

$$\text{plate : } I_2 = \frac{m(\sqrt{2}r)^2}{12} + m(2r)^2$$

$$= \frac{mr^2}{6} + 4mr^2 = \frac{25}{6}mr^2$$

$$I = I_1 + I_2 = \frac{mr^2}{4} + \frac{25mr^2}{6} = \frac{53}{12}mr^2$$

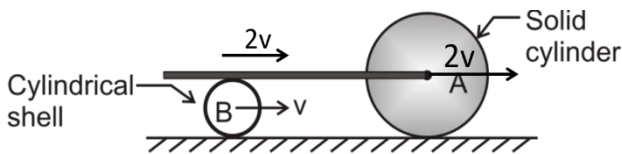
Q9. $KE_t = \frac{KE}{1 + \frac{1}{mr^2}} \Rightarrow \frac{1}{2}mv^2 = \frac{mg \left(\frac{7v^2}{10g} \right)}{\left(1 + \frac{I}{mr_2} \right)}$

$$\Rightarrow \frac{1}{2} \left(1 + \frac{I}{mr_2} \right) = \frac{7}{10}$$

$$\Rightarrow 1 + \frac{I}{mr_2} = \frac{7}{5} \Rightarrow \frac{I}{mr_2} = \frac{7}{5} - 1$$

$$\Rightarrow \frac{I}{mr_2} = \frac{2}{5} \Rightarrow \text{this object is solid sphere}$$

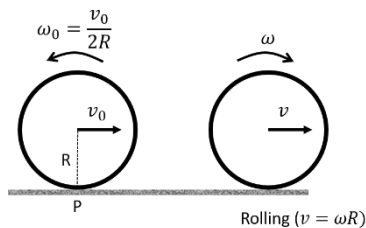
Q10. $KE = KE_A + KE_{\text{plank}} + KE_B$



$$KE = \frac{1}{2}m(2v)^2 \left[1 + \frac{1}{2} \right] + \frac{1}{2}M(2v)^2 + \frac{1}{2}mv^2(1+1)$$

$$= 3mv^2 + 2mv^2 + mv^2 = 6mv^2$$

Q11.



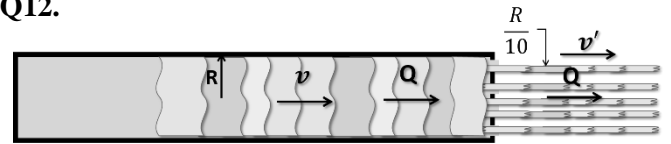
$$\tau_p = 0 \Rightarrow l_i = l_f$$

$$\Rightarrow mv_0 R - I_0 \omega_0 = mvR + I_0 \omega$$

$$\Rightarrow mv_0 R - mR^2 \frac{v_0}{2R} = mvR + mR^2 \frac{v}{R}$$

$$\Rightarrow mv_0 \frac{R}{2} = 2mvR \Rightarrow v = \frac{v_0}{4}$$

Q12.



$$\text{Flow through tube} \Rightarrow Q = \pi R^2 v \dots (1)$$

$$\text{Total flow through holes} \Rightarrow Q = 5 \times \left[\pi \left(\frac{R}{10} \right)^2 v' \right]$$

$$\Rightarrow Q = 5\pi \frac{R^2}{100} v' \Rightarrow Q = \frac{\pi R^2}{20} v' \dots (2)$$

$$\text{Equating (1) and (2): } \pi R^2 v = \frac{\pi R^2}{20} v' \\ \Rightarrow v' = 20v$$

Q13.

$$E_1 = E_2$$

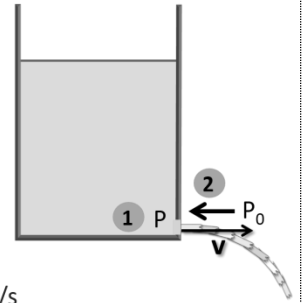
$$P = P_0 + \frac{1}{2} \rho v^2$$

$$\Rightarrow 5.5 \times 10^5$$

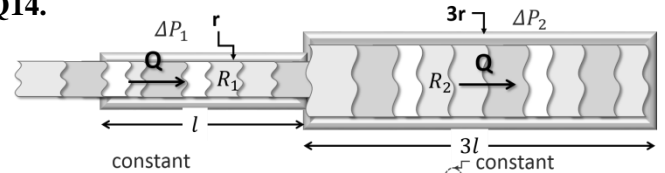
$$= 1 \times 10^5 + \frac{1}{2} \times 1000 \times v^2$$

$$\Rightarrow 4.5 \times 10^5 = \frac{1}{2} \times 1000 \times v^2$$

$$\Rightarrow v^2 = 9 \times 10^2 \Rightarrow v = 30 \text{ m/s}$$



Q14.

