

Variadores compactos y de alto rendimiento
Serie FRENIC-Mini (C2)





FRENIC-Mini (C2)

The next generation FRENIC-Mini inverter is a high performance AC drive in a compact size. Get our most user-friendly drive yet; with its rich functionality, compact design, simple operation, and global compatibility. With the highest standards of control and performance in its class, the FRENIC-Mini (C2) elevates the performance of a wide range of devices and equipment including conveyors, fans, pumps, centrifugal separators, and food processing machines. Its capabilities gives you the system integration, energy efficiency, reduce labor, and overall costs for which you are looking.

With standard functions like high starting torque, synchronous motor control, optimum energy savings, PID control, built in Modbus RTU, plus more all in a compact size makes the FRENIC Mini (C2) ideal for OEM's and panel builders. The optional NEMA/UL Type 1 kit allows the FRENIC-Mini (C2) to also be easily applied to stand alone applications.

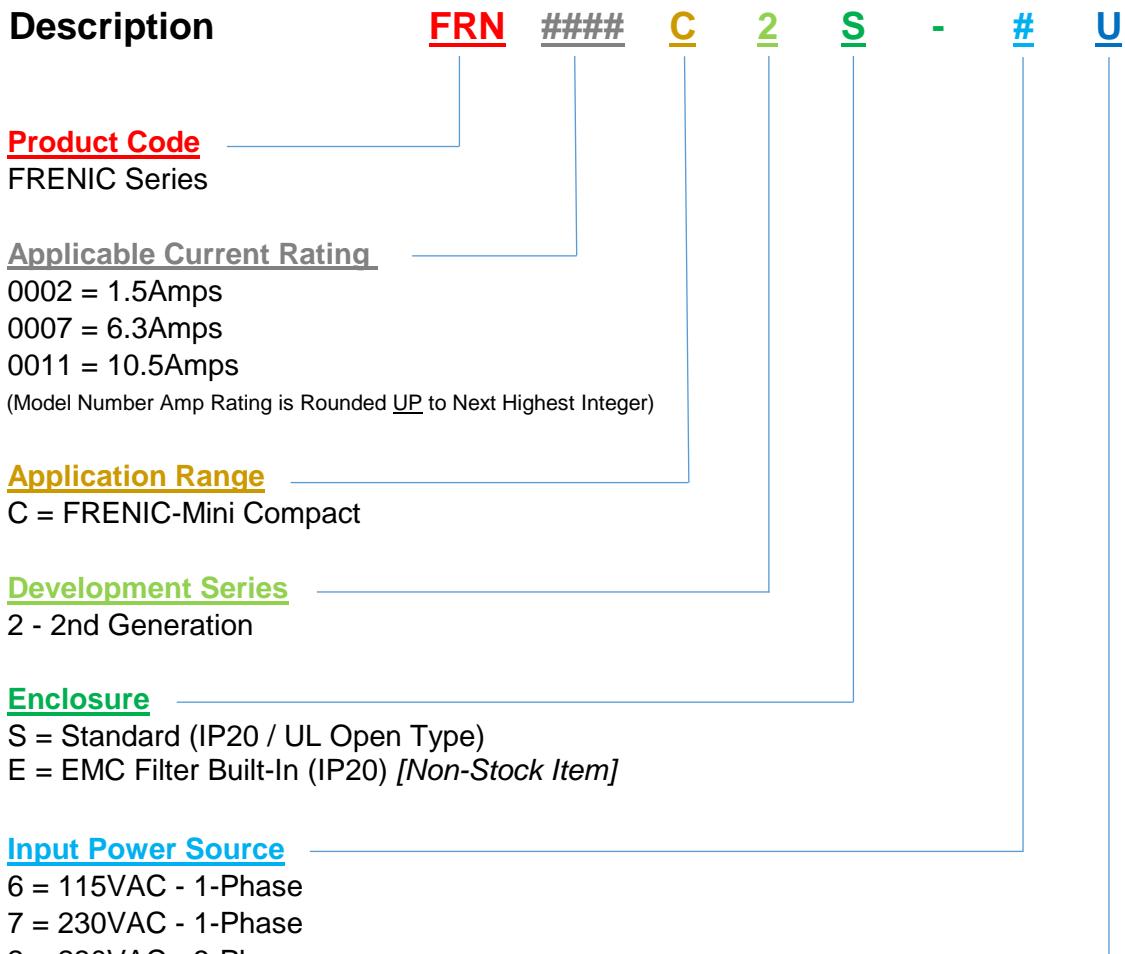


**Uso General:
(Par Constante)** Transportadores, Agitadores, Elevadores, Extrusoras, Molinos, Trituradoras, Troqueladoras, Grúas (Puente, Carro, Gancho), Enrolladora, Cortadora, Trefiladora, etc.

Par Variable: HVAC, Bombas y Ventiladores Centrífugos, Chillers, Sopladores, Aire acondicionado

FRENIC-Mini (C2)

FRENIC-Mini (C2) Model Numbering System Diagram



Destination/Manual
U = USA/English
E = Europe/English (EMC Filter Built-in Version) [Non-Stock Item]

Variadores FRENIC-Mini (C2)

Variadores compactos y de alto rendimiento

El FRENIC-Mini (C2) es nuestra generación de variadores más reciente y completamente compatible con el modelo previo (C1) que ofrece una potencia extendida (hasta 20 HP) con un diseño compacto. El FRENIC-Mini (C2) es nuestro controlador más intuitivo hasta el momento, su rendimiento se ha mejorado y el modelo básico viene con RS-485, control de par dinámico, motor con imán permanente y control PID. Esta rica funcionalidad se combina con un diseño compacto para una mejor experiencia de usuario, y los clientes disfrutarán la facilidad de operación y la compatibilidad global. El nuevo FRENIC-Mini eleva el rendimiento de una amplia variedad de dispositivos y equipamiento que incluyen transportadores, ventiladores, bombas, separadores centrífugos y máquinas de procesamiento de alimentos. Sus capacidades le proporcionan la integración del sistema, la eficiencia energética y la reducción de los costos generales que está buscando.

