One Stop Shop for Collaborative Applications

All the tools you need at one place to automate more





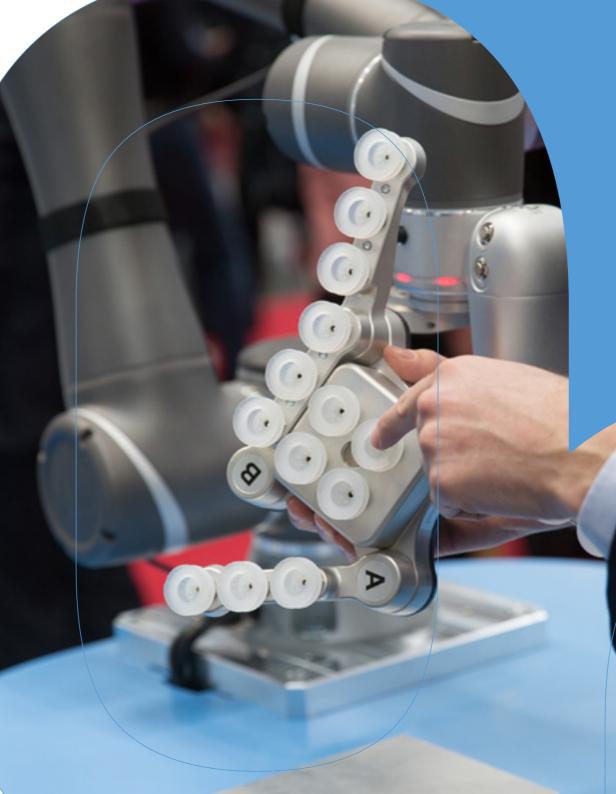


Collaborative applications are the future of automation, enabling rapid deployment, easy changeovers, and safe operation alongside human workers. Manufacturers gain true value from innovative collaborative applications that are enabled by a full range of Plug & Produce grippers, sensors, vision, and the software that drives them.

We offer the industry's broadest range of end-of-arm tooling and software solutions for collaborative applications, using a unified mechanical interface that helps manufacturers automate quickly and efficiently. Our innovative, manufacturer-focused approach saves you time and money so you can get on with the business of production.

We are excited to show you what you can accomplish with flexible, cost-effective collaborative applications.

Enrico Krog Iversen, CEO OnRobot



About OnRobot

OnRobot was born a global company in June 2018 with the merger of Danish On Robot, Hungarian OptoForce and American Perception Robotics. Danish company Purple Robotics was welcomed into the fold a short time later. The IP assets belonging to Blue Workforce were acquired in April 2019. Each company was known for developing unique technologies for collaborative applications and together they represent a formidable catalogue of the industry's best tools. The tools include grippers, sensors, tool changers and software that enable small and medium sized manufacturers to automate their processes like never before – quickly, efficiently and cost-effectively.

Any robot you choose. One **OnRobot** system.

Save integration time and simplify deployment with our complete solution.



*If your robot arm is not represented above, contact your local partner for information on compatibility on other robot brands.

ANY APPLICATION

– What do you want to automate?

Now you can automate processes that were previously too complicated



• One Stop Shop for collaborative applications. We provide all the tools you need at one place so you can automate more.

 Multiple tools, robots and applications - for multiple returns. Save cost and increase productivity with flexible automation tools.

• One system, zero complexity. Save time and grow your business fast with unified programming and easy redeployment.

