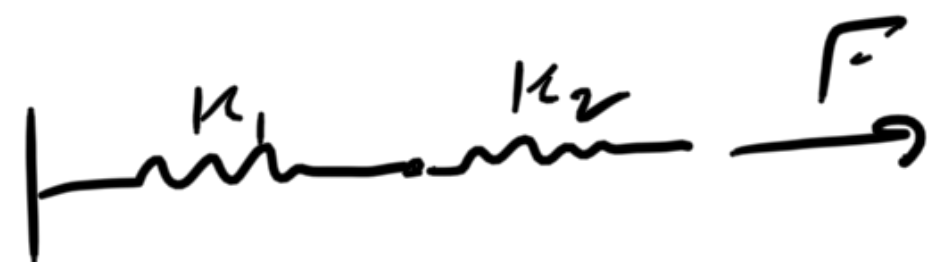


2019 B #3



$$U_1 / U_2 = ?$$

$$U = \frac{1}{2} k x^2$$

$$\frac{U_1}{U_2} = \frac{k_1 x_1^2}{k_2 x_2^2}$$

$$F = k x$$

$$x = F / k$$

$$F_1 = k_1 x_1$$

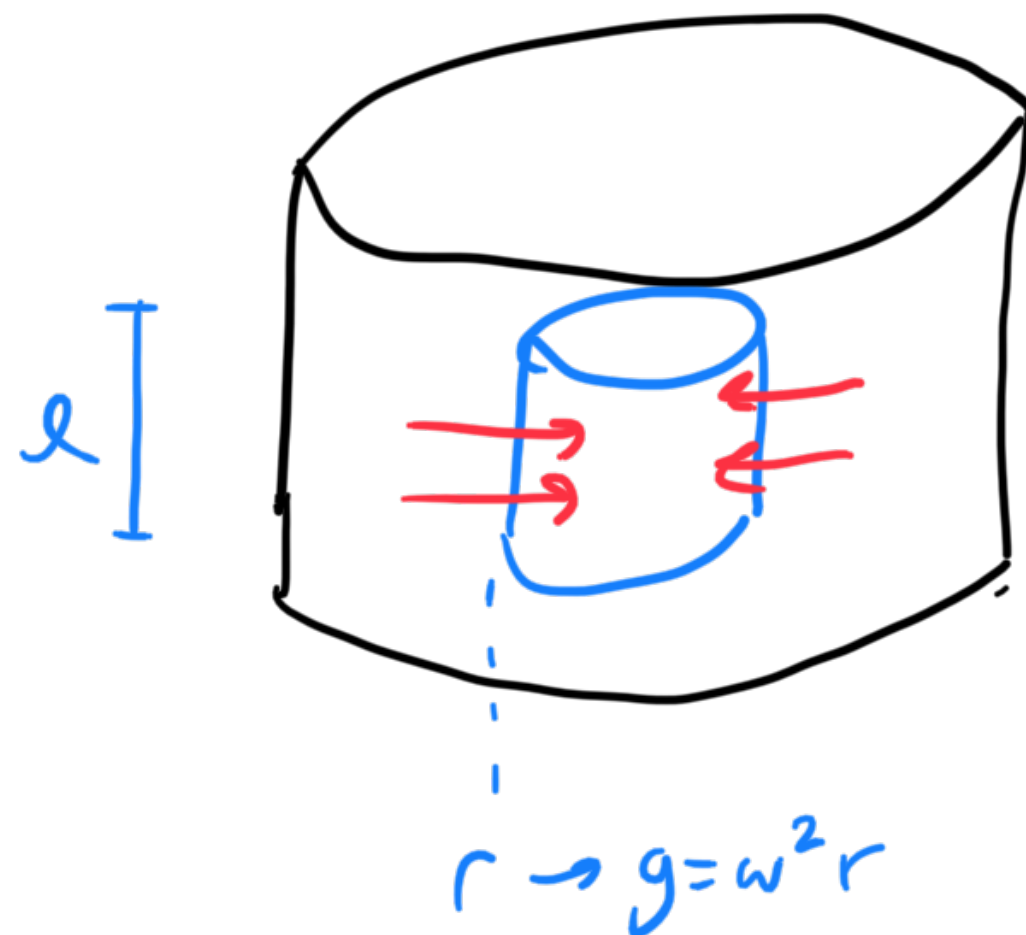
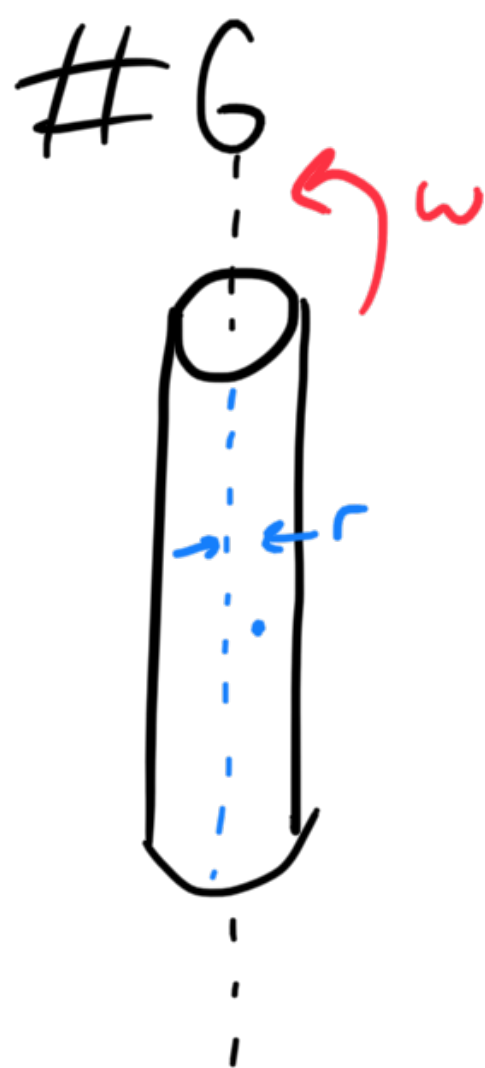
$$F_2 = k_2 x_2$$

