

# Selecting a Pair of Differential and Integral Experiments that Reduce Uncertainties in Intermediate-Energy Nuclear Data

E. Christi Thompson

T. Cutler (PI), M. Devlin (PI), M. Grosskopf, D. Neudecker (PI), S. Vander Wiel

FIESTA  
November 2024

# Objectives

## What is the goal?

- Optimally select a pair of candidate LANSCE (differential) and NCERC (integral) experiments that would best reduce uncertainties in intermediate energy nuclear data (ND).
  - Particular interest in  $^{239}\text{Pu}$  from 1-600keV.
  - Concept of differential and integral data introduced later.
- A key component of understanding  $^{239}\text{Pu}$  ND from the perspective of integral data is fission data (PFNS,  $\bar{\nu}$ , and fission cross section).
  - Fission observables are key data (among most sensitive) to simulate integral data.
  - We also explore a differential fission experiment.
- Ultimately, this is an example of how to select the best experiments to understand application needs tied to fission.

# Objectives

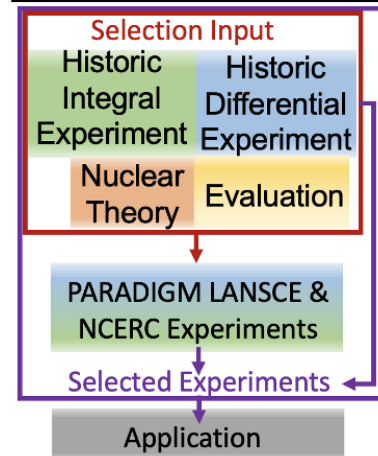
## What is the goal?

- Optimally select a pair of candidate LANSCE (differential) and NCERC (integral) experiments that would best reduce uncertainties in intermediate energy ND (particularly  $^{239}\text{Pu}$  from 1-600keV).

## How will we accomplish this?

- Combine **theory** model curves with historic **differential** and **integral** benchmark experiments to initially constrain ND.
  - Use of historic data avoids repeating existing experiments.
  - Integral experiments are maximally sensitive to  $^{239}\text{Pu}$  fission cross section.
- Compare additional improvements from candidate experiments to what has been attained through adjustments to historic data.