One Simple OnRobot System

One Interface

One Training

One Person to Call

SAVES YOU TIME AND MONEY

Deployment

Training

Flexibility

RG2/RG6

Plug & Produce grippers for multiple purposes

RG2 TECHNICAL SPECIFICATIONS

General Properties	Minimum	Maximum	Unit
Payload Force Fit	-	2 4.4	[kg] [lb]
Total stroke (adjustable)	0 0	110 4.33	[mm] [inch]
Gripping force (adjustable)	3	40	[N]
Gripping speed	38	127	[mm/s]
Gripping time	0.06	0.21	[s]
IP Classification	IP54		

RG6 TECHNICAL SPECIFICATIONS

General Properties	Minimum	Maximum	Unit
Payload Force Fit	-	6 13,2	[kg] [lb]
Total stroke (adjustable)	0 -	160 6.3	[mm] [inch]
Gripping force (adjustable)	25	120	[N]
Gripping speed	51	160	[mm/s]
Gripping time	0.05	0.15	s
IP Classification	54		

POWER UP PRODUCTION

- Flexible grippers can be used for a **wide** range of part sizes and shapes.
- Plug & Produce design **reduces deployment** time from a day to an hour.
- Easy deployment with out-of-the box grippers reduces programming time by 70%

Applications:









Plastic

Cardboard



Grab & Go – gentle but firm gripping inspired by nature

GECKO TECHNICAL SPECIFICATIONS

General Properties					
Workpiece Material	Polished Steel	Acrylic	Glass	Sheet Metal	
Maximum payload (x2 safety factor)	6.5kg 13.2 lb	6.5kg 13.2 lb	5.5kg 13.2 lb	5.5kg 8.8 lb	[kg] [lb]
Preload required for max adhesion	140				[N]
Detachment time	300 msec				[msec]
Holds workpiece on power loss?	yes				
Pads					
Pad Change-out interval	150 000 to 200 (200 000 to 250 ([cycles]
Manual Cleaning	Isopropyl alcoho	ol and lint free	cloth		
Robotic cleaning system	Cleaning Statior	ו			
Sensors					
	Pre-load sensor		Ultrason	ic Range se	пѕог
Range	40 N - 140N 9 lb - 31 lb		0	260 [mm] 10 [inch]	[N][mm] [lb][inch]
Еггог	7% 2%				
IP	42				

POWER UP PRODUCTION

- No compressed air requirement saves maintenance costs and provides faster payback in as little as 5 months.
- Precise, no-mark gripper technology increases productivity in Pick & Place tasks.
- Innovative gecko technology enables gripping of flat, porous objects such as PCBs to extend automation capabilities.
- No requirement for external air supply reduces noise and dust.





Applications:

Packaging & Palletizing

Pick & Place

Awards for the Gecko Gripper:

- IERA Award
- Hannover Messe 2019 Robotics Award
- Silver Edison Award for Innovation in Robotics
- Global Robotics Expo Innovation Award for Robotics



Can be used with products of various sizes and materials, including:

Metal



Plastic

Glossy Packaging

Glass

probot

GECKO GRIPPER

SP1/SP2/SP3 Gecko Single Pad Gripper

TECHNICAL SPECIFICATIONS

General Properties			Unit
	SP-1	1 / 2.2	[kg] / [lb]
Maximum payload	SP-2	3 / 6.6	[kg] / [lb]
	SP-3	5/11	[kg] / [lb]
	Minimum	SP1: 2.8 SP3: 8.2 SP5: 11.6	[N]
Preload required	Medium	SP1: 8.2 SP3: 23.4 SP5: 33	[N]
	Maximum	SP1: 13.3 SP3: 38.6 SP5: 54.4	[N]
Detachment	time	100-1000 (dependent on robot speed)	[msec]
Holds workpie power los		Yes. How long? Potentially days if well centered and u	undisturbed
IP Classification		IP42	
Dimensions (HxW)	69 x 71 / 2.7 x 2.8	[mm] / [inch]
	SP-1	0.267 / 0.587	[kg] / [lb]
Weight	SP-2	0.297 / 0.653	[kg] / [lb]
	SP-3	0.318 / 0.7	[kg] / [lb]

Pads general properties		Unit	
Material	Proprietary silicone blend		
Wear properties	Depends on surface roughne	ess	
Change-out interval	~200.000	[cycles]	
Cleaning systems	1) OnRobot cleaning station 2) Silicone roller 3) Isopropyl Alcohol and lint-free cloth		
Cleaning interval	variable		
Recovery	100%		

