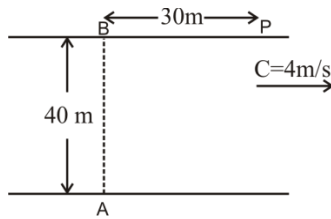


Q2.



$$x = (v \sin \theta + c) \frac{d}{v \cos \theta}$$

$$30 = (v \sin \theta + 4) \frac{40}{v \cos \theta}$$

$$\frac{3v}{4} \cos \theta = v \sin \theta + 4$$

$$v \left[\frac{3}{4} \cos \theta - \sin \theta \right] = 4 \dots \dots \dots (1)$$

$$\left[\frac{3}{4} \cos \theta - \sin \theta \right] + v \left[\frac{3}{4} (-\sin \theta) - \cos \theta \right] = 0$$

$$\frac{3}{4} (-\sin \theta) = \cos \theta$$

$$\Rightarrow \tan \theta = -\frac{4}{3}$$

$\Rightarrow \theta = -53^\circ$ (-ve sign means on left side of vertical line)

Direction from d/s $\rightarrow 90^\circ + 53^\circ = 143^\circ$

From eq. (1)

$$v_{\min} \left[\frac{3}{4} \cos (-53^\circ) - \sin (-53^\circ) \right] = 4$$

$$v_{\min} \left[\frac{3}{4} \times \left(\frac{3}{5} \right) + \frac{4}{5} \right] = 4 \Rightarrow v_{\min} \left[\frac{9}{20} + \frac{4}{5} \right] = 4$$

$$\Rightarrow v_{\min} \left[\frac{5}{4} \right] = 4 \Rightarrow v_{\min} = \frac{16}{5} \text{ m/s}$$

Q3. $y = 2x^2 - 4x$

$$\frac{dy}{dt} = 4x \frac{dx}{dt} - 4 \frac{dx}{dt} \Rightarrow v_y = 4xv_x - 4v_x$$

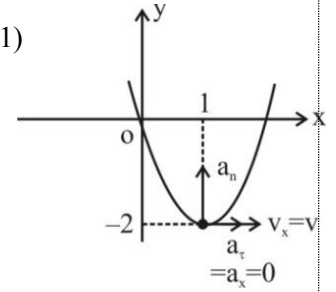
$$\Rightarrow v_y = 4v_x(x-1) \dots (1)$$

at vertex

$$x = 1$$

$$y = -2$$

$$\Rightarrow v_x = v, v_y = 0$$



(as velocity can be tangential only)

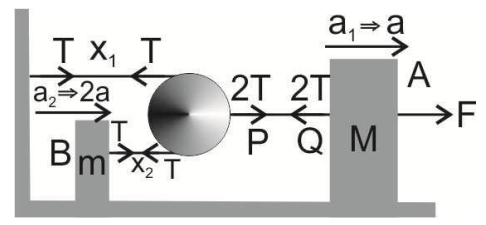
$$a_r = a_x = 0 \text{ (as } v_x = v \text{ is constant)}$$

$$\Rightarrow \frac{dv_y}{dt} = 4 \left[v_x \left(\frac{dx}{dt} \right) + (x-1)a_x \right]$$

$$\Rightarrow a_y = 4 \left[v_x^2 + (x-1)a_x \right] \dots \dots \dots (2)$$

at $x = 1, a_y = 4v_x^2 = 4v^2$

Q4. $x_1 + x_2 = l$



$$a_1 + (a_1 - a_2) = 0$$

$$2a_1 = a_2 \Rightarrow \text{if } a_1 = a$$

$$\text{then } a_2 = 2a$$

$$Ma = F - 2T \dots \dots \dots (1)$$

$$m_2a = T \dots \dots \dots (2)$$

$$(1) + (2) \times 2: Ma + 3ma = F \Rightarrow a = F / (M + 4m)$$

$$a_2 = 2a = 2F / (M + 4m)$$

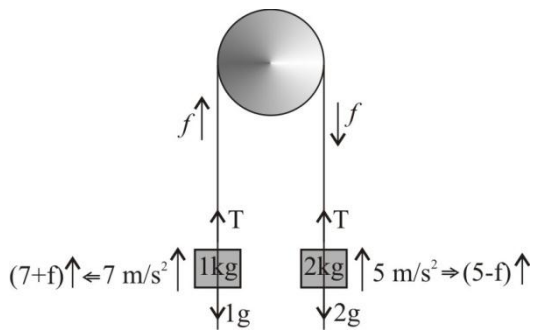
from eq. (2) $m \times \frac{2F}{(M + 4m)} = T$

