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Learning Outcomes

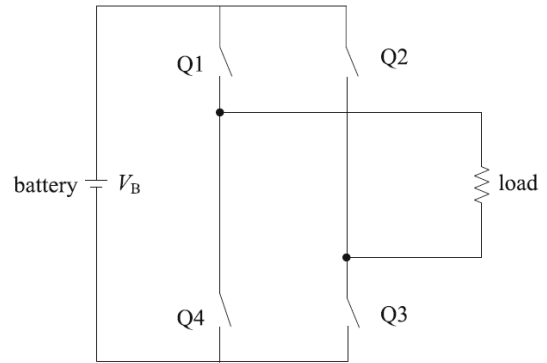
At the end of this lecture, you will be able to:

- ✓ draw and understand the basic operational principles of inverters
- ✓ describe the differences in squarewave and sinusoidal inverters
- ✓ determine the power output supplied by an inverter

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Inverters: Basic Circuit

- Use solid-state switching to alternate polarity of voltage applied to a load
- Switch in pairs
 - Q1, Q3 open and close at same time
 - Q2, Q4 open and close at the same time
- Voltage output can be increased via DC-DC converter at the input or transformer at the output (or both)

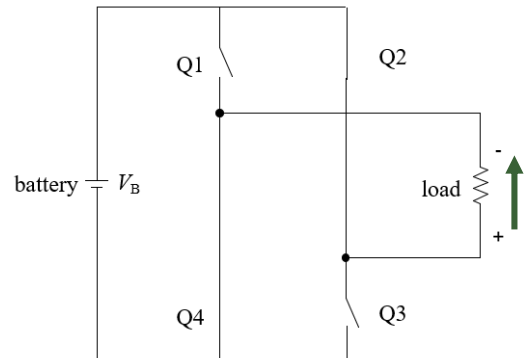
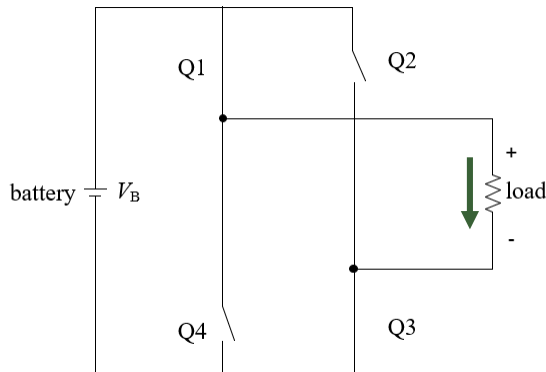


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Inverters: Basic Circuit



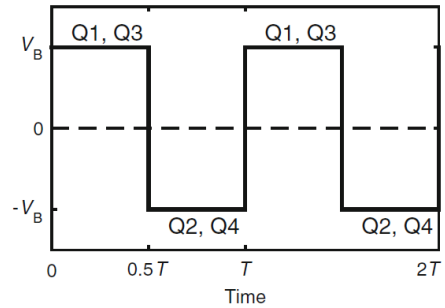
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Output Signal

