

Er. Vinay Kumar /  
dy. de Tutorial

OMR ANSWER SHEET JEE- Advance (Paper-2)

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INSTRUCTIONS FOR FILLING THE SHEET :-

- This sheet should not be folded or crushed.
- Use only blue/black ball point pen to fill the circles.
- Use of pencil is strictly prohibited.
- Circles should be darkened completely and properly.
- Cutting and erasing on this sheet is not allowed.
- Do not use any stray marks on the sheet.
- Do not use marker or white fluid to hide the mark.

WRONG METHODS      CORRECT METHOD

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SECTION-II

9    10    11    12    13    14

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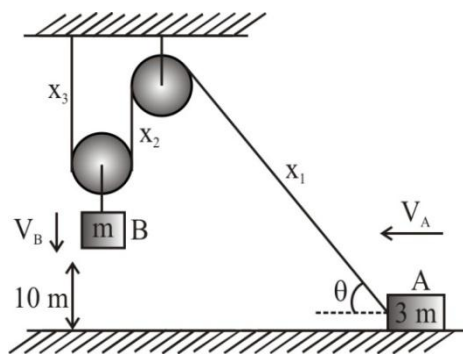
Candidate's Name : Solution

Father's Name : \_\_\_\_\_

Batch : MWF / TTS

Date : 12 01 20

Q1.



$$x_1 + x_2 + x_3 = l$$

$$-V_A \cos \theta + V_B + V_B = 0 \Rightarrow 2V_B = V_A \cos \theta$$

when the body strikes the floor :  $\theta = 60^\circ$

$$2V_B = V_A \cos 60^\circ \Rightarrow V_A = 4V_B$$

$\Rightarrow$  If  $V_B = V$  then  $V_A = 4V$

$$W = \Delta KE$$

$$\Rightarrow mg \times 10 = \left( \frac{1}{2} m V_B^2 + \frac{1}{2} (3m) V_A^2 \right) - 0$$

$$\Rightarrow m \times 0.8 \times 10 = \frac{1}{2} m v^2 + \frac{1}{2} (3m) (4v)^2$$

$$\Rightarrow 100 m = \frac{1}{2} m v^2 + \frac{48}{2} m v^2$$

$$\Rightarrow 98m = \frac{49}{2} v^2 \Rightarrow v^2 = 4 \Rightarrow v = 2m/s$$

(a)  $V_B = V = 2 m/s$

(b)  $V_A = 4V = 4 \times 2 = 8m/s$

(c)  $W_{mg} = mg \times 10 = m \times 9.8 \times 10 = 98m$

(d) work done by T force on the whole system is zero, not on the individual body.

Q2.  $U_1 = T + m_1 g$

$$250 \times 10^{-6} \times \rho_l \times 10$$

$$= T + 250 \times 10^{-6} \times 0.8 \times 10^3 \times 10 \dots\dots (1)$$

$$U_2 + T = m_2 g \Rightarrow U_2 = m_2 g - T$$

$$\Rightarrow 250 \times 10^{-6} \times \rho_l \times 10$$

$$= 250 \times 10^{-6} \times 1.2 \times 10^3 \times 10 - T \dots\dots (2)$$

Equating (1) & (2) :

$$T + 250 \times 10^{-6} \times 0.8 \times 10^3 \times 10$$

$$= 250 \times 10^{-6} \times 1.2 \times 10^3 \times 10 - T$$

$$\Rightarrow 2T = 250 \times 10^{-6} (1.2 - 0.8) \times 10^3 \times 10$$

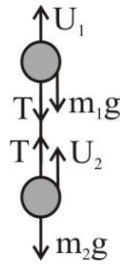
$$\Rightarrow T = 0.5 \text{ N} \dots\dots(3)$$

From eq, (1) and (3):

$$250 \times 10^{-6} \times \rho_l \times 10 = T + 250 \times 10^{-6} \times 0.8 \times 10^3 \times 10$$

$$\Rightarrow 250 \times 10^{-5} \times \rho_l = 0.5 + 2$$

$$\Rightarrow 2.5 \times 10^{-3} \times \rho_l = 2.5 \Rightarrow \rho_l = 10^3$$



Q3. Efflux velocity  $v = \sqrt{2gy} \dots\dots (1)$

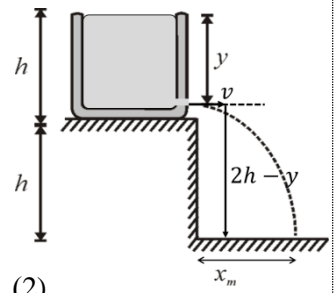
For range to be found :  $\left[ h = \frac{1}{2} g \frac{x^2}{u^2} \right]$