$$\Rightarrow T = 2mF / (M + 4m)$$

Tension in connector $\Rightarrow 2T = 4mF / (M + 4m)$

Q5. $2(5 - f) = T - 2g \dots \dots \dots (1)$

$$1(7 + f) = T - 1g \dots \dots \dots (2)$$



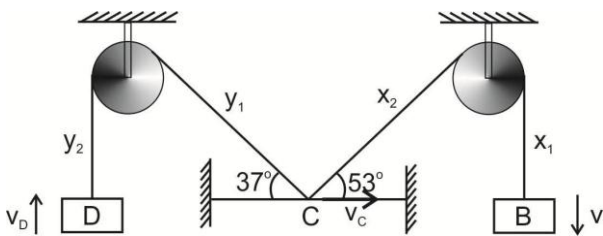
(1) - (2) : $3 - 3f = -g \Rightarrow 3 - 3f = -10$
 $\Rightarrow 3f = 13 \Rightarrow f = \frac{13}{3} \Rightarrow f = 4.3 \text{ m/s}^2$

acc. of 1 kg body :
 $\Rightarrow 7 + f = 7 + 4.3 = 11.3 \text{ m/s}^2$

acc. of 2 kg body :
 $\Rightarrow 5 - f = 5 - 4.3 = 0.7 \text{ m/s}^2$

from eq. (1) : $2(5 - 4.3) = T - 2 \times 10$
 $\Rightarrow 1.4 = T - 20 \Rightarrow T = 21.4 \text{ N}$

Q6.



$x_1 + x_2 = l$

$\Rightarrow v - v_C \cos 53^\circ = 0$

$\Rightarrow v - v_C \frac{3}{5} = 0$

$\Rightarrow v_C = \frac{5}{3}v \dots\dots (1)$

$y_1 + y_2 = l_2$

$\Rightarrow v_C \cos 37^\circ - v_D = 0$

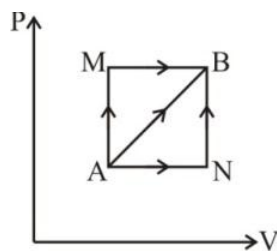
$\Rightarrow v_C \frac{4}{5} = v_D \Rightarrow v_C = \frac{5}{4}v_D \dots\dots (2)$

Equating (1) & (2) $\Rightarrow \frac{5}{3}v = \frac{5}{4}v_D$

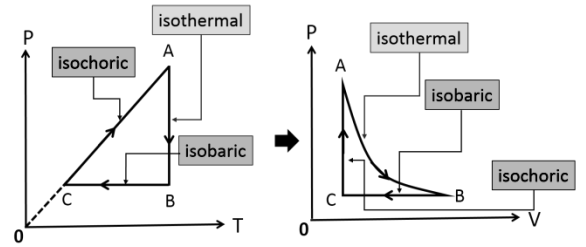
$\Rightarrow v_D = \frac{4}{3}v$

Q7.

In all the processes ΔU is same as initial & final states are same as $Q = \Delta U + W$ therefore Q depends only on W. $W_{AMB} > W_{AB} > W_{ANB}$ as area of AMB process is greater than process AB which is greater than process ANB, hence $Q_1 > Q_2 > Q_3$



Q8.



Q9.

T	Error = $T - T_{mean}$	Error = ΔT
0.52	0.52 ~ 0.58	0.06
0.58	0.56 ~ 0.58	0.02
0.62	0.57 ~ 0.58	0.01
0.58	0.54 ~ 0.58	0.04
0.60	0.59 ~ 0.58	0.01

$T_{mean} = \frac{0.52 + 0.58 + 0.62 + 0.58 + 0.60}{5} = \frac{2.90}{5} = 0.58$

Error = ΔT
0.06
0.02
0.01
0.04
0.01

$\Delta T_{mean} = \frac{0.06 + 0.02 + 0.01 + 0.04 + 0.01}{5} = \frac{0.14}{5} = 0.028 \approx 0.03$

% Error in T = $\frac{\Delta T_{mean}}{T_{mean}} \times 100 = \frac{0.03}{0.58} \times 100 = 5.17\%$

For % error in measurement of g \Rightarrow

$T = 2\pi \sqrt{\frac{3(l-r)}{5g}} \Rightarrow T \propto \sqrt{\frac{(l-r)}{g}} \Rightarrow T^2 \propto \frac{(l-r)}{g}$