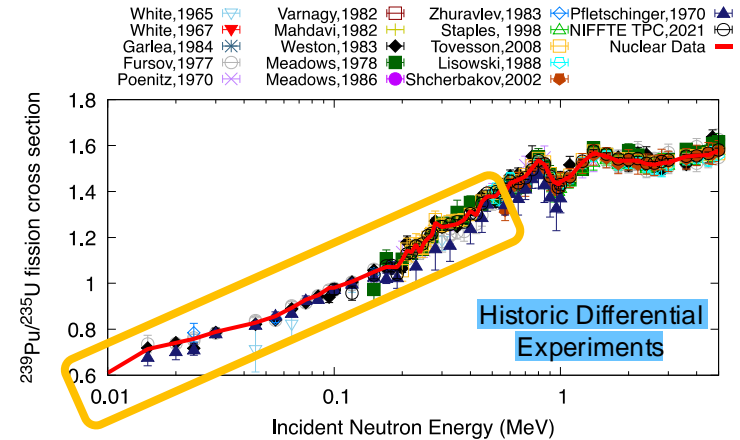
## PARADIGM process



# Intermediate-energy ND

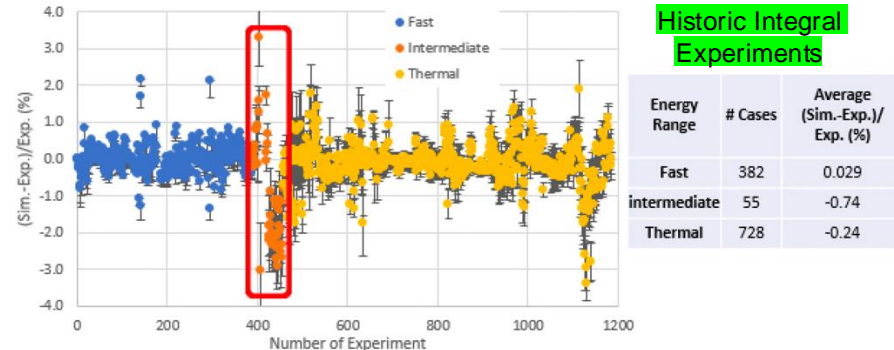
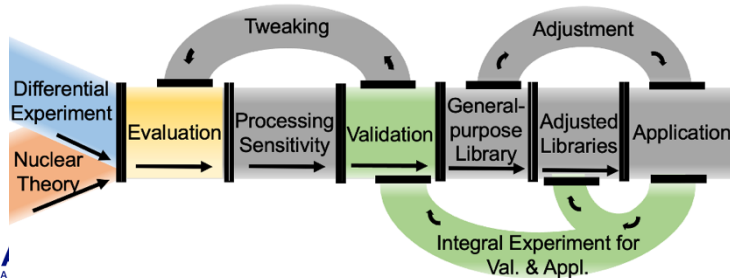
- Intermediate ND are poorly understood due to:

- **Nuclear theory:** LANL developing current model to smoothly connect between theories for the various energy ranges.
- **Differential experiments:** scarce and uncertain due to low neutron flux.
- **Integral experiments:** sensitivities to this range are sparse (only 5% of ICSBEP benchmarks).



Database from Neutron Data Standards (IAEA)

## The linear ND pipeline



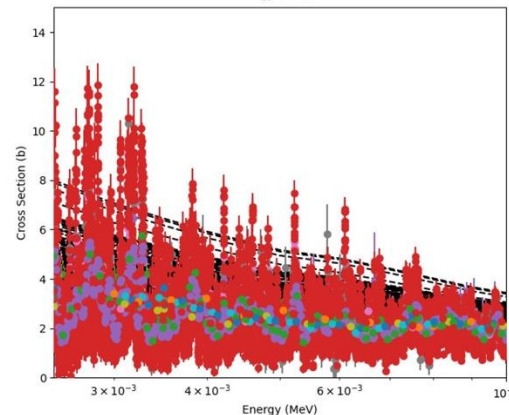
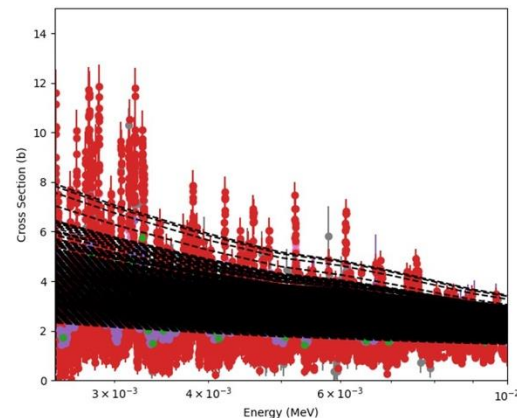
# How do we better understand the intermediate energy range?

- We are interested in performing 1-2 **integral** benchmark experiments with supporting **differential** experiment that focus on  $^{239}\text{Pu}$  from 1-600keV.
  - **Integral:** Candidate experiment designs with ZPPR Pu plates and Cu reflector are investigated by a genetic algorithm and several materials interstitials (including boron) are observed.
    - Optimized to be maximally sensitive to  $^{239}\text{Pu}$  fission cross sections from 1-600 keV.
  - **Differential:** Candidate experiments focused on reaction channels for  $^{239,240}\text{Pu}$  and  $^{63,65}\text{Cu}$  and  $^{10}\text{B}(n,\text{tot})$ .
- Consider optimistic and conservative (e.g. experiment uncertainties, contaminated beam, increased background) point of view for each candidate experiment.

