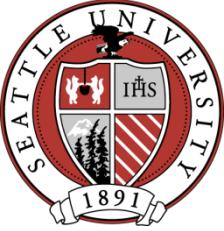


# 10-Maximum Power Point Tracking

ECEGR 4530  
Renewable Energy Systems



# Overview

- PV Applications
- Maximum Power Point
- Boost Converter
- Illustrative Simulation

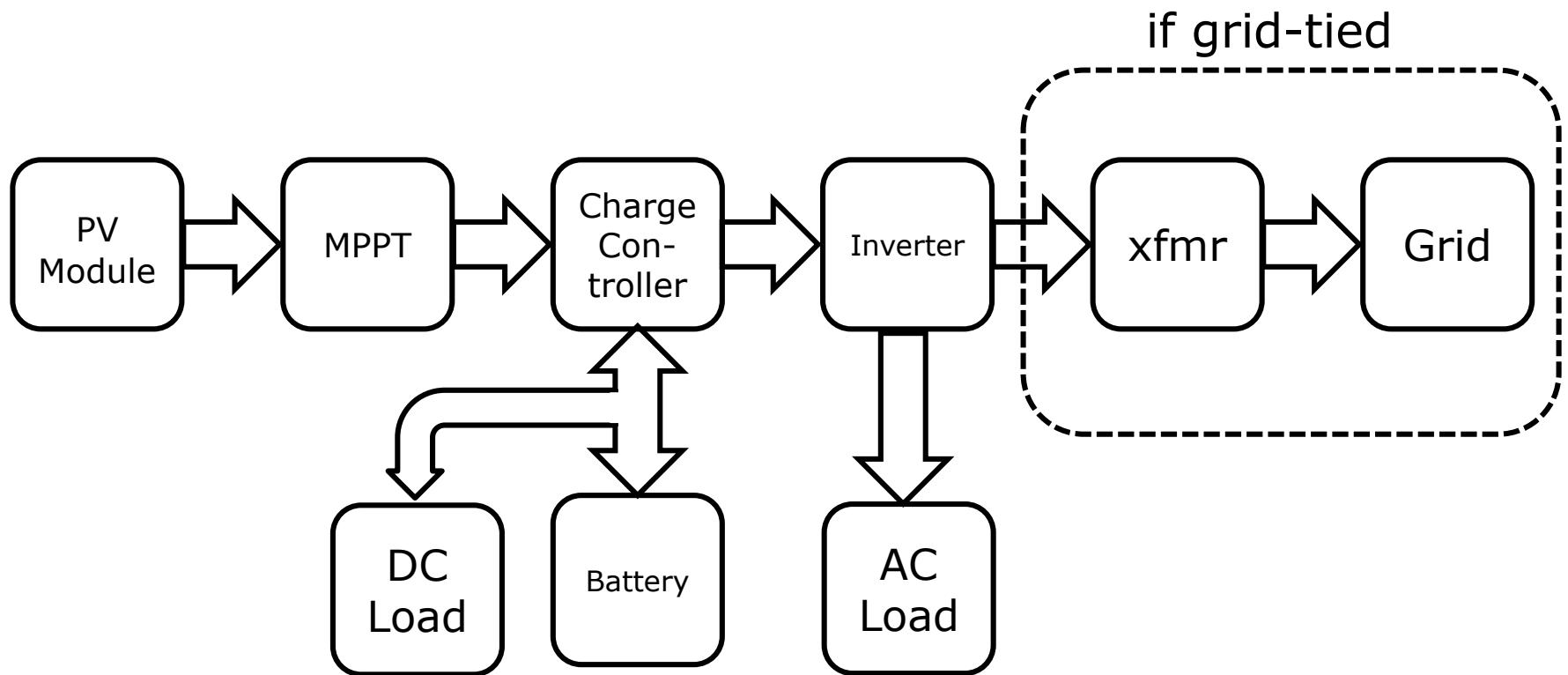


# PV Applications

- Stand-Alone: all energy supplied to load originates from PV
  - remote applications
- Grid Connected: energy from PV may serve local load or be exported to the electric grid. Import of energy from the grid possible
  - PV power plants
  - urban applications
- Hybrid: PV + one or more generation sources (such as diesel generator), may be connected to the grid



# Common PV System Elements





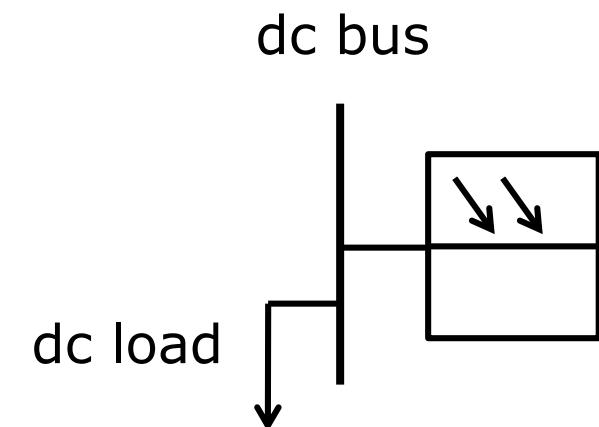
# PV System Elements

- Generation
  - PV module(s)
  - diesel
  - other
- Power electronic converters
  - DC/AC (inverters)
  - DC/DC (buck, boost, buck boost)
- Load
  - AC
  - DC
- Storage (stand alone systems)
  - battery
  - hydrogen
- Transformer (grid connected)



# Stand Alone PV System

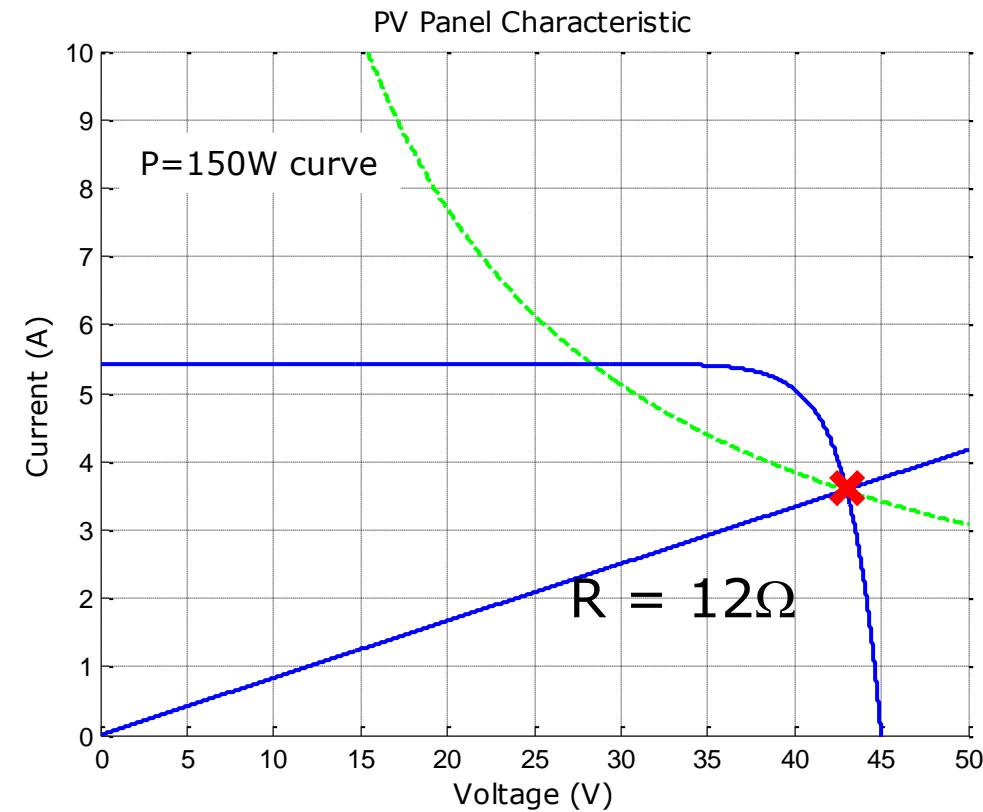
- Simple dc system
  - one PV module
  - one 12 Ohm resistive load (a heater)





# Stand Alone PV System

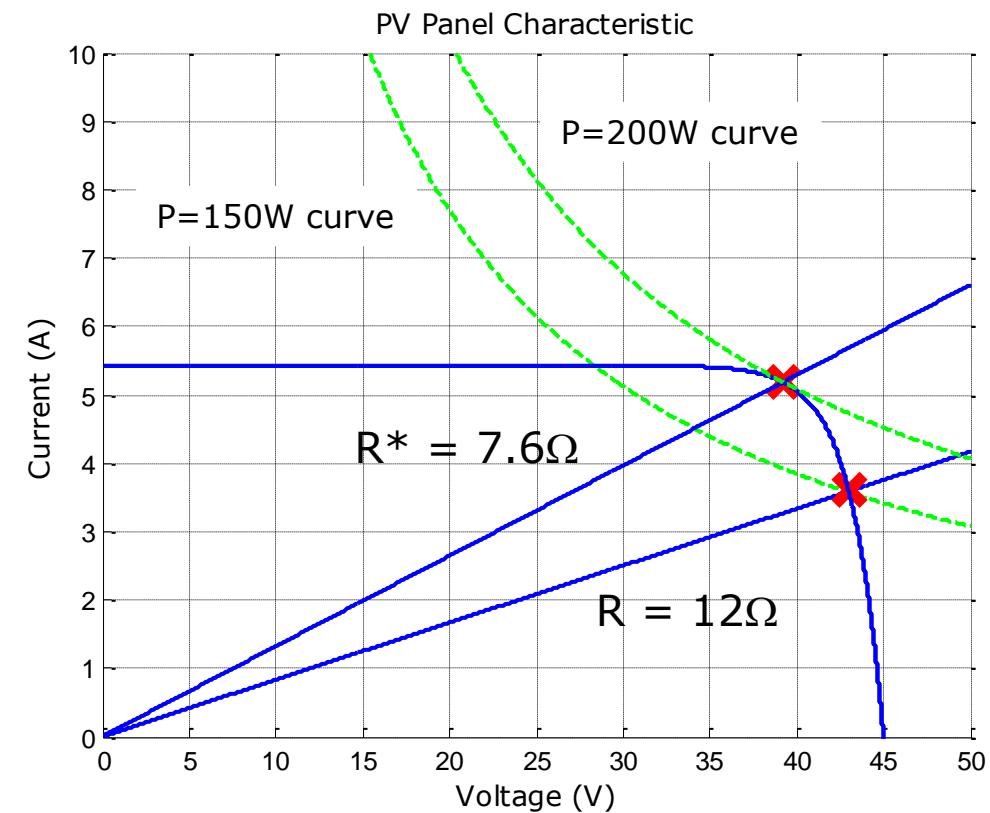
- With 12 Ohm load
  - $P = 150 \text{ W}$
- Module Characteristics
  - $P^* = 200 \text{ W}$
  - Power output is not maximized