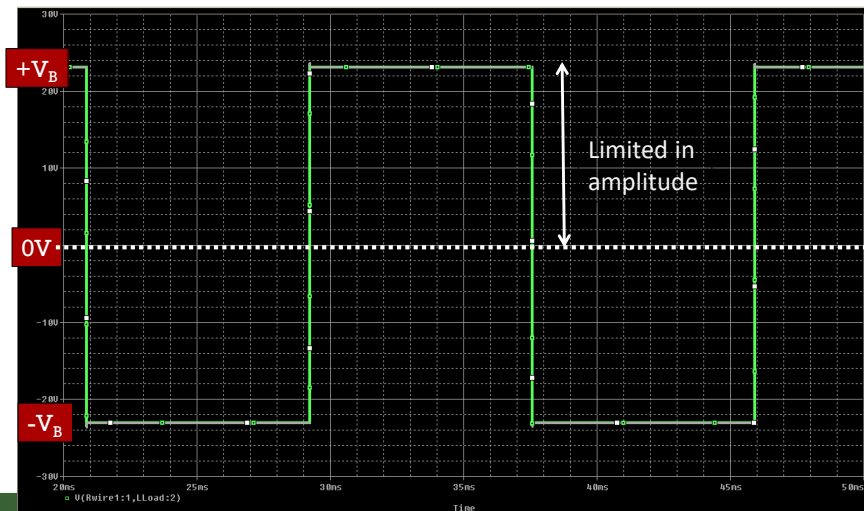
- Waveform is square
- Centered at zero



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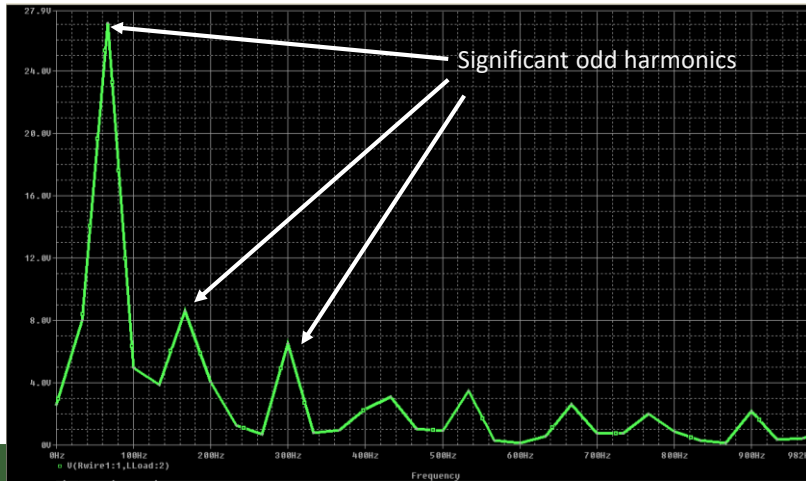


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Inverter

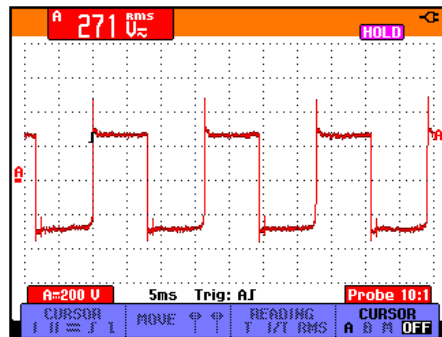


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Squarewave Inverter



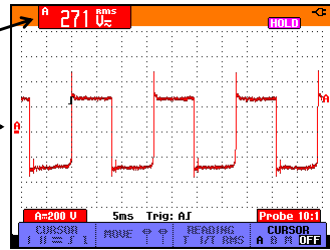
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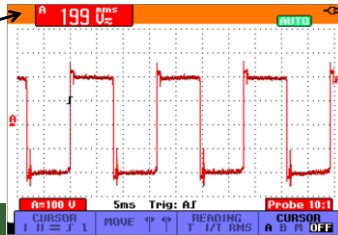
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Squarewave Inverter

$V_B = 12.4 \text{ V}$



$V_B = 9 \text{ V}$



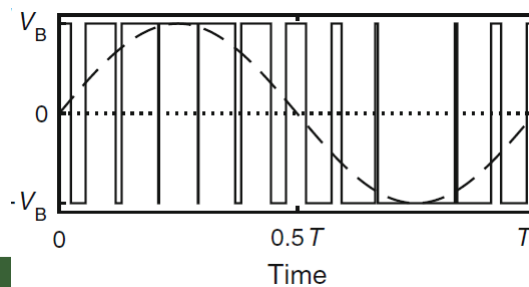
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PWM Inverters

- Distortion in output can be reduced using PWM
- Vary duty cycle over the course of the output



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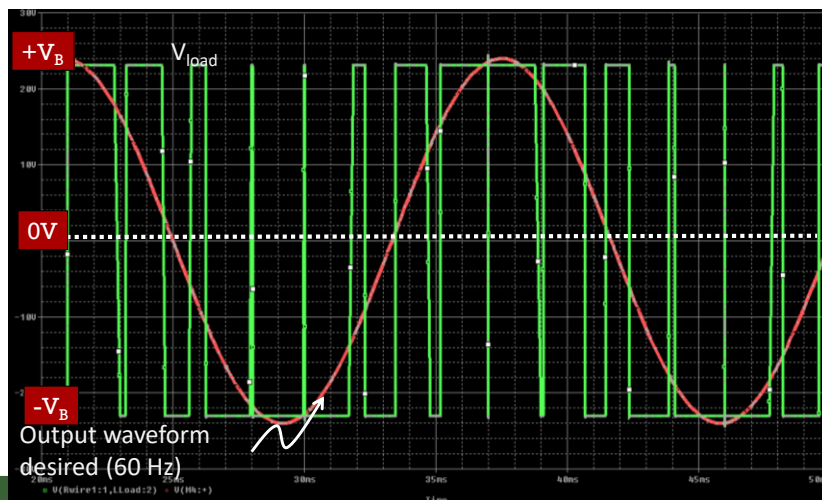
PWM Inverter

