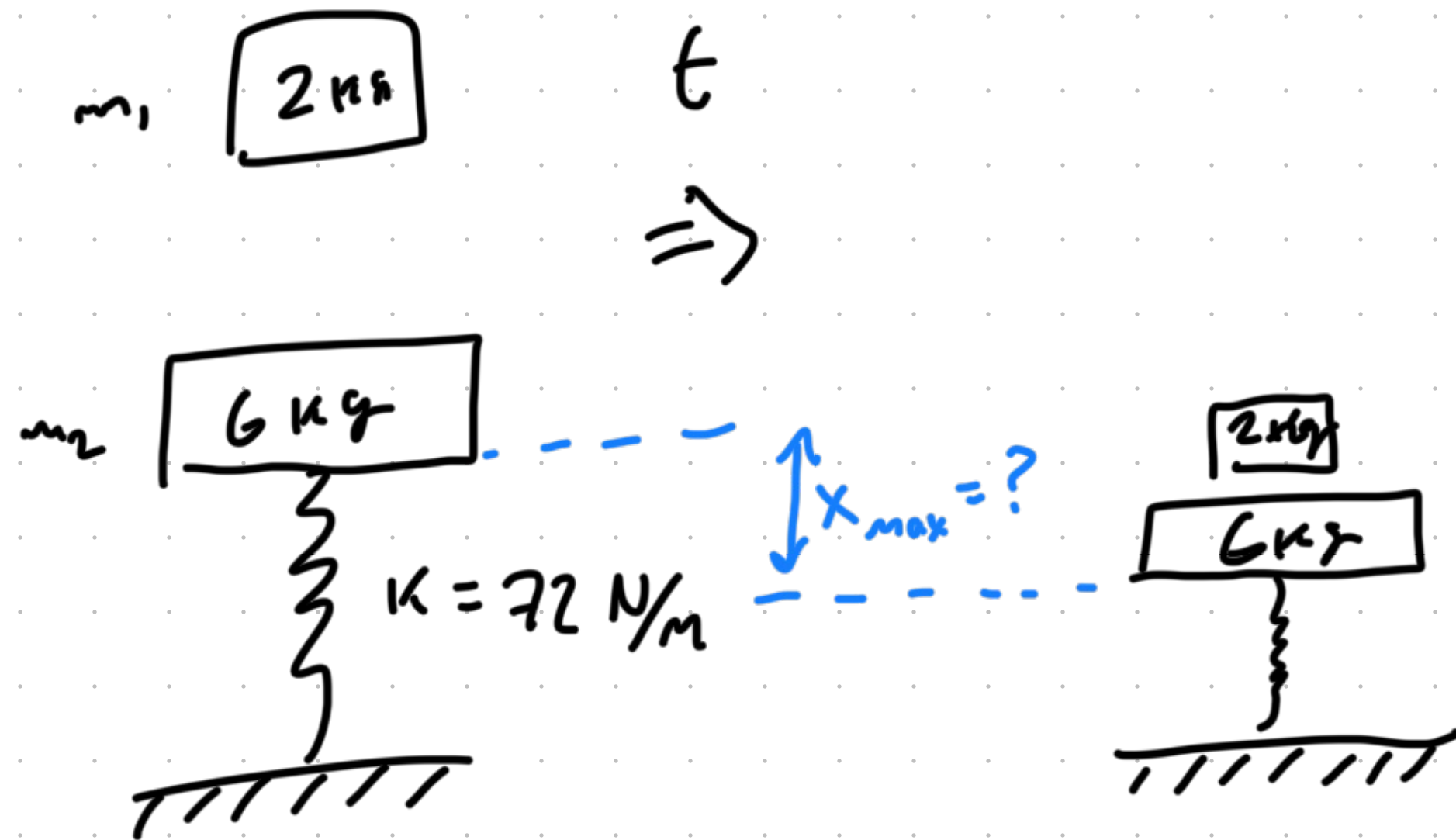


2015 #23



$$\Delta E = \frac{1}{2} K(h+x)^2 - \frac{1}{2} Kh^2 = \frac{1}{2} Kx^2 + \underline{Khx} !$$