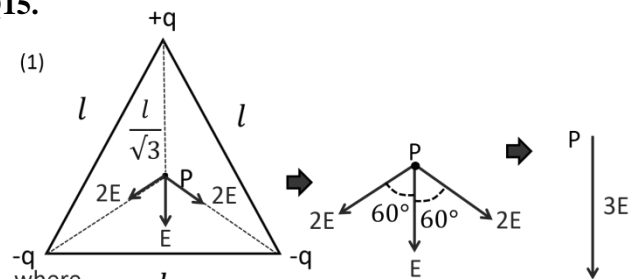


$$Q = \frac{\Delta P}{R} \Rightarrow \Delta P \propto R \Rightarrow \Delta P \propto \frac{8\eta l}{\pi r^4} \Rightarrow \Delta P \propto \frac{l}{r^4}$$

$$\Rightarrow \frac{\Delta P_1}{\Delta P_2} = \frac{l_1}{l_2} \times \left(\frac{r_2}{r_1} \right)^4 \Rightarrow \frac{\Delta P_1}{\Delta P_2} = \frac{l}{3l} \times \left(\frac{3r}{r} \right)^4 \Rightarrow \frac{\Delta P_1}{\Delta P_2} = \frac{1}{3} \times 3^4$$

$$\Rightarrow \frac{\Delta P_1}{\Delta P_2} = 27$$

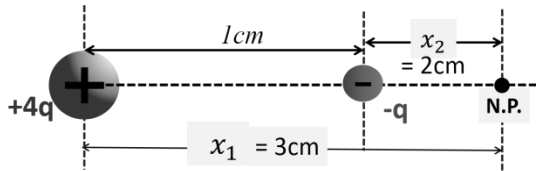
Q15.



$$\text{where } E = \frac{1}{4\pi \epsilon_0} \frac{lq}{r^2} \Rightarrow E = \frac{1}{4\pi \epsilon_0} \frac{q}{\left(\frac{l}{\sqrt{3}} \right)^2} = \frac{1}{4\pi \epsilon_0} \frac{3q}{l^2}$$

$$\text{Field intensity} = 3E = 3 \left(\frac{1}{4\pi \epsilon_0} \frac{3q}{l^2} \right) = \frac{1}{4\pi \epsilon_0} \frac{9q}{l^2}$$

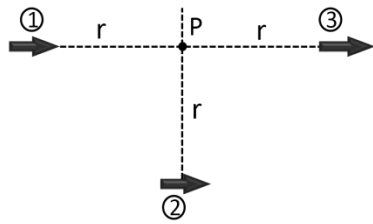
Q16.



$$x_1 = \frac{l\sqrt{q_1}}{\sqrt{q_1} + \sqrt{q_2}} \Rightarrow x_1 = \frac{1\sqrt{9q}}{\sqrt{9q} + \sqrt{4q}}$$

$$\Rightarrow x_1 = \frac{1 \times 3}{3 + 2} \Rightarrow x_1 = 3\text{cm} \Rightarrow x_2 = 3 - 1 = 2\text{cm}$$

Q17. (1)



$$V_p = V_1 + V_2 + V_3$$

$$\Rightarrow V_p = \left(+\frac{1}{4\pi\epsilon_0} \frac{p}{r^2} \right) + (0) + \left(-\frac{1}{4\pi\epsilon_0} \frac{p}{r^2} \right)$$

$$\Rightarrow V_p = 0$$

Q18.