- Switching frequency should be much greater (4kHz - 10kHz) than fundamental frequency (60 Hz or 50 Hz)
- Basic idea: vary the duty ratios within each switching period to replicate a sine wave

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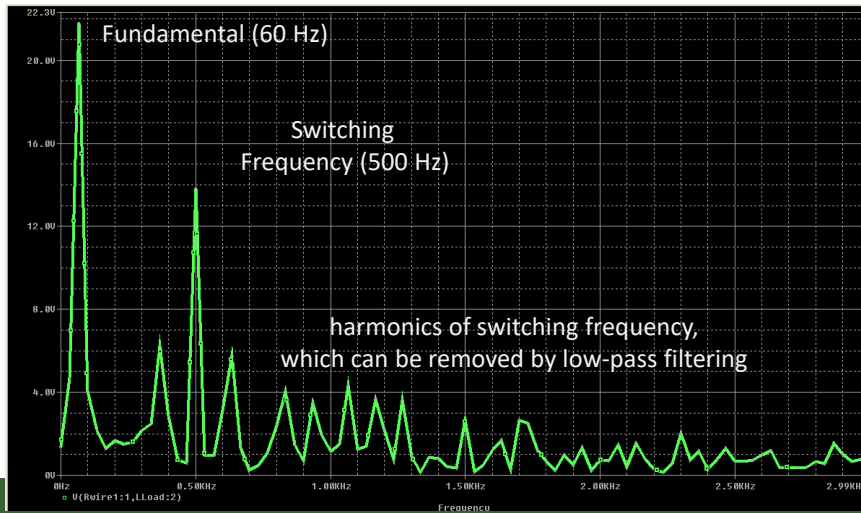
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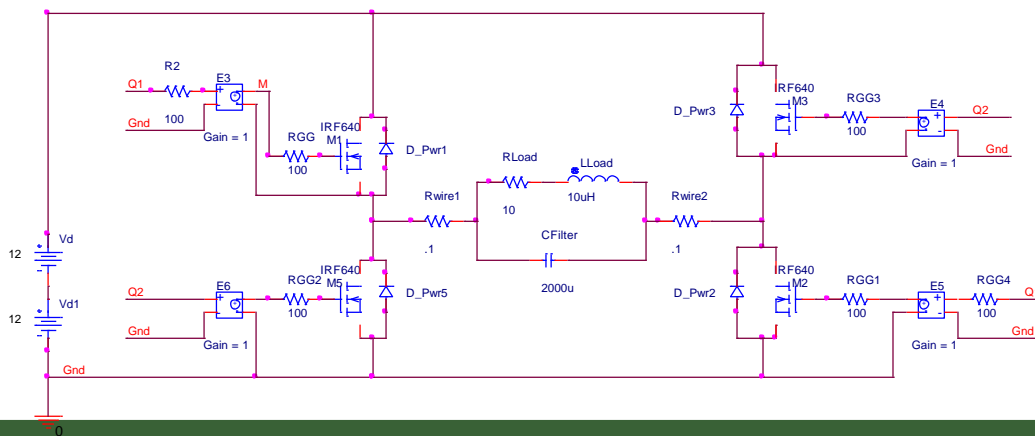