# Nuclear Theory: Sampled curves via Hauser-Feshbach statistical theory

- $\text{CoH}_3$  is used to calculate average cross sections in the unresolved resonance region for  $^{239,240}\text{Pu}$  and  $^{63,65}\text{Cu}$ .
  - Reactions include total elastic, inelastic, capture, (n,2n), fission cross sections; elastic and inelastic angular distributions.
- Hauser-Feshbach statistical theory cannot provide unresolved resonance region structures.
  - Covariance is too strongly correlated, imposing strict smoothness on cross sections.

$^{239}\text{Pu}$  Fission Cross Section



# Summary of historic differential and integral experiments

- **Differential:** EXFOR database used for historic experiments.

| Nuclide           | Reactions   |
|-------------------|---|
| $^{239}\text{Pu}$ | PFNS, $\bar{\nu}$ , (n,f), (n,tot), (n,g), (n,el), (n,inl) cs |
| $^{240}\text{Pu}$ | PFNS, $\bar{\nu}$ , (n,f), (n,tot), (n,g), (n,el), (n,inl) cs |
| $^{63}\text{Cu}$  | (n,tot), (n,g), (n,p) (n,el), (n,inl) cs                      |
| $^{65}\text{Cu}$  | (n,tot), (n,g), (n,el), (n,inl) cs                            |

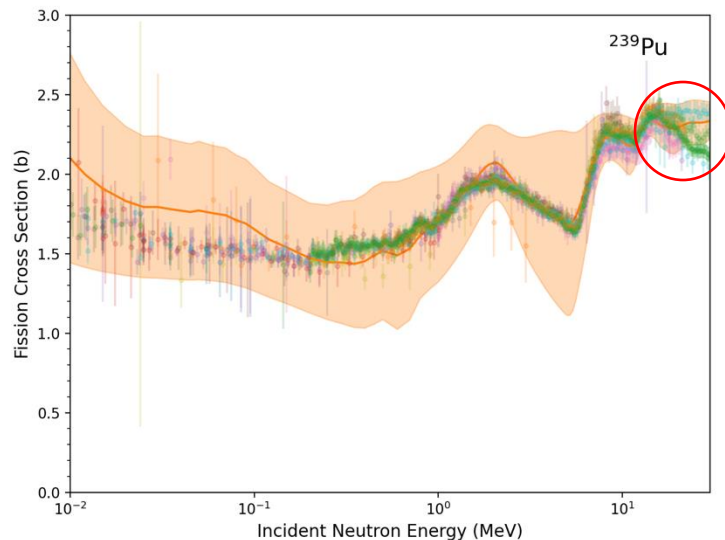
Detailed UQ is undertaken for each experiment by experts to correctly judge impact of candidate experiment vis-a-vis existing data.

- **Integral:** Whisper benchmark suite of ~1100 ICSBEP models and 30 experiments performed at NCERC used for historic experiments.

| Series        | Name   |
|---------------|--|
| HEU-MET-FAST  | 028-001, 047-001, 048-011 059-002, 072-001, 072-003, 073-001, 084-002, 084-004, 084-006, 084-007, 084-017, 085-001, 085-002, 100-002, 102-001, 104-001 |
| HEU-MET-INTER | 006-001—004, 011-001—005   |
| PU-MET-MIXED  | 002-001, 002-003, 003-001, 003-003   |
| PU-MET-INTER  | 003-001, 004-001   |
| PU-MET-FAST   | 001-001, 006-001, 024-001, 027-001, 032-001, 038-001, 047-001  |
| PU-SOL-THERM  | 011-001, 011-005, 011-008  |
| PU-COMP-MIXED | 002-005, 002-006   |
| Other         | euclid-3x2-crit, euclid-8x1-crit   |

# Challenges of the data

- Discrepancies from missing model structure and between experiments:
  - **Theory** curves do not capture true resonance structure.
  - **Differential** data often do not agree with one another within their reported uncertainties.
- High dimensional data over different energy grids:
  - **Theory/ENDF/B-VIII.0**: 12,200+ values spanning 15 nuclides.
  - **Differential**: 8,400+ observables spanning 122 experiments.
  - **Integral**: 46 experiments with sensitivities to 12,200+ ND inputs.