$$\Rightarrow (2h - y) = \frac{1}{2} g \frac{x^2}{v^2}$$

$$\Rightarrow 2h - y = \frac{1}{2} g \frac{x^2}{(2gy)}$$

$$\Rightarrow x^2 = 4y (2h - y)$$

$$\Rightarrow x^2 = 8yh - 4y^2 \dots\dots (2)$$



For x to be maximum  $\Rightarrow \frac{dx}{dy} = 0$

Differentiating eq. (2)  $\Rightarrow 2x \frac{dx}{dy} = 8h - 8y$

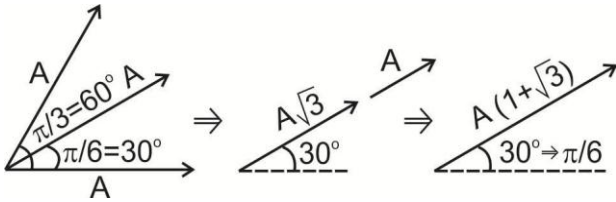
$\Rightarrow 0 = 8h - 8y \Rightarrow 8h = 8y \Rightarrow y = h$

From eq. (2)  $\Rightarrow x^2 = 8yh - 4y^2$

$\Rightarrow x_{\max}^2 = 8h.h - 4h^2 = 4h^2$

$\Rightarrow x_{\max} = 2h$

**Q4.**



Amplitude =  $A(1 + \sqrt{3})$

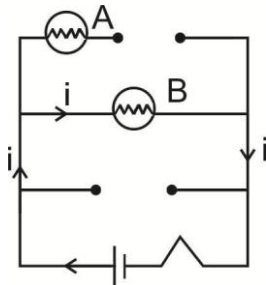
Epoch =  $\pi/6$

$v_{\max} = \omega A$

$= \omega \times A(1 + \sqrt{3}) = \omega A(1 + \sqrt{3})$

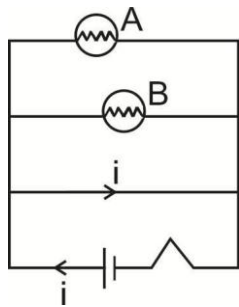
KE vibrates with double frequency  $\Rightarrow 2\omega$

**Q5.** Just at the moment the switch is connected inductance coils create insulation then the effective circuit at this moment is  $\Rightarrow$



All the current passes through B and B immediately glows.

In steady state the coils act like zero resistance  $\Rightarrow$



The whole circuit is short circuited and both the bulbs die out.

- Q7.** (a) due to symmetry the sides BC & AD experience force of same value but of opposite direction  
 (b) Force on BC is upward and on AD is downward giving clock wise rotation as seen from O during charging

**Q9.**  $T_1 = T_2 e^{\mu\theta} \Rightarrow T_1 = T_2 e^{\frac{1}{\pi}}$

$\Rightarrow T_1 = T_2 e \dots \dots \dots (1)$

$\Rightarrow T_2 = T_3 e^{\frac{1}{\pi}} \Rightarrow T_2 = T_3 e \dots \dots \dots (2)$

from (1) & (2) :  $T_1 = (T_3 e) e$

$\Rightarrow T_1 = T_3 e^2 \dots \dots \dots (3)$

for body A :  $2m \cdot 2a = 2mg - T_1$

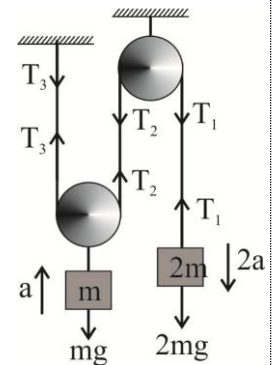
$\Rightarrow 4ma = 2mg - T_1 \dots (1)$

for body B :

$ma = (T_2 + T_3) - mg$

$\Rightarrow ma = \left( \frac{T_1}{e} + \frac{T_1}{e^2} \right) - mg$

$\Rightarrow ma = T_1 \left( \frac{e+1}{e^2} \right) - mg \dots \dots \dots (2)$



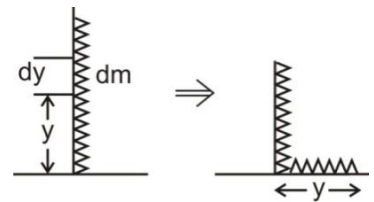
(1)  $\times \left( \frac{e+1}{e^2} \right) + (2) :$

