

Q1.

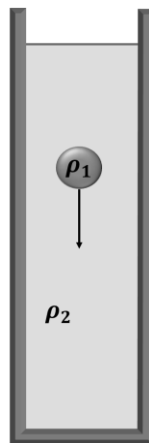
When terminal velocity appears

$$mg = F_D + U \Rightarrow V\rho_1 g = k\sqrt{v} + V\rho_2 g$$

$$\Rightarrow k\sqrt{v} = V\rho_1 g - V\rho_2 g$$

$$\Rightarrow k\sqrt{v} = V(\rho_1 - \rho_2)g \Rightarrow \sqrt{v} = \frac{V(\rho_1 - \rho_2)g}{k}$$

$$\Rightarrow v = \left[\frac{V(\rho_1 - \rho_2)g}{k} \right]^2$$



Q2. $\frac{1}{2}\rho v_1^2 = \rho g \frac{h}{2} \Rightarrow v_1^2 = gh \dots (1)$

$$\frac{1}{2}2\rho \cdot v_2^2 = \rho gh + 2\rho g \frac{h}{2}$$

$$\Rightarrow v_2^2 = 2gh \dots (2)$$

$$F = \rho v^2 A \Rightarrow F_1 = \rho v_1^2 A = \rho ghA$$

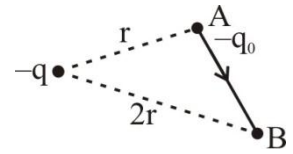
$$\Rightarrow F_2 = 2\rho v_2^2 A = 2\rho(2gh)A \Rightarrow F_2 = 4\rho ghA$$

$$F = F_1 + F_2 = \rho ghA + 4\rho ghA = 5\rho ghA \dots (3)$$

Mass of liquids = $\rho_1 V_1 + \rho_2 V_2 = \rho hA_0 + 2\rho hA_0$
 $= 3\rho hA_0$

Acceleration = $\frac{F}{M} = \frac{5\rho ghA}{3\rho hA_0} = \frac{5}{3} \frac{A}{A_0} g$

Q3. $V_A = \frac{1}{4\pi\epsilon_0} \frac{-q}{r}$
 $V_B = \frac{1}{4\pi\epsilon_0} \frac{-q}{2r}$



$$\Delta V = V_B - V_A = \frac{1}{4\pi\epsilon_0} \left[\frac{-q}{2r} - \frac{-q}{r} \right] = \frac{1}{4\pi\epsilon_0} \frac{q}{r} \left[-\frac{1}{2} + 1 \right]$$

$$= \frac{1}{4\pi\epsilon_0} \frac{q}{2r}$$

$$[W_C = -q_0 \Delta V] \Rightarrow W_C = -(-q_0) \left(\frac{1}{4\pi\epsilon_0} \frac{q}{2r} \right)$$

$$\Rightarrow W_C = \frac{1}{4\pi\epsilon_0} \frac{qq_0}{2r}$$

Q4. $F = \frac{1}{4\pi\epsilon_0} \frac{q^2}{r^2} \dots (1)$

$$F' = \frac{1}{4\pi\epsilon_0} \frac{q^2}{\left[\left(r - \frac{r}{2} \right) + \sqrt{4} \frac{r}{2} \right]^2} = \frac{1}{4\pi\epsilon_0} \frac{q^2}{\left[\frac{r}{2} + r \right]^2}$$

$$= \frac{1}{4\pi\epsilon_0} \frac{4q^2}{9r^2} \dots (2)$$

$$(2) \Rightarrow \frac{F'}{F} = \frac{4q^2/9r^2}{q^2/r^2} = \frac{4}{9} \Rightarrow F' = \frac{4}{9} F$$

Q5. For plank : $m \cdot 2a = fr_2 \dots (1)$

For cylinder $ma = F - fr_1 - fr_2 \dots (2)$

$$I\alpha = fr_1 r - fr_2 r \dots (3)$$

$$a = \alpha r \dots (4)$$

From (3) & (4) :

$$\frac{mr^2}{2} \times \frac{a}{r} = (fr_1 - fr_2) r \Rightarrow \frac{ma}{2} = fr_1 - fr_2 \dots (5)$$