■ Control de entradas/salidas

- 5 entradas digitales: X1 a X3, funciones de FWD (avance) y REV (retroceso) programables, 21 funciones seleccionables
- 2 entradas analógicas: 1 - 0 a + 10 Vdc y 1 - 4 a 20 mA
- 2 salidas digitales: 1 relé de forma C y 1 transistor, 23 funciones seleccionables
- 2 salidas analógicas: Tipo seleccionable: 0 a 10 VCC o 4 a 20 mA, 43 funciones de señal de salida proporcional seleccionables
- 1 conector RS-485: Puerto RJ45
- TECLADO del operador con pantalla de LED Indicador de operación del sistema y conversión de unidades asociadas en la pantalla
- Indicación del teclado de operaciones, número de veces que la unidad se ubica en el funcionamiento, duración y kWh de salida
- Terminal de salida de 24 VCC: 50 mA de suministro máximo

■ Completamente compatible con los productos existentes (FRENIC-Mini C1)

- Dimensiones externas: Intercambiable
- Dimensiones para la instalación: Intercambiable
- Número de terminales: Iguales para el circuito principal y los controladores
- Posición de terminal: Terminal compatible con el largo
- Códigos de función: Códigos de función compatibles
- Comunicación RS-485 incorporada: Protocolo de comunicación compartido

■ Flexibilidad

- El teclado de FRENIC-Mini muestra la velocidad, la corriente, la frecuencia o la salida de voltaje, los datos de operación PID y puede configurarse para indicar unidades en funcionamiento.
- Teclado USB opcional
- Software cargador de programación de PC
- Datos de mantenimiento fácil: Simulacro de defectos, número de inicios, tiempo acumulativo de funcionamiento del motor, potencia total, registro de desconexiones, etc.
- Control de ahorro de energía automático: control óptimo del controlador y pérdida del motor
- Controlador PID con modo de suspensión, configuración de parámetros proporcional, integral y diferencial para maximizar el control
- Función de control de ENCENDIDO/APAGADO del ventilador de refrigeración
- Configuración de 3 pasos no lineal V/F
- 2 controles de interruptor de motor
- Señal de frenado
- Control de dirección de rotación
- Modelos de entrada monofásica disponibles
- Control de motor sincrónico

■ Control de motor

- Capacidad de control de motor PM
- Control: control V/F, compensación de desplazamiento, aumento de par automático, sistema de control vectorial de par dinámico
- Niveles: 150 % por 1 min
200 % por 0.5 s

■ Seguridad y estándares

- EN61800-5-1 (directiva de bajo voltaje)
- UL 508C, CE
- Kit tipo 1 según NEMA/UL opcional
- Cumplimiento de la normativa RoHS

■ Garantía

- 3 años desde la fecha de envío

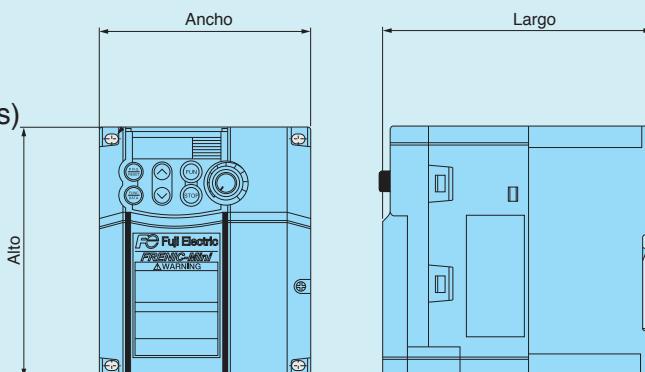
Dimensiones

| Modelo | | HP | FLA | Masa (lb) | Alto | Ancho | Largo |
|----------------------------|---------------|-----|------------|-----------|-------|-------|-------|
| Monofásico de 115 V | FRN0001C2S-6U | 1/8 | 0.7 | 1.5 | 4.72 | 3.15 | 3.94 |
| | FRN0002C2S-6U | 1/4 | 1.4 | 1.5 | 4.72 | 3.15 | 3.94 |
| | FRN0003C2S-6U | 1/2 | 2.5 | 1.8 | 4.72 | 3.15 | 4.53 |
| | FRN0005C2S-6U | 1 | 4.2 | 2.9 | 5.12 | 4.33 | 5.47 |
| Monofásico de 230 V | FRN0001C2S-7U | 1/8 | 0.8(0.7) | 1.3 | 4.72 | 3.15 | 3.15 |
| | FRN0002C2S-7U | 1/4 | 1.5(1.4) | 1.3 | 4.72 | 3.15 | 3.15 |
| | FRN0004C2S-7U | 1/2 | 3.5(2.5) | 1.5 | 4.72 | 3.15 | 3.74 |
| | FRN0006C2S-7U | 1 | 5.5(4.2) | 2.0 | 4.72 | 3.15 | 5.51 |
| | FRN0010C2S-7U | 2 | 9.2(7.0) | 4.0 | 5.12 | 4.33 | 5.87 |
| | FRN0012C2S-7U | 3 | 12.0(10.0) | 5.5 | 7.09 | 5.51 | 5.47 |
| Trifásico de 230 V | FRN0001C2S-2U | 1/8 | 0.8(0.7) | 1.3 | 4.72 | 3.15 | 3.15 |
| | FRN0002C2S-2U | 1/4 | 1.5(1.4) | 1.3 | 4.72 | 3.15 | 3.15 |
| | FRN0004C2S-2U | 1/2 | 3.5(2.5) | 1.5 | 4.72 | 3.15 | 3.74 |
| | FRN0006C2S-2U | 1 | 5.5(4.2) | 1.8 | 4.72 | 3.15 | 4.72 |
| | FRN0010C2S-2U | 2 | 9.2(7.0) | 3.7 | 5.12 | 4.33 | 5.47 |
| | FRN0012C2S-2U | 3 | 12.0(10.0) | 3.7 | 5.12 | 4.33 | 5.47 |
| | FRN0020C2S-2U | 5 | 19.1(16.5) | 5.5 | 7.09 | 5.51 | 5.47 |
| | FRN0025C2S-2U | 7.5 | 25.0(23.5) | 6.8 | 8.66 | 7.09 | 6.22 |
| | FRN0033C2S-2U | 10 | 33.0(31.0) | 6.8 | 8.66 | 7.09 | 6.22 |
| | FRN0047C2S-2U | 15 | 47.0(44.0) | 9.8 | 10.24 | 8.66 | 7.48 |
| Trifásico de 460 V | FRN0002C2S-4U | 1/2 | 1.8(1.5) | 2.6 | 5.12 | 4.33 | 4.53 |
| | FRN0004C2S-4U | 1 | 3.1(2.5) | 2.9 | 5.12 | 4.33 | 5.47 |
| | FRN0005C2S-4U | 2 | 4.3(3.7) | 3.7 | 5.12 | 4.33 | 5.47 |
| | FRN0007C2S-4U | 3 | 6.3(5.5) | 3.7 | 5.12 | 4.33 | 5.47 |
| | FRN0011C2S-4U | 5 | 10.5(9.0) | 5.5 | 7.09 | 5.51 | 5.47 |
| | FRN0013C2S-4U | 7.5 | 13 | 6.8 | 8.66 | 7.09 | 6.22 |
| | FRN0018C2S-4U | 10 | 18 | 6.8 | 8.66 | 7.09 | 6.22 |
| | FRN0024C2S-4U | 15 | 24 | 9.8 | 10.24 | 8.66 | 7.48 |
| | FRN0030C2S-4U | 20 | 30 | 9.8 | 10.24 | 8.66 | 7.48 |

Cuando la temperatura ambiente supera los 40 °C (104 °F), use la información (##). Consulte el manual de instrucciones INR-SI-47-1729a-E para obtener más información.