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PWM Inverter

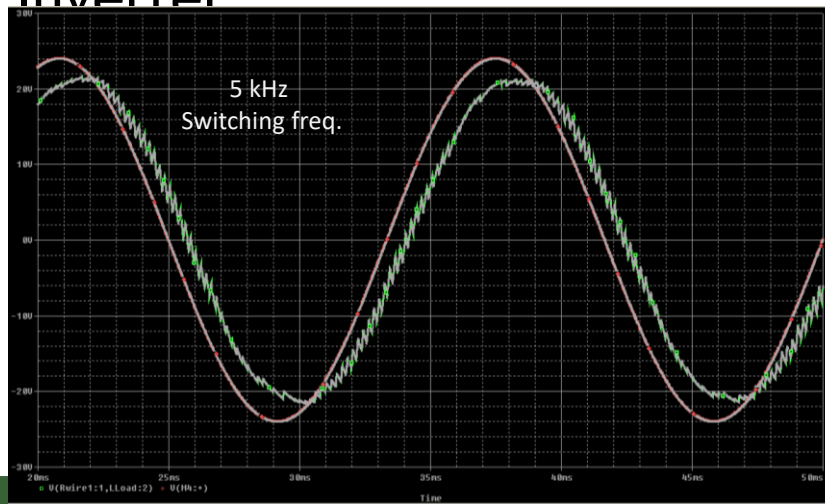


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PWM Inverter



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PWM Inverter

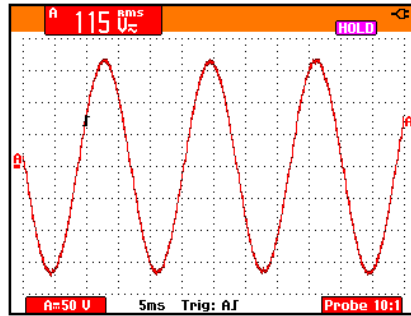


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PWM Inverter

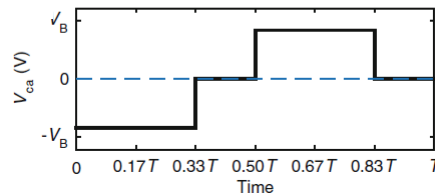
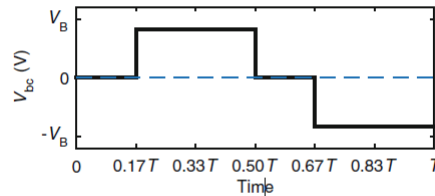
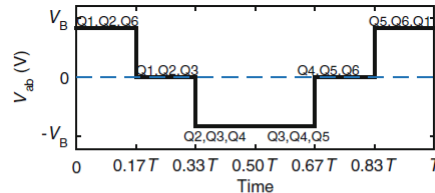
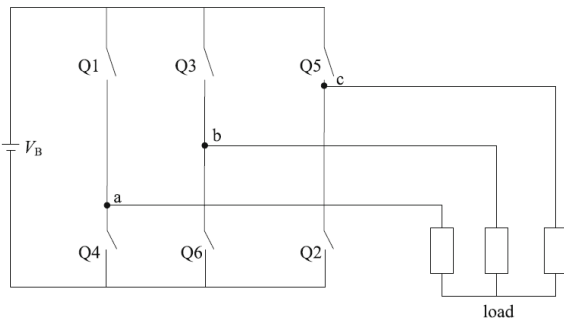


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Three-Phase Inverters



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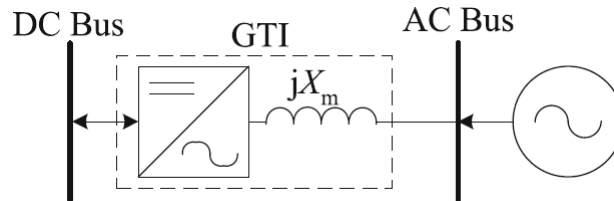
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Grid Tied Inverters (GTI)

- Certain inverters can be coupled to AC Bus's with other AC coupled sources

Note that "grid tied" does not necessarily mean the national grid is on site



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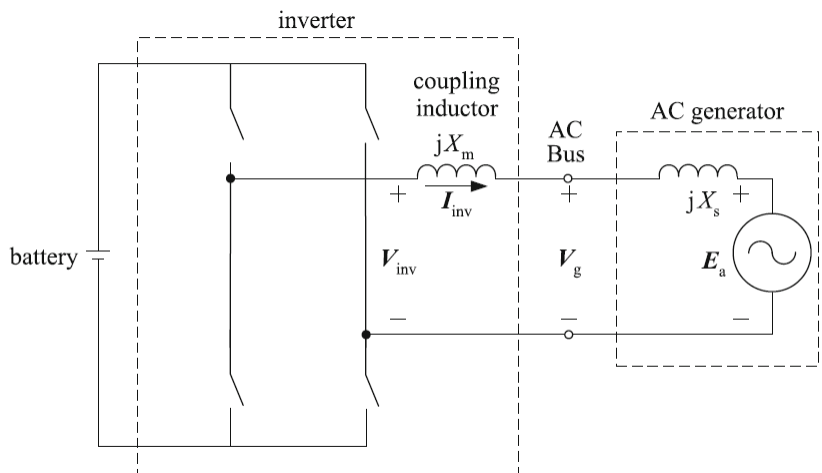
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GTI