# Notation for model

## Initial ND quantities

- $\sigma$  = initial uncertain ND.
- $\sigma_{init}$  = mean from theory curves and ENDF/B-VIII.0.
- $V_{init}$  = covariance from theory curves and ENDF/B-VIII.0.

# Notation for model

## Initial ND quantities

- $\sigma$  = initial uncertain ND.
- $\sigma_{init}$  = mean from theory curves and ENDF/B-VIII.0.
- $V_{init}$  = covariance from theory curves and ENDF/B-VIII.0.

## Differential ND quantities

- $y_{diff}$  = differential observations.
- $\Delta$  = differential covariance.
- $L$  = linear interpolation matrix from the evaluation grid to observed data.

Added Gaussian process (GP) to  $V_{init}$  and  $\Delta$  to combat missing model structure and between experiment discrepancies.

# Notation for model

## Initial ND quantities

- $\sigma$  = initial uncertain ND.
- $\sigma_{init}$  = mean from theory curves and ENDF/B-VIII.0.
- $V_{init}$  = covariance from theory curves and ENDF/B-VIII.0.

## Differential ND quantities

- $y_{diff}$  = differential observations.
- $\Delta$  = differential covariance.
- $L$  = linear interpolation matrix from the evaluation grid to observed data.

Added Gaussian process (GP) to  $V_{init}$  and  $\Delta$  to combat missing model structure and between experiment discrepancies.

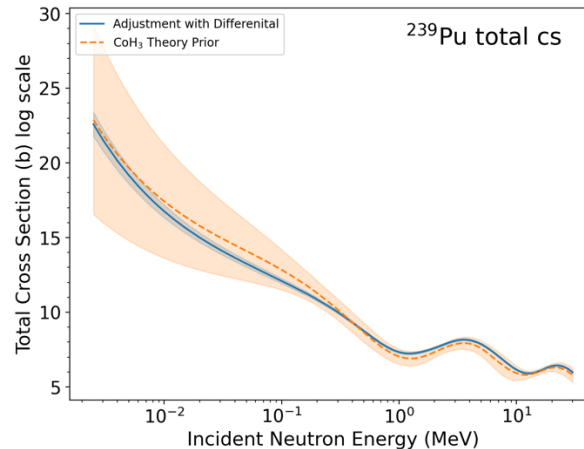
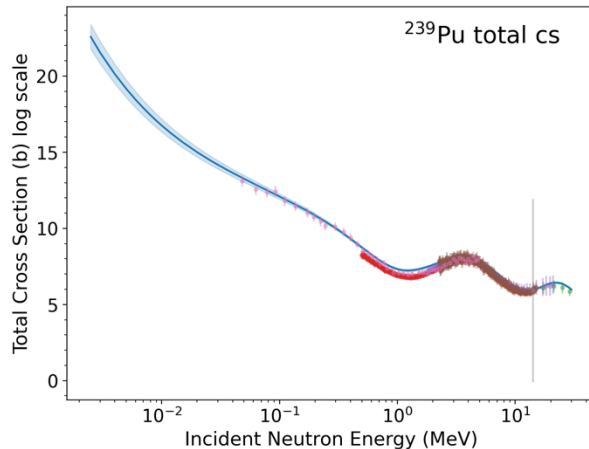
## Integral ND quantities

- $y_e$  = set of experimentally measured values of integral benchmarks.
- $y_c$  = set of calculated values of integral benchmarks.
- $S$  = response sensitivity matrix with respect to ND inputs.