initial compression $F_s = m_2 g = Kh$

$$h = \frac{m_2 g}{K} = 0.23 \text{ m}$$

impact speed

$$mgy = \frac{mv^2}{2} \quad v = \sqrt{2gh} = 10 \text{ m/s}$$

post-impact speed $V_g = \frac{m_1 v}{m_1 + m_2} = 2.5 \text{ m/s}$

$$KE_1 = \frac{1}{2} (m_1 + m_2) V_g^2$$

$$KE_2 = 0$$

$$U_{s1} = \frac{1}{2} Kh^2$$

$$U_{s2} = \frac{1}{2} K(h+x_{\text{max}})^2$$

$$U_{g1} = 0$$

$$U_{g2} = -(m_1 + m_2) g x_{\text{max}}$$

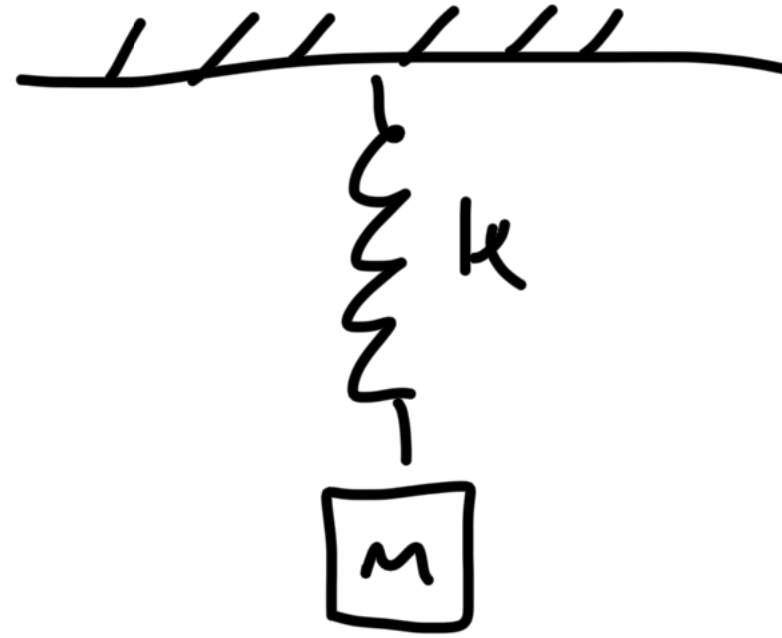
$$(m_1 + m_2) V_g^2 + \cancel{Kh^2} = K(h+x_{\text{max}})^2 - 2(m_1 + m_2) g x_{\text{max}}$$

$$= \cancel{Kh^2} + 2Kh x_{\text{max}} + Kx_{\text{max}}^2 - 2(m_1 + m_2) g x_{\text{max}}$$

$$0 = Kx_{\text{max}}^2 + 2[Kh - (m_1 + m_2)g]x_{\text{max}} - (m_1 + m_2) V_g^2$$

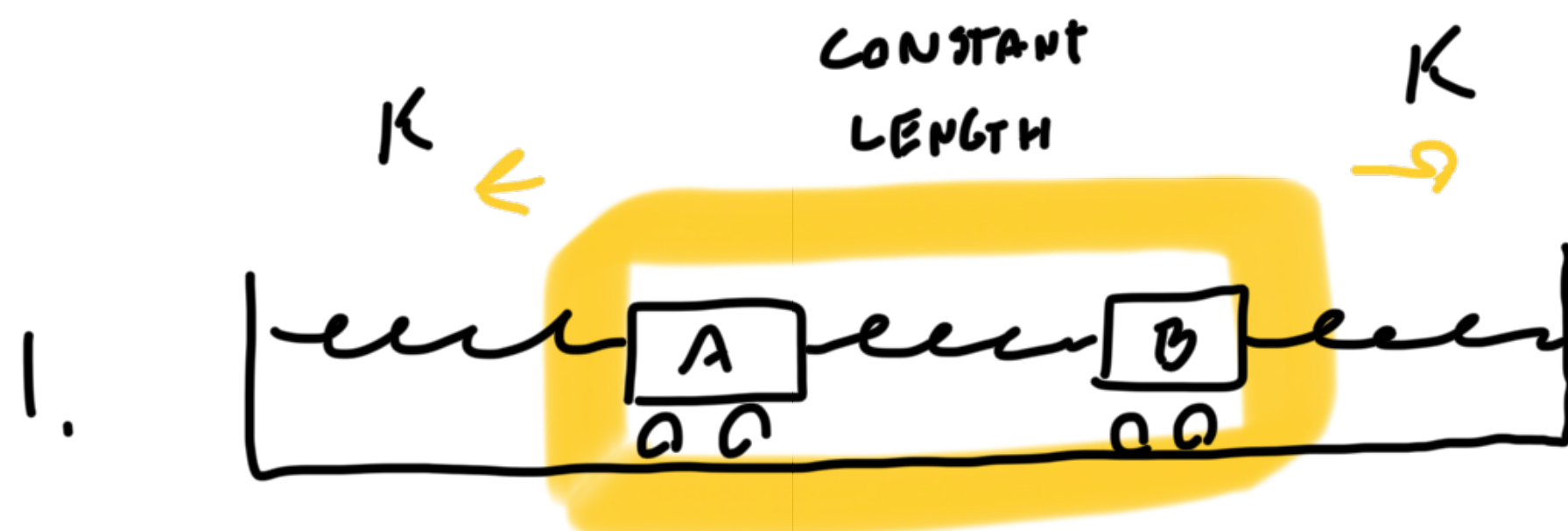
Sol. $x_{\text{max}} = 1.16 \text{ m}$

(B)



