## CSD ET Series Drives

## INTRODUCTION

- New series of stepping motor drives with EtherCAT interface.
- Drives optimized for coupling with SANYO DENKI stepping motors, fitted with encoder.
- Compact system, developed to offer a wide variety of integrated functions and optimized for the most demanding motion control applications.


## HIGHLIGHTS

- Communication by means of EtherCAT interface.
- Modes of operation: PROFILE POSITION and CSP.
- Full digital microstepping drive.
- Extremely compact size.

■ A highly sophisticated operation system, preserving anyhow the traditional ease of use of R.T.A. drives.


| Series | Model | $V_{D C}$ range | I nom. | Dimensions |
| :---: | :---: | :---: | :---: | :---: |
| CSD ET | 04 | $($ Volt $)$ | $(\mathrm{Amp})$ | $(\mathrm{mm})$ |

## TECHNICAL FEATURES

－Range of operating voltage： $24-48 \mathrm{~V}_{\mathrm{DC}}$ ．
－Protections：
－Protection against under－voltage and over－voltage． －Protection against a short－circuit at motor outputs． －Overtemperature protection．
－Electronic damping facility for further acoustic noise and mechanic vibrations reduction．
－Available in boxed version with plug－in connectors． Maximum compactness．
－Optoinsulated auxiliary and programmable inputs and outputs．
－Warranty： 24 months．

## SETTING BY MEANS OF EtherCAT．${ }^{*}{ }^{*}$ INTERFACE

－Wide range of motor phase current setting．
－Motor current overboost．
－Intelligent management of the current profile．
－Communication by means of EtherCAT（CoE）interface．
－Modes of operation：PROFILE POSITION and CSP．
－Different variety of HOMING operation modes．
－Encoder feedback．


Encoder feedback．

POWER AND LOGIC CONNECTIONS


## EtherCAT．

## MECHANICAL DIMENSIONS



