# LTDARit EXPLORER R



Max Range @ Reflectivity	Laser accuracy	Point Cloud RMSE @100m	Echoes	Maximum recommended scan Height
150 m @ 20%	2cm @ 150m	2.5 cm @ 50 m	2	100 m

## High accuracy Multi-platform LiDAR system.







## Multi-purpose LiDAR system.

From canopy penetration, accuracy stockpile measurements, or underground/indoor survey to detailed surveying of the complete studies area. See point-cloud images by our user across the globe below.







#### **Platform**

#### **LiDAR Sensor**

Range: 150m (@20%)
Maximum recommended Scan Height: 100m
Maximum recommended Distance between lines: 100m
Point Cloud RMSE @ 50m: 2.5cm

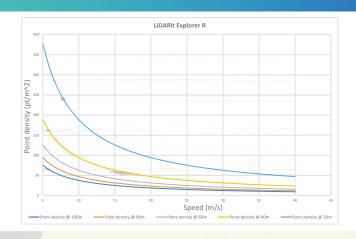
Laser: 16 Channels
Number of echoes: 2
Laser class: Class 1
Pulses: 320k/s
Field of view: 360°x30°
Rotation rate: 5Hz - 20Hz

#### Mechanical/Electrical/Operational

Voltage main port:19.5VVoltage secundary port:15-30VWeight:1600grPower Consumption:30 - 50W

### Point density at certain speed

0.09°x2.0° 71p/m²



#### **Navigation System**

Constellation support: GPS, GLONASS, BEIDOU, GALILEO Support Alignment: Static, Kinematic, dual antenna Operation mode: Real-time and postprocessing Heading accuracy (RMS  $2\sigma$ ): 0.011° IMU options GNSS accuracy (RMS  $2\sigma$ ): < 1cm Roll and Pitch accuracy (RMS  $2\sigma$ ): 0,005° Data rate: 200Hz

LiDARit Manager included
Data processing by

Resolution:

Point density at 100m:

Data processing by just two Clicks

Empower your collaborators with cloud-based processing web viewer and expert supervision.

Data processing: Automatic

**Security:** Encrypted end to end