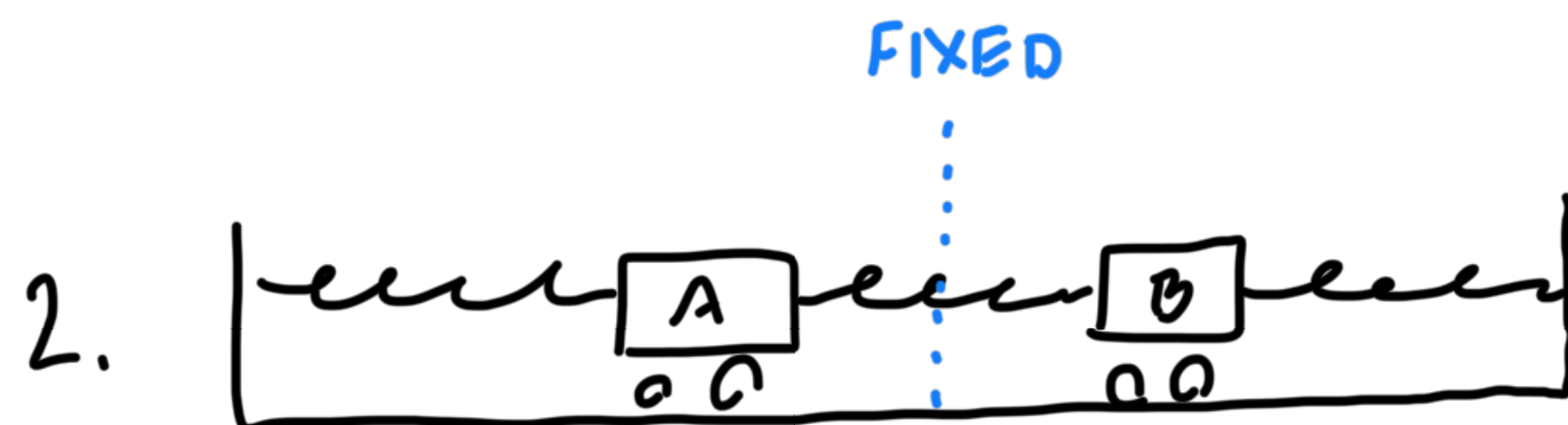
Same ω
different equilibrium lengths

2015 #25

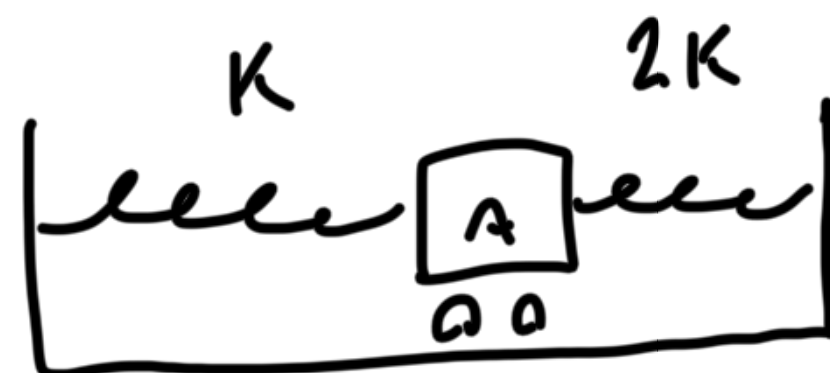


$$\omega_1 = \sqrt{\frac{2K}{2m}} = \sqrt{\frac{K}{m}}$$

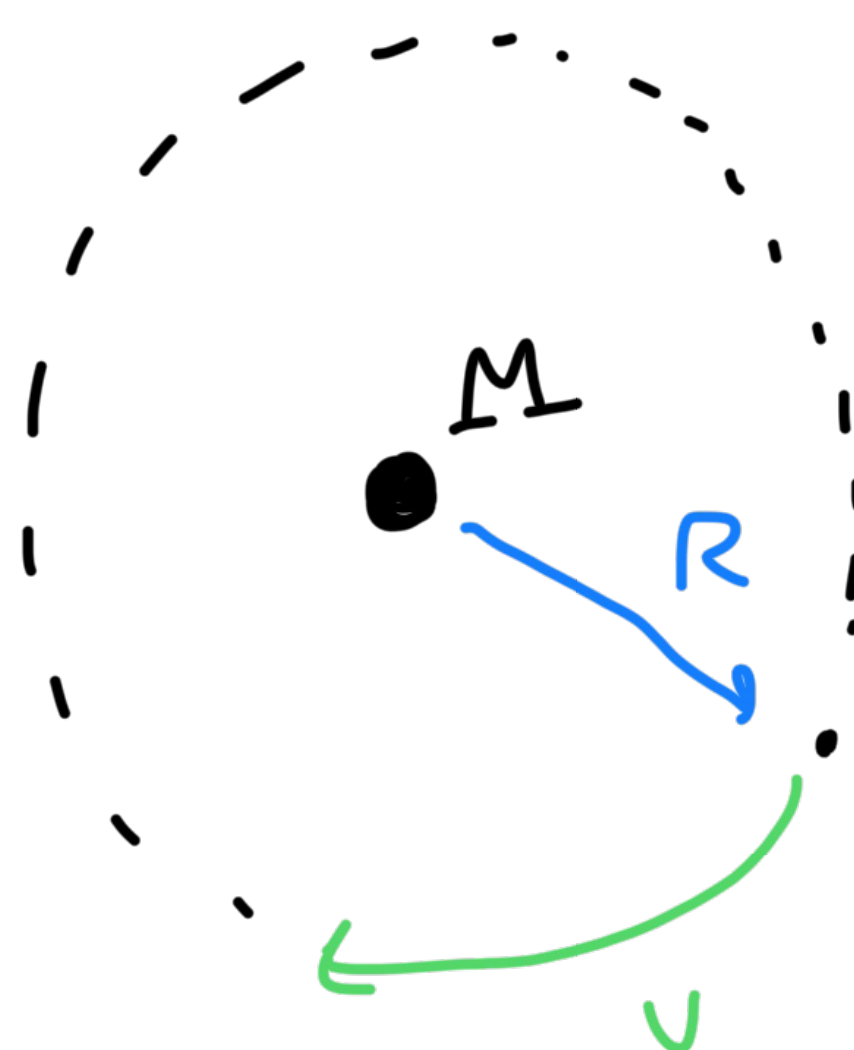
$$\frac{\omega_2}{\omega_1} = \sqrt{3} \quad \textcircled{A}$$



