

Methods to represent the interface conditions during austenite to ferrite transformation

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Content

- 1. The issue
- 2. Sharp interface
 - LENP
 - PARA
 - Interface kinetics
- 3. Finite thickness interface
 - Solute drag theories
 - Larsson-Hillert
- 4. Diffuse interface
 - Phase field
- 5. No interface at all
- 6. Conclusions



1. The issue

- We want to predict the rate of phase transformations (e.g. austenite -> ferrite)
- We want to calculate the rate from quantities which are "easily" accesible.
- We want to tackle "real" problems.
- Conditions for rapid transformation?



The mode of transformation?

- Partitional composition change
 - Partitional for all elements (very slow)
 - Non partitional for substitutional elements (rapid)
- Non partitional for all elements
 - Massive (very rapid)
 - Martensitic (very-very rapid)
- Change in mode
 - Change in rate
 - Change in morphology



Rate controlling mechanisms

- Diffusion
 - in bulk
 - along grain boundaries and interfaces
 - across interfaces (trans-interface) solute drag
- Interface migration finite mobility
- Mixed mode (bulk-diffusion and interface mobility)



Modeling of the local state of phase interface

- Sharp interface no thickness
- Finite interface thickness

continuous variation in properties

Diffuse interface

no sharp boundary between interface and bulk (phase-field method)

No interface

Only bulk properties are used, i.e. not even an operating interfacial tieline calculated.



2. Sharp interface (Stefan Problem)

Transport equations in each phase solved. In an *N* component system *N* extra conditions are needed at phase interface.

- Local equilibrium
- Para equilibrium
- Interface kinetics



Local equilibrium





Local equilibrium non partitioning (LENP) Ternary system Fe-M-C



"Quasi-paraequilibrium" (LENP)



Para equilibrium

 $u_{M} = u_{M}^{\alpha} = u_{M}^{\gamma}$ $X - C \quad (2 \text{ effective components}) \ N = 2$ $X = Fe_{(1-u_{M})}M_{u_{M}} \Longrightarrow \mu_{X} = (1-u_{M})\mu_{Fe} + u_{M}\mu_{M}$ $f_{1} = \mu_{X}^{\alpha}(u_{C}^{\alpha}, u_{M}, T) - \mu_{X}^{\gamma}(u_{C}^{\gamma}, u_{M}, T) = 0$ $f_{2} = \mu_{C}^{\alpha}(u_{C}^{\alpha}, u_{M}^{\alpha}, T) - \mu_{C}^{\gamma}(u_{C}^{\gamma}, u_{M}^{\gamma}, T) = 0$







LENP and PARA equilibrium very powerful methods because...

- Only involve bulk thermodynamic properties.
- Thermodynamic extremes. Truth in between?
- No information on interface needed.





From G. Inden 2008



Transition para to LENP

• Thickness of alloy element spike



- Early stages high growth rate: PARA
- Later stages lower rates change to LENP.





G. Inden 2008



Interface kinetics

- The driving force across the interface is consumed by two independent processes:
 - Transformation of crystalline lattice (finite interface mobility)
 - Change in composition by transinterface diffusion

The processes are assumed independent and thus each needs a positive driving force.

$$f_k = \mu_k^{\alpha} - \mu_k^{\gamma} - (\Delta \mu_k^{cryst} + \Delta \mu_k^{trans}) = 0$$



Example: substitutional system A - B

Transinterface diffusion and finite interface mobility yields:

$$\Delta \mu_A = \frac{v}{V_m} \left[\frac{V_m^2}{M} + \frac{x_B^{\gamma/\alpha}}{L_{BB}} \left(x_B^{\gamma/\alpha} - x_B^{\alpha} \right) \right] > 0$$

$$\Delta \mu_B = \frac{v}{V_m} \left[\frac{V_m^2}{M} - \frac{(1 - x_B^{\gamma/\alpha})}{L_{BB}} \left(x_B^{\gamma/\alpha} - x_B^{\alpha} \right) \right]$$

 $\Delta \mu_A$ and $\Delta \mu_B$ are functions of the composition on each side of the interface and may be described by suitable thermodynamic models of the γ and α phase, respectively.



For a given interface velocity the equations may be solved to yield the composition on each side of interface.





Aziz model (1982)

Similar as the previous sharp interface models but:

$$-J_{A}^{t} = J_{B}^{t} = -\frac{D^{i}}{V_{m}f^{\alpha}}(a_{B}^{\gamma/\alpha} - a_{B}^{\alpha})/\lambda$$

where

 $a_B^{\gamma/\alpha}$ and a_B^{α} : B activity on γ and α side of interface

- f^{α} : activity coefficient in α , D^{i} : diffusivity in interface
- λ : Thickness of interface

Assuming activity coefficients constant one finds:

$$k_{B}^{\alpha/\gamma} = \frac{\beta + {}^{eq} k_{B}^{\alpha/\gamma}}{\beta + 1} \quad \beta = \frac{\nu}{D^{i}/\lambda}$$