$$F_1 = F_2$$

$$x_1 = F_1 / k_1$$

$$x_2 = F_2 / k_2$$

$$\begin{aligned} \frac{U_1}{U_2} &= \frac{k_1 \cancel{F_1} / k_1^2}{k_2 \cancel{F_2} / k_2^2} \\ &= \frac{k_2}{k_1} \end{aligned}$$



Gauss's Law

$$\oiint \mathbf{g} \cdot d\mathbf{A} = 4\pi G M_{\text{enc.}}$$

$$g A_{\text{col.}} = 2\pi r l g$$

$$g = \frac{2GM}{r l} = \frac{2G\lambda}{r}$$

$$= \omega^2 r$$

$$\frac{2G\lambda}{r} = \omega^2 r$$

$$\lambda = \frac{\omega^2 r^2}{2G} = \frac{\omega^2}{2\pi G} A \phi r$$

$$A = \pi r^2$$

only held by grav.

$$\rho(r) = ?$$

λ = length density

#10

$$\sum F_x = 0 \Rightarrow P_{x_i} = P_{x_f}$$

$$P_{x_i} = (M_c + m) v_c$$

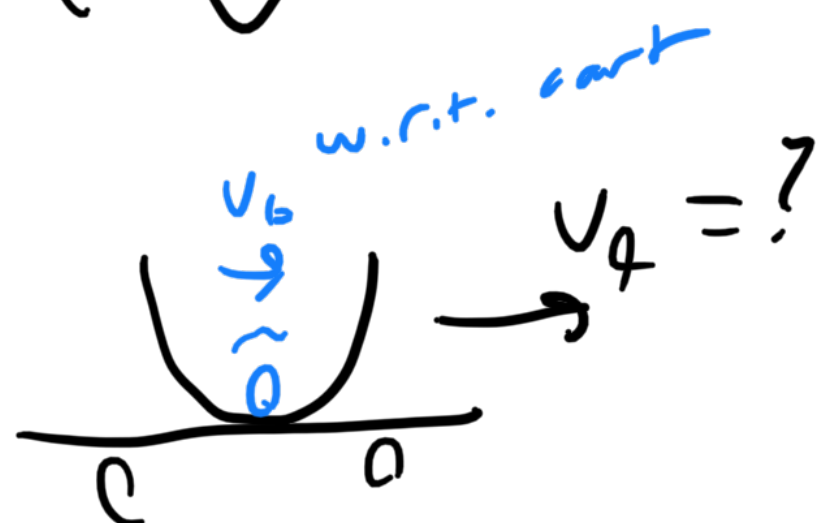
$$= P_{x_f} = (M_c + m) v_f + m v_b$$

w.r.t. cart

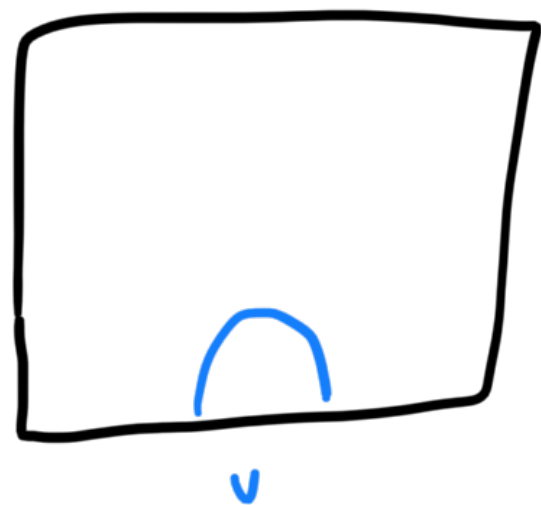
$$\Rightarrow v_f = \frac{(M_c + m) v_c - m v_b}{(M_c + m)}$$



t ↓↓



#13



$$U = 2U$$

How does
wet region
change?