$$\omega_2 = \sqrt{\frac{3K}{m}}$$



Orbits



$$F_{\text{cent}} = \frac{mv^2}{R} = \frac{GMm}{R} = F_{\text{grav}}$$

given R , $v = \sqrt{\frac{GM}{R}}$

$$T = 2\pi \frac{R}{v} = 2\pi \frac{R}{\sqrt{GM/R}} = 2\pi \sqrt{\frac{R^3}{GM}}$$

Non-gravitational orbits

$$F \propto R^{-2}$$

let $F = \gamma R^{-2} = \frac{mv^2}{R} \Rightarrow v = \sqrt{\frac{\gamma}{mR}}$

$$\gamma = GMm \Rightarrow v = \sqrt{\frac{GM}{R}}$$

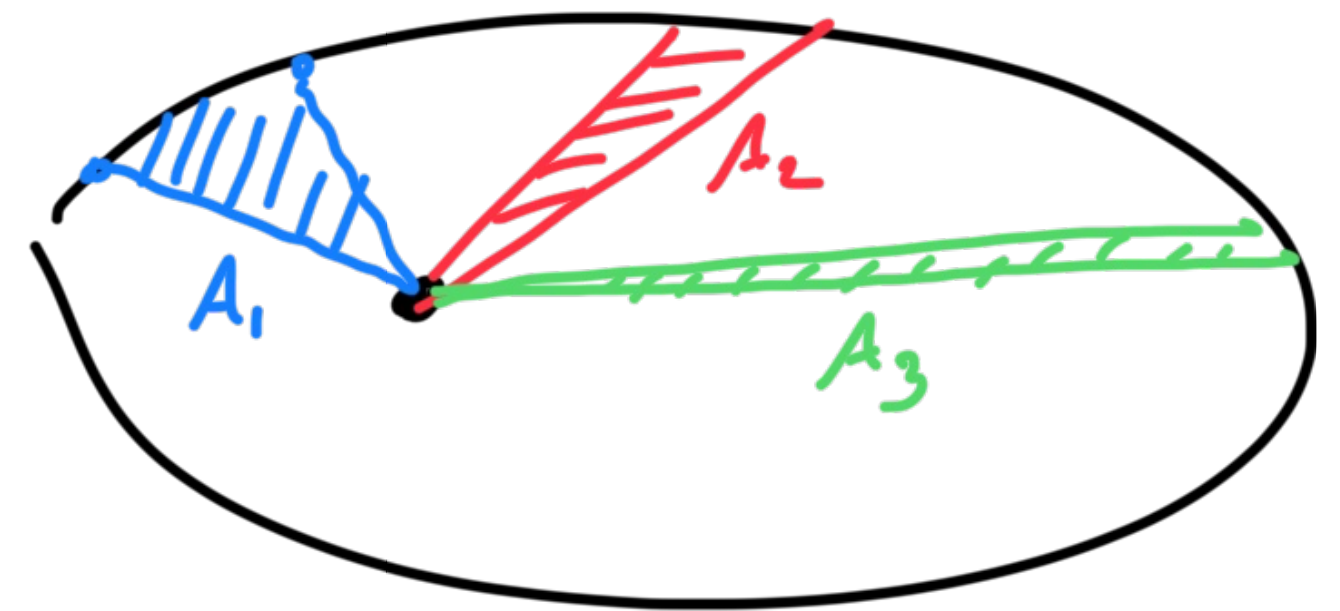
Kepler's Laws

1. all bound orbits are elliptical with the orbited body at a focus.