# Stand Alone PV System

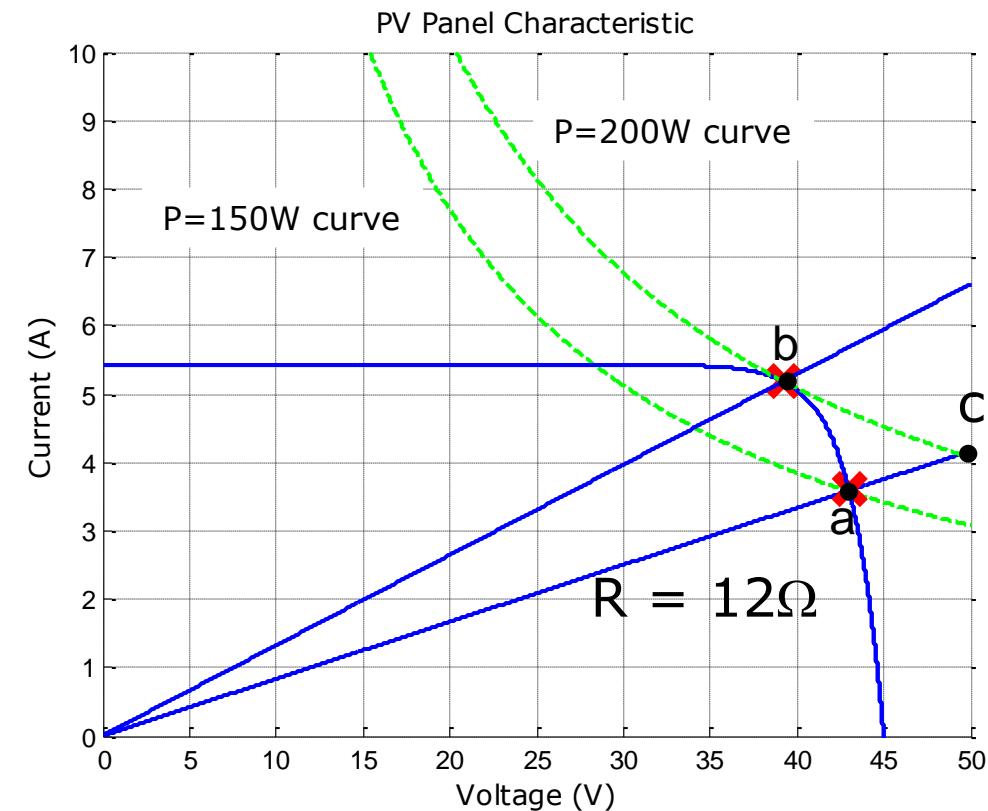
- At optimal operating point  $R = 7.6\Omega$





# Stand Alone PV System

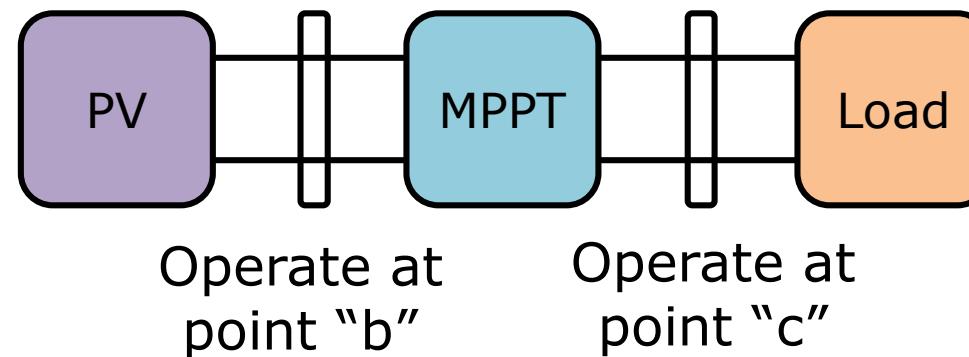
- Need to “move” operating point of the PV from a to b
- Need to move operating point of the load from a to c (increase voltage)
- Need an interface between PV panel and load





# Maximum Power Point Trackers

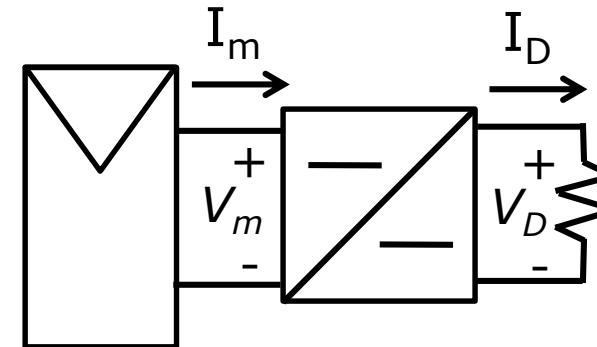
- Use Maximum Power Point Tracker (MPPT): dc-dc converter
- MPPT changes the resistance “seen” by the PV panel
- HOMER assumes that the design has a MPPT in the converter

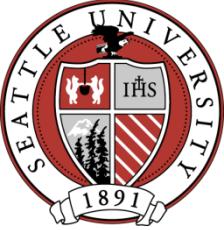




# Maximum Power Trackers

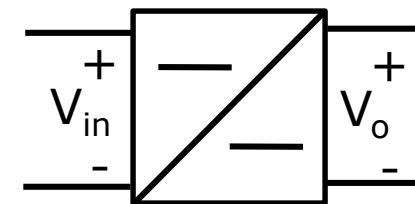
- DC-DC converter
  - controls output voltage
  - ideal (no losses)
  - power is conserved  $(V_m \times I_m) = (V_D \times I_D)$





# Maximum Power Trackers

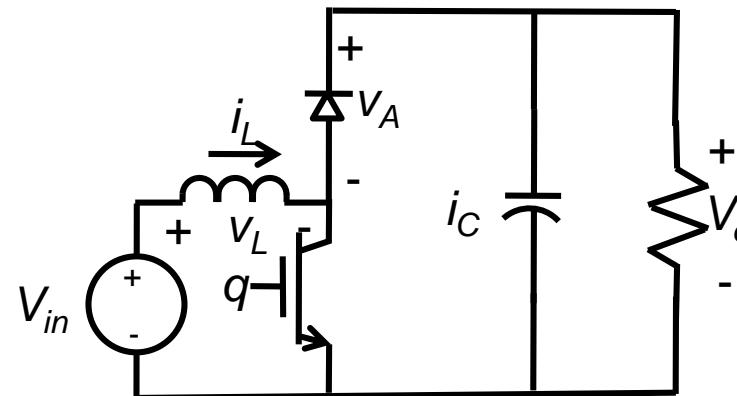
- In most cases, the voltage at the load must be greater than the PV module voltage for maximum power transfer
- Voltage must be “boosted”
  - $V_o > V_{in}$
- Use a Boost Converter





# Boost Converter

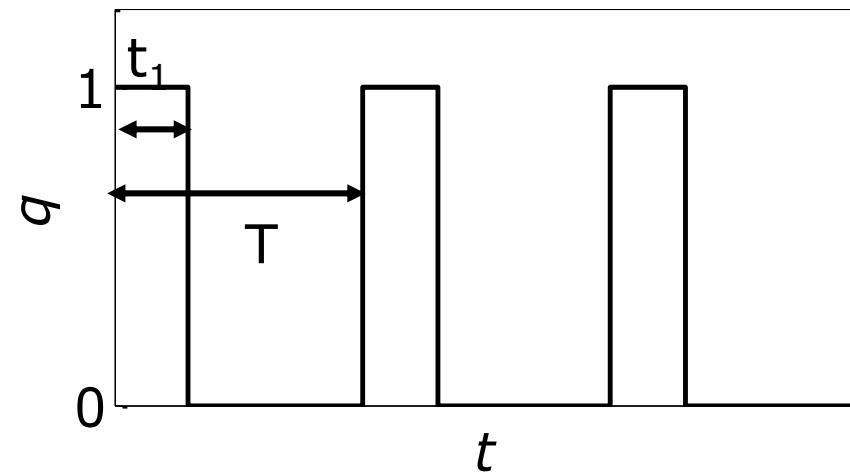
- Used to efficiently produce output voltage that is **greater** than input voltage
- Ratio of input voltage to output voltage depends on the duty cycle of the switch “q”
- Duty cycle (D): portion of the time that q is high during one period





# Duty Cycle

$$D = \frac{t_1}{T}$$





# Boost Converters

- It can be shown that:

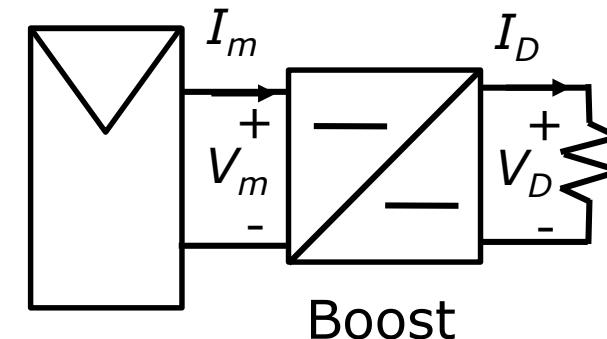
$$V_o = \frac{1}{1-D} V_{in}$$

$$D = 1 - \frac{V_{in}}{V_o}$$

Where  $V_{in} = V_m$   
and  $V_o = V_D$

- If we assume the MPPT is lossless, then, just like a transformer, power is preserved:

$$P_m = V_m I_m = V_D I_D = P_D$$

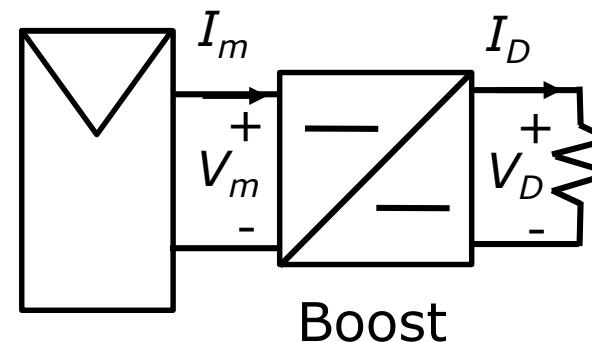




# Duty Ratio

- For MPP tracking, we must find D that maximizes the power output
- $V_m$  is not a voltage source, so D cannot be made arbitrarily large
- At MPP, D is such that

$$P_m^* = V_m I_m = V_D I_D$$





# Maximum Power Trackers

- What should the voltage at the load be to ensure maximum power transfer?