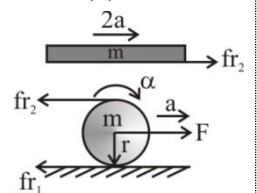
$$(1) \times 2 + (2) + (3) :$$

$$4ma + ma + \frac{ma}{2} = 2fr_2 + F - fr_1 - fr_2 + fr_1 - fr_2$$

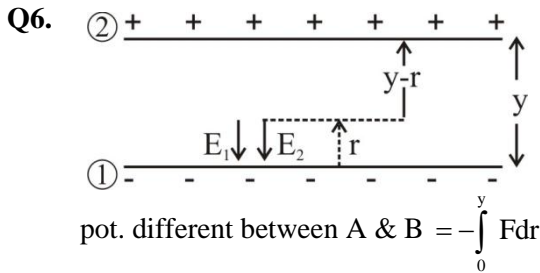
$$\Rightarrow \frac{11ma}{2} = F \Rightarrow a = \frac{2F}{11m}$$

Acc. of plank = $2a = \frac{4F}{11m}$

$$(1) + (5) : 2ma + \frac{ma}{2} = fr_1 \Rightarrow fr_1 = \frac{5ma}{2}$$



$$\Rightarrow fr_1 = \frac{5}{2}m \times \frac{2F}{11m} \Rightarrow fr_1 = \frac{5F}{11m}$$



$$E = E_1 + E_2$$

$$= \frac{1}{4\pi\epsilon_0} \left[\frac{2\lambda}{r} + \frac{2\lambda}{(y-r)} \right]$$

$$= \frac{2\lambda}{4\pi\epsilon_0} \left[\frac{1}{r} + \frac{1}{y-r} \right]$$

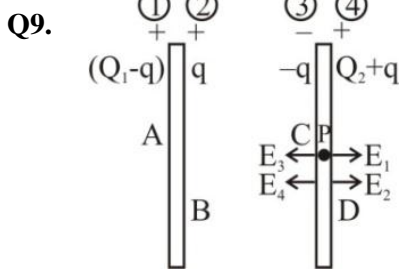
$$\Delta V = -\int_0^y \frac{2\lambda}{4\pi\epsilon_0} \left[\frac{1}{r} + \frac{1}{y-r} \right] dr$$

$$\Rightarrow = \frac{2\lambda}{4\pi\epsilon_0} [\ln r - \ln(y-r)]_0^y$$

$$= -\frac{2\lambda}{4\pi\epsilon_0} \left[\ln \left(\frac{r}{y-r} \right) \right]_0^y$$

$$= \frac{2\lambda}{4\pi\epsilon_0} \left[\ln \frac{y-r}{r} \right]_0^y = \frac{2\lambda}{4\pi\epsilon_0} \left[\ln \left(\frac{y}{r} - 1 \right) \right]_0^y$$

$$= \frac{2\lambda}{4\pi\epsilon_0} [\ln 0 - \ln \infty] \Rightarrow \text{non defined}$$



$$E_1 + E_2 = E_3 + E_4$$

$$\frac{Q_1 - q}{2\epsilon_0 A} + \frac{q}{2\epsilon_0 A} = \frac{q}{2\epsilon_0 A} + \frac{Q_2 + q}{2}$$

$$\Rightarrow Q_1 - q + q = q + Q_2 + q$$

$$2q = Q_1 - Q_2 \Rightarrow q = \frac{Q_1 - Q_2}{2}$$

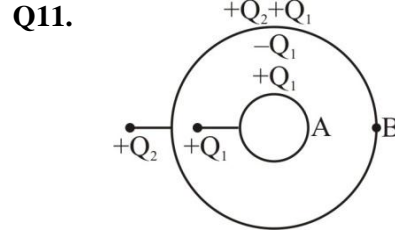
Charge on A

$$\Rightarrow Q_1 - q = Q_1 - \left(\frac{Q_1 - Q_2}{2} \right) = \frac{Q_1 + Q_2}{2}$$