2. equal areas in equal times

$$T^2 \cdot \frac{r^2}{2} \cdot \frac{d\theta}{dt} = \pi ab$$

3. $T^2 \propto R^3$



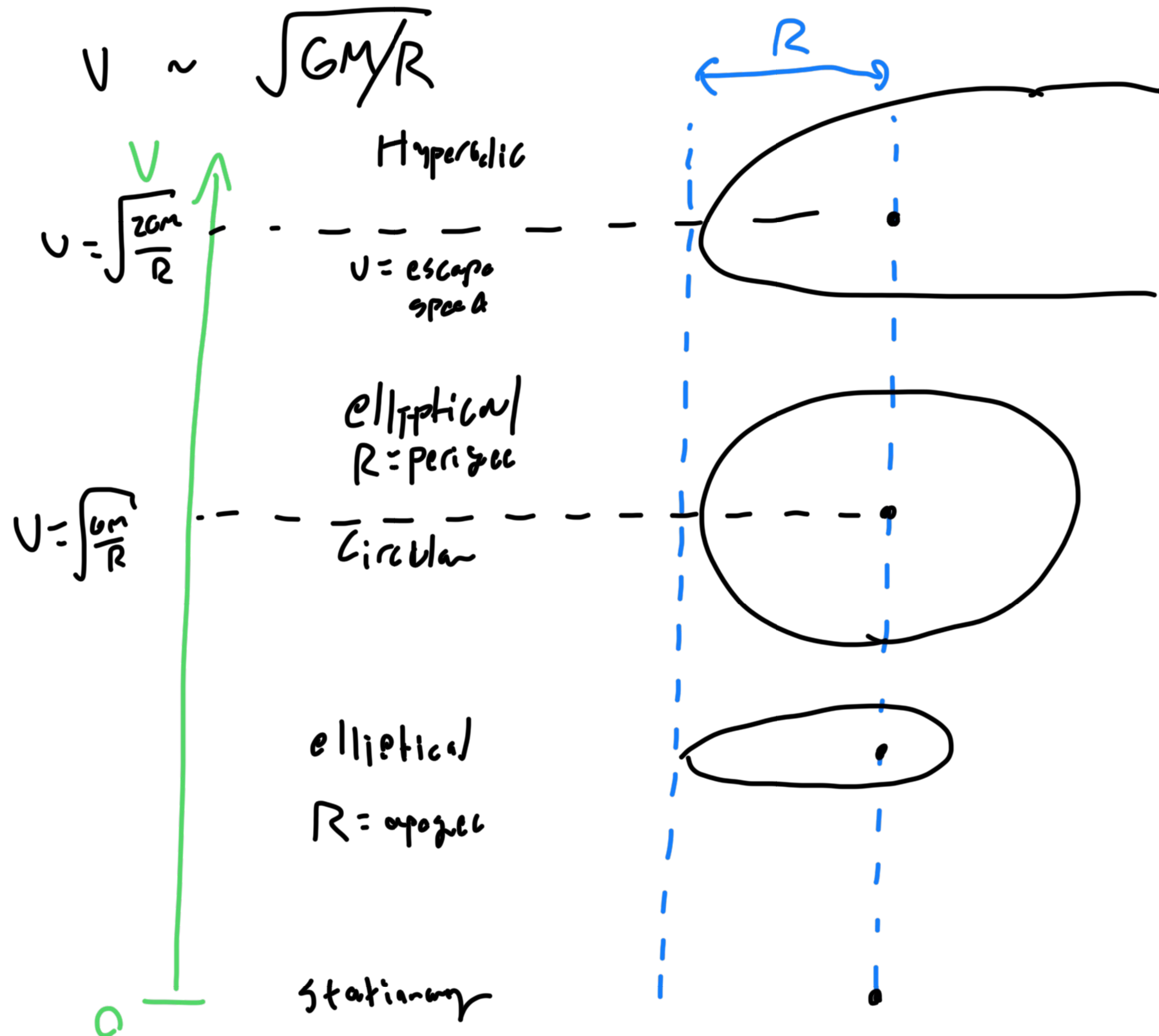
$$A_1 = A_2 = A_3$$

$$t_1 = t_2 = t_3$$

$$\dot{\theta}_1 < \dot{\theta}_2 < \dot{\theta}_3$$

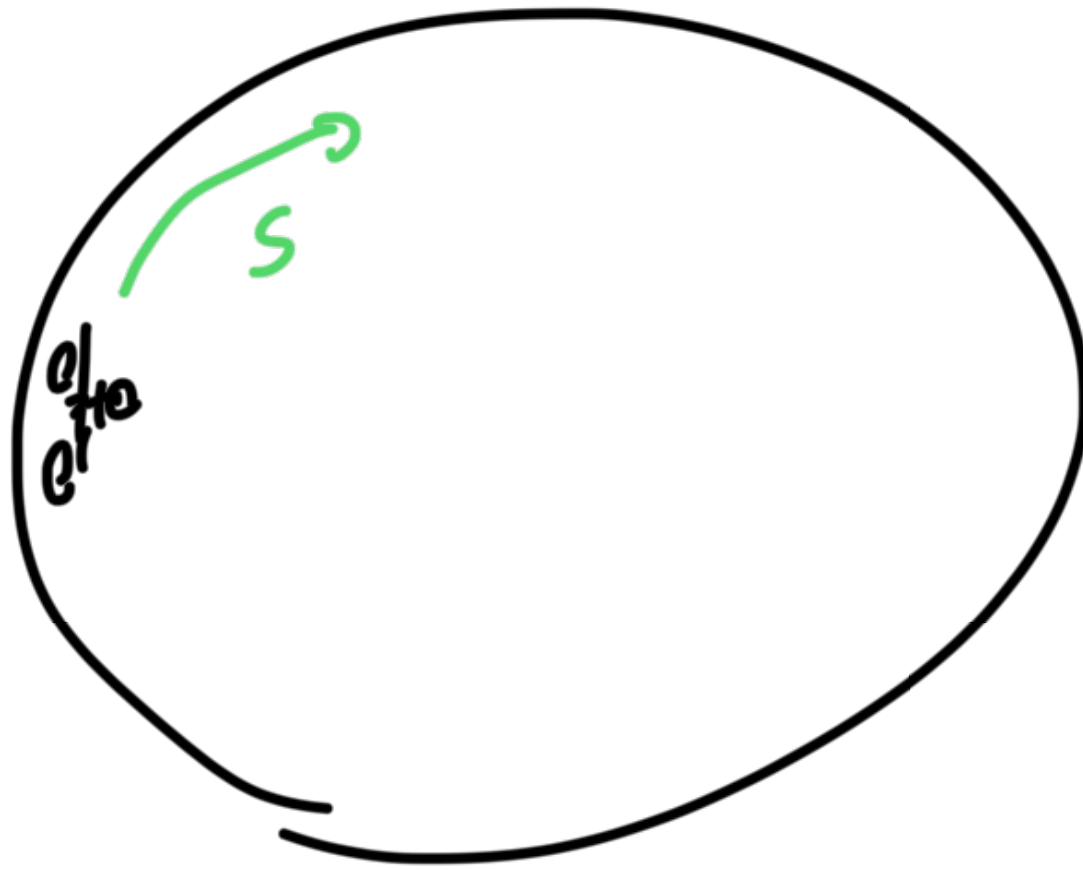
$$\dot{\theta} = \frac{d\theta}{dt} \neq \omega$$

Non-circular orbits



Topic 7.4

2017 #1



$\otimes g$
into page

Friction is up, to counter gravity.