Opciones

- Kit tipo 1 según NEMA/UL
- Adaptador de carril DIN (5 HP y menos)
- Resistor DB (1/2 HP y más)
- Teclado USB
- Filtro CE



Variadores FRENIC-Mini (C2)

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Especificaciones

| | |
|--------------------------|---|
| Capacidad | Monofásico de 115 V: 1/8 a 1 HP Monofásico de 230 V: 1/8 a 3 HP Trifásico de 230 V: 1/8 a 20 HP Trifásico de 460 V: 1/2 a 20 HP |
| Capacidad de sobrecarga | 150 % 1 min; 200 % 0.05 s |
| Potencia de entrada | 115 V/230 V mono/trifásico: 200 a 240 V, 50/60 Hz Trifásico de 460 V: 380 a 480 V, 50/60 Hz Voltaje: +10 % a -15 % (Desbalance de 2 % o menos) Frecuencia: +5 % a -5 % |
| Control | Control V/F (motor de inducción) Control vectorial de par dinámico (motor de inducción) Imán permanente/motor síncrono con control V/F |
| Frecuencia de salida | 0.1 a 400Hz |
| Precisión de salida | Configuración analógica: +/- 2 % de frecuencia máxima Configuración digital: +/- 0.01 % de frecuencia máxima (por configuración de teclado) |
| Par de arranque | 150 % funcionando a 1 Hz con compensación de deslizamiento |
| Transistor de frenado | Incorporado excepto en 1/4 HP y menor |
| Temperatura ambiente | -10 a 50 °C (14 a 122 °F) para funcionamiento -25 a 75 °C (-13 a 158 °F) para almacenamiento |
| Humedad relativa | 5 a 95 % HR (sin condensación) |
| Ubicación de instalación | Grado 2 de polución según el estándar de IEC 60664-1. (Libre de gases corrosivos, gases inflamables, vapor de aceite, polvo y luz solar directa). Solo para uso en interiores. |
| Altitud | Nivel del mar a 3300 ft (1000 m): sin disminución 3300 ft (1000 m) a 9900 ft (3000 m): con disminución |
| Carcasa | Tipo abierto según UL, tipo 1 por kit de opciones según NEMA/UL |
| Estándar | UL508C, EN 61800-5-1:2007 |

General Specifications

Environmental

| | |
|---------------------|---|
| Enclosure | UL Open Type (IP20), Optional UL Type 1 |
| Ambient Temperature | +14 to +122°F (-10 to +50°C) - UL Open Type +14 to +104°F (-10 to +40°C) - UL Type 1 |
| Storage Temperature | -13 to +158°F (-25 to +70°C) |
| Humidity | 5% to 95% With No Condensation |
| Altitude | 0 to 3,300 ft. (1,000 m) Without Derating, Derate Output Current for Higher Altitudes per User's Manual |

Codes and Standards

UL508C, EN 61800-5-1:2007

Electrical

| | |
|-------------------------------------|---|
| Input Voltage: Range-Phase | 100-120VAC-1Ph, 200-240VAC-1Ph, 200-240VAC-3Ph, 380-480VAC-3Ph |
| Input Voltage: Tolerance, Unbalance | 3-Ph Input = +10% to -15%, \leq 2% 1-Ph Input = +10% to -10% |
| Input Frequency: Nominal, Tolerance | 50/60Hz, +/-5% |
| Displacement Power Factor | \geq 0.98 (@ Rated Load) |
| Output Voltage: Range-Phase | 0 to Maximum Input Voltage-3Ph 0 to 230VAC-3Ph for 115VAC Input |
| Maximum Output Frequency | 400Hz |
| Motor Control Method | <u>Induction Motor</u> : V/f, Dynamic Torque Vector, Slip Comp, Auto-Torque Boost, Automatic Energy Savings <u>Synchronous Motor (PMAC)</u> : Sensorless Magnetic Positioning [speed control range: 10% of base frequency and up] |
| Overload Capacity | 150% Rated Current for 1 min. 200% Rated Current for 0.5 sec. |
| Analog Inputs | Qty 1: 0 to +10VDC Qty 1: 0/4-20mA |
| Digital Inputs | Qty 5: Programmable |
| Analog Outputs | Qty 1: 0 to +10VDC, User Selectable Proportional Analog Signal Functionality |
| Digital Outputs | Qty 1: Form C (1N.O. & 1N.C.) Dry Contacts Rated 0.3A @ 230V Max, User Selectable Functionality Qty 1: Transistor Output Rated 50mA @ 27Vdc Max, User Selectable Functionality |
| Power Supply | Qty 1: 24VDC, 50mA Max |

1. Standard Specifications

1) Three-phase 200V series (0.1 to 15kW / 1/8 to 20HP) ($\Delta = A, U$ only)

| Items | | Specifications | | | | | | | | | | | | | |
|---|---|---|--------------------------------|--------------------------------|--------------------------------|--------------------------------|----------------------------------|---|-----------------------------------|-----------------------------------|-----------------------------------|--|--|--|--|
| Type (FRN□□C2S-2△、 △ = A,U) | 0001 | 0002 | 0004 | 0006 | 0010 | 0012 | 0020 | 0025 | 0033 | 0047 | 0060 | | | | |
| Nominal applied motor ¹⁾ [kW] (△=A) | 0.1 | 0.2 | 0.4 | 0.75 | 1.5 | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | | | | |
| Nominal applied motor ¹⁾ [HP] (△=U) | 1/8 | 1/4 | 1/2 | 1 | 2 | 3 | 5 | 7.5 | 10 | 15 | 20 | | | | |
| Output ratings | Rated capacity ²⁾ [kVA] | 0.30 | 0.57 | 1.3 | 2.0 | 3.5 | 4.5 | 7.2 | 9.5 | 12 | 17 | | | | |
| | Rated voltage ³⁾ [V] | Three-phase 200~240V (With AVR) | | | | | | | | | | | | | |
| | Rated current [A] | 0.8 (0.7) ^{*4)} | 1.5 (1.4) ^{*4)} | 3.5 (2.5) ^{*4)} | 5.5 (4.2) ^{*4)} | 9.2 (7.0) ^{*4)} | 12.0 (10.0) ^{*4)} | 19.1 (16.5) ^{*4)} | 25.0 (23.5) ^{*10)} | 33.0 (31.0) ^{*10)} | 47.0 (44.0) ^{*10)} | | | | |
| | Overload capability | 150% of rated current for 1min 150% of rated current for 1min or 200% of rated current for 0.5s (If the rated current is in parenthesis) | | | | | | 150% of rated current for 1min or 200% of rated current for 0.5s | | | | | | | |
| Input ratings | Rated frequency | 50, 60Hz | | | | | | | | | | | | | |
| | Main power supply | Three-phase 200~240V, 50/60Hz | | | | | | | | | | | | | |
| | Voltage/frequency variations | Voltage: +10 to -15% (Voltage unbalance: 2% or less ⁷⁾), Frequency: +5 to -5% | | | | | | | | | | | | | |
| | Rated current ⁸⁾ [A] | With DCR | 0.57 | 0.93 | 1.6 | 3.0 | 5.7 | 8.3 | 14.0 | 21.1 | 28.8 | | | | |
| | Without DCR | 1.1 | 1.8 | 3.1 | 5.3 | 9.5 | 13.2 | 22.2 | 31.5 | 42.7 | 60.7 | | | | |
| Braking | Required power supply capacity ⁵⁾ [kVA] | 0.2 | 0.3 | 0.6 | 1.1 | 2.0 | 2.9 | 4.9 | 7.4 | 10 | 15 | | | | |
| | Braking torque ⁶⁾ [%] | 150 | | 100 | | 50 | 30 | | 20 | | | | | | |
| | DC braking | Starting frequency ⁹⁾ : 0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level: 0 to 100% | | | | | | | | | | | | | |
| Applicable safety standards | Transistor for braking resistor | | | | | | | | | | Built-in | | | | |
| | UL508C, EN 61800-5-1:2007 | | | | | | | | | | | | | | |
| Enclosure | | IP20 (IEC 60529:1989) / UL open type (UL50) | | | | | | | | | | | | | |
| Cooling method | | Natural cooling | | | | Fan cooling | | | | | | | | | |
| Mass [kg] (△=A) | 0.6 | 0.6 | 0.7 | 0.8 | 1.7 | 1.7 | 2.5 | 3.1 | 3.1 | 4.5 | 4.5 | | | | |
| Mass [lbs] (△=U) | 1.3 | 1.3 | 1.5 | 1.8 | 3.7 | 3.7 | 5.5 | 6.8 | 6.8 | 9.8 | 9.8 | | | | |