$\Rightarrow g \propto \frac{(l-r)}{T^2} \Rightarrow \frac{\Delta g}{g} = \frac{\Delta(l-r)}{(l-r)} - 2 \frac{\Delta T}{T}$

$\Rightarrow \frac{\Delta g}{g} = \frac{(\Delta l - \Delta r)}{(l-r)} - 2 \frac{\Delta T}{T}$

maximum error $\Rightarrow \frac{\Delta g}{g} = \frac{(\Delta l + \Delta r)}{(l-r)} + 2 \frac{\Delta T}{T}$

$\Rightarrow \frac{\Delta g}{g} = \frac{(1+1)}{(50-10)} + 2 \times \frac{5.17}{100} \Rightarrow \frac{\Delta g}{g} = \frac{2}{40} + \frac{10.34}{100}$

$\Rightarrow \% \frac{\Delta g}{g} = \frac{2}{40} \times 100 + \frac{10.34}{100} \times 100$

$\Rightarrow \% \frac{\Delta g}{g} = 5\% + 10.34\% \Rightarrow \% \frac{\Delta g}{g} = 15.34\%$

Q10.

$P = \frac{100}{f \text{ in cm}} \Rightarrow P_o = \frac{100}{f_o} \Rightarrow 100 = \frac{100}{f_o} \Rightarrow f_o = 1 \text{ cm}$

$P_e = \frac{100}{f_e} \Rightarrow 20 = \frac{100}{f_e} \Rightarrow f_e = 5 \text{ cm}$

$$\Rightarrow M_i = m_o M_e \Rightarrow M_i = \left(\frac{f_o - v_{oi}}{f_o}\right) \left(1 + \frac{D}{f_e}\right)$$

$$\Rightarrow -50 = \left(\frac{1 - v_{oi}}{1}\right) \left(1 + \frac{25}{5}\right) \Rightarrow -50 = \left(\frac{1 - v_{oi}}{1}\right) \left(\frac{30}{5}\right)$$

$$\Rightarrow -50 = (1 - v_{oi}) \times 6 \Rightarrow -50 = 6 - 6v_{oi}$$

$$\Rightarrow 6v_{oi} = 56 \Rightarrow v_{oi} = \frac{56}{6} \Rightarrow v_{oi} = \frac{28}{3}$$

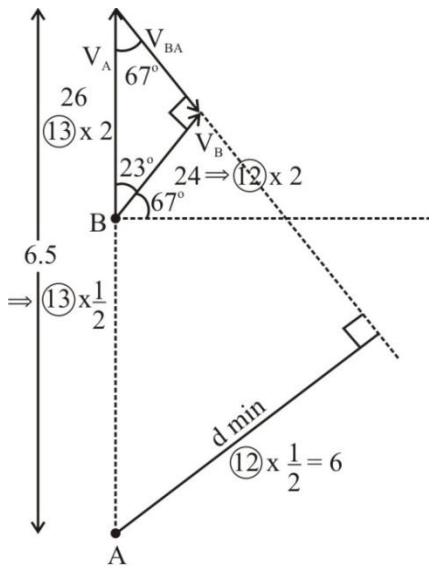
$$\Delta L = v_{of} - v_{oi} \Rightarrow -2 = v_{of} - \frac{28}{3} \Rightarrow v_{of} = \frac{28}{3} - 2$$

$$\Rightarrow v_{of} = \frac{28 - 6}{3} \Rightarrow v_{of} = \frac{22}{3}$$

$$M_f = \left(\frac{f_o - v_{of}}{f_o}\right) \left(1 + \frac{D}{f_e}\right) \Rightarrow M_f = \left(\frac{1 - \frac{22}{3}}{1}\right) \left(1 + \frac{25}{5}\right)$$

$$\Rightarrow M_f = -\frac{19}{3} \times \frac{30}{5} \Rightarrow M_f = -\frac{19}{3} \times 6 \Rightarrow M_f = -38$$

Q11.