$$F_N = \frac{ms^2}{R}$$

$$F_f \leq \mu F_N = \mu \frac{ms^2}{R} = mg$$

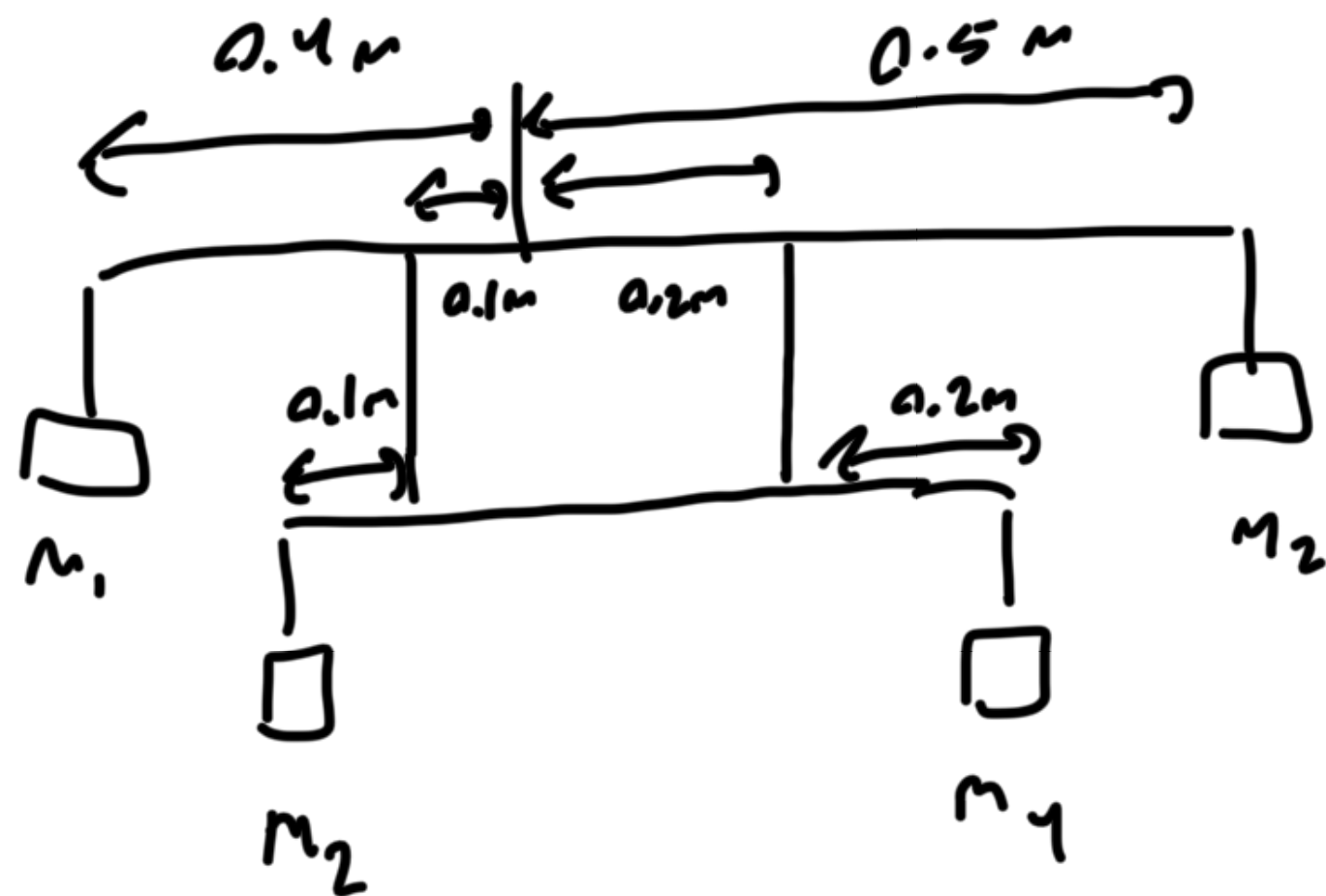
$$\mu \propto s^k \quad k = ?$$

to prevent sliding down wall

$$\mu_{\min} = \frac{gR}{s^2} \propto s^{-2}$$

(D)

2017 #6



$$m_1 = 400\text{ g}$$

$$m_2 = 200\text{ g}$$

$$m_4 = 500\text{ g}$$

$$m_3 = ?$$

CCW positive