*1) Fuji Electric's/US 4-pole standard motor.

*2) Rated capacity is calculated by regarding the output rated voltage as 220V for three-phase 200V series.

*3) Output voltage cannot exceed the power supply voltage.

*4) The load shall be reduced so that the continuous operating current is the rated current in parenthesis or less if the carrier frequency is set to 3kHz or above or ambient temperature exceeds 40°C(104°F).

*5) Obtained when a DC REACTOR is used.

*6) Average braking torque when a motor of no load decelerates from 60Hz.(Varies with the efficiency of the motor).

$$*7) \text{ Voltageunbalance} = \frac{\text{Max. voltage[V]} - \text{Min. voltage[V]}}{\text{Three - phaseaveragevoltage[V]}} \times 67\% \quad (\text{IEC61800-3 : 2004})$$

If this value is 2 to 3%, use an AC REACTOR.

*8) The currents are calculated on the condition that the inverters are connected to power supply of 500kVA (In the case of inverter capacity is more than 50kVA, it is 10 times of the inverter capacity), %X=5%.

*9) Effective function only in induction motor drive.

*10) The load shall be reduced so that the continuous operating current is the rated current in parenthesis or less if the carrier frequency is set to 4kHz or above or ambient temperature exceeds 40°C(104°F).

2) Three-Phase 400V Series (0.4 to 15kW / 1/2 to 20HP)

| Items | | Specifications | | | | | | | | | | | |
|---|--|---|-------------------------------|-------------------------------|-------------------------------|---|------|------|------|------|------|--|--|
| Type (FRN□□□C2S-4△、 △ = A,C,E,U) | 0002 | 0004 | 0005 | 0007 | 0011 | 0013 | 0018 | 0024 | 0030 | | | | |
| Nominal applied motor ¹⁾ [kW] (△=A,C,E) | 0.4 | 0.75 | 1.5 | 2.2 | 3.7(△=A,C)/ 4.0(△=E) | 5.5 | 7.5 | 11 | 15 | | | | |
| Nominal applied motor ¹⁾ [HP] (△=U) | 1/2 | 1 | 2 | 3 | 5 | 7.5 | 10 | 15 | 20 | | | | |
| Output ratings | Rated capacity ²⁾ [kVA] | 1.3 | 2.3 | 3.2 | 4.8 | 8.0 | 9.9 | 13 | 18 | 22 | | | |
| | Rated voltage ³⁾ [V] | Three-phase 380~480V (With AVR) | | | | | | | | | | | |
| | Rated current [A] | 1.8 (1.5) ⁴⁾ | 3.1 (2.5) ⁴⁾ | 4.3 (3.7) ⁴⁾ | 6.3 (5.5) ⁴⁾ | 10.5 (9.0) ⁴⁾ | 13.0 | 18.0 | 24.0 | 30.0 | | | |
| | Overload capability | 150% of rated current for 1min 150% of rated current for 1min or 200% of rated current for 0.5s (If the rated current is in parenthesis) | | | | 150% of rated current for 1min or 200% of rated current for 0.5s | | | | | | | |
| Input ratings | Rated frequency | 50, 60Hz | | | | | | | | | | | |
| | Main power supply | Three-phase 380~480V, 50/60Hz | | | | | | | | | | | |
| | Voltage/frequency variations | Voltage: +10 to -15% (Voltage unbalance: 2% or less ⁷⁾), Frequency: +5 to -5% | | | | | | | | | | | |
| | Rated current ⁸⁾ [A] | With DCR | 0.85 | 1.6 | 3.0 | 4.4 | 7.3 | 10.6 | 14.4 | 21.1 | 28.8 | | |
| Braking | Without DCR | | 1.7 | 3.1 | 5.9 | 8.2 | 13.0 | 17.3 | 23.2 | 33.0 | 43.8 | | |
| | Required power supply capacity ⁵⁾ [kVA] | | 0.6 | 1.1 | 2.0 | 2.9 | 4.9 | 7.4 | 10 | 15 | 20 | | |
| | Braking torque ⁶⁾ [%] | 100 | | 50 | 30 | | 20 | | | | | | |
| | DC braking | Starting frequency ⁹⁾ : 0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level: 0 to 100% | | | | | | | | | | | |
| Transistor for braking resistor | | Built-in | | | | | | | | | | | |
| Applicable safety Standards | | UL508C, EN 61800-5-1:2007 | | | | | | | | | | | |
| Enclosure | | IP20 (IEC 60529:1989) / UL open type (UL50) | | | | | | | | | | | |
| Cooling method | | Natural cooling | | Fan cooling | | | | | | | | | |
| Mass [kg] (△=A,C,E) | | 1.2 | 1.3 | 1.7 | 1.7 | 2.5 | 3.1 | 3.1 | 4.5 | 4.5 | | | |
| Mass [lbs] (△=U) | | 2.6 | 2.9 | 3.7 | 3.7 | 5.5 | 6.8 | 6.8 | 9.8 | 9.8 | | | |

*1) Fuji Electric's/US 4-pole standard motor.

*2) Rated capacity is calculated by regarding the output rated voltage as 440V for three-phase 400V series.

*3) Output voltage cannot exceed the power supply voltage.

*4) The load shall be reduced so that the continuous operating current is the rated current in parenthesis or less if the carrier frequency is set to 3kHz or above or ambient temperature exceeds 40°C(104°F).

*5) Obtained when a DC REACTOR is used.