in frame of A

Q12. $\vec{a} = \frac{d\vec{v}}{dt} = \frac{dx}{dt} \vec{i} = v_x \vec{i} = x \vec{i} \Rightarrow a = x$

$$a_r = \frac{dv}{dt} = \frac{d}{dt} \sqrt{x^2 + 1} = \frac{1}{2} \times \frac{1}{\sqrt{x^2 + 1}} \cdot 2x \frac{dx}{dt}$$

$$= \frac{xv_x}{\sqrt{x^2 + 1}} = \frac{x^2}{\sqrt{x^2 + 1}}$$

$$a_n = \sqrt{a^2 - a_r^2} = \sqrt{x^2 - \left(\frac{x^2}{\sqrt{x^2 + 1}}\right)^2} = \sqrt{x^2 - \frac{x^4}{1 + x^2}}$$

$$= \sqrt{\frac{1 + x^4 - x^4}{1 + x^2}} = \frac{1}{\sqrt{1 + x^2}}$$

$$r = \frac{v^2}{a_n} = \frac{x^2 + 1}{\frac{1}{\sqrt{1 + x^2}}} = (1 + x^2)^{3/2}$$

at $x=1$ $r = (1+1^2)^{3/2} = 2\sqrt{2}$

$$2\sqrt{a} = 2\sqrt{2} \Rightarrow a = 2$$

Q13.

$$VT^2 = \text{const.}$$

$$[PV \propto T]$$

$$\Rightarrow VP^2V^2 = \text{const} \Rightarrow P^2V^3 = \text{const}$$

$$\Rightarrow PV^{3/2} = \text{const} \Rightarrow n = 3/2$$

$$C = C_V + \frac{R}{1-n}$$

$$\Rightarrow C = \frac{R}{\gamma-1} + \frac{R}{1-n} = \frac{R}{\frac{7}{5}-1} + \frac{R}{1-\frac{3}{2}}$$

$$= \frac{R}{\frac{2}{5}} - \frac{R}{\frac{1}{2}} = \frac{5}{2}R - 2R = \frac{R}{2}$$

$$Q = \mu C \Delta T$$

$$= 2 \times \frac{R}{2} \times (200 - 100) = R \times 100$$

$$= +100 R \text{ [+ve} \Rightarrow \text{Heat given to the gas]}$$

Q14.

Let the condition be limiting: $\mu_s = 0.5$, $\mu_k = 0.4$, smooth surface

$f_{r_{max}} = \mu_s R$
 $= 0.5 \times 10g = 50N$
 $10a_1 = 70 - 50$
 $\Rightarrow a_1 = 2m/s^2$
 $50a_2 = 50$
 $\Rightarrow a_2 = 1m/s^2$
 $a_1 > a_2$
 \Rightarrow Condition is kinetic

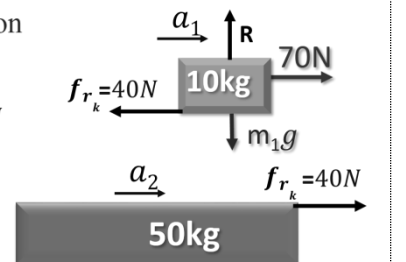
\Rightarrow for kinetic condition

$$f_r = \mu_k R$$

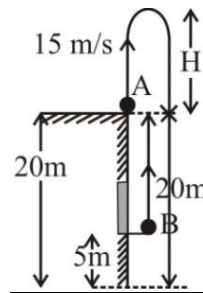
$$= 0.4 \times 10g = 40N$$

$$10a_1 = 70 - 40$$

$$\Rightarrow a_1 = 3m/s^2$$



Q15.



$$(p) s = ut + \frac{1}{2}at^2 \Rightarrow -20 = 15t + \frac{1}{2}(-10)t^2$$

$$\Rightarrow -20 = 15t - 5t^2 \Rightarrow 5t^2 - 15t - 20 = 0$$

$$\Rightarrow t^2 - 3t - 4 = 0 \Rightarrow t^2 - 4t + t - 4 = 0$$

$$\Rightarrow (t-4)(t+1) = 0 \Rightarrow t = 4 \text{ sec.}$$

(q) in frame of B

$$u_r \Rightarrow u_{AB} = 20 - 15 = 5 \text{ ms} \downarrow a_r = g - g = 0$$

$$s_r = u_r t + \frac{1}{2} a_r t^2 \Rightarrow 15 = 5 \times t \Rightarrow t = 3 \text{ sec.}$$

(r) the position of A after 3 sec.

$$s = ut + \frac{1}{2} at^2 \Rightarrow s = 15 \times 3 + \frac{1}{2} (-10) \times 3^2$$

$\Rightarrow s = 45 - 45 = 0$ i.e. at the top of building from where the body A is thrown (i.e. 20 m above the ground)