$$P_m^* = V_m^* I_m^* \quad \text{Recall: } P^* \text{ is the maximum power under the given conditions}$$

$$P_D = V_D I_D = \frac{V_D^2}{R} = P_m^*$$

$$V_D^* = \sqrt{P_m^* R}$$

- Therefore:  $D = 1 - \frac{V_{STC}^*}{V_D^*} = 1 - \frac{V_{STC}^*}{\sqrt{P^* R}}$
- The duty ratio should not exceed this value



# Maximum Power Trackers

- Find D of a boost MPPT if:
  - load resistance is 12 Ohms
  - $V^* = 38 \text{ V}$
  - $P^* = 200 \text{ W}$



## Exercise

- Find D of a boost MPPT if:
  - load resistance is 12 Ohms
  - $V^* = 38 \text{ V}$
  - $P^* = 200 \text{ W}$

$$D = 1 - \frac{V^*}{V_D^*} = 1 - \frac{V^*}{\sqrt{P^* R}} = 0.224$$

$$V_D = \frac{1}{1-D} V_m = 48.96V$$

$$P_D = \frac{V_m^2}{R} = \frac{48.96^2}{12} = 200W$$



# Observation

- In the previous exercise
  - Note: the voltage at load is:  $V_D = \frac{1}{1-D} V_m = 48.96V$
  - And the power at the load is:  $P_D = \frac{V_m^2}{R} = \frac{48.96^2}{12} = 200W$
- The power consumed by the load is equal to the maximum power of the PV panel at the given irradiance conditions
- The resistance “seen” by the PV panel is

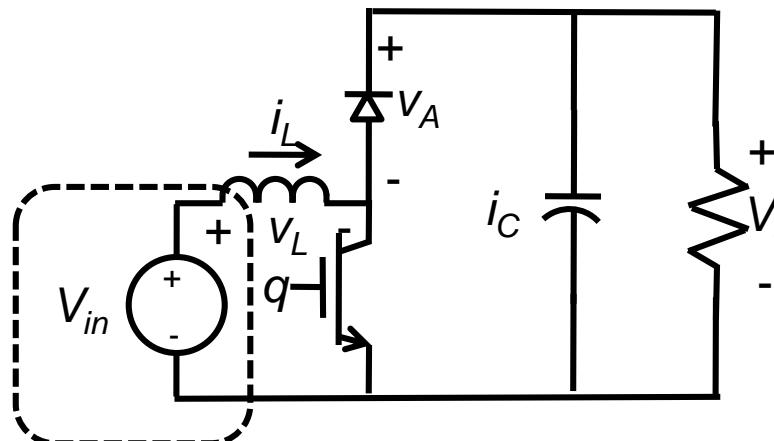
$$R_m = \frac{38^2}{200} = 7.22\Omega$$

When the output voltage is boosted the resistance seen by the PV panel decreases

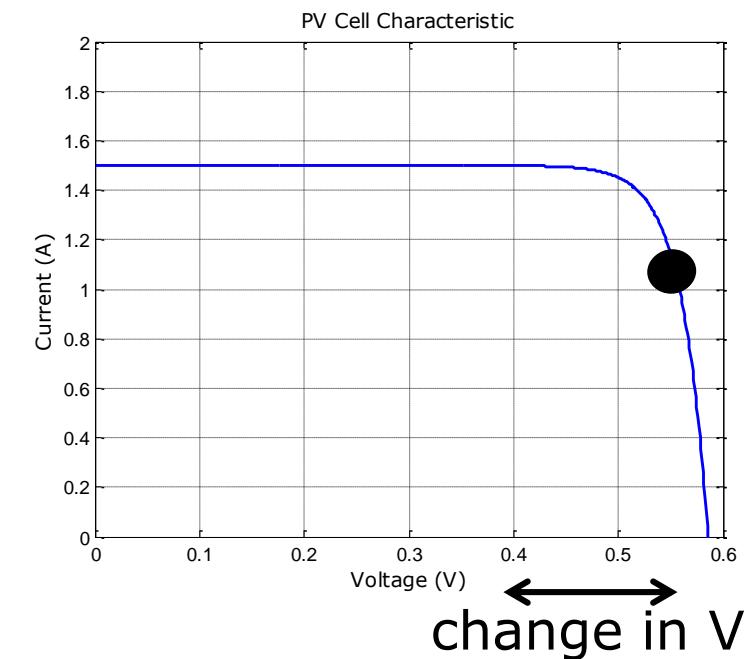


# Maximum Power Trackers

- Note: PV panels cannot be modeled as independent voltage sources
  - As  $I_{in}$  increases, the voltage decreases



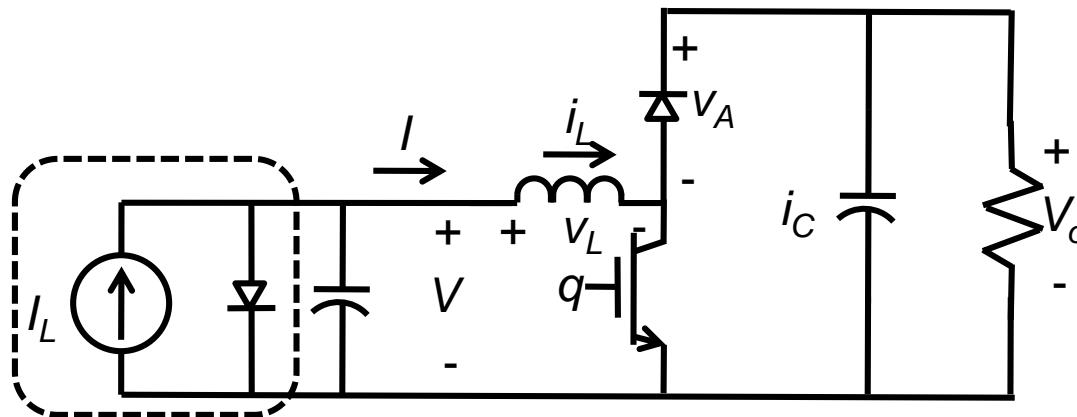
Inappropriate PV model





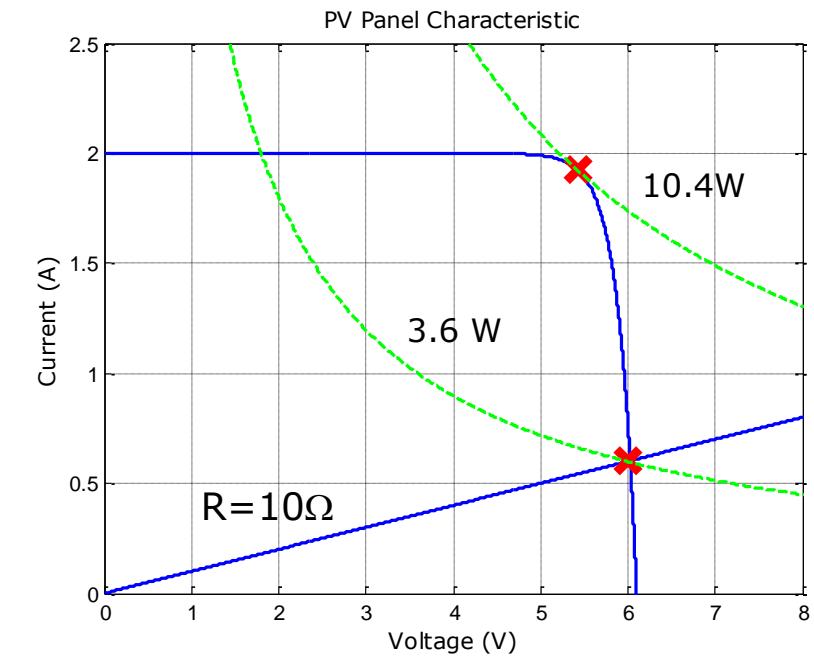
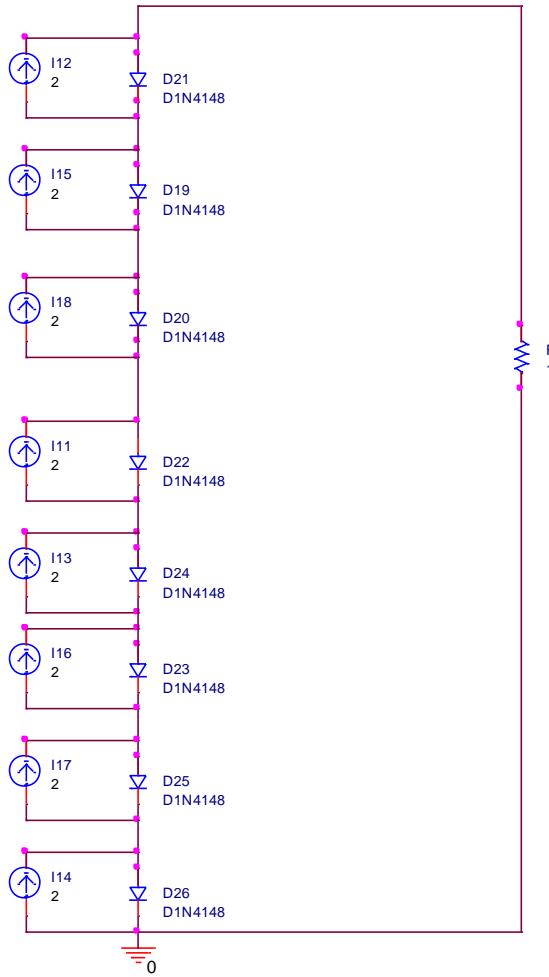
# Maximum Power Trackers

- Include input capacitor to steady voltage





# Maximum Power Trackers



$$D = 1 - \frac{V_{STC}^*}{\sqrt{P_{STC}^* R}} = 1 - \frac{5.42}{\sqrt{10.4 \times 2.8}} = 0.47$$