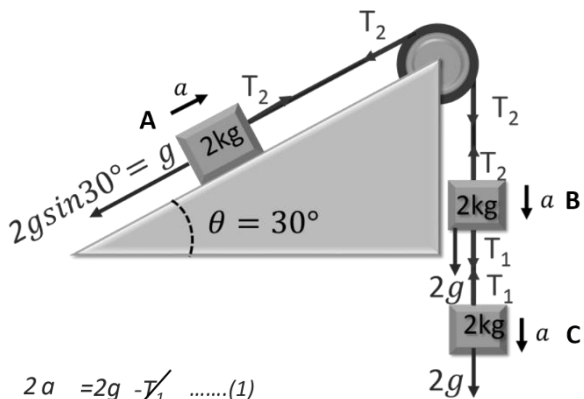
$$\vec{E} = -\left(\frac{\partial}{\partial x} i + \frac{\partial}{\partial y} j + \frac{\partial}{\partial z} k \right) (4x^2)$$

$$= -\left[\frac{\partial}{\partial x} (4x^2) i + \frac{\partial}{\partial y} (4x^2) j + \frac{\partial}{\partial z} (4x^2) k \right]$$

$$= -[8xi + 0j + 0k]$$

$$= -8xi$$

Q19.



$$2a = 2g - T_1 \dots\dots(1)$$

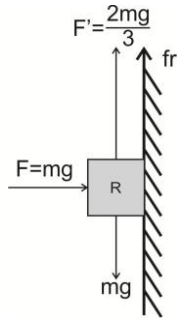
$$2a = T_1 + 2g - T_2 \dots\dots(2)$$

$$2a = T_2 - g \dots\dots(3)$$

$$\frac{6a}{3} = 3g \Rightarrow a = \frac{g}{2}$$

$$\Rightarrow a = \frac{10}{2} \Rightarrow a = 5\text{m/s}^2$$

Q20. Since $mg > F'$ in vertical direction hence there is a tendency to move the body down hence friction force will act upward to oppose the downward motion.



$$R = mg \dots\dots(1)$$

$$\mu_s R = \frac{1}{2} \times mg \dots\dots(2)$$

Action force

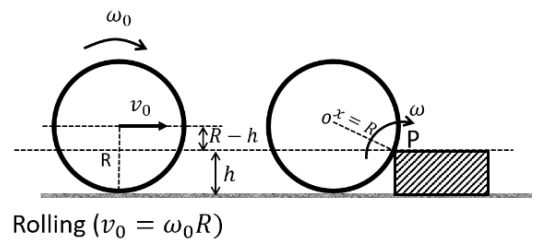
$$mg - F' = mg - \frac{2mg}{3} = \frac{mg}{3} < \mu_s R \left(= \frac{mg}{2} \right)$$

\Rightarrow static condition

\Rightarrow fr = action force

$$= \frac{mg}{3}$$

Q21.



$l_i = l_f$ about point p

$$mv_o \times (R - h) + I_o \omega_o = I_p \omega$$

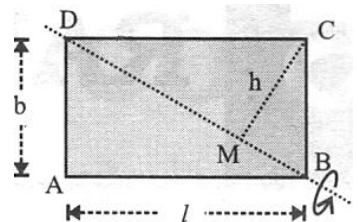
$$\Rightarrow mv_o (R - h) + \frac{2}{5} mR^2 \times \frac{v_o}{R} = \left[\frac{2}{5} mR^2 + mR^2 \right] \omega$$

$$\Rightarrow mv_o \left[R - h + \frac{2}{5} R \right] = \frac{7}{5} mR^2 \omega$$

$$\Rightarrow v_o \left[\frac{7}{5} R - h \right] = \frac{7}{5} R^2 \omega$$

$$\Rightarrow \omega = \frac{v_o \left[\frac{7}{5} R - h \right]}{\frac{7}{5} R^2} \Rightarrow \omega = \left(1 - \frac{5h}{7R} \right) \frac{v_o}{R}$$

Q22. The lamina can be considered as two joint identical triangular lamina each of height h about base DB.