POWER UP PRODUCTION

- Compact, lightweight Gecko Single Pad Gripper requires no cables, electricity, air, or programming for **cost-effective**, plug-and-play performance
- Innovative adhesive gripper for flat, smooth, or perforated objects **automates** tasks that were previously not possible
- No-mark gripping even for shiny surfaces means no cleaning step is required, **saving** time and improving productivity
- No requirement for external air supply reduces noise and dust, lowers maintenance costs, and speeds deployment

Applications:

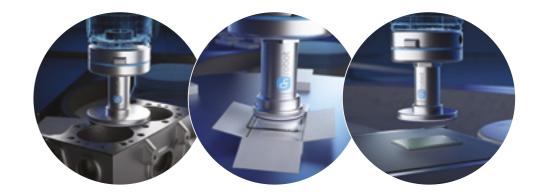




Packaging & Palletizing

Pick & Place

Gecko Single Pad Gripper





Can be used with products of various sizes and materials, including:



Plastic

Glossv Packaging



Pick & Collaborate – helping hand with a sense of touch

The world's first gripper that can detect objects using built-in force/torque and proximity sensors.

RG2-FT TECHNICAL SPECIFICATIONS

General Properties	Minimum	Maximum	Unit
Payload Force Fit	-	2 4.4	[kg] [lb]
Total stroke (adjustable)	0 0	100 3.93	[mm] [inch]
IP Classification	IP54		

Force Sensor Properties	Fxy	Fz	Тху	Tz	Units
Nominal capacity (N.C.)	20	40	0.7	0.5	[N] [Nm]
Noise free resolu- tion	0.1	0.4	0.008	0.005	[N] [Nm]

POWER UP PRODUCTION

- Accurate sensing improves production quality by reducing defect rate as much as 60% in delicate Pick & Place processes.
- Easy-to-program sensing **allows robot** to act like an operator's third arm, with human-like part hand-offs.
- Ability to automate insertion tasks **that** weren't previously possible can reduce operation costs by 40%.

Applications:







Packaging & Palletizing



Machine Tending

Pick & Place

Quality Testing and Inspection

RG2-FT

Can be used with products of various sizes and materials, including:









onrobot

Plastic

Metal

Cardboard

Wood



Grab & Go - flexible, adjustable electrical vacuum gripper

VG10 TECHNICAL SPECIFICATIONS

General Properties	Minimum	Maximum		Unit
Vacuum	5 % -0.05 1.5	80 % -0.810 24		[Vacuum] [Bar] [inHg]
Air flow	0	12		[Nl/min]
Payload	0 0	15 [kg] 33 [lb]		
Recommended workpiece size	10x10 0.5x0.5	500x500 20x20		[mm] [inch]
Vacuum cups	1	16		[pcs.]
Gripping time	-	0.35	-	[s]
Releasing time	-	0.20	-	[s]
Vacuum pump	Integrated, electric BL	DC		
Arms	4, adjustable by hand, 2	2 vacuum chann	iels	
IP Classification	IP54			
Dimensions (folded)				n] :h]
Dimensions (unfolded)				n] :h]
Weight	1.62 3.57		[kg] [lb]	

POWER UP PRODUCTION

- Out-of-the-box deployment plug into the robot arm and configure the gripper to fit the product – provides fast productivity and ROI.
- No external air supply required **reduces maintenance costs and speeds deployment.**
- Dual gripping functionality **enables shorter** cycle time.