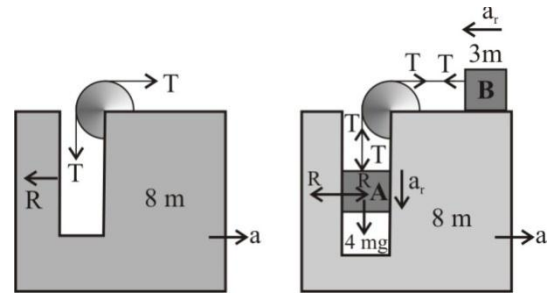
$$\text{Charge on B} \Rightarrow q = \frac{Q_1 - Q_2}{2}$$

$$\text{Charge on C} = -q = -\left(\frac{Q_1 - Q_2}{2} \right) = \frac{Q_2 - Q_1}{2}$$

$$\text{Charge on D} = Q_2 + q = Q_2 + \left(\frac{Q_1 - Q_2}{2} \right) = \frac{Q_1 + Q_2}{2}$$



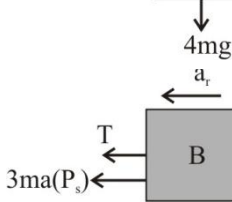
Q13.



$$8ma = T - R \dots\dots\dots(1)$$

$$4ma_r = 4mg - T \dots\dots(2)$$

$$R = 4ma \dots\dots\dots(3)$$



$$3ma_r = T + 3ma \dots\dots(4)$$

$$\text{from eq. (1) \& (3) } 8ma = T - 4ma$$

$$\Rightarrow 12ma = T \dots\dots\dots(5)$$

$$(2) \times 3 - (4) \times 4: 12ma_r = 12mg - 3T$$

$$12ma_r = 4T + 12ma$$

$$0 = -7T + 12mg - 12ma$$

$$\Rightarrow 7T = 12mg - 12ma \dots\dots\dots(6)$$

$$\text{from (5) \& (6) : } 7(12ma) = 12mg - 12ma$$

$$7a = g - a \Rightarrow 8a = g$$

$$\Rightarrow a = g/8 = 10/8 = 5/4 \text{ m/s}^2 = 1.25 \text{ m/s}^2$$

Q14. $y^2 + y - x = 0 \Rightarrow 2y \frac{dy}{dt} + \frac{dy}{dt} - \frac{dx}{dt} = 0$

$\Rightarrow 2y \cdot v_y + v_y - v_x = 0$

$\Rightarrow v_y(2y+1) = v_x \dots\dots\dots(1)$

differentiating eq. (1) with time :

$\frac{dv_y}{dt}(2y+1) + v_y \left(2 \frac{dy}{dt} \right) = \frac{dv_x}{dt}$

$\Rightarrow a_y(2y+1) + 2v_y^2 = a_x \dots\dots\dots(2)$

at (0, 0) $a_y = 0$, $a_x = 4$ from eq. (2)

$0 \times (2y+1) + 2v_y^2 = 4$

$\Rightarrow v_y^2 = 2 \Rightarrow v_y = \sqrt{2} \text{ m/s}$

from eq. (1) $v_y(2y+1) + v_x \Rightarrow$ at (0, 0)

$\sqrt{2}(2 \times 0 + 1) = v_x \Rightarrow v_x = \sqrt{2} \text{ m/s}$

$v = \sqrt{v_x^2 + v_y^2} = \sqrt{(\sqrt{2})^2 + (\sqrt{2})^2} = 2 \text{ m/s}$

Q15. $\vec{v} = \vec{u} + \vec{a}t$

$\vec{v}'_1 = \vec{v}_1 + \vec{a}t$

$\Rightarrow v_1 i - (gj)t$

$\Rightarrow v_1 i - (gt)j \dots\dots (1)$

$\vec{v}'_2 = \vec{v}_2 + \vec{a}t = -v_2 i - gt j = -v_2 i - gt j$

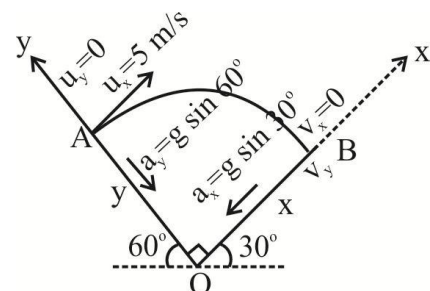
$\vec{v}'_1 \perp \vec{v}'_2 \Rightarrow (v_1 i - gt j) \cdot (-v_2 i - gt j) = 0$