$$\text{Moment of inertia of the lamina} = 2 \left[\frac{\left(\frac{m}{2}\right) h^2}{6} \right]$$

$$= \frac{mh^2}{6} \dots\dots\dots (1)$$

To find h

$$\text{Area of triangle} = \frac{1}{2} \times \text{Area of rectangle}$$

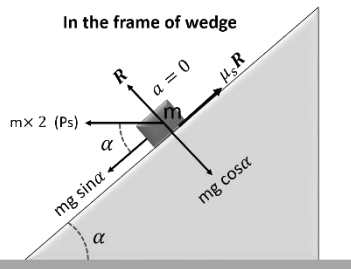
$$\Rightarrow \frac{1}{2} \times h \times DB = \frac{1}{2} \times b \times l$$

$$\Rightarrow h \times \sqrt{b^2 + l^2} = b \times l \Rightarrow h = \frac{bl}{\sqrt{b^2 + l^2}} \dots\dots(2)$$

$$\text{From (1) \& (2) } I = \frac{m}{6} \times \left(\frac{bl}{\sqrt{b^2 + l^2}} \right)^2$$

$$= \frac{mb^2l^2}{6(b^2 + l^2)} = \frac{12b^2l^2}{6(b^2 + l^2)} = \frac{2b^2l^2}{(b^2 + l^2)}$$

Q23. Since minimum value of friction force is acting hence the condition of friction becomes limiting.



Along the plan of wedge \Rightarrow

$$mg \sin \alpha + 2m \cos \alpha = \mu_s R \dots\dots(1)$$

Perpendicular to the plan of wedge \Rightarrow

$$mg \cos \alpha = R + 2m \sin \alpha$$

$$\Rightarrow R = mg \cos \alpha - 2m \sin \alpha \dots\dots(2)$$

From (1) & (2)

$$mg \sin \alpha + 2m \cos \alpha = \mu_s (mg \cos \alpha - 2m \sin \alpha)$$

Dividing equation by $\cos \alpha \Rightarrow$

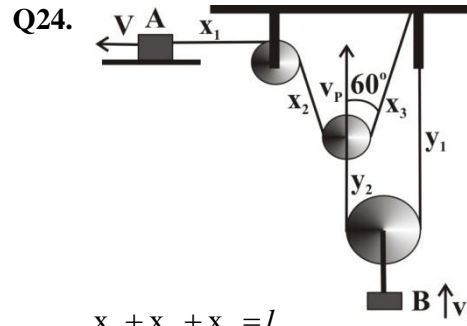
$$mg \tan \alpha + 2m = \mu_s (mg - 2m \tan \alpha)$$

$$\Rightarrow g \tan \alpha + 2 = \mu_s (g - 2 \tan \alpha)$$

$$\Rightarrow 10 \times \frac{1}{5} + 2 = \mu_s \left(10 - 2 \times \frac{1}{5} \right)$$

$$\Rightarrow 2 + 2 = \mu_s \left(\frac{50 - 2}{5} \right)$$

$$\Rightarrow 4 = \mu_s \times \frac{48}{5} \Rightarrow \mu_s = \frac{5}{12}$$



$$x_1 + x_2 + x_3 = l$$

$$v - v_P \cos 60^\circ - v_P \cos 60^\circ = 0$$

$$\Rightarrow v - \frac{v_P}{2} - \frac{v_P}{2} = 0$$

$$\Rightarrow v = v_P \dots\dots(1)$$

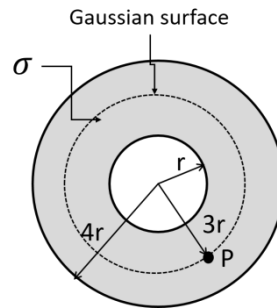
$$y_1 + y_2 = l' \Rightarrow -v_B + (v_P - v_B) = 0$$

$$\Rightarrow v_P = 2v_B \dots\dots(2)$$

from (1) & (2) : $v = 2v_B \Rightarrow v_B = v/2$

$$\Rightarrow v_B = \frac{10}{2} = 5 \text{ m/s}$$

Q25.



$$E 4\pi (3r)^2 = \frac{\left[\frac{4}{3} \pi (3r)^3 - \frac{4}{3} \pi r^3 \right]}{\epsilon_0} \rho$$

$$\Rightarrow E 4\pi \cdot 9r^2 = \frac{4}{3} \pi r^3 [27 - 1] \rho$$

$$\Rightarrow E \cdot 9 = \frac{26r}{3\epsilon_0} \rho \Rightarrow E = \frac{26\rho}{27\epsilon_0} r$$

$$30 - \beta = 27 \Rightarrow \beta = 3$$