- Inverters have large coupling inductors
- Inverter current:

$$I_{inv} = \frac{V_{inv} - V_g}{jX_m}$$



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Inverter Power

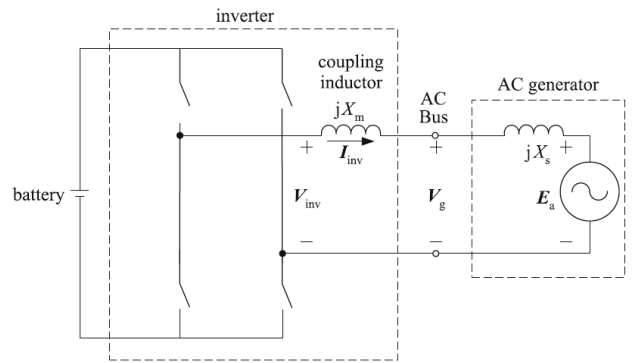
$$P_{\text{inv}} = \text{Re} \{ \mathbf{V}_{\text{inv}} \mathbf{I}_m^* \} = \text{Re} \left\{ \mathbf{V}_{\text{inv}} \left(\frac{\mathbf{V}_{\text{inv}} - \mathbf{V}_g}{jX_m} \right)^* \right\}$$

$$P_{\text{inv}} = \text{Re} \left\{ \frac{|\mathbf{V}_{\text{inv}}|^2}{-jX_m} - \frac{\mathbf{V}_m \mathbf{V}_g}{-jX_m} \right\}$$

$$P_{\text{inv}} = \text{Re} \left\{ \frac{|\mathbf{V}_{\text{inv}}|^2}{-jX_m} - \frac{|\mathbf{V}_{\text{inv}}| |\mathbf{V}_g| \cos(\delta) + j |\mathbf{V}_m| |\mathbf{V}_g| \sin(\delta)}{-jX_m} \right\}$$

$$P_{\text{inv}} = \frac{|\mathbf{V}_{\text{inv}}| |\mathbf{V}_g| \sin(\delta)}{X_m}$$

Power supplied by the inverter can be controlled by adjusting the inverter's voltage magnitude and phase



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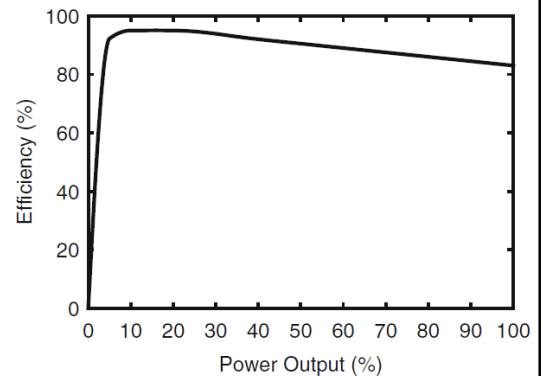
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Inverter Efficiency

- Inverter efficiency is not constant, and is non-linear
- Low efficiency at low-loading
- Inverter efficiency is sometimes reported as the “European” efficiency, which considers different operating points

$$\eta_{\text{inv}} = 0.03\eta_{\text{inv}}(0.05) + 0.06\eta_{\text{inv}}(0.10) + 0.13\eta_{\text{inv}}(0.20) + 0.10\eta_{\text{inv}}(0.30) + 0.48\eta_{\text{inv}}(0.50) + 0.20\eta_{\text{inv}}(1.00)$$



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Practical Considerations

- Higher-quality inverters feature:

- output sinusoidal voltage with little distortion and constant frequency and magnitude;
- good voltage regulation;
- high efficiency at low loading;
- insensitivity to changes in input voltage;
- short-term increased surge capacity;
- low-voltage disconnect capability;
- can be configured in the field;
- include data logging and diagnostic features

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Contact Information

Henry Louie, PhD

Associate Professor

Fr. Wood Endowed Research Chair

Seattle University

 @henrylouie

hlouie@ieee.org

Office: +1-206-398-4619

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