$\Rightarrow -v_1 v_2 + g^2 t^2 = 0 \Rightarrow t = \sqrt{\frac{v_1 v_2}{g^2}}$

$= \frac{\sqrt{v_1 v_2}}{g}$

$t = \frac{\sqrt{20 \times 80}}{10} = \frac{\sqrt{1600}}{10} = \frac{40}{10} = 4 \text{ sec}$

Q16



$v_x = u_x + a_x t$

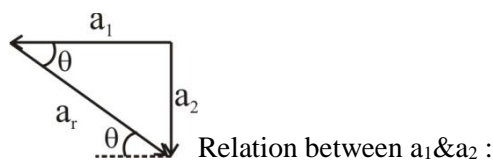
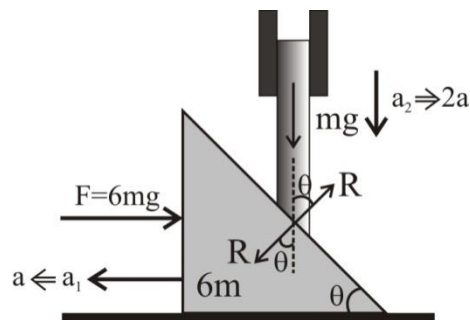
$\Rightarrow 0 = 5 - g \sin 30^\circ \times t$

$5 = 10 \times \frac{1}{2} \times t \Rightarrow t = 1 \text{ sec.}$

$y = u_y t + \frac{1}{2} a_y t^2 \Rightarrow OA = 0 + \frac{1}{2} (g \sin 60^\circ) \times 1^2$

$= \frac{1}{2} \times 10 \times \frac{\sqrt{3}}{2} = 2.5 \sqrt{3} = 4.33 \text{ m}$

Q17.



Relation between a_1 & a_2 :

$\tan \theta = \frac{a_2}{a_1}$

$\Rightarrow 2 = \frac{a_2}{a_1} \Rightarrow a_2 = 2a_1$

if $a_1 = a$ then $a_2 = 2a$

on the piston : $m2a = mg - R \cos \theta$

$\Rightarrow 2ma = mg - R \frac{1}{\sqrt{5}} \dots\dots\dots(1)$

on the wedge : $6ma_1 = R \sin \theta - 6mg$

$\Rightarrow 6ma = R \frac{2}{\sqrt{5}} - 6mg \dots\dots\dots(2)$

$(1) \times 2 + (2) : 10ma = -4mg$

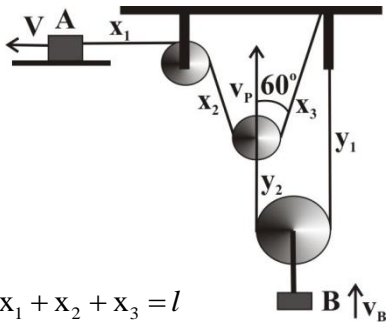
$\Rightarrow a = -\frac{4}{10} g = -\frac{4}{10} \times 10 = -4 \text{ m/s}^2$

$\Rightarrow 4 \text{ m/s}^2$ towards right

acc. of piston \Rightarrow

$= 2a = 2 \times (-4) = -8 \text{ m/s}^2 \Rightarrow 8 \text{ m/s}^2$ upward

Q18.



$$x_1 + x_2 + x_3 = l$$

$$v - v_P \cos 60^\circ - v_P \cos 60^\circ = 0$$

$$\Rightarrow v - \frac{v_P}{2} - \frac{v_P}{2} = 0$$

$$\Rightarrow v = v_P \dots (1)$$

$$y_1 + y_2 = l'$$

$$\Rightarrow -v_B + (v_P - v_B) = 0$$

$$\Rightarrow v_P = 2v_B \dots (2)$$

from (1) & (2) : $v = 2v_B$

$$\Rightarrow v_B = v/2 \Rightarrow v_B = \frac{10}{2} = 5 \text{ m/s}$$