$$\Sigma \tau_{\text{top}} = (0.4\text{ m}) m_1 g + (0.1\text{ m}) T_1 - (0.2\text{ m}) T_2 - (0.5\text{ m}) m_2 g = 0$$

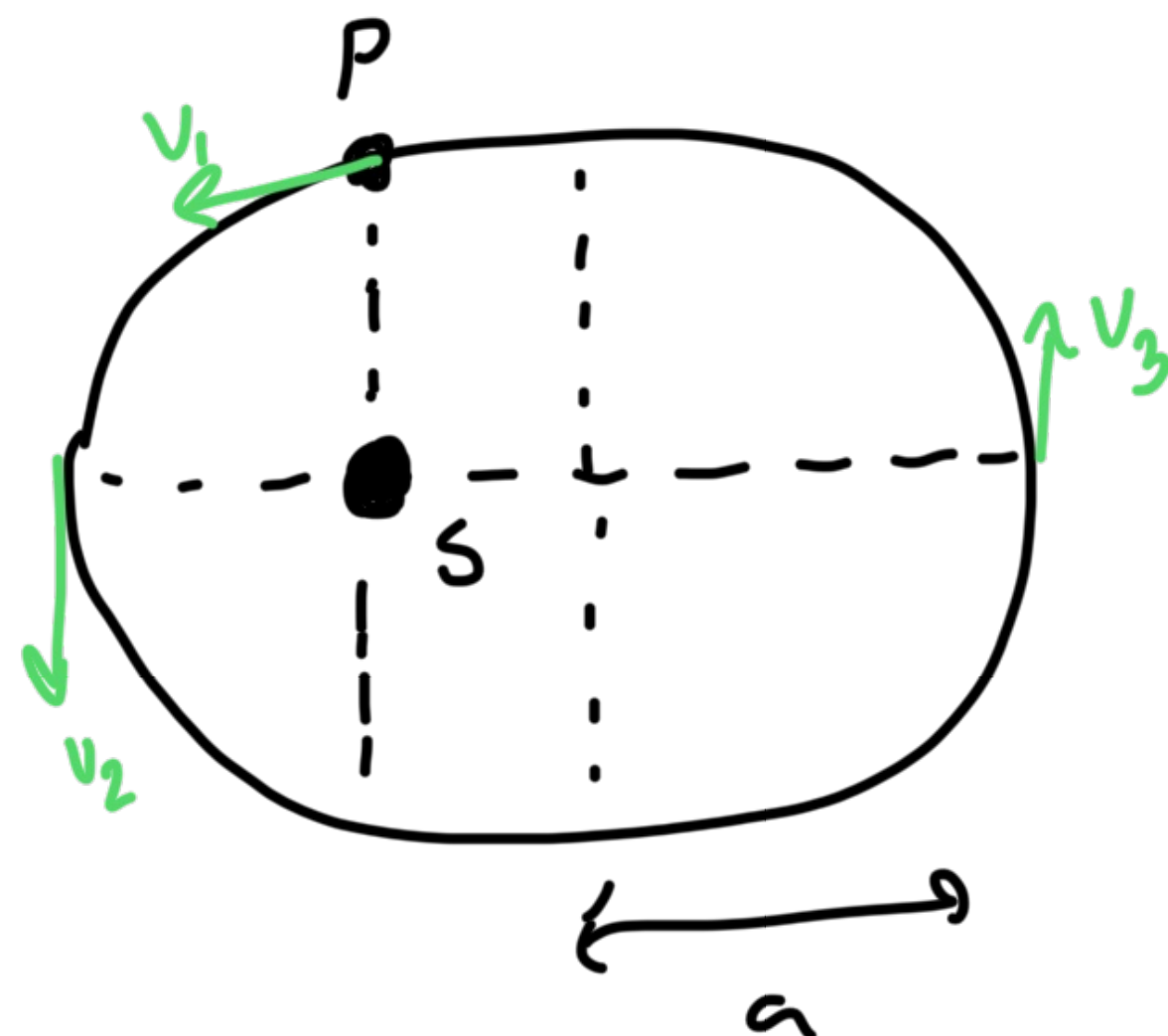
$$\Sigma \tau_{\text{bot}} = (0.2\text{ m}) m_3 g - (0.1\text{ m}) T_1 + (0.2\text{ m}) T_2 - (0.4\text{ m}) m_4 g = 0$$

$$m_3 = 700\text{ g}$$

$$\Sigma \tau_{\text{top}} + \tau_{\text{bot}} = (0.4\text{ m}) m_1 g + (0.2\text{ m}) m_3 g - (0.5\text{ m}) m_2 g - (0.4\text{ m}) m_4 g = 0$$

