^2}
$$



- Very efficient method quite simple calculations.
- No details about the phase interface.
- Satisfactory accuracy for low supersaturation, less good for high.



## 6. Conclusions

- Sharp interface methods are computationally simple but may show problems with convergency.
- Solute drag models may be better than sharp interface models but have similar convergency problems.
- Larsson-Hillert method very promising
- • Phase-field approach very powerful – no convergency problems – heavy computations.
- No-interface methods quick calculations, limited accuracy.