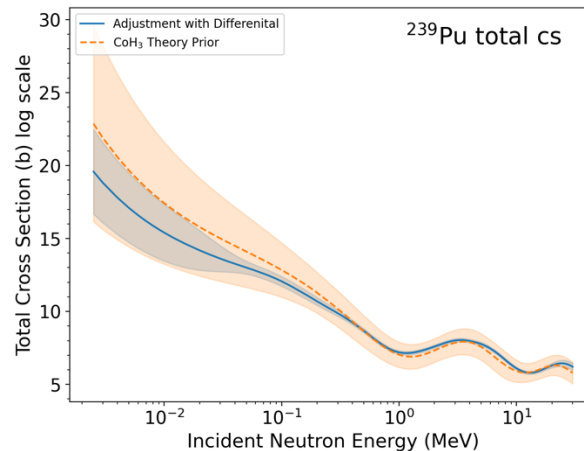
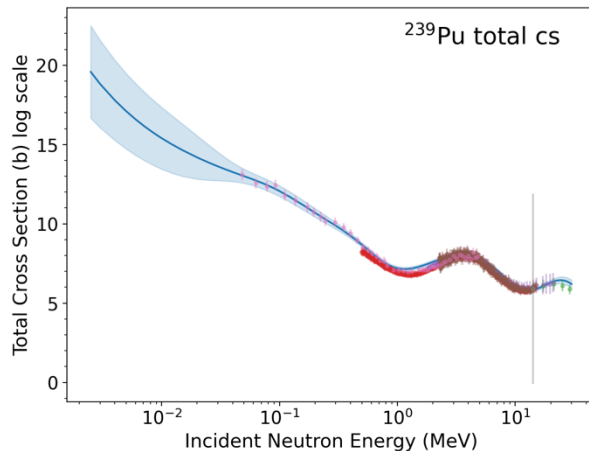
Three sources of input represent multivariate Gaussian distributions and are assumed to be independent.

# Impact of GPs on adjustment

No GPs on **initial** or **differential** covariances



With GPs on **initial** and **differential** covariances



# Generalized least squares (GLS) model to initially constrain ND

## Step 1: Adjust to historic differential data

We update the **initial** ND quantities as

$$\begin{aligned}\sigma_{diff} &= \sigma_{init} + V_{init} L^T (L V_{init} L^T + \Delta)^{-1} (y_{diff} - L \sigma_{init}) \\ V_{diff} &= V_{init} - V_{init} L^T (L V_{init} L^T + \Delta)^{-1} L V_{init}\end{aligned}$$

## Step 2: Calibrate to historic integral benchmark experiments

We update the **differential** adjusted ND quantities using

$$(y_e - y_c) \sim N(0, S V_{diff} S^T + \Sigma_e)$$

to obtain

$$\begin{aligned}\sigma_{post} &= \sigma_{diff} + V_{diff} S (S^T V_{diff} S + \Sigma_e)^{-1} (y_e - y_c) \\ V_{post} &= V_{diff} - V_{diff} S (S^T V_{diff} S + \Sigma_e)^{-1} S^T V_{diff}\end{aligned}$$

Initial ND

$\sigma_{init}, V_{init}$



Updated ND with  
differential

$\sigma_{diff}, V_{diff}$



Updated ND with  
integral

$\sigma_{post}, V_{post}$

# Experiment selection

## Step 3: Use D-optimality criterion to guide experiment selection

- A D-optimal set of experiments will best reduce the uncertainty volume in the intermediate range after adjustment to all reliable historic experiments.
- Further update  $V_{post} \rightarrow V_{cand}$  by running Steps 1-2 with uncertainties for a pair of candidate experiments.
- Subset  $V_{post}$  and  $V_{cand}$  to only include isotopes appearing in the candidate **integral** experiments (PARADIGM isotopes) from 1-600keV.
- For each pair of candidate **integral** and **differential** experiments, compute