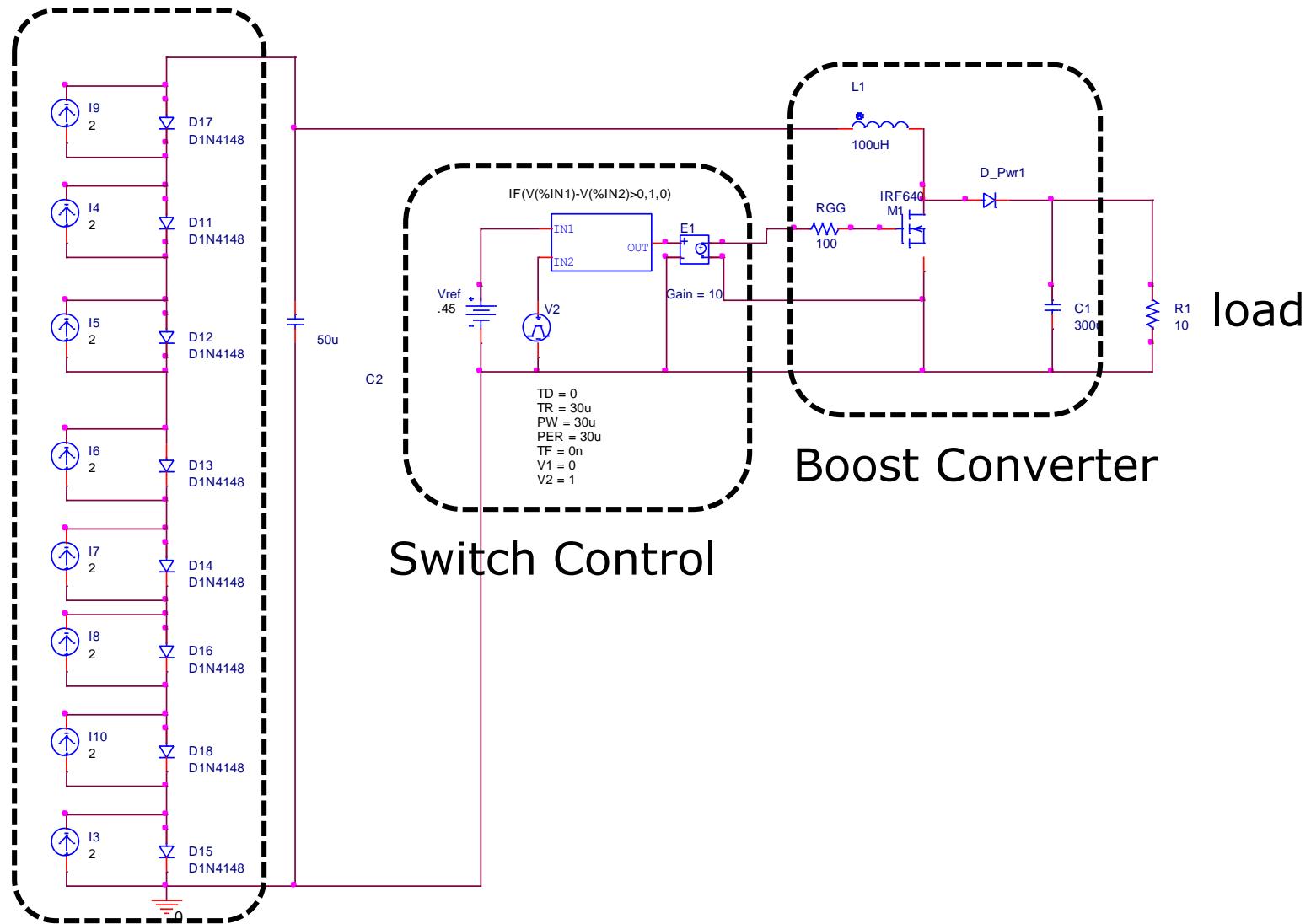
# Maximum Power Trackers





# Maximum Power Trackers

PV  
Module





# Switch Control

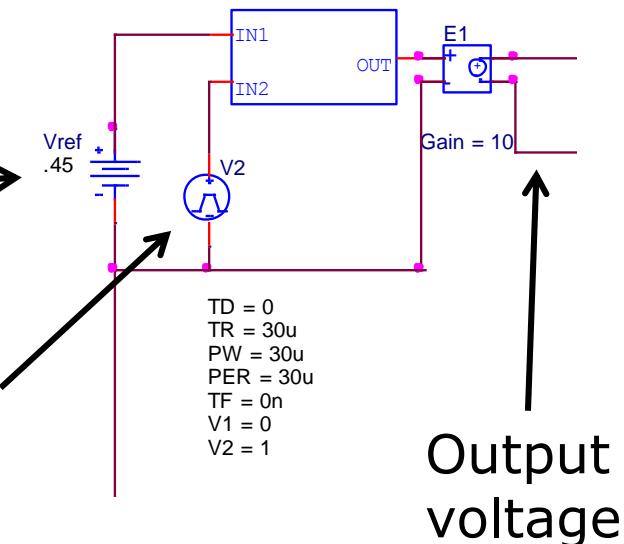
- Function: output square voltage wave of desired duty ratio to control boost converter MOSFET or IGBT

Reference voltage

Sawtooth waveform

comparator

IF( $V(\%)IN1-V(\%)IN2>0,1,0$ )