*6) Average braking torque when a motor of no load decelerates from 60Hz. (Varies with the efficiency of the motor).

$$*7) \text{ Voltageunbalance} = \frac{\text{Max. voltage[V]} - \text{Min. voltage[V]}}{\text{Three - phaseaveragevoltage[V]}} \times 67\% \quad (\text{IEC61800-3 : 2004})$$

If this value is 2 to 3%, use an AC REACTOR.

*8) The currents are calculated on the condition that the inverters are connected to power supply of 500kVA (In the case of inverter capacity is more than 50kVA, it is 10 times of the inverter capacity), %X=5%.

*9) Effective function only in induction motor drive.

3) Single-Phase 200V Series (0.1 to 2.2kW / 1/8 to 3HP)

| Items | | Specifications | | | | | | | |
|---|---|---|--------------|--------------|--------------|--------------|--|--|--|
| Type (FRN□□□C2S-7△、 △ = A,C,E,U) | 0001 | 0002 | 0004 ② | 0006 | 0010 | 0012 | | | |
| Nominal applied motor ^{①)} [kW] (△=A,C,E) | 0.1 | 0.2 | 0.4 | 0.75 | 1.5 | 2.2 | | | |
| Nominal applied motor ^{①)} [HP] (△=U) | 1/8 | 1/4 | 1/2 | 1 | 2 | 3 | | | |
| Output ratings | Rated capacity ^{②)} [kVA] | 0.30 | 0.57 | 1.3 | 2.0 | 3.5 | | | |
| | Rated voltage ^{③)} [V] | Three-phase 200~240V (With AVR) | | | | | | | |
| | Rated current [A] ^{④)} | 0.8 (0.7) | 1.5 (1.4) | 3.5 (2.5) | 5.5 (4.2) | 9.2 (7.0) | | | |
| | Overload capability | 150% of rated current for 1min 150% of rated current for 1min or 200% of rated current for 0.5s (If the rated current is in parenthesis) | | | | | | | |
| Input ratings | Rated frequency | 50, 60Hz | | | | | | | |
| | Main power supply | Single-phase 200~240V, 50/60Hz | | | | | | | |
| | Voltage/frequency variations | Voltage: +10 to -10%, Frequency: +5 to -5% | | | | | | | |
| | Rated current ^{⑦)} [A] | With DCR | 1.1 | 2.0 | 3.5 | 6.4 | | | |
| Braking | Without DCR | | 1.8 | 3.3 | 5.4 | 9.7 | | | |
| | Required power supply capacity ^{⑤)} [kVA] | | 0.3 | 0.4 | 0.7 | 1.3 | | | |
| | Braking torque ^{⑥)} [%] | | 150 | 100 | 50 | 30 | | | |
| DC braking | DC braking | Starting frequency ^{⑨)} : 0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level: 0 to 100% | | | | | | | |
| | Transistor for braking resistor | - | | Built-in | | | | | |
| Applicable safety standards | | UL508C, EN 61800-5-1:2007 | | | | | | | |
| Enclosure | | IP20 (IEC 60529:1989) / UL open type (UL50) | | | | | | | |
| Cooling method | | Natural cooling | | | Fan cooling | | | | |
| Mass [kg] (△=A,C,E) | | 0.6 | 0.6 | 0.7 | 0.9 | 1.8 | | | |
| Mass [lbs] (△=U) | | 1.3 | 1.3 | 1.5 | 2.0 | 4.0 | | | |
| | | | | | | | | | |
| | | | | | | | | | |

*1) Fuji Electric's/US 4-pole standard motor.

*2) Rated capacity is calculated by regarding the output rated voltage as 220V.

*3) Output voltage cannot exceed the power supply voltage.

*4) The load shall be reduced so that the continuous operating current is the rated current in parenthesis or less if the carrier frequency is set to 3kHz or above or ambient temperature exceeds 40°C(104°F).

*5) Obtained when a DC REACTOR is used.

*6) Average braking torque when a motor of no load decelerates from 60Hz. (Varies with the efficiency of the motor).

*8) The currents are calculated on the condition that the inverters are connected to power supply of 500kVA (In the case of inverter capacity is more than 50kVA, it is 10 times of the inverter capacity), %X=5%.

*9) Effective function only in induction motor drive.

4) Single-Phase 100V Series (0.1 to 0.75kW / 1/8 to 1HP) ($\Delta = U$ only)

| Items | | Specifications | | | | | | | |
|--|--|--|------|----------|-----|--|--|--|--|
| Type (FRN□□□C2S-6△、 △ = U) | 0001 | 0002 | 0003 | 0005 | | | | | |
| Nominal applied motor ¹⁾ [HP] | 1/8 | 1/4 | 1/2 | 1 | | | | | |
| Output ratings | Rated capacity ²⁾ [kVA] | 0.26 | 0.53 | 0.95 | 1.6 | | | | |
| | Rated voltage ³⁾ [V] | Three-phase 200~240V (With AVR) | | | | | | | |
| | Rated current [A] | 0.7 | 1.4 | 2.5 | 4.2 | | | | |
| | Overload capability | 150% of rated current for 1min or 200% of rated current for 0.5s | | | | | | | |
| | Rated frequency | 50, 60Hz | | | | | | | |
| Input ratings | Main power supply | Single-phase 100~120V, 50/60Hz | | | | | | | |
| | Voltage/frequency variations | Voltage: +10 to -10%, Frequency: +5 to -5% | | | | | | | |
| | Rated current ⁸⁾ [A] | With DCR | 2.2 | 3.8 | 6.4 | | | | |
| | | Without DCR | 3.6 | 5.9 | 9.5 | | | | |
| | Required power supply capacity ⁵⁾ [kVA] | | 0.3 | 0.5 | 0.7 | | | | |
| Braking | Braking torque ⁶⁾ [%] | 150 | | 100 | | | | | |
| | DC braking | Starting frequency ⁹⁾ : 0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level: 0 to 100% | | | | | | | |
| | Transistor for braking resistor | - | | Built-in | | | | | |
| Applicable safety standards | UL508C | | | | | | | | |
| Enclosure | IP20 (IEC 60529:1989) / UL open type (UL50) | | | | | | | | |
| Cooling method | Natural cooling | | | | | | | | |
| Mass [kg] | 0.7 | 0.7 | 0.8 | 1.3 | | | | | |
| Mass [lbs] | 1.5 | 1.5 | 1.8 | 2.9 | | | | | |

*1) Fuji Electric's/US 4-pole standard motor.

*2) Rated capacity is calculated by regarding the output rated voltage as 220V.

*3) Output voltage cannot exceed the twice of power supply voltage.

*5) Obtained when a DC REACTOR is used.

*6) Average braking torque when a motor of no load decelerates from 60Hz. (Varies with the efficiency of the motor).

*8) The currents are calculated on the condition that the inverters are connected to power supply of 50kVA, %X=5%.

*9) Effective function only in induction motor drive.