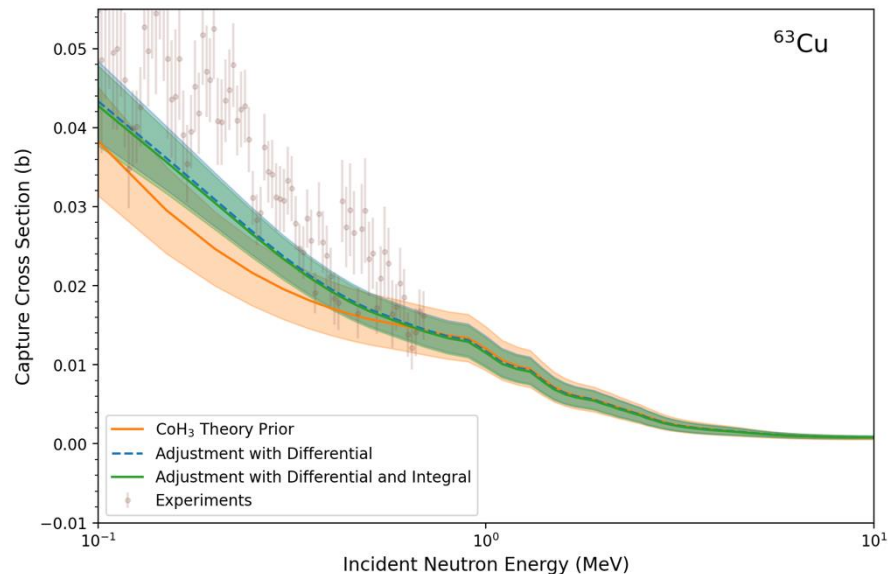
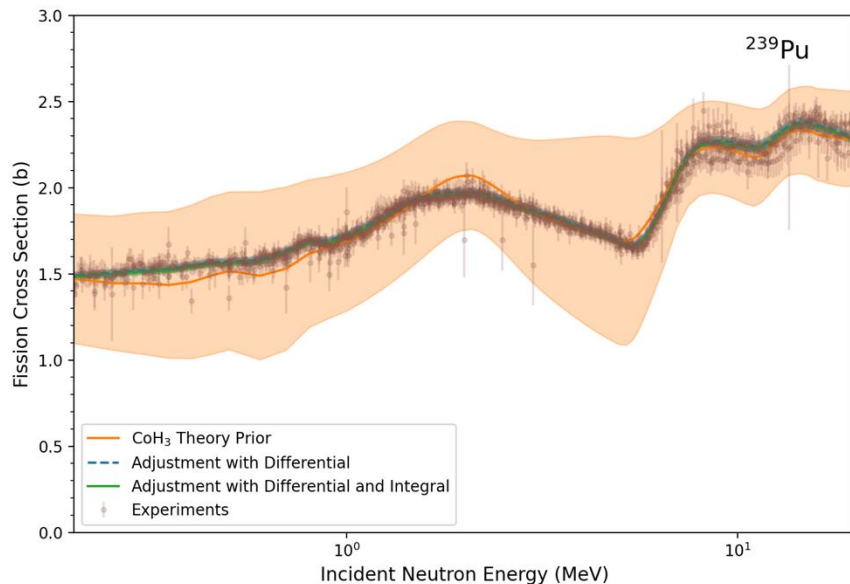
$$D_{cand} = \log \det V_{post} - \log \det V_{cand}$$

Updated ND with  
integral  
 $\sigma_{post}, V_{post}$



Further updated ND  
with candidate  
differential and  
integral  
 $\sigma_{cand}, V_{cand}$