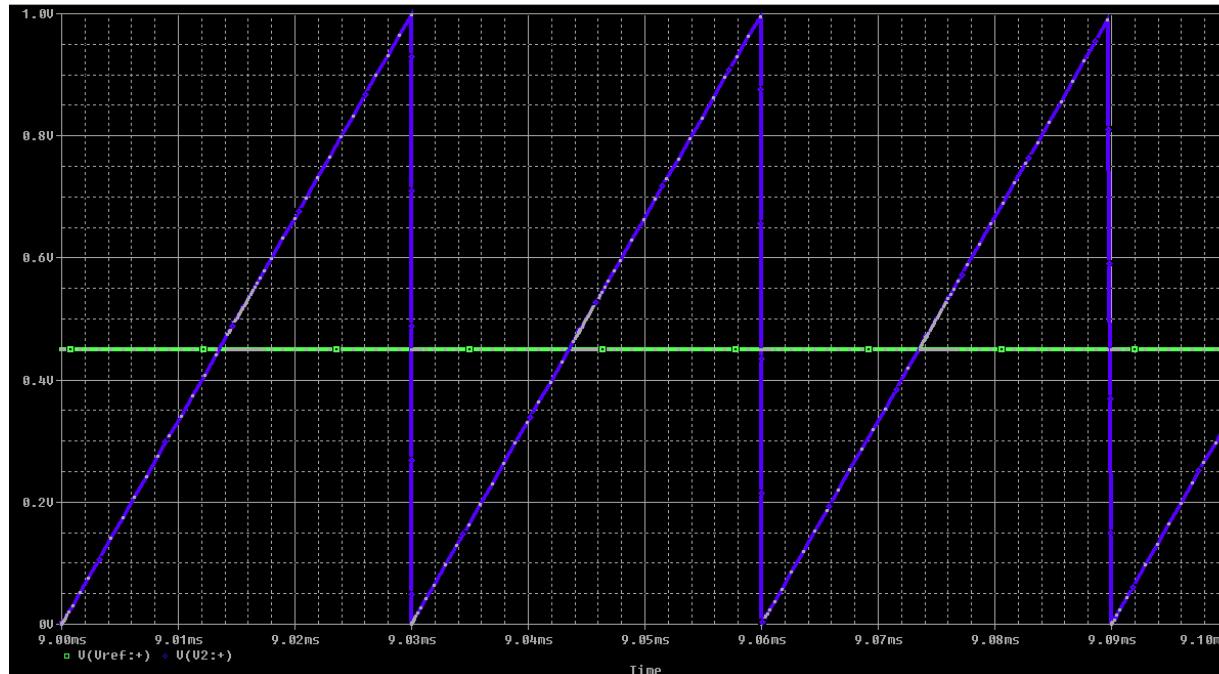


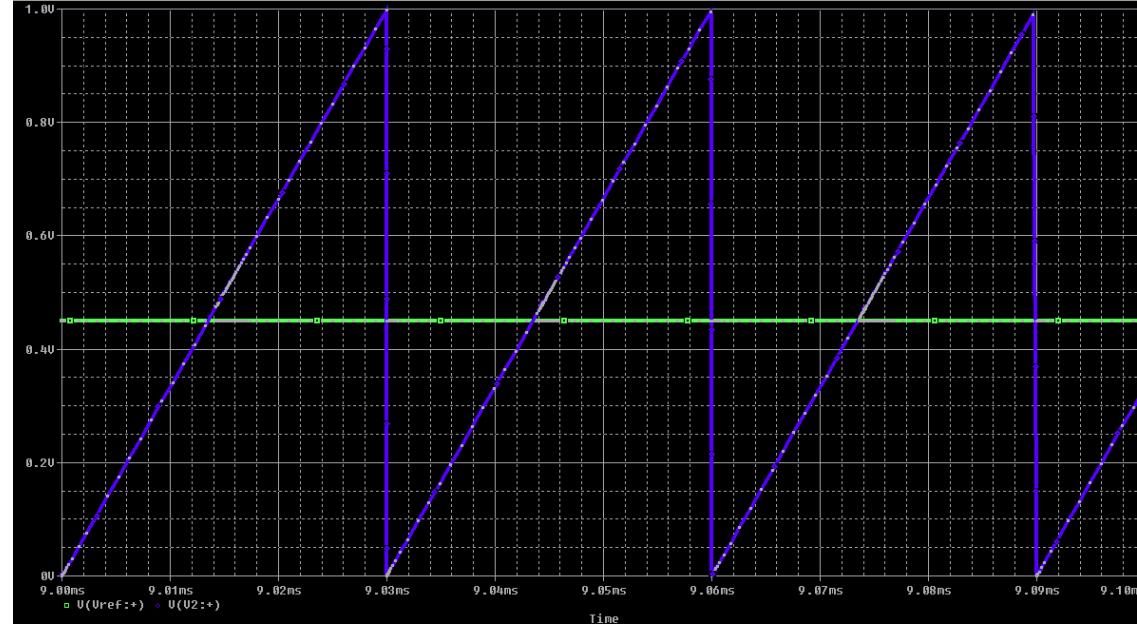
# Switch Control

Set reference voltage to desired duty ratio

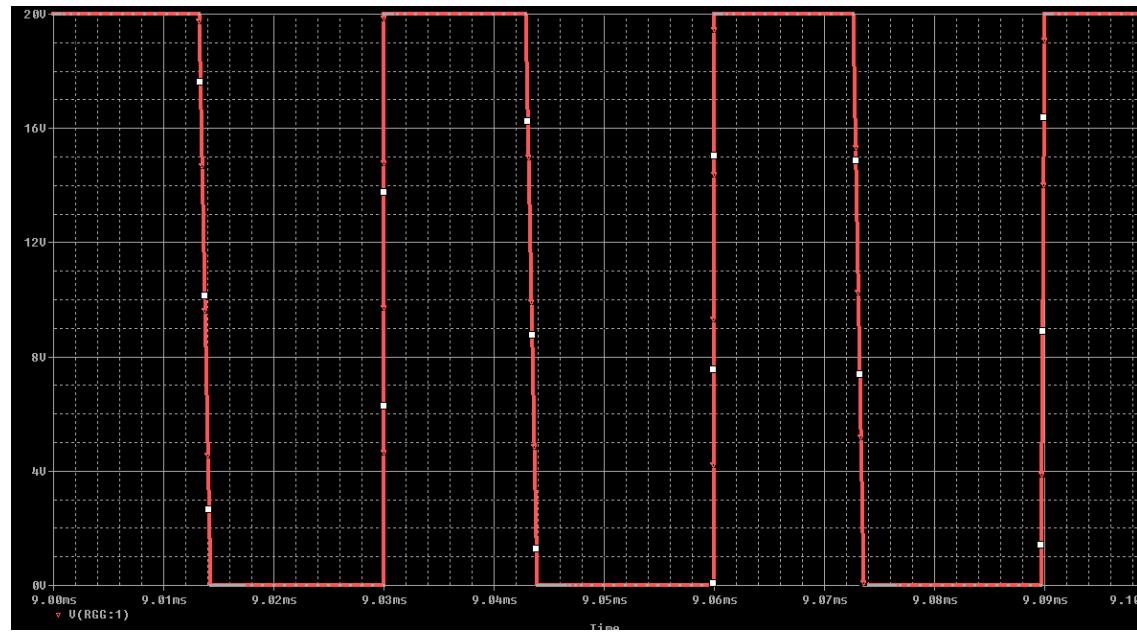
If  $V_{ref} > V_{saw}$ ,  $q = 1$

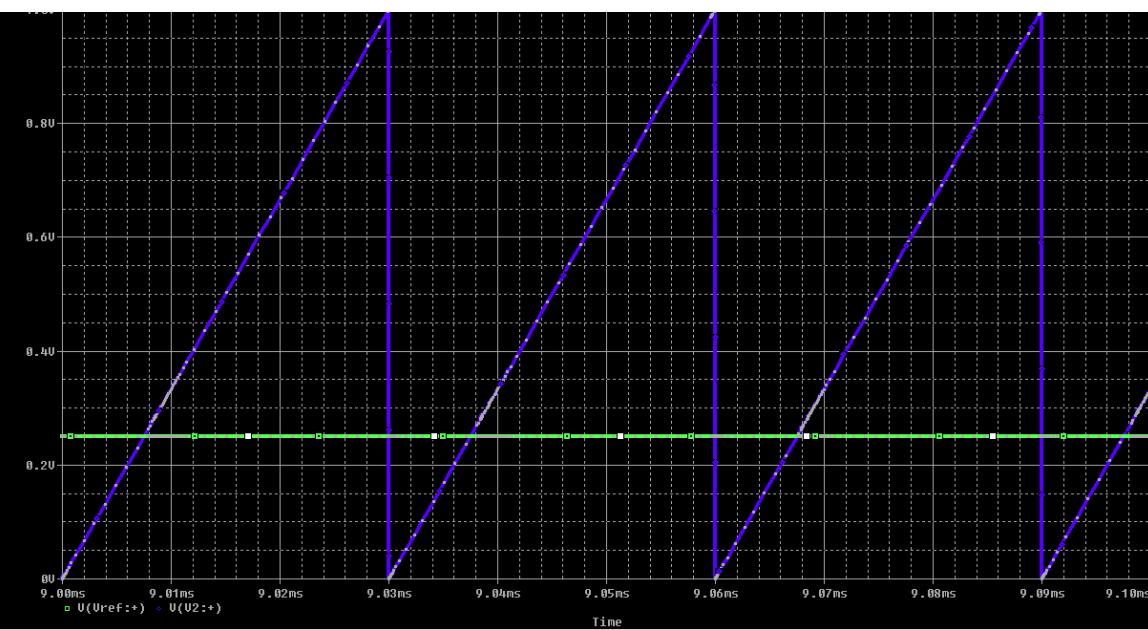
else,  $q = 0$



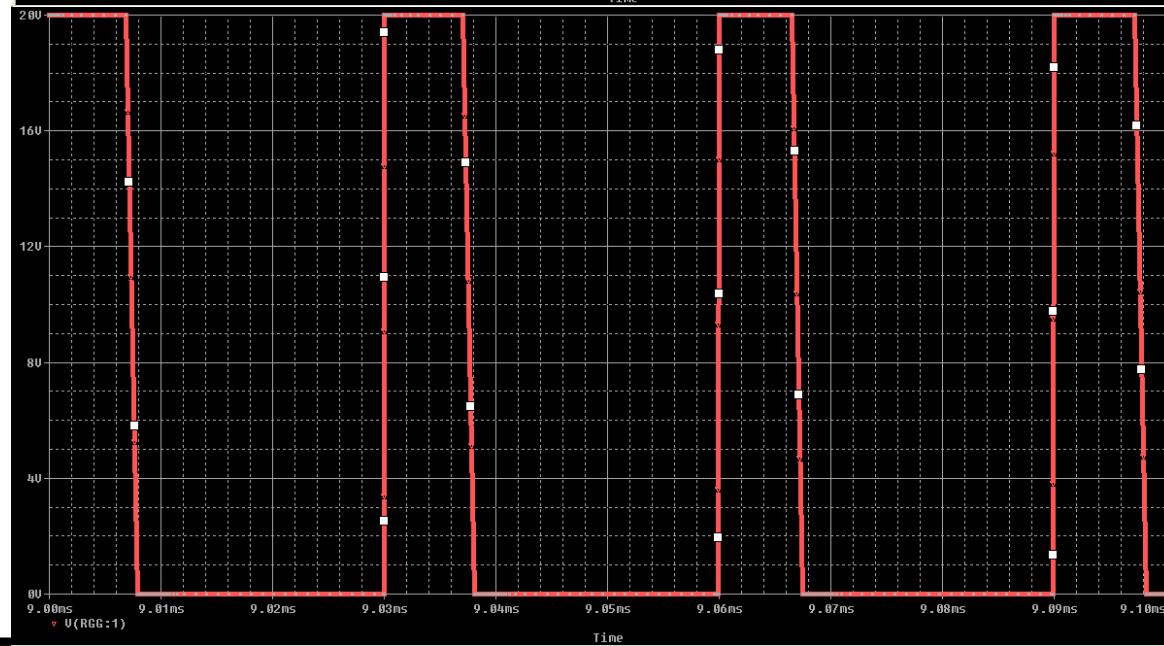


$D = 0.45$





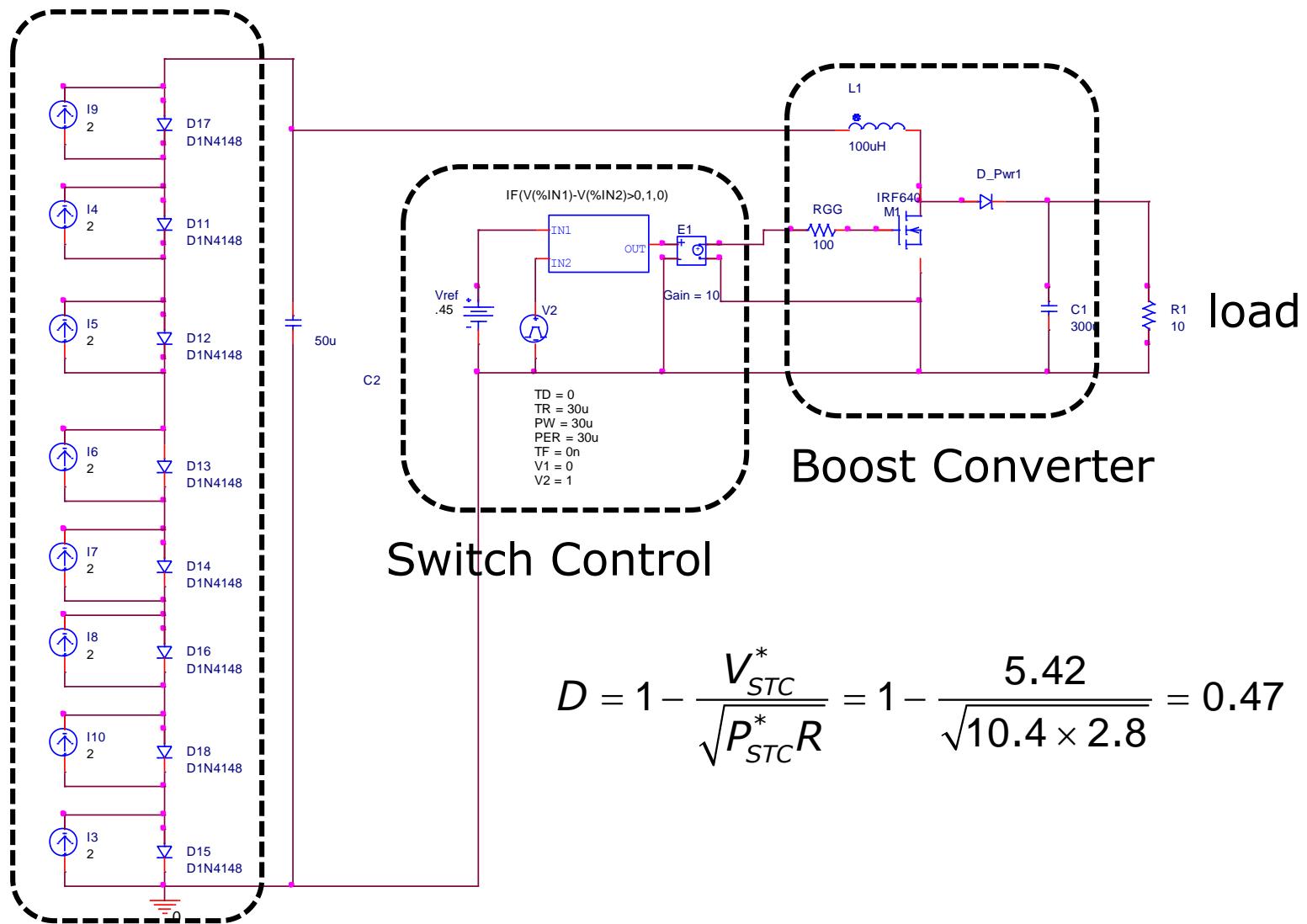
$D = 0.25$





# Maximum Power Trackers

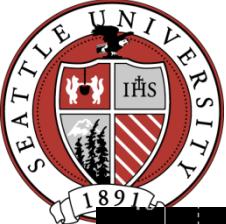
PV  
Module



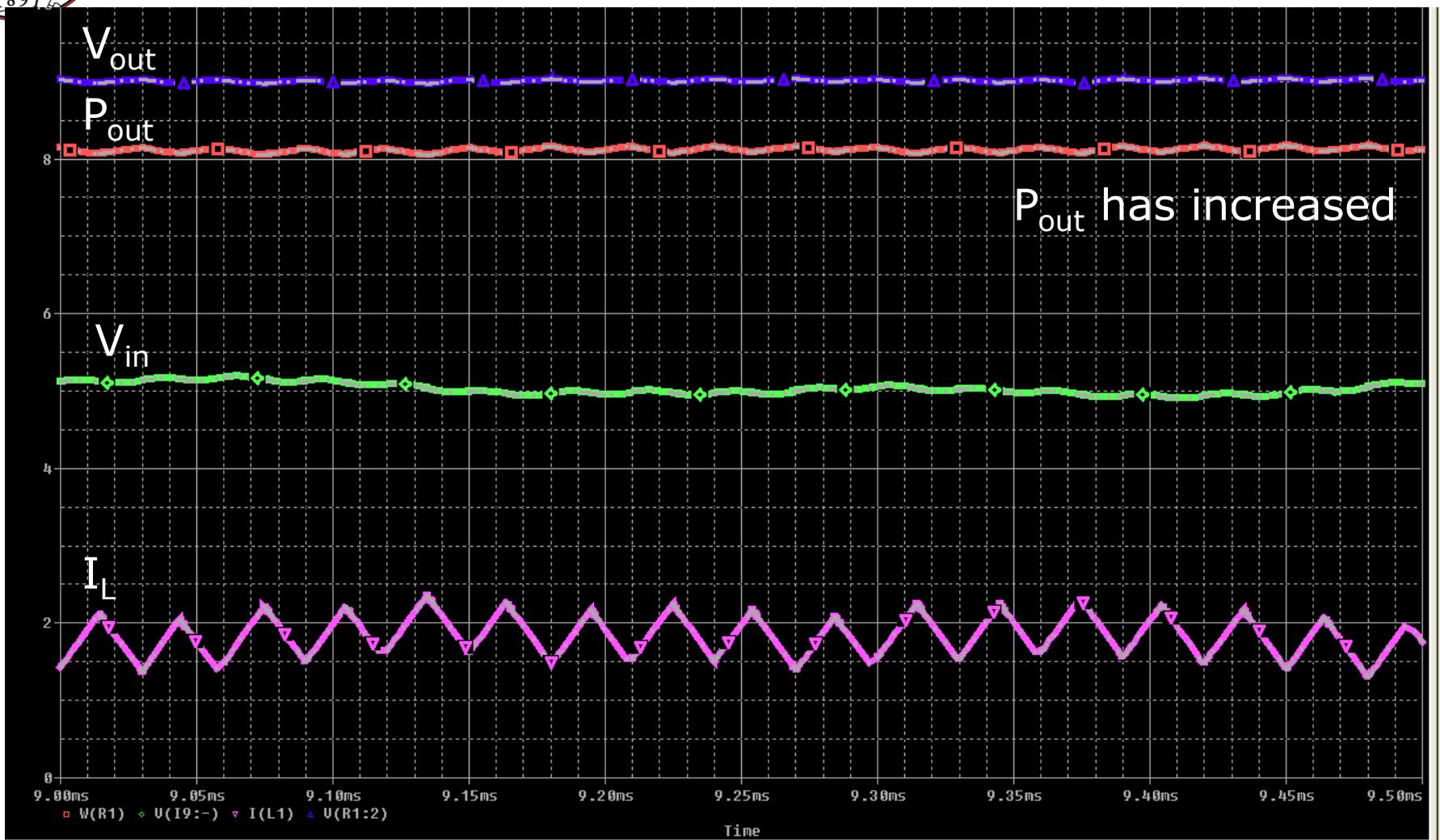


# Without MPPT





# With MPPT





## MPPT

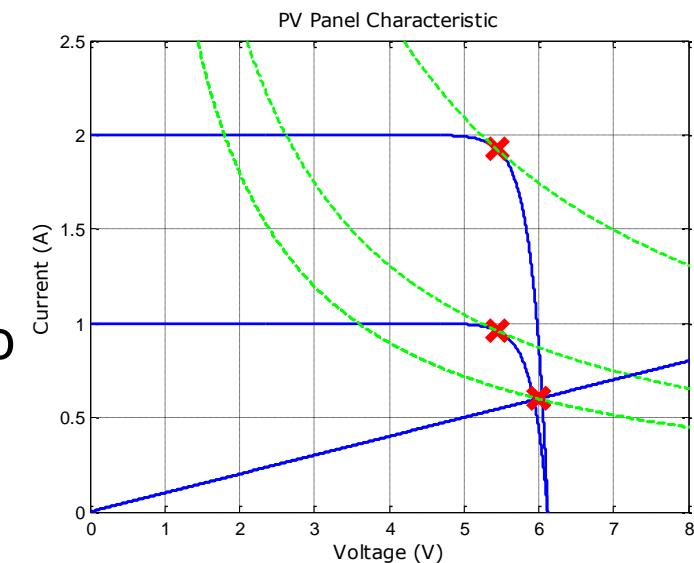
- For a given irradiance level, the optimal MPPT duty ratio is 0.45. If the irradiance decreases, how should the duty ratio be adjusted?
  - A. it should decrease
  - B. it should increase
  - C. it should stay the same