Note

When driven by 100 VAC, the single-phase 100 V series of inverters limit their shaft output and maximum output torque as listed below. This is to prevent their output voltage from decreasing when load is applied.

| | Shaft output (%) | Maximum torque (%) |
|----------------------|------------------|--------------------|
| w/o DC reactor (DCR) | 90 | 150 |
| w/ DC reactor (DCR) | 85 | 120 |

6. Outline: Standard Models

Fig. 1

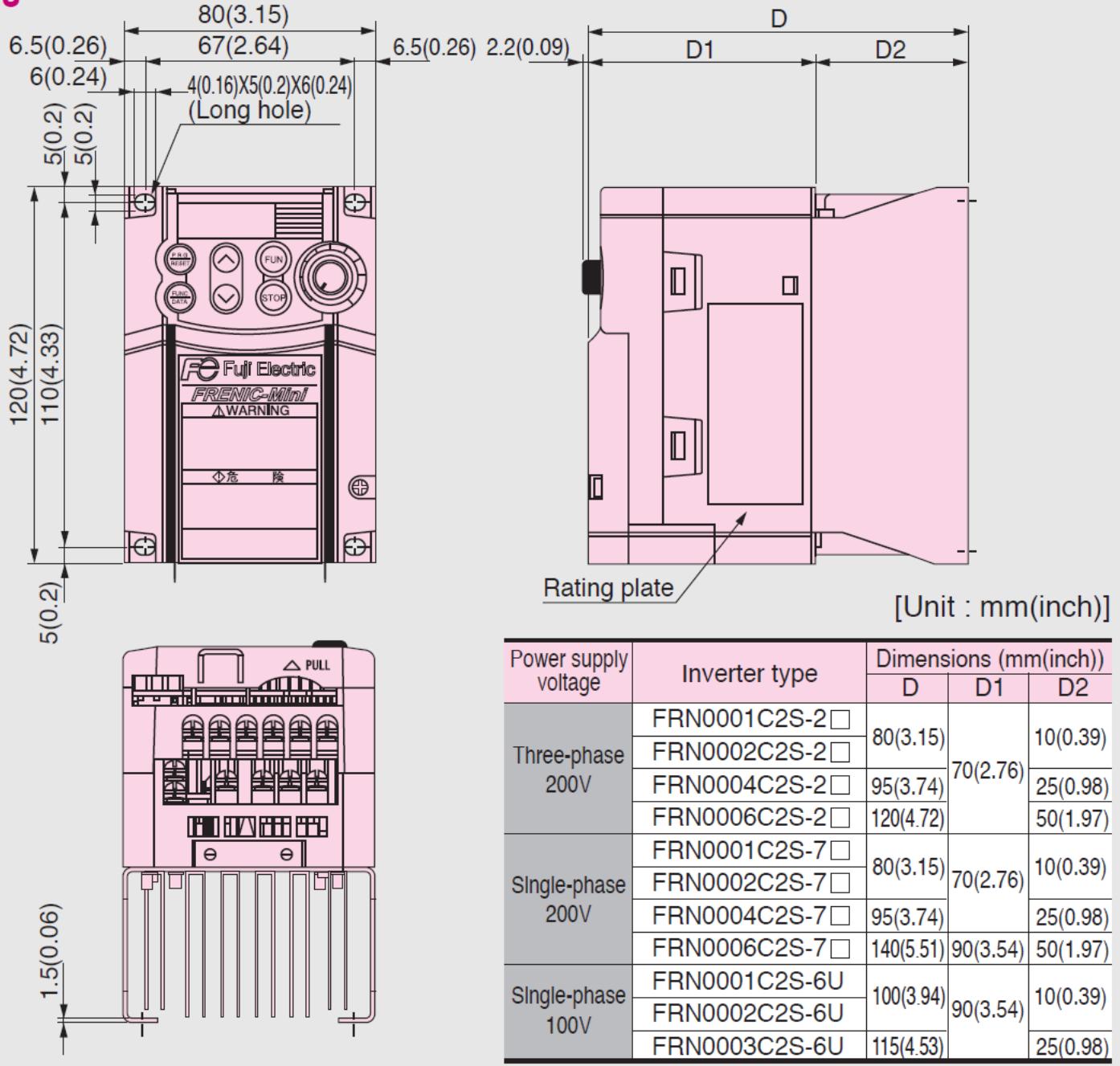
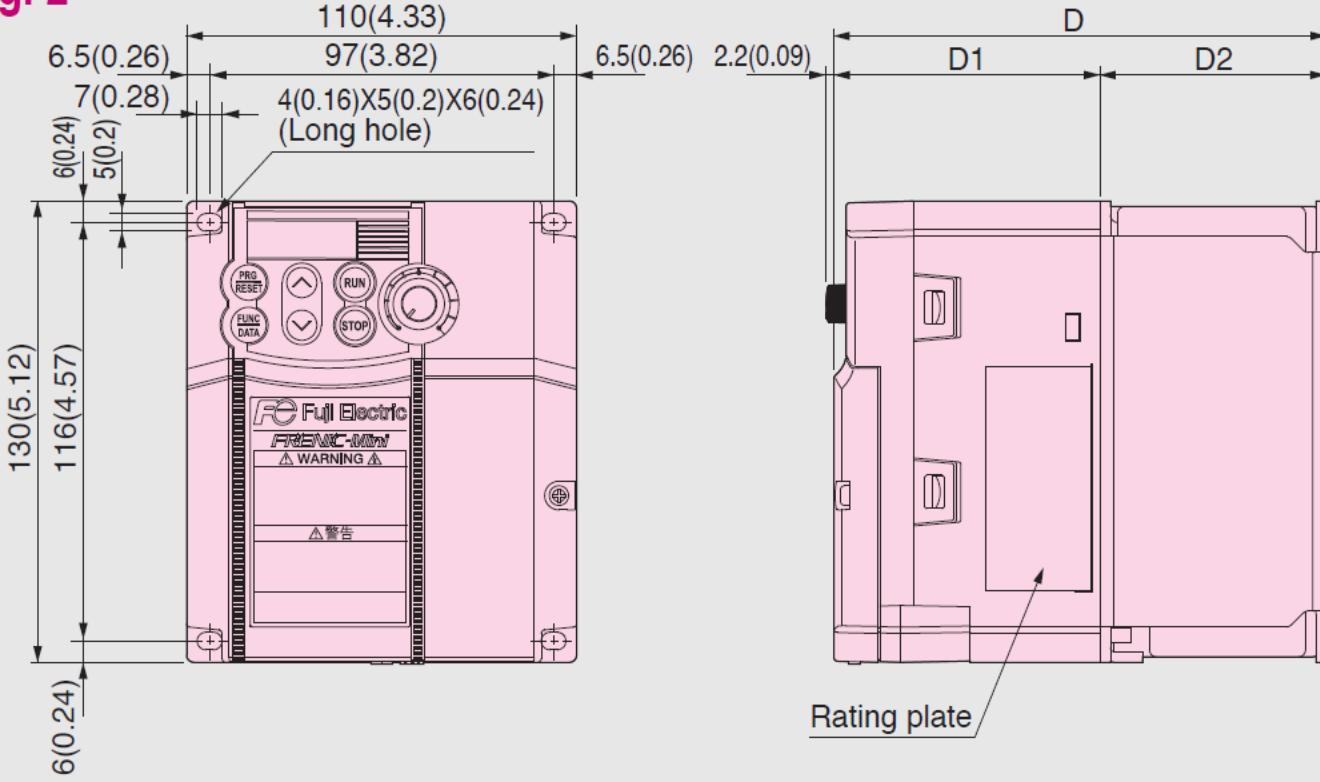
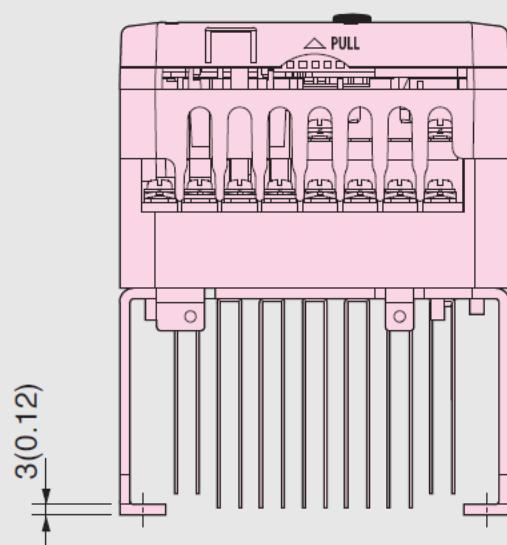


