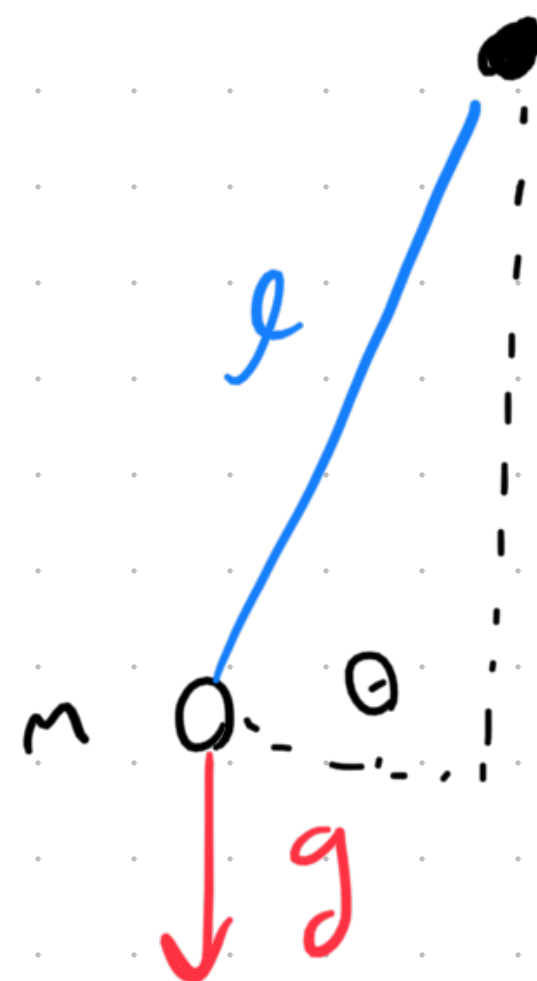


Dimensional Analysis

what is the period
of this pendulum?



A $\sqrt{g/l}$

B $\sqrt{l/g}$

~~C~~ $\sqrt{mg/l}$

~~D~~ $\sqrt{l/mg}$

~~E~~ $\sqrt{lg}$

goal units [s]

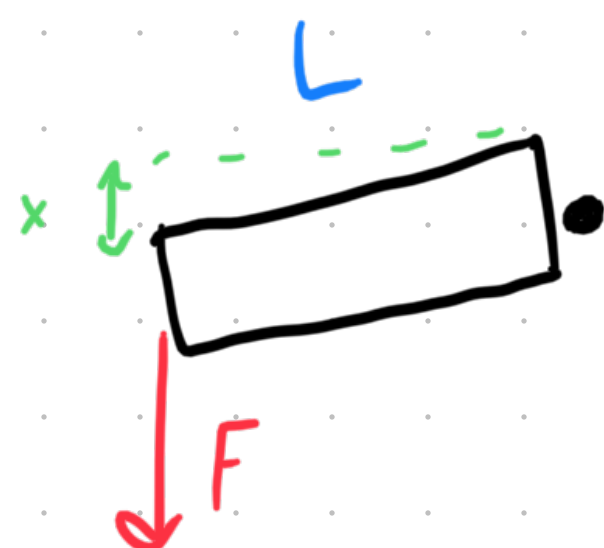
$$[l] = m$$

$$[g] = \frac{m}{s^2}$$

A $\left[\sqrt{\frac{g}{l}} \right] = \left(\frac{m}{s^2} \cdot \frac{1}{m} \right)^{\frac{1}{2}} = s^{-1}$

B $\left[\sqrt{\frac{l}{g}} \right] = \left(m \cdot \frac{s^2}{m} \right)^{\frac{1}{2}} = s$

2018 B #6



$$X = \frac{F}{I} E^{\alpha} L^{\beta}$$

$$[F] = N$$

$$[I] = m^4$$

$$[E] = N m^{-2} \rightsquigarrow \text{Newtons cancel } \alpha = -1$$

$$[L] = m$$

$$X = \frac{F}{IE} L^{\beta}$$

$$\left[\frac{F}{IE} \right] = m^{-2}$$

$$[L^{\beta}] = m^3$$

$$\Rightarrow \beta = 3$$

$$\text{thus, } X \propto L^3$$

(D)