# MPPT

- For a given irradiance level, the optimal MPPT duty ratio is 0.45. If the irradiance decreases, how should the duty ratio be adjusted?
  - A. it should decrease
  - B. it should increase
  - C. it should stay the same

Input voltage is nearly constant, but output voltage must decrease, so D must decrease





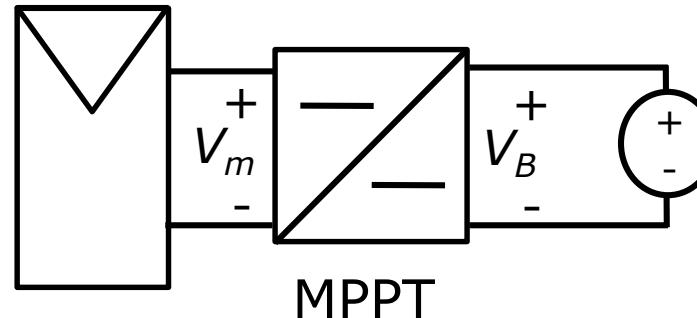
# Maximum Power Point Trackers

- Other power electronic converters may be used
  - Buck (decrease voltage)
  - Buck-Boost (increase or decrease voltage)
  - Others
- Efficiencies in the range of 90% are possible
- MPPTs are very important for motors and pumps
  - Increases power output
  - Prolongs life



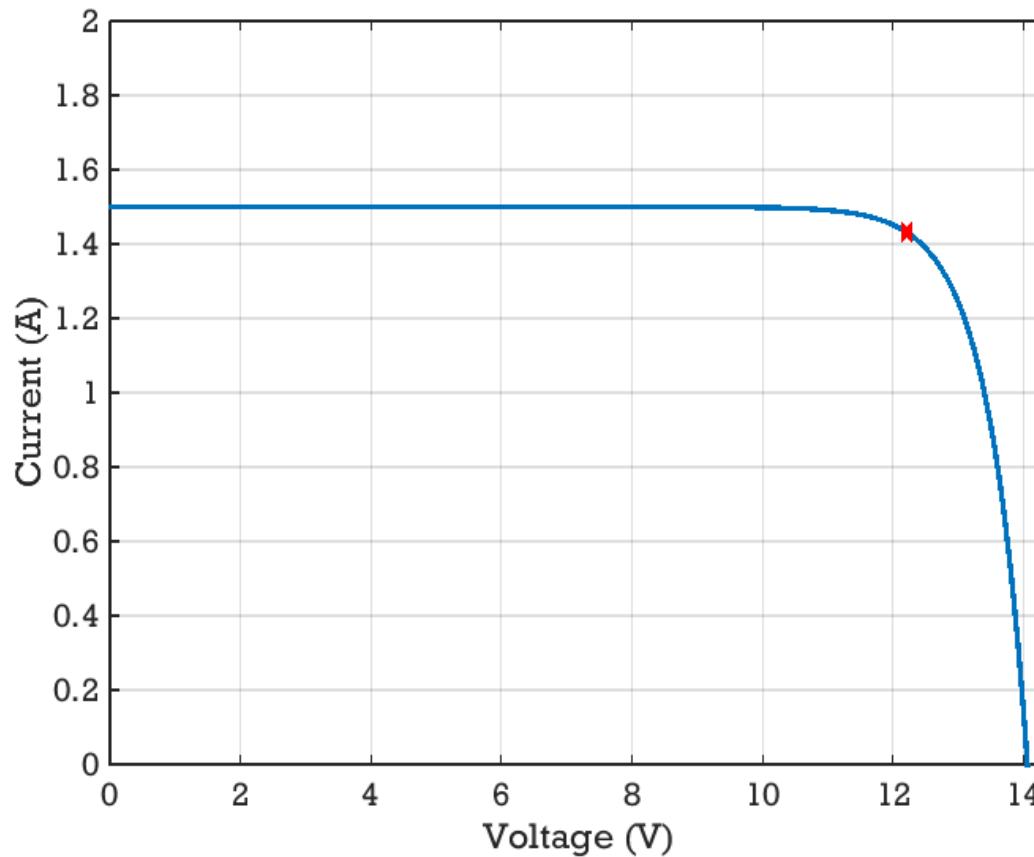
# Constant Voltage Loads

- MPPTs are often used when the PV array interfaces with a battery or inverter
- The output voltage is fixed at  $V_D = V_B$