Fig. 2



[Unit : mm(inch)]



| Power supply voltage | Inverter type | Dimensions (mm/inch) | | |
|----------------------|---------------|----------------------|----------|----------|
| | | D | D1 | D2 |
| Three-phase 400V | FRN0002C2S-4□ | 115(4.53) | 75(2.95) | 40(1.57) |
| | FRN0004C2S-4□ | 139(5.47) | | 64(2.52) |
| Single-phase 100V | FRN0005C2S-6U | 139(5.47) | 99(3.9) | 40(1.57) |

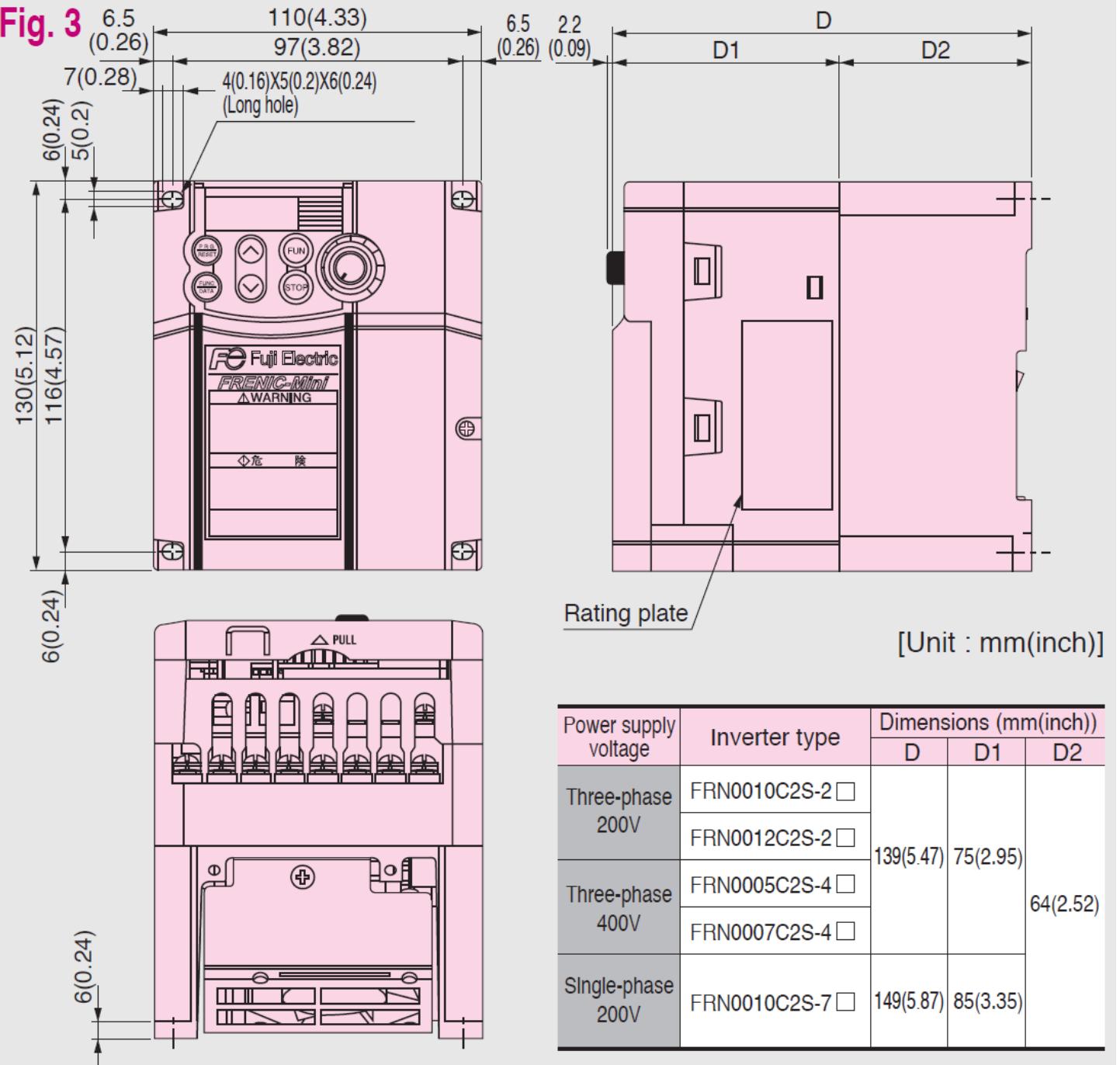
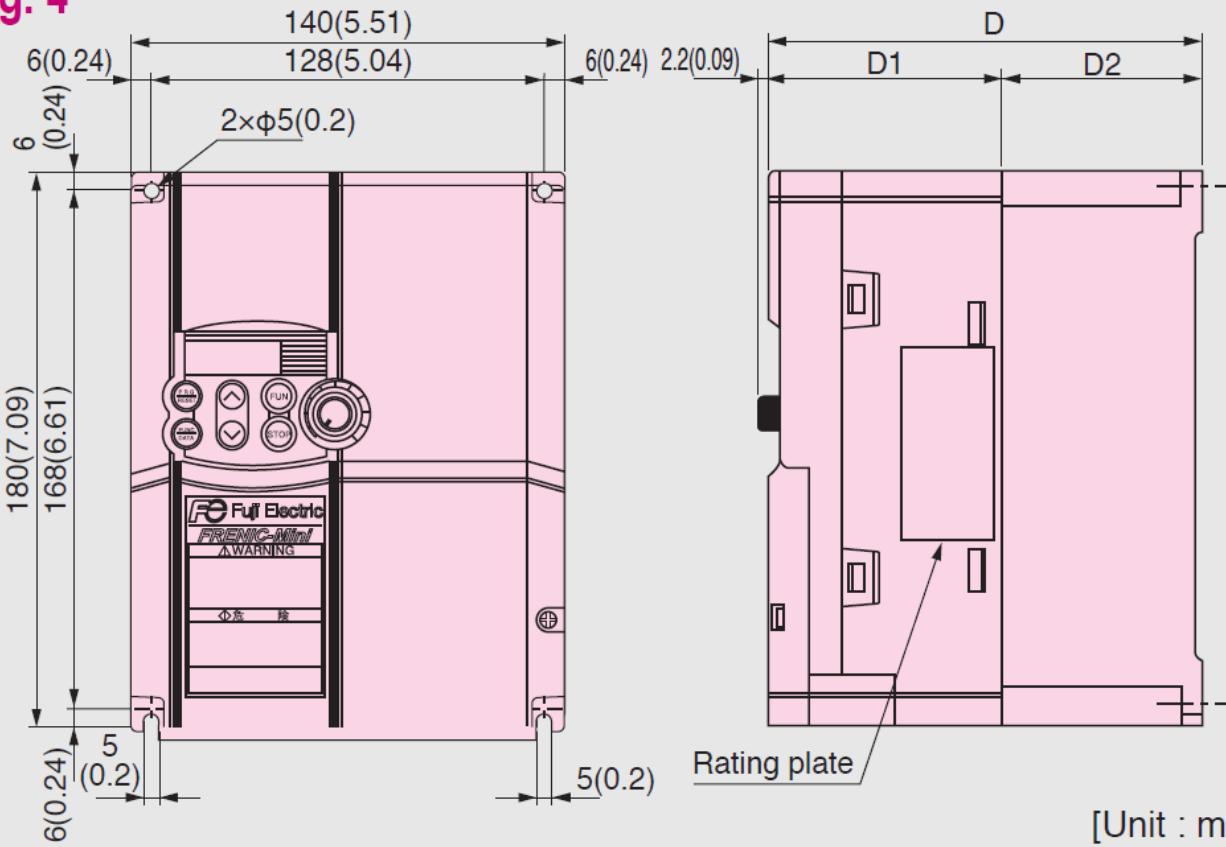
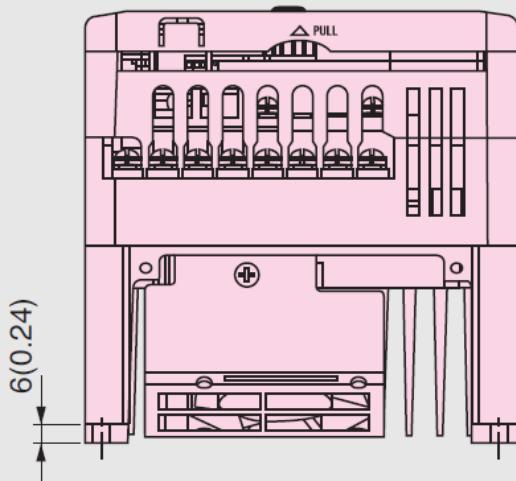
Fig. 3