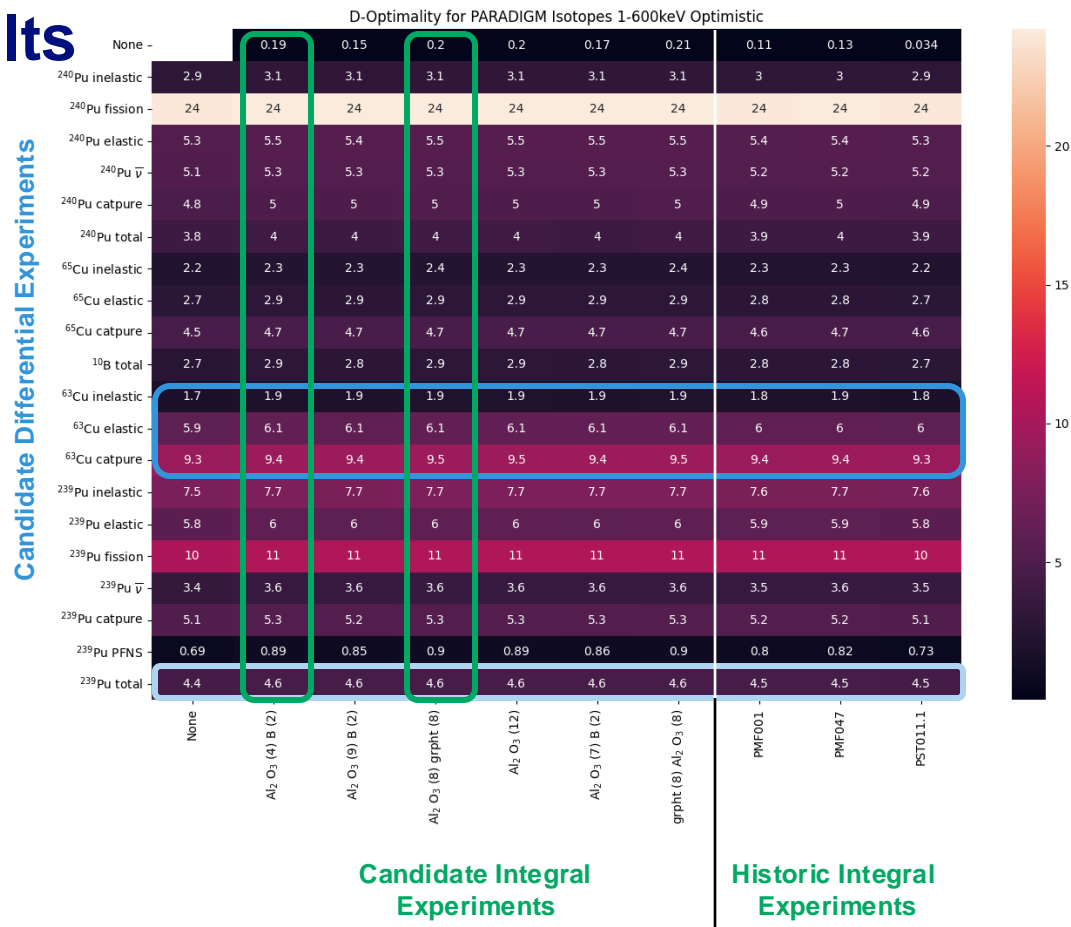
# Comparison with differential experiments overlayed



Adjustments are mostly driven by differential data with minor influence from integral data.

# D-optimality (D-opt) results

- The higher the D-opt, the more impact from candidate experiments.
- Differential** candidates are the big drivers of D-opt relative to **integral** candidates with minor and nearly equal improvements.
  - Several direct measurements vs single indirect measurement.
- Final decision for combination of experiments based on D-opt and feasibility constraints.





# Conclusion and future work in developing modeling capabilities

- Combined **theory** with historic **differential** and **integral** data to constrain ND.
  - We can better understand fission data with combined knowledge from all parts of the ND pipeline.
- Steer experimental design by selecting a pair of experiments that best reduce intermediate ND using D-opt criterion.
- Additions to modeling capabilities:
  - Incorporate flux distribution for response sensitivity matrix.
  - Theory model curves to include resonance features.
  - Modify model to Bayesian framework to handle disagreements between differential experiments.
  - Include more integral responses into adjustment.