$ma \left[ \frac{4(e+1)}{e^2} + 1 \right] = mg \left[ \frac{2(e+1)}{e^2} - 1 \right]$

$\Rightarrow a \left[ \frac{4e+4+e^2}{e^2} \right] = \left[ \frac{2e+2-e^2}{e^2} \right] g$

$\Rightarrow a = \left[ \frac{2e+2-e^2}{4e+4+e^2} \right] g \Rightarrow x=2$

**Q10.** Retarding force created on the trolley due to loading of chain



$F = v_r \frac{dm}{dt} \dots \dots (1)$

The elemental length  $dy$  is loaded after falling by a height  $y$ .

$$\text{Rate of loading } \frac{dm}{dt} = \frac{\lambda dy}{dt} \Rightarrow \frac{dm}{dt} = \lambda v$$

..... (2)

$v \Rightarrow$  velocity with which the element strikes the trolley after falling under gravity

$$\Rightarrow v^2 = 2gy \Rightarrow v = \sqrt{2gy} \quad \text{..... (3)}$$

$$\text{From (2) \& (3): } \frac{dm}{dt} = \lambda \sqrt{2gy} \quad \text{..... (4)}$$

The relative velocity of loading with respect to trolley  $\Rightarrow v$  therefore  $F = v \lambda \sqrt{2gy}$

$$\text{Retardation} = \frac{F}{m_o + m} = \frac{\lambda \sqrt{2gy} \cdot v}{m_o + \lambda y} \Rightarrow x=2$$

**Q11.** Velocity of centre of mass :

$$2mv_o = mv + m2v \Rightarrow v_o = \frac{3}{2}v$$

$$\text{in the frame of centre of mass : } \frac{3v}{2}$$

at maximum extension the bodies stop moving i.e. all the kinetic energy is converted into potential energy of extended spring

$$\frac{1}{2}kx^2 = \frac{1}{2}m\left(\frac{v}{2}\right)^2 \Rightarrow kx^2 = \frac{mv^2}{2} \Rightarrow x = v\sqrt{\frac{m}{2k}}$$

$$\Rightarrow \alpha = 2$$

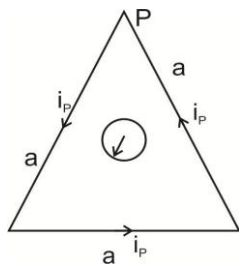
**Q12.**  $\phi_s = B_p A_s$

$$= \frac{\mu_o}{4\pi} \frac{i_p}{a} \left[ 4 \times 3 \sin \frac{180^\circ}{3} \cdot \tan \frac{180^\circ}{3} \right] \pi r^2$$

$$= \frac{\mu_o}{4\pi} \frac{i_p}{a} \left[ 12 \times \sin 60^\circ \tan 60^\circ \right] \pi r^2$$

$$= \frac{\mu_o}{4} \frac{r^2}{a} \left[ 12 \times \frac{\sqrt{3}}{2} \times \sqrt{3} \right] i_p$$

$$= \frac{\mu_o}{4} \frac{r^2}{a} [18] i_p = \left( \frac{9}{2} \mu_o \frac{r^2}{a} \right) i_p$$



$$\left. \phi_s = \left( \frac{9}{2} \mu_o \frac{r^2}{a} \right) i_p \right\} \Rightarrow M = \frac{9}{2} \mu_o \frac{r^2}{a} \Rightarrow n=9$$

also  $\phi_s = Mi_p$

**Q13.**

$$A = A_o e^{-bt} \Rightarrow \frac{A}{A_o} = e^{-bt} \Rightarrow \frac{80}{100} = e^{-5b}$$

$$\Rightarrow 0.8 = e^{-5b} \quad \text{....(1)}$$

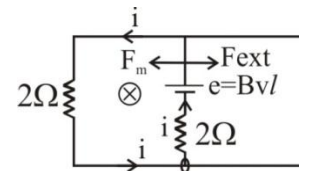
$$\frac{A}{A_o} = e^{-bt} \Rightarrow \frac{\alpha}{100} = e^{-b(5+5)} \Rightarrow \alpha = 100e^{-10b}$$

$$\Rightarrow \alpha = 100(e^{-5b})^2 \quad \text{....(2)}$$

$$\text{From eq (1) and (2): } \Rightarrow \alpha = 100(0.8)^2 \Rightarrow \alpha = 64$$