"Sharp" interface with with representative composition (Ågren 1989)

$$-J_{A}^{trans} = J_{B}^{trans} = -L_{BB}\Delta(\mu_{B} - \mu_{A}) = \frac{v}{V_{m}} \left(x_{B}^{i} - x_{B}^{\alpha}\right)$$
$$\Rightarrow \Delta G_{m}^{trans} = -\left(x_{B}^{i} - x_{B}^{\alpha}\right)\Delta(\mu_{B} - \mu_{A})$$
$$\Delta G_{m}^{cryst} = x_{A}^{i}\Delta\mu_{A} + x_{B}^{i}\Delta\mu_{B}$$
$$\Delta\mu_{A} = \frac{v}{V_{m}} \left[\frac{V_{m}^{2}}{M} + \frac{x_{B}^{i}}{L_{BB}}\left(x_{B}^{i} - x_{B}^{\alpha}\right)\right]$$

$$\Delta \mu_{B} = \frac{v}{V_{m}} \left[\frac{V_{m}^{2}}{M} - \frac{(1 - x_{B}^{i})}{L_{BB}} \left(x_{B}^{i} - x_{B}^{\alpha} \right) \right]$$

Alemi 7, ISIJ Tokyo, March 26-28, 2008



Limit for partitionless transformation



Jönsson and Ågren 1990

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3. Finite interface thickness

Diffusion inside the interface \rightarrow solute drag Property



Solute drag theory (Cahn, Hillert and Sundman, Brechet and Purdy)

Distance *y*



• Solution of steady state equation inside interface.

$$-J_{A}^{t} = J_{B}^{t} = -L_{BB} \frac{\partial(\mu_{B} - \mu_{A})}{\partial y} = \frac{v}{V_{m}} \left(x_{B} - x_{B}^{\alpha} \right)$$

A specific model yields $(\mu_B - \mu_A) = f(y, x_B)$. For given *v* and x_B^{α} we may thus calculate $x_B^{\alpha}(y)$.

• Integration of dissipation over interface:

$$\Delta G_m = -\frac{V_m}{v} \int_{\delta} J_B^t \frac{d(\mu_B - \mu_A)}{dy} dy + \frac{v}{M} V_m$$

Total driving force

$$\Delta G_m^{tot} = \sum_{k=1}^n x_k^{int} (\mu_k^{\gamma} - \mu_k^{\alpha})$$



Driving force = Dissipation:



The compositions on each side of the phase interface depend on interface velocity and they approach each other.

$$u_B^{\alpha} = f(T, v) \to u_B^{\alpha eq} \text{ as } v \to 0$$
$$u_B^{\gamma} = g(T, v) \to u_B^{\gamma eq} \text{ as } v \to 0$$

Above a critical velocity transformation turns partitionless.





Maximum possible growth rate for alloy 1



Fe-Ni-C The interfacial tieline depends on the growth rate. (Odqvist et al. 2002)



- At high growth rates the state is close to paraequilibrium.
- At slower rates there is a gradual change towards NPLE.
- For each alloy composition there is a maximum size which can be reached under non-partitioning conditions.
- This size may be reached before there is carbon impingement. See also Srolovitz 2002.



Ferrite formation under "practical" conditions in Fe-Ni-C (Oi et al. 2000)

Thickness of M spike in γ :

 D_M / v .

Local equilibrium, i.e. quasi paraequilibrium impossible if $D_M / v <$ atomic dimensions.

$$v = 4.8 \ 10^{-7} \,\mathrm{ms}^{-1}$$

$$D_M / v = 3.5 \ 10^{-14} \,\mathrm{m}$$







Calculated limit of the massive transformation in Fe-Ni alloys (dashed lines) calculated for two different assumptions on properties of interface.

(Odqvist et al. 2002)

Exp: Borgenstam and Hillert 2000











- Larsson and Borgenstam analyzed the critical limit for the massive transformation in Fe-Ni and found
 - high diffusivity across phase interface displaces critical limit towards onephase field.
 - High interface mobility displaces critical limit towards T₀.

These results are in agreement with Jönssons analysis.





4. Diffuse interfaces – phase-field method

- Some properties of interface modelled.
- Solution of a diffusion equation to obtain concentreation profile.
- Cahn-Allen equation plays a similar role as the equation for interfacial friction.

But: Thickness of interface must be treated not only as a numerical parameter but as a physical quatity.



Example: Formation of WS-ferrite in steels



Loginova et al. 2004







Loginova et al. 2004



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5. No Interface at all

Svoboda et al. 2004 (by Onsager extremum principle) Ågren et al. 1997 (from other principles)

$$\frac{d\Re}{dt} = \frac{1}{\Re} M_{eff} \left(\sum_{i=1}^{C} x_i^{\beta} \mu_i^{\alpha} - G_m^{\beta} - \frac{2\sigma V_m^{\beta}}{\Re} - \frac{\dot{\Re}}{M} V_m \right)$$

where

$$M_{eff} = \frac{1}{\sum_{i=1}^{C} \frac{\left(x_i^{\beta} - x_i^{\alpha}\right)^2}{x_i^{\alpha} M_i}}$$



- Very efficient method quite simple calculations.
- No details about the phase interface.
- Satisfactory accuracy for low supersaturation, less good for high.



6. Conclusions

- Sharp interface methods are computationally simple but may show problems with convergency.
- Solute drag models may be better than sharp interface models but have similar convergency problems.
- Larsson-Hillert method very promising
- Phase-field approach very powerful no convergency problems heavy computations.
- No-interface methods quick calculations, limited accuracy.