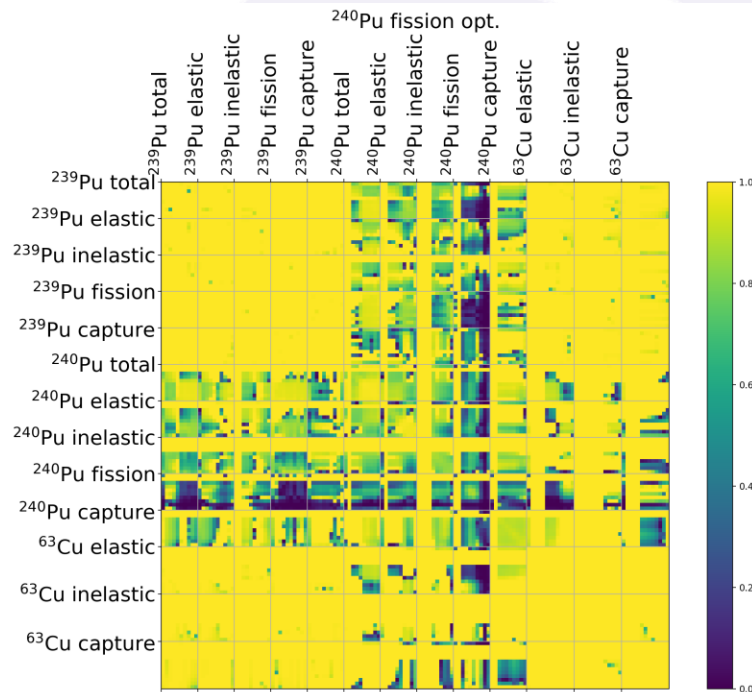
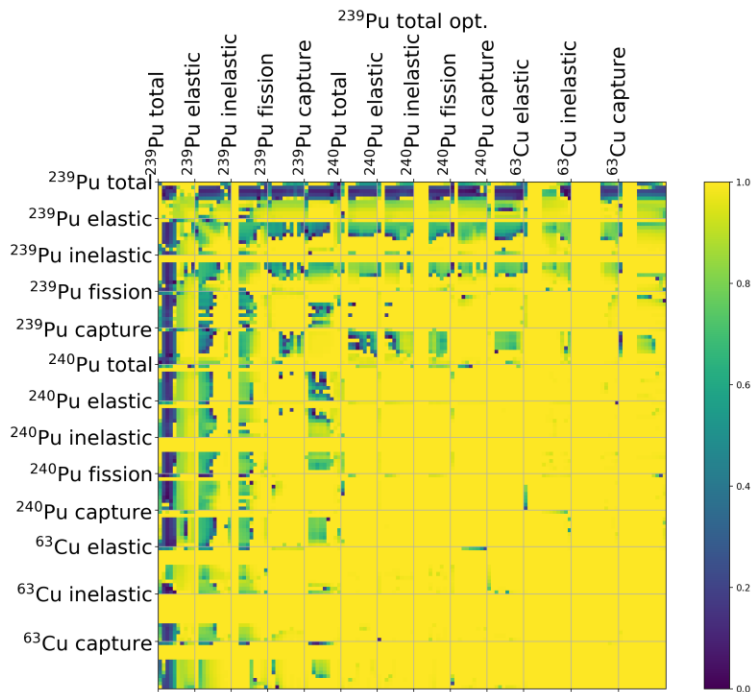
# Acknowledgments

- Research reported in this publication was supported by the U.S. Department of Energy LDRD program at Los Alamos National Laboratory.

**Thank you for your attention!**

# Backup slides

# Covariance Improvements Concentrate on the Isotope Selected for the Differential Experiment - $^{239}\text{Pu}$ vs $^{240}\text{Pu}$



Relative change in covariance:  $\left| \frac{V_{cand}}{V_{post}} \right|$