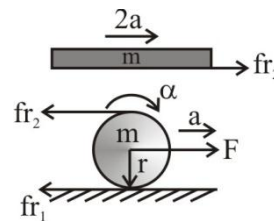
$$\text{Q14. } i = \frac{Bvl}{2+2} = \frac{2 \times 2 \times 1}{4}$$

$$= 1A$$



$$F_{ext} = Fm = ilB = 1 \times 1 \times 2 = 2N$$

**Q15.**



**For plank :**

$$m \cdot 2a = fr_2 \quad \text{..... (1)}$$

**For cylinder:**

$$ma = F - fr_1 - fr_2 \quad \text{..... (2)}$$

$$I\alpha = fr_1 r - fr_2 r \quad \text{..... (3)}$$

$$a = \alpha r \quad \text{..... (4)}$$

From (3) & (4) :

$$\frac{mr^2}{2} \times \frac{a}{r} = (fr_1 - fr_2) r \Rightarrow \frac{ma}{2} = fr_1 - fr_2 \quad \text{..... (5)}$$

(1) × 2 + (2) + (3) :

$$4ma + ma + \frac{ma}{2} = 2fr_2 + F - fr_1 - fr_2 + fr_1 - fr_2$$

$$\Rightarrow \frac{11ma}{2} = F \Rightarrow a = \frac{2F}{11m} \Rightarrow a = \frac{2F}{11 \times 2}$$

$$\Rightarrow a = \frac{F}{11}$$

$$\text{Acc. of plank } \Rightarrow 2a = 2 \times \frac{F}{11} = \frac{2F}{11}$$

$$(1) + (5): 2ma + \frac{ma}{2} = fr_1 \Rightarrow fr_1 = \frac{5ma}{2}$$

$$\Rightarrow fr_1 = \frac{5}{2}m \times \frac{2F}{11m} \Rightarrow fr_1 = \frac{5F}{11}$$

From eq. (1):

$$m \cdot 2a = fr_2$$

$$\Rightarrow m \frac{4F}{11m} = fr_2 \Rightarrow fr_2 = \frac{4F}{11}$$

**Q16.**  $p_i = p_f \Rightarrow mu = mv + m[-(v_r - v)]$

$$\Rightarrow u = v - v_r + v \Rightarrow u = 2v - v_r \dots\dots\dots (1)$$

Since the body just reaches the highest point this the case of critical circular motion, hence

velocity at top :  $v_r = \sqrt{gR} \dots\dots\dots (2)$

$$W = \Delta KE$$

$$\Rightarrow -mg2R = \frac{1}{2}mv^2 + \frac{1}{2}m(v_r - v)^2 - \frac{1}{2}mu^2$$

$$\Rightarrow -2mgR = \frac{1}{2}m[v^2 + (v_r - v)^2 - u^2]$$

$$\Rightarrow v^2 + v_r^2 - 2vv_r + v^2 - u^2 = -4gR$$

$$\Rightarrow v^2 + v_r^2 - 2vv_r + v^2 - (2v - v_r)^2 = -4gR$$

$$2v^2 + v_r^2 - 2vv_r - (4v^2 - 4vv_r + v_r^2) = -4gR$$

$$\Rightarrow 2v^2 + v_r^2 - 2vv_r - 4v^2 + 4vv_r - v_r^2 = -4gR$$

$$\Rightarrow -2v^2 + 2vv_r = -4gR \Rightarrow v^2 - vv_r = 2gR$$

$$v^2 - vv_r = 2v_r^2 \text{ (from eq. 2)}$$

$$\Rightarrow v^2 - vv_r - 2v_r^2 = 0$$

$$\Rightarrow v^2 - 2vvr + vvr - 2v^2 = 0$$

$$\Rightarrow v(v - 2v_r) + v_r(v - 2v_r) = 0$$

$$\Rightarrow (v + v_r)(v - 2v_r) = 0$$

$$\Rightarrow v = -v_r \text{ or } v = 2v_r \quad v \Rightarrow (-) \text{ is not possible}$$

hence  $v = 2v_r = 2\sqrt{gR} \dots\dots\dots (3)$

From (1), (2) & (3)

$$u = 2v - v_r = 2(2\sqrt{gR}) - \sqrt{gR} = 3\sqrt{gR}$$

Actual velocity at P :

$$-(v_r - v) = -(\sqrt{gR}) - 2\sqrt{gR} = \sqrt{gR}$$