Simple Harmonic Oscillations



$$F(x) = -kx$$

$$ma = -kx$$

$$m\ddot{x} = -kx$$

$$T = \frac{1}{f} = \frac{2\pi}{\omega}$$

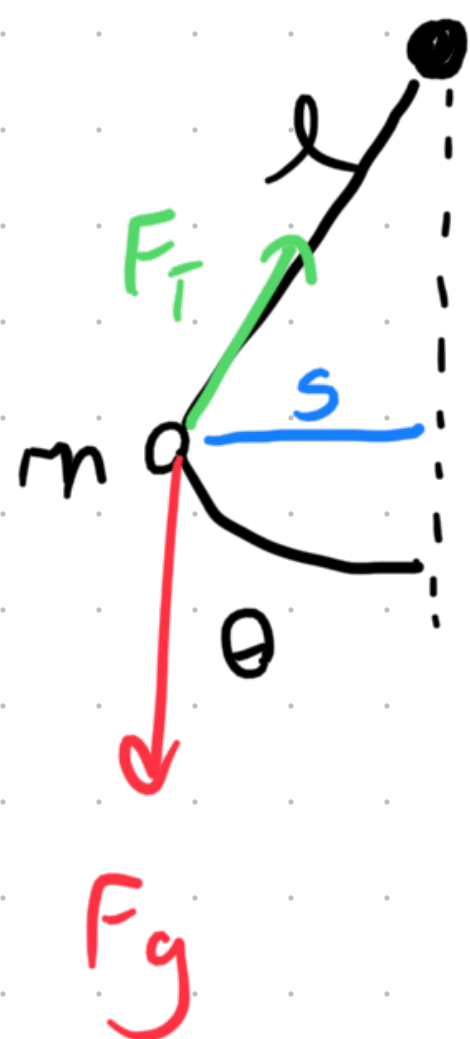
$$x = A \cos(\omega t + \phi)$$

A = max. displacement

$$\omega = \sqrt{k/m}$$

$$E_{osc} = \frac{1}{2} k A^2$$

Pendulums & small angle approximation.



natural oscillation frequency

$$\omega = ?$$

$$F_{T\theta} = F_T \sin \theta \approx F_T \theta$$

$$F_T \approx F_g$$

$$F_{T\theta} \approx -F_g \theta = -F_g \frac{s}{l}$$

$$F(s) \propto -s$$

Restoring Force!