Applications:





Packaging & Palletizing

Pick & Place

Can be used with products of various sizes and materials, including:







Plastic

Metal G

Glossy Packaging



VG10

VGC10 Compact vacuum gripper for all your needs

VGC10 TECHNICAL SPECIFICATIONS

General Properties	Minimum	Typical	Maximum	Unit	
Vacuum	5 % -0.05 1.5	- - -	80 % -0.810 24	[Vacuum] [Bar] [inHg]	
Air flow	0		12	[Nl/min]	
Payload	0	-	15 33	[kg] [lb]	
Recommended workpiece size	Unlimited, depends on custom arms				
Vacuum cups	1	-	7	[pcs.]	
Gripping time	-	0.35	-	[s]	
Releasing time	-	0.20	-	[s]	
Vacuum pump	Integrated, e	lectric BLDC			
Arms	Replaceable,	customizable			
Dust filters	Integrated 50)µm, field repla	ceable		
IP Classification	IP54				
Dimensions (folded)	101 x 100 x 100 [mm] 3.97 x 3.94 x 3.94 [inch]				
Weight	0.814 1.79			[kg] [lb]	

POWER UP PRODUCTION

- Flexible electric vacuum gripper with unlimited customization fits all your application needs
- Small, lightweight gripper is perfect for tight spaces but with plenty of power for objects up to 15kg
- No external air supply needed for reduced maintenance costs and faster deployment

Applications:





Packaging & Palletizing

Pick & Place

Machine Tending







VGC10

Can be used with products of various sizes and materials, including:





Plastic

Glossy Packaging

Glas

Glass





Touch & Go – automation made simple with a sense of touch

HEX-E QC TECHNICAL SPECIFICATIONS

General Properties	6-Axis Force/Torque Sensor		Unit		
	Fxy	Fz	Тху	Tz	
Nominal Capacity (N.C)	200	200	10	5.5	[N] [Nm]
Single axis deformation at N.C (typical)	± 1.7 ± 0.067	± 0.3 ± 0.011	± 2.5 ± 2.5	±5 ±5	[mm] [°] [inch] [°]
Resolution (Noise- free)	0.2	0.8	0.01	0.002	[N] [Nm]
IP Classification	67				
Dimensions	50 x 71 x 93 1.97 x 2.79 x 3.66			[mm] [inch]	

HEX-H QC TECHNICAL SPECIFICATIONS

General Properties	6-Axis Force/Torque Sensor		Unit		
	Fxy	Fz	Тху	Tz	
Nominal Capacity (N.C)	200	200	20	13	[N] [Nm]
Single axis deformation at N.C (typical)	± 0.6 ± 0.023	± 0.25 ± 0.009	±2 ±2	± 3.5 ± 3.5	[mm] [°] [inch] [°]
Resolution (Noise-free)	0.5	1	0.036	0.008	[N] [Nm]
IP Classification	67				
Dimensions	50 x 71 x 93 1.97 x 2.79 x 3.66			[mm] [inch]	

POWER UP PRODUCTION

- Flexible sensor extends automation **possibilities** to processes that weren't previously possible.
- Out-of-the-box integration reduces deployment time for precise insertion tasks from months to days.
- High-accuracy sensor technology **provides 95%** better quality in insertion and assembly tasks.
- Sensor-based applications speed cycle time **by up** to 60% to produce more with the same number of employees.
- Easy programming gets even **complex polishing** tasks up and running in less than a day.

Applications:







Assembly

Surface Finishing

Pick & Place

Quality Testing and Inspection

HEX Force/Torque SENSOR

Can be used with products of various sizes and materials, including:



Metal



Plastic

Wood

Glass

,obot



Quick Changer & Dual Quick Changer Bracket

With the Dual Quick Changer, you can now use two tools in one cycle, achieving higher utilization of your robots.



RG2 Gripper

For picking and placing items up to 2kg Maximum stroke 110mm

Chrobot

RG6 Gripper

For when you need a bigger grip - 160mm stroke and payload of 6kg

RG2-FT Gripper

For high-precision assembly applications where fingertip sensitivity is required

Gecko Gripper

For perforated or more fragile objects Leaves no mark on the surface Payload up to 6.5 kg

YASKAW

1111

Co robot

VG10 Electrical Vacuum Gripper

For larger objects or applications where two parts should be moved separately Payload up to 15kg

-

073

HEX Sensor

For high precision insertion tasks. Handles variation like a pro Surface finishing, gluing

Grobot

9

A