# Constant Voltage Loads

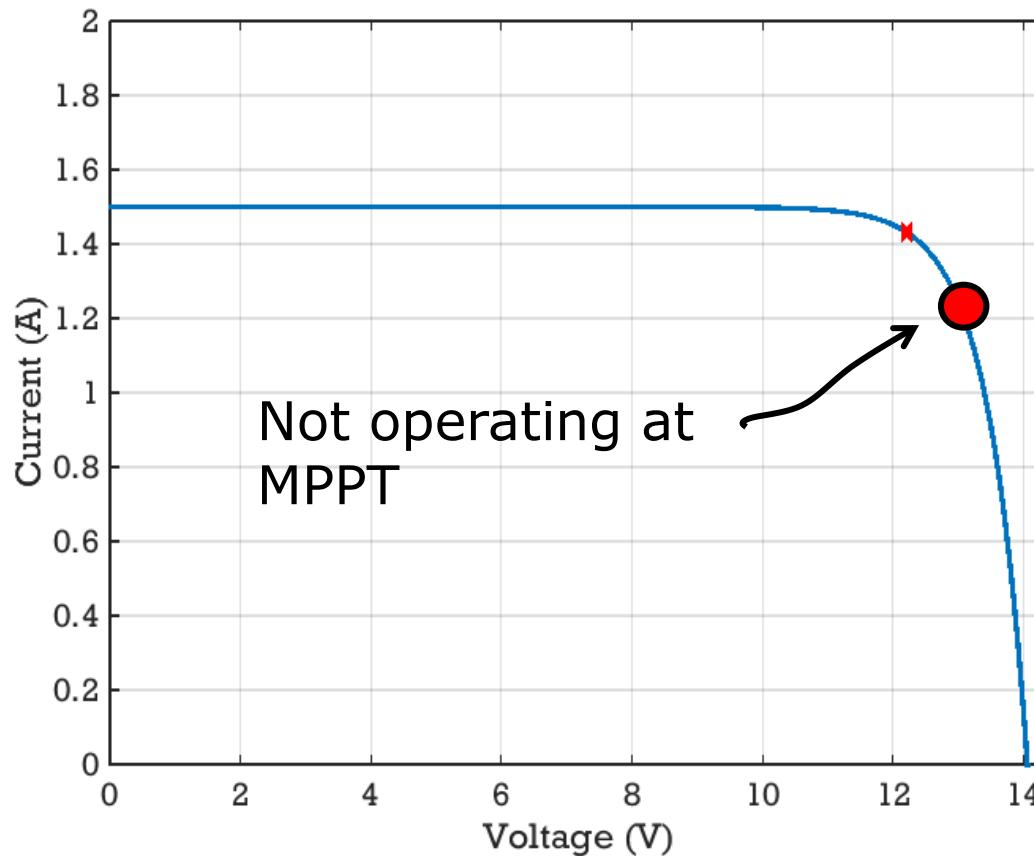


$$\begin{aligned}V^* &= 12.21 \text{ V} \\I^* &= 1.43 \text{ A} \\P^* &= 17.47 \text{ W}\end{aligned}$$

“Resistance” seen by  
The PV array at MPP  
 $V^*/I^* = 8.54$  Ohms



# Constant Voltage Loads



Consider the case without MMPT

Let  $V_B = 13V$ , then

$$V_m = V_B$$

$$I_m = 1.24A$$

$$P_m = P_D = \underline{16.12W}$$

"Resistance" seen by  
The PV array is:  
 $V_m/I_m = 10.5$  Ohms



# Constant Voltage Loads

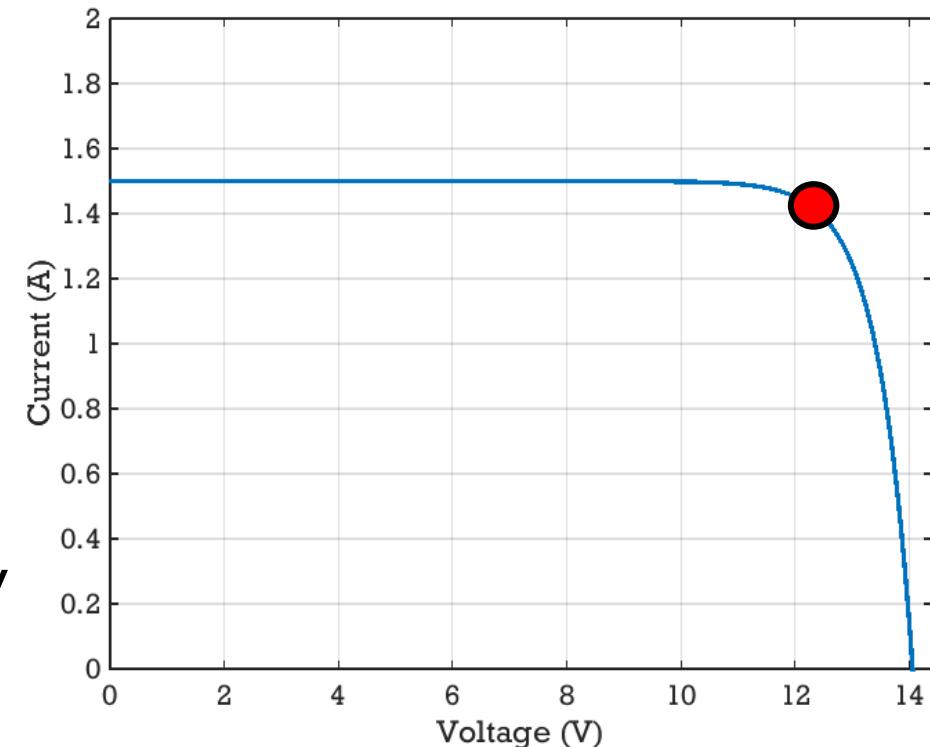
- Adjust the duty cycle of MPPT so that  $V_m = V^*$  given  $V_D = V_B$

$$V_D = \frac{1}{1-D} V_m$$

$$13 = \frac{1}{1-D} 12.21$$

$$D = 1 - \frac{12.21}{13} = 0.061$$

- Operating at MPP
- Power to the battery is maximized: 17.47W





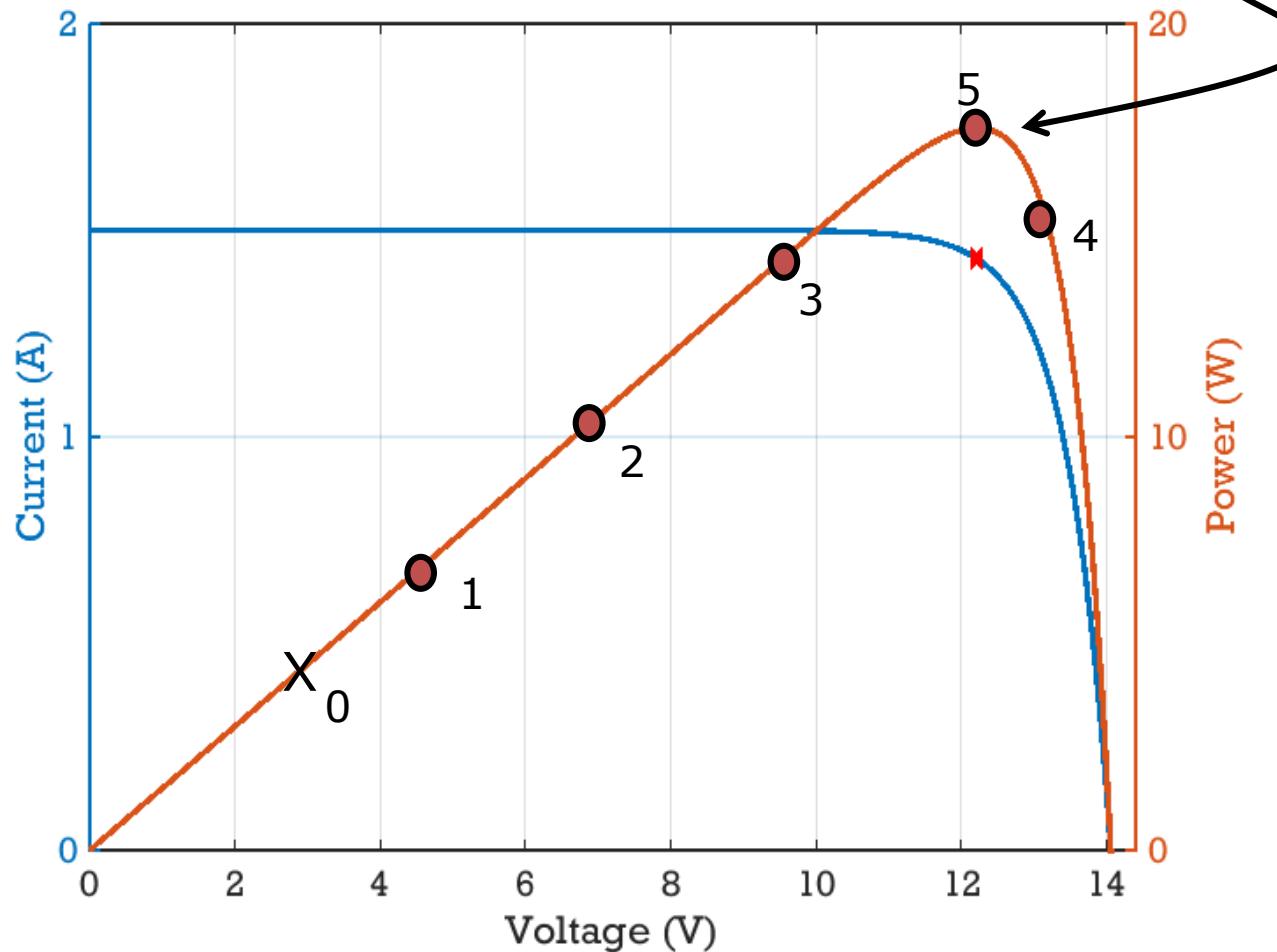
# Maximum Power Point Trackers

- Maximum power tracker control requires PV voltage and current sensing to control the duty ratio (irradiance and perhaps the load are constantly changing)
- Common methods:
  - Perturb and Observe (P&O)
  - Incremental Conductance (IC)
- Both methods are non-model methods (meaning you do not need to explicitly model the circuit), and both use a “hill climbing” approach



Adjust voltage by some amount until maximum is reached.