$$\omega = \sqrt{k/m}$$

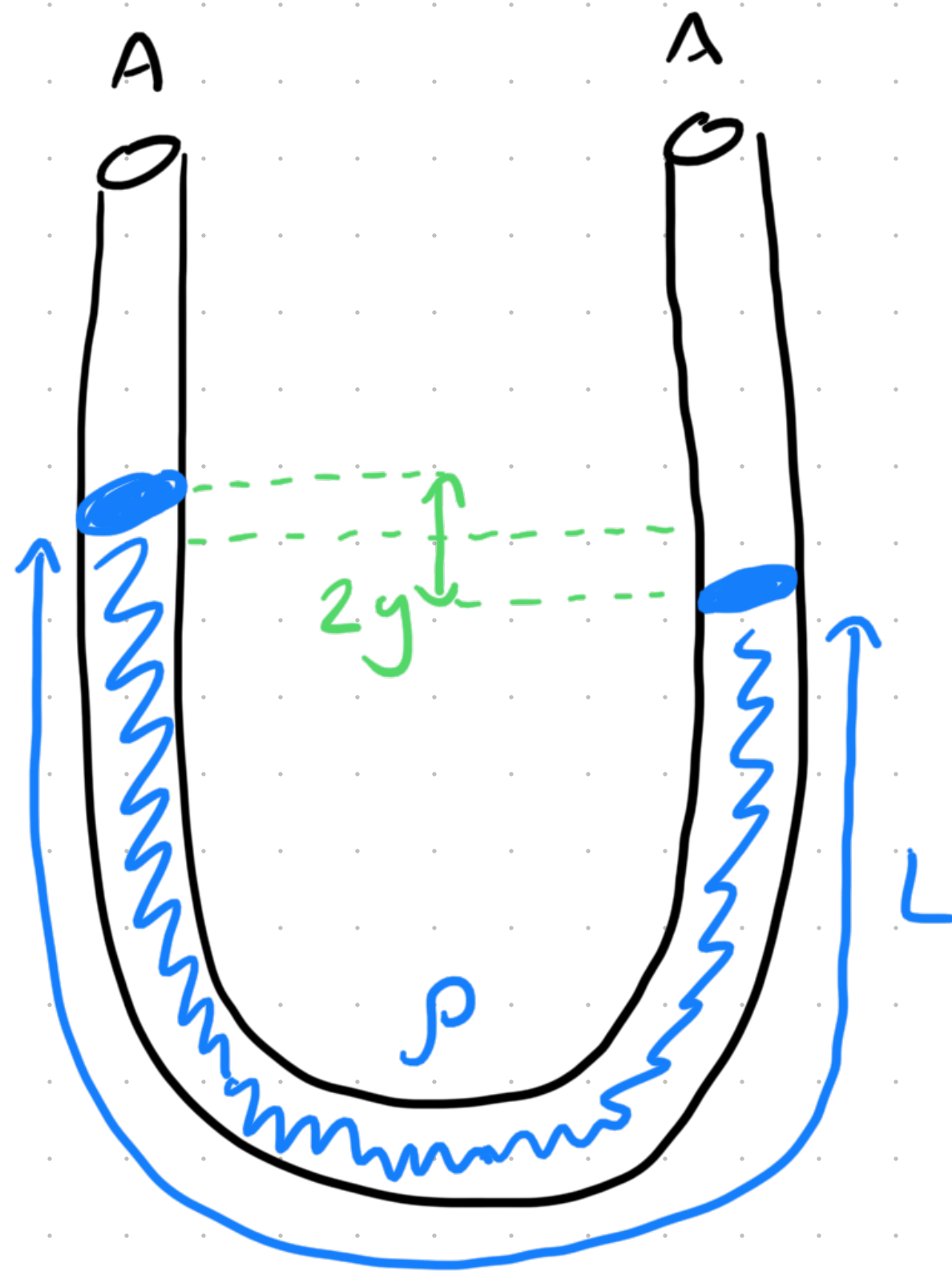
$$F(s) = -ks$$

$$k = \frac{F_g}{l}$$

$$= mg/l$$

$$\omega = \sqrt{\frac{mg/l}{m}}$$

$$\omega = \sqrt{g/l}$$



$$\omega = ?$$

$$F_{\text{disp}} = m_{\text{disp}} g = -2\rho g y A$$

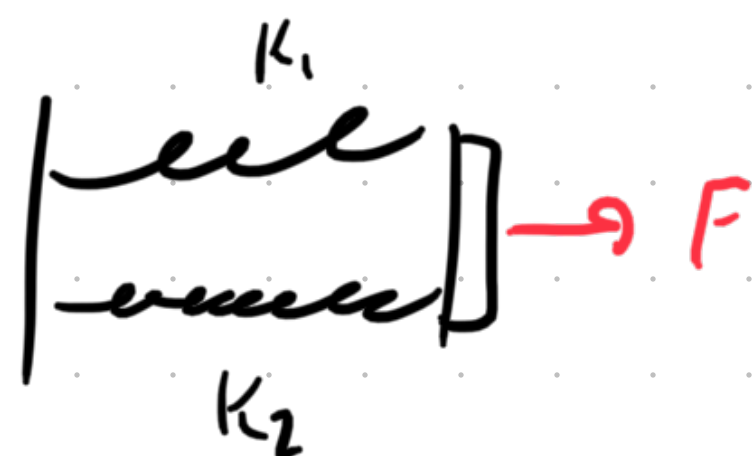
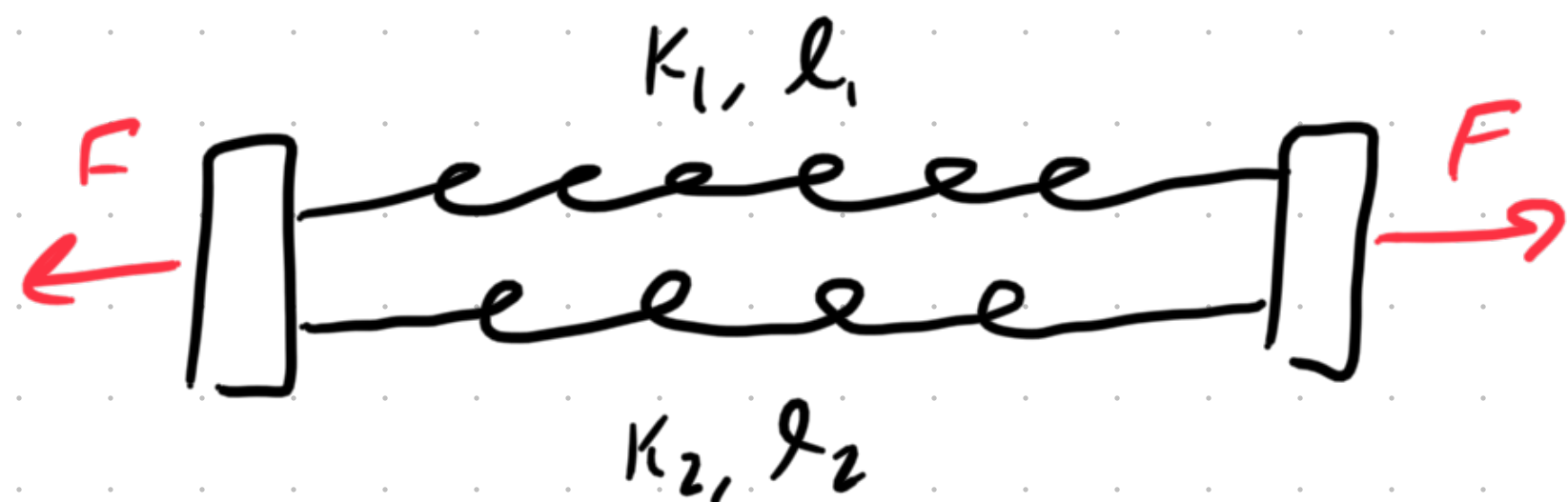
$$= -k y$$

$$k = 2\rho A g$$

$$m = \rho L A$$

$$\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{2\rho A g}{\rho L A}} = \sqrt{\frac{2g}{L}}$$

2018 B #18



$$F = -Kx$$

$$x = \frac{-F}{K}$$



$$F_1 = K_1 x$$

$$F_2 = K_2 x$$

$$F = F_1 + F_2 = K_1 x + K_2 x = (K_1 + K_2) x$$

$$K_{\text{eff}} = K_1 + K_2$$

$$F_{\text{net}} = 0 \quad \text{for equilibrium}$$

$$= K_1(l - l_1) + K_2(l - l_2)$$

$$K_1 l_1 + K_2 l_2 = (K_1 + K_2) l$$

$$l = \frac{K_1 l_1 + K_2 l_2}{K_1 + K_2}$$

(B)