$$U = m/s$$

$$g = m/s^2$$

$$L = U^2/g \rightarrow U^2 \quad (D)$$

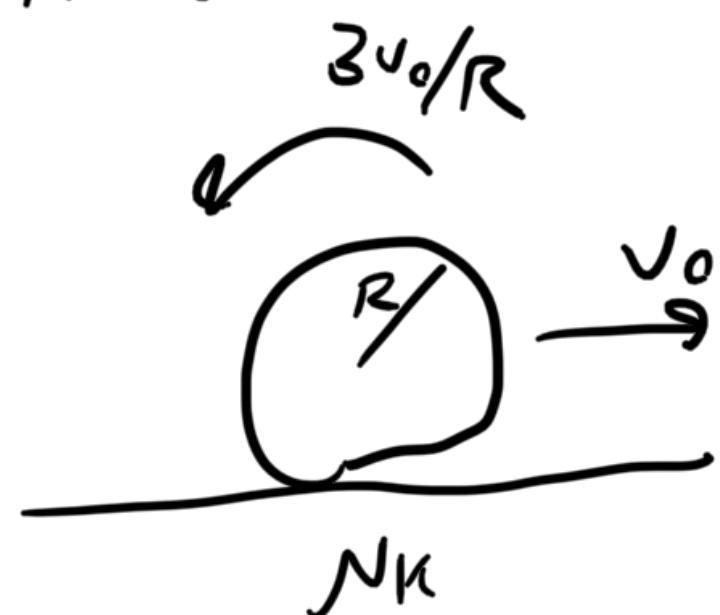


$$h = \frac{1}{2} U^2 = \frac{U^2}{2g}$$

$$D = U \sin \theta \cdot \frac{2U \cos \theta}{g} = \frac{U^2 \sin 2\theta}{g}$$

$$\propto U^2 \quad (D)$$

#16



T to return to starting position?

Slipping:

$$a = F_k/m$$

$$\alpha = -F_k r / I$$

$$F_k = -\mu g$$

$$v(t) = v_0 + at \quad \omega(t) = \omega_0 + \alpha t$$

$$v(T) = r\omega(T)$$

$$v_0 - \mu g T = \left(-\frac{3v_0}{r} + \mu g T / r \right) r$$

$$T = \frac{2v_0}{\mu g}$$

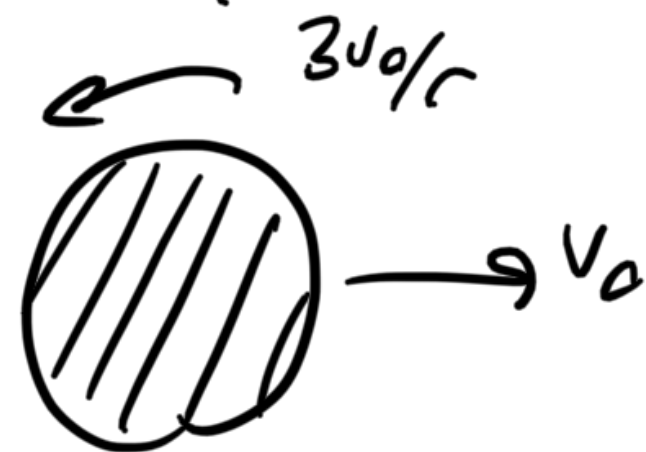
after T , $v = v(T)$

$$v\left(\frac{2v_0}{\mu g}\right) = v_0 - \mu g \frac{2v_0}{\mu g} = -v_0$$

$$x(T) = v_0 T + \frac{1}{2} a T^2 = v_0 \frac{2v_0}{\mu g} - \frac{1}{2} \mu g \left(\frac{2v_0}{\mu g}\right)^2$$