Top of the hill  
(MPP)





## P&O

- Basic idea: perturb the duty cycle in a direction (e.g. increase it) and see if the power output increases. If power output increases, continue increasing the duty cycle; else decrease the duty cycle and repeat
- Disadvantages:
  - Oscillations around the MPP tend to occur
  - Does not rapidly converge on MPP when irradiance conditions rapidly change (compared to other methods)

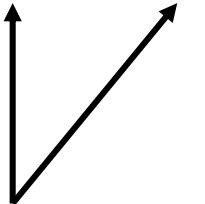


# Incremental Conductance

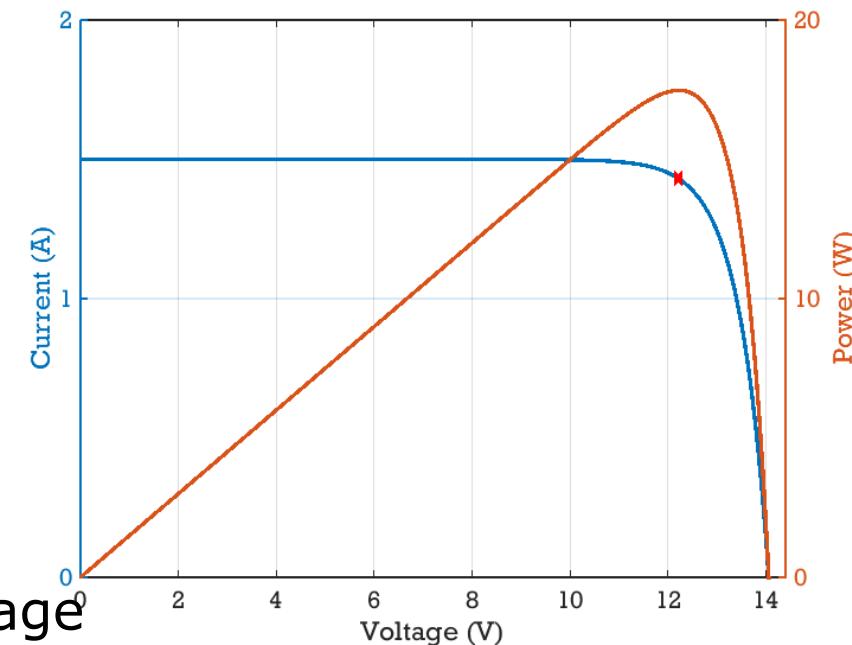
- Basic idea: at MPP, the derivative of power with respect to voltage is zero (it is a maximum point)
- Conductance  $G = I/V$  (inverse of resistance)

$$\frac{dP}{dV} = 0 \text{ (at the MPP)}$$

$$P = IV = I(V)V$$



Recall that the current out of a PV panel is a non-linear function of voltage





# IC Method

$$\frac{dP}{dV} = I(V)V$$

$$I(V)V = \frac{dI}{dV} V + I(V) = 0 \quad \text{at the maximum}$$

$$\frac{dI}{dV} V = -I(V)$$

$$\frac{dI}{dV} = \frac{-I(V)}{V}$$

Applying the product rule  
for derivatives



# IC Method

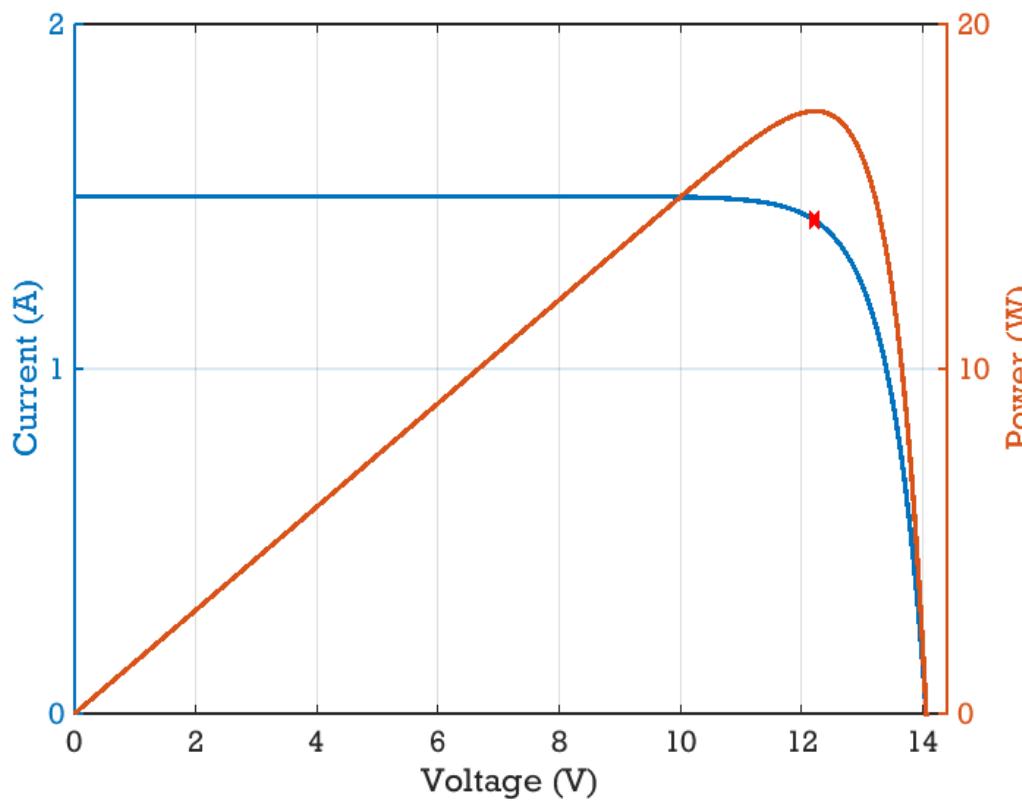
$$-\frac{\Delta I}{\Delta V} = \frac{I(V)}{V}$$

$$-\frac{\Delta I}{\Delta V} = \frac{I}{V}$$

Maximum power is achieved when the incremental conductance is equal to the negative of the instantaneous conductance



# Example



$$V^* = 12.22V$$

$$I^* = 1.40A$$

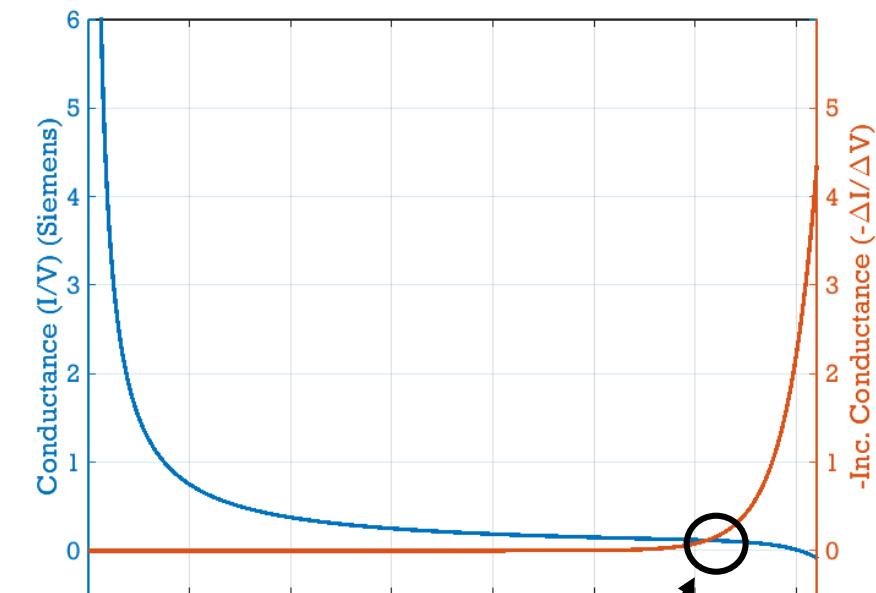
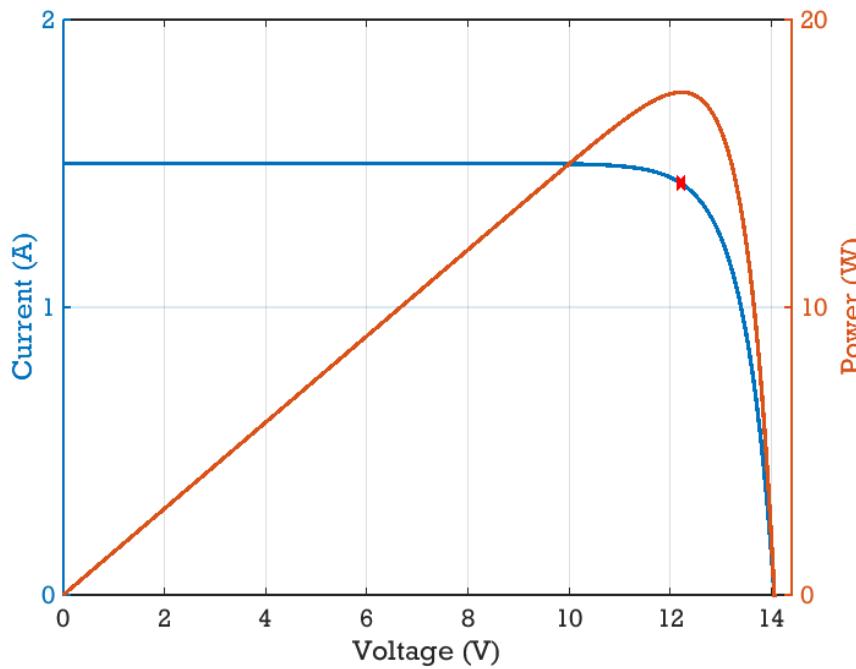
Instantaneous G at MPP

$$I^*/V^* = 0.117 \text{ Siemens}$$

Incremental G at MPP

$$\frac{\Delta I(V^*)}{\Delta V(V^*)} = \frac{-0.0028}{0.0240} \approx -0.117$$

numerically determined



Maximum power point



# IC Method

- Method is implemented by rapidly sampling the current and voltage of the PV panel:
  - $I[0], I[1], \dots I[t], \dots$
  - $V[0], V[1], \dots V[t], \dots$
- Compute incremental conductance:
  - $\Delta I / \Delta V = (I[t] - I[t-1]) / (V[t] - V[t-1])$
- Compute the instantaneous conductance:
  - $I[t]/V[t]$



# IC Method