(s) distance traveled = 2H and

$$u^2 = 2gh \Rightarrow 15^2 = 2 \times 10 \times H$$

$$\Rightarrow H = \frac{15 \times 15}{20} \Rightarrow H = \frac{225}{20} = 11.25$$

distance travelled

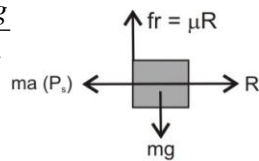
$$= H + H + 20$$

$$= 11.25 + 11.25 + 20 = 42.5$$

Q16. (a) for the system :

$$2ma = F \Rightarrow a = \frac{F}{2m} = \frac{4mg}{2m}$$

$$\Rightarrow a = 2g \dots \dots \dots (1)$$



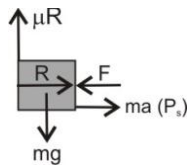
for body A : $R = ma = m2g \dots \dots \dots (2)$

$$fr = \mu R = mg \Rightarrow \mu 2mg = mg \Rightarrow \mu = \frac{1}{2}$$

(b) for the system :

$$2ma = F \Rightarrow 2ma = 4mg$$

$$\Rightarrow a = 2g \dots \dots (1)$$



for the body A

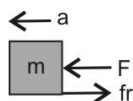
$$R + ma = F \Rightarrow R + m.2mg = 4mg$$

$$\Rightarrow R = 2mg$$

$$fr = \mu R = mg \Rightarrow \mu 2mg = ma$$

$$\Rightarrow \mu = \frac{1}{2}$$

(c) for the system : $2ma = F$



$$\Rightarrow a = F / 2m = \frac{4ma}{2m} = 2g \dots \dots \dots (1)$$

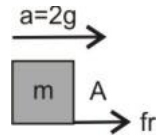
for body A : $ma = F - fr$

$$\Rightarrow m \times 2g = 4mg - fr \Rightarrow fr = 2mg$$

$$\mu R = 2mg \Rightarrow \mu \cdot mg = 2mg \Rightarrow \mu = 2$$

(d) for the system : $2ma = F$

$$\Rightarrow a = \frac{F}{2m} = \frac{4mg}{2m} = 2g \dots \dots \dots (1)$$

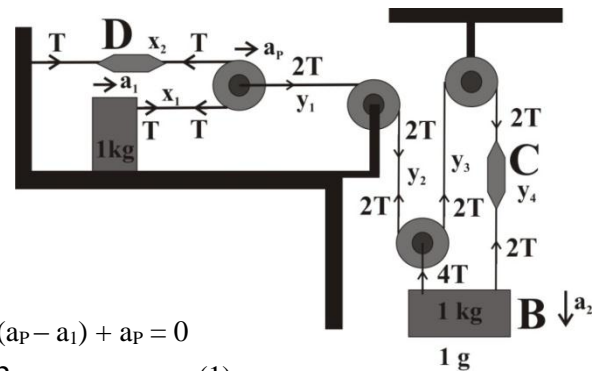


For body A :

$$ma = fr \Rightarrow m2g = fr \Rightarrow fr = 2mg$$

$$\mu R = 2mg \Rightarrow \mu mg = 2mg \Rightarrow \mu = 2$$

Q17. $x_1 + x_2 = l_1$



$$(a_p - a_1) + a_p = 0$$

$$2a_p = a_1 \dots \dots \dots (1)$$

$$y_1 + y_2 + y_3 + y_4 = l_2$$

$$a_p + a_2 + a_2 + a_2 = 0 \Rightarrow a_p = 3a_2 \dots \dots \dots (2)$$

$$\text{from (1) \& (2) : } 2(3a_2) = a_1 \Rightarrow 6a_2 = a_1 \dots \dots (3)$$

$$\text{If } a_2 = a, a_1 = 6a$$

$$\text{for body A : } 1 \times 6a = T \dots \dots \dots (4)$$

for body B :

$$1 \times a = 1g - 4T - 2T \Rightarrow a = g - 6T \dots \dots \dots (5)$$

$$(4) \times 6 + (5) : 37a = g \Rightarrow a = g / 37$$

$$\text{acc. of A : } a_1 = 6a = 6g / 37 ;$$

$$\text{acc. of B : } a_2 = a = g / 37$$

from eq. (4) :

$$6a = T \Rightarrow T = 6 \times g / 37 = 6g / 37$$

$$\text{Reading in C : } 2T = 2(6g / 37) = 12g / 37$$

$$\text{Reading in D : } T = 6g / 37$$