$$= 0 \quad \checkmark$$

#17



$$T_{\text{disk}} \stackrel{?}{=} T_{\text{hoop}}$$

$$\alpha' = 2\mu g/r \quad (\text{since } I' = I/2)$$

$$\tau' = \tau \quad \leftarrow F_k \text{ stays the same}$$

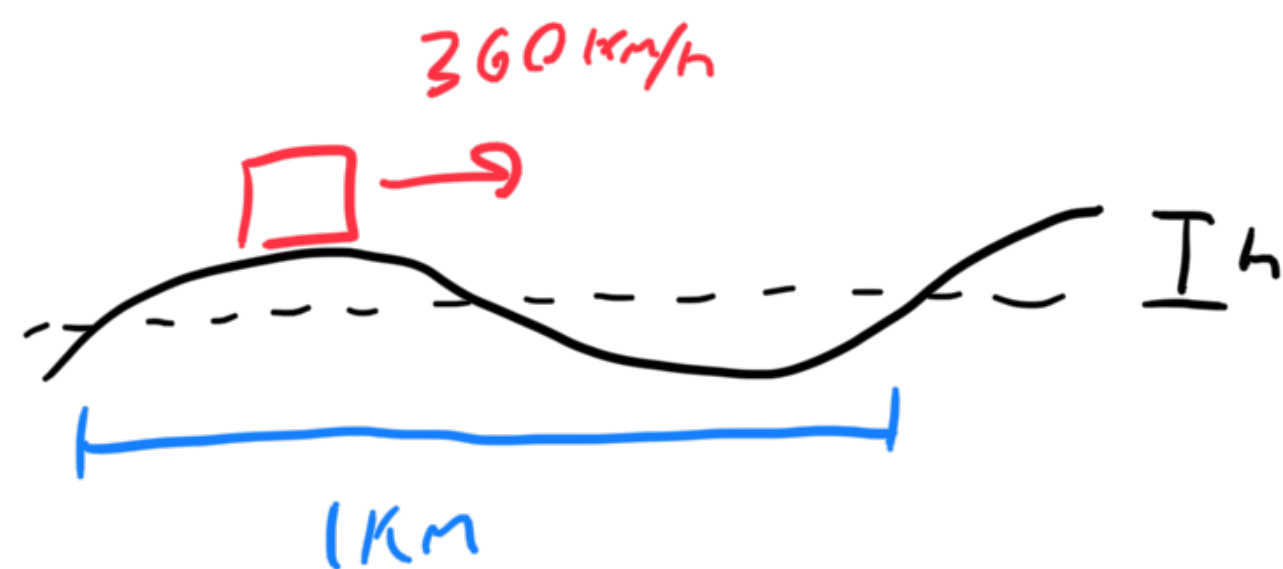
$$T' = \frac{4v_0}{3\mu g} \quad \text{stops slipping too soon.}$$

$$v(T) = \frac{-v_0}{3} \quad x(T) = \frac{4v_0^2}{9\mu g}$$

$$\begin{aligned} T_{\text{tot}} &= T' + \left| \frac{x(T)}{v(T)} \right| = \frac{4v_0}{3\mu g} + \frac{4v_0}{3\mu g} \\ &= \frac{8v_0}{3\mu g} \neq T \end{aligned}$$

(D)

#23



$$a_{\max} = 0.1 \text{ m/s}^2$$

$$\text{max } h = ?$$

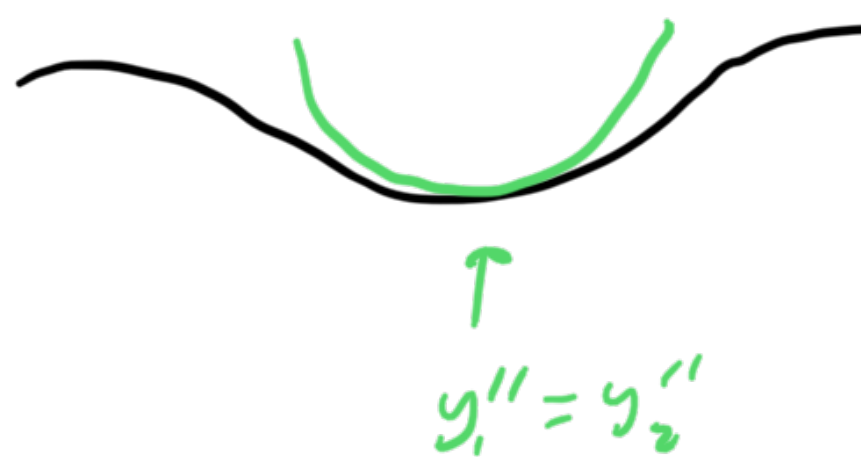
$$T = \frac{1 \text{ km}}{360 \text{ km/h}} = 10 \text{ s}$$

$$= 2\pi \sqrt{k/m} \Rightarrow k = \frac{4\pi^2 m}{T^2}$$

$$a = \frac{F}{m} = \frac{kh}{m} = \frac{4\pi^2 h}{T^2}$$

$$h \leq T^2 a_{\max} / 4\pi^2$$

$$h = 25 \text{ cm}$$



$$y(t) = h \sin(2\pi t/T)$$

$$y''(t) = -\frac{4\pi^2 h}{T^2} \sin(2\pi t/T)$$

$$a_{\max} \leq \frac{4\pi^2 h}{T^2}$$

$$h \leq T^2 a_{\max} / 4\pi^2$$