

HIKMICRO

Clamp-on Ultrasonic Flow Meter

