

Robot Mass	0.433 Kg
Coefficient of friction	0.4 Plastic on wood. https://mae.ust.hk/designlab/Class%20Projects/Background%20Information/Friction%20coefficients.htm
Gravitational acceleration	9.8 m/s ²
Force of friction	1.7 N
Predicted Thrust	6.5 N

$$d = \frac{1}{2} at^2$$

$$a = 2d/(t^2)$$

$$F = m^*2d/(t^2)$$

Formula = 1 -
Actual Net Thrust (Expected + Force of Friction Thrust)/(Actual Applied Thrust)

Actual Net Thrust X Impulse Duration $v = (\text{Actual Net Thrust} * \text{Impulse duration})/\text{Mass}$

Run	Impulse Phase		Glide Phase		Time			Distance			Impulse phase				
	Start Time (s)	End time (s)	Start Time	End Time	Impulse duration	Glide Duration (s)	Total Travel time (s)	Total Distance travelled (m)	Impulse Phase Distance (m)	Glide Distance (m)	Actual Net Thrust (N)	Actual Applied Thrust (N)	% Difference in Thrust (Model vs Measured)	Actual Net Impulse (Ns)	Peak Velocity (m/s)
1	13.98	14.4	14.4	15.4	0.42	1.0	1.4	2.82	0.8	2.02	3.9	5.6	14%	1.6	3.8
2	13.16	13.56	13.56	14.66	0.4	1.1	1.5	3.10	0.8	2.30	4.3	6.0	8%	1.7	4.0
3	17.03	17.37	17.37	18.14	0.34	0.8	1.1	1.68	0.5	1.22	3.4	5.1	22%	1.2	2.7
4	11.51	11.9	11.9	13.01	0.39	1.1	1.5	2.97	0.8	2.17	4.6	6.3	4%	1.8	4.1
5	11.2	11.57	11.57	12.46	0.37	0.9	1.3	2.24	0.7	1.57	3.9	5.6	15%	1.4	3.3

Legend

- Green Actual measurement data
- Clear Calculated from data using arithmetic
- Gold Well known value, sourced via an external source
- Grey Predicted by model
- Orange Indirect measurement: using actual data and Newton's laws of motion and motion equations