2018B #21



$$T = 2\pi \sqrt{\frac{I}{mgx}}$$

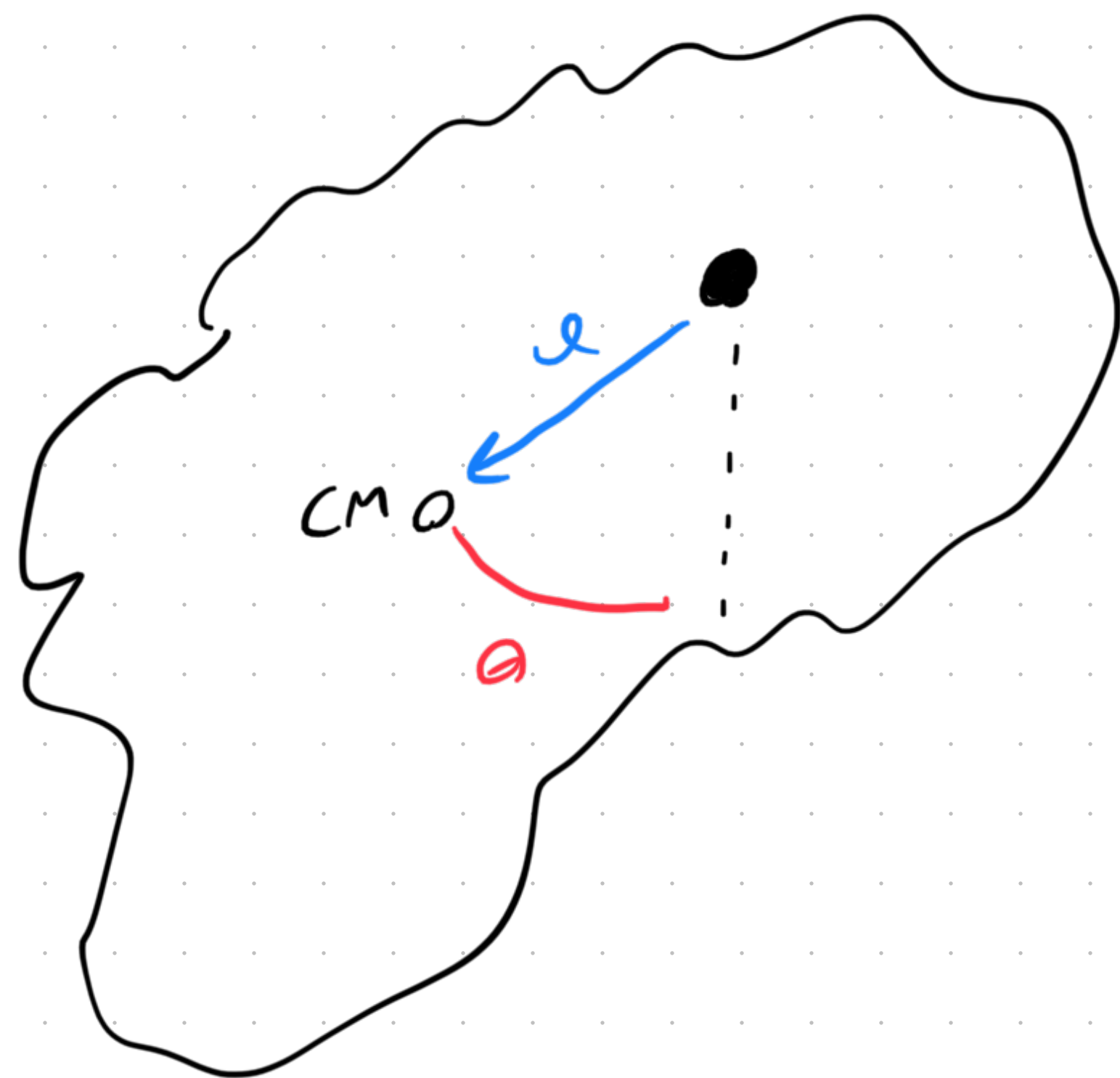
$$I = \frac{1}{12} mL^2 + mx^2$$

$$\text{minimize } \frac{I}{mx} = x + \left(\frac{L^2}{12}\right)x^{-1}$$

$$C\left(z + \frac{1}{z}\right) \text{ minimized when } z = 1$$

$$z = \frac{x}{L/(2\sqrt{3})} \Rightarrow x = \frac{L}{2\sqrt{3}}$$

(B)



I_{CM} given

$$I_{rot} = I_{cm} + ml^2 \quad \text{parallel axis thm}$$

$$\tau = I_{rot} \alpha = -F_g l \sin \theta$$

$$= -F_g l \theta \quad \text{small angle approx}$$

$$= -mg l \theta$$

$$ma = -kx$$

$$m\ddot{x} = -kx$$

$$I\alpha = -k\theta$$

$$I\ddot{\theta} = -k\theta$$

$$\omega = \sqrt{\frac{k}{I}} = \sqrt{\frac{mg l}{I_{rot}}}$$