Fig. 4



[Unit : mm(inch)]



| Power supply voltage | Inverter type | Dimensions (mm(inch)) | | |
|----------------------|---------------|-----------------------|----------|----------|
| | | D | D1 | D2 |
| Three-phase 200V | FRN0020C2S-2□ | | | |
| Three-phase 400V | FRN0011C2S-4□ | 139(5.47) | 75(2.95) | 64(2.52) |
| Single-phase 200V | FRN0012C2S-7□ | | | |

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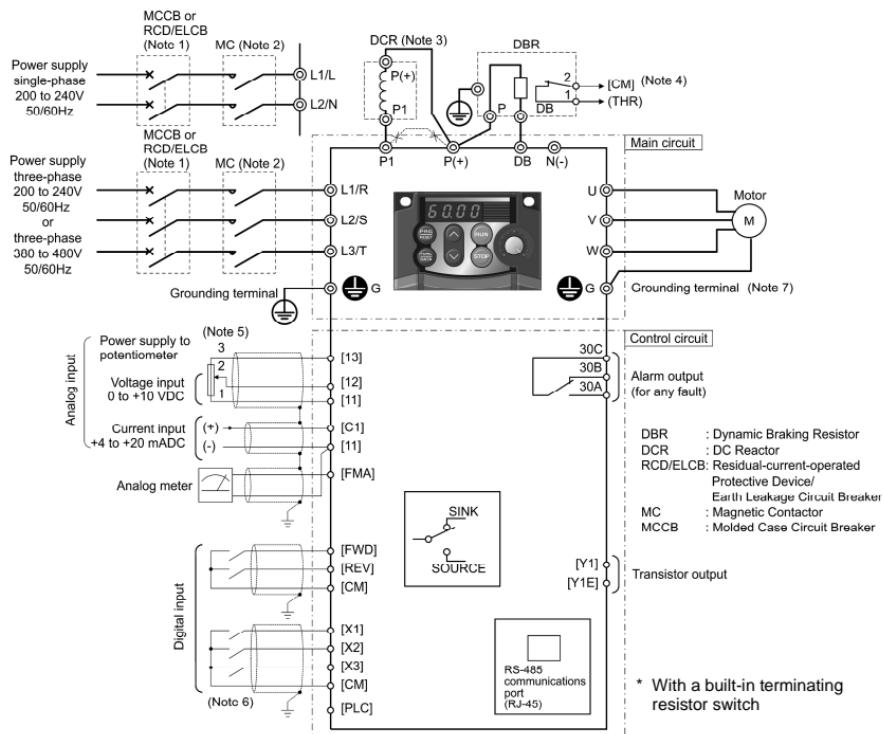
47520 Westinghouse Drive, Fremont, CA 94539

Phone: 510-440-1060

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Connection diagram



- (Note 1) Install a recommended molded case circuit breaker (MCCB) or a residual-current-operated protective device (RCD)/earth leakage circuit breaker (ELCB) (with overcurrent protection) in the primary circuit of the inverter to protect wiring. Do not use an MCCB or RCD/ELCB whose capacity exceeds the recommended rated current.
- (Note 2) A magnetic contactor (MC) should, if necessary, be mounted independent of the MCCB or ELCB to cut off the power fed to the inverter. Refer to page 9-2 for details. MCs or solenoids that will be installed close to the inverter require surge absorbers to be connected in parallel to their coils.
- (Note 3) When connecting a DC reactor (option), remove the jumper bar from terminals [P1] and [P+].
- (Note 4) The **THR** function can be used by assigning "9" (External alarm) to any of terminals [X1] to [X3], [FWD] or [REV] (function code E01 to E03, E98, or E99). For details, refer to Chapter 9.
- (Note 5) Frequency can be set by connecting a frequency setting device (external potentiometer) between terminals [11], [12], and [13] instead of inputting voltage signal (0 to +10 VDC or 0 to +5 VDC) between terminals [12] and [11].
- * With a built-in terminating resistor switch