(E)

2017 #25

Perigee = $0.5a$ $v_2 = ?$ $\overline{SP} = ?$

$$SP + \sqrt{SP^2 + a^2} = 2a$$

$$SP = 3a/4$$

$$\frac{1}{2}mv_2^2 - \frac{GMm}{a/2} = \frac{1}{2}mv_3^2 - \frac{GMm}{3a/2}$$

$$\frac{mv_2^2 a}{2} = \frac{3mv_3^2 a}{2} \Rightarrow v_3 = \frac{v_2}{3}$$

Can't do
K2L w/o v_3 !

$$\frac{4}{9}mv_2^2 = \frac{GMm}{a/2} - \frac{GMm}{3a/2} = \frac{4GMm}{3a}$$

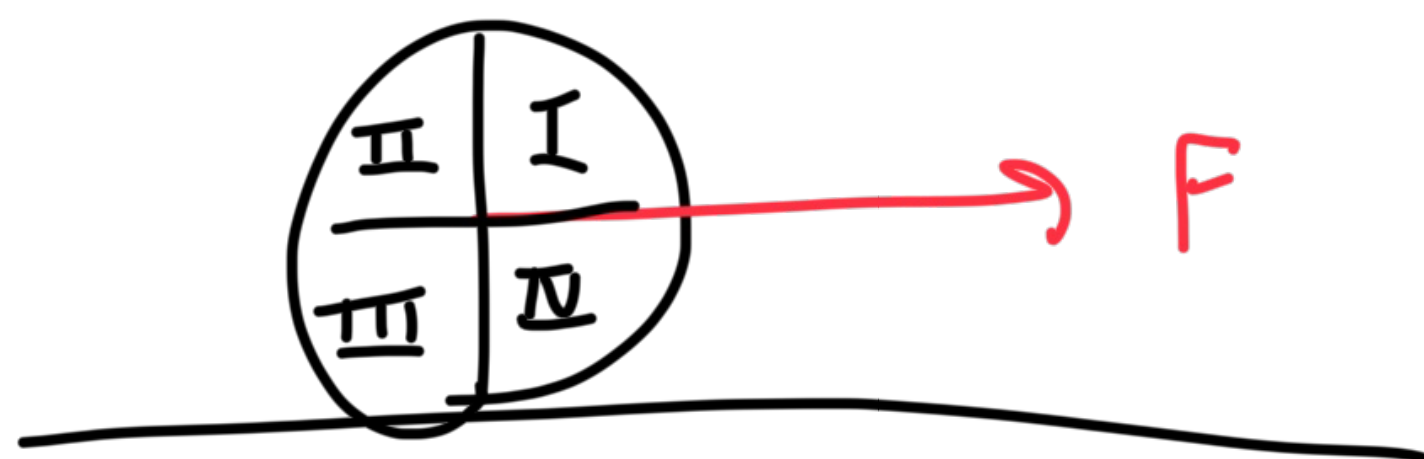
$$v_2^2 = \frac{3GM}{a}$$

$$\frac{1}{2}mv_2^2 - \frac{GMm}{a/2} = \frac{1}{2}mv_1^2 - \frac{GMm}{3a/4}$$

$$v_1^2 = v_2^2 - \frac{4GM}{a} + \frac{8GM}{3a} = GM \left(\frac{3}{a} - \frac{4}{a} + \frac{8}{3a} \right)$$
$$= \frac{5GM}{3a}$$

$$\frac{v_2^2}{v_1^2} = \frac{3GM/a}{\frac{5}{3}GM/a} = \frac{9}{5} \Rightarrow \frac{v_2}{v_1} = \frac{3}{\sqrt{5}} \quad \textcircled{A}$$

2017 #18

Any points with $|a| = 0$?

$$a_c = \omega^2 r \quad \text{towards center}$$

$$a_t = \alpha r \quad \text{direction of rotation}$$

$$a \text{ (translational)} \rightarrow F$$

$$\text{I. } \vec{a}_c + \vec{a}_t \text{ is downwards } \times$$

$$\text{II. } \vec{a}_c + \vec{a}_t \text{ is rightwards } \times$$

$$\text{III. } \vec{a}_c + \vec{a}_t \text{ is upwards } \times$$

$$\text{IV. } \vec{a}_c + \vec{a}_t \text{ is leftward maybe?}$$

$$\|\vec{a}_c + \vec{a}_t\| = r\sqrt{\omega^4 + \alpha^2} \quad \|a\| = \alpha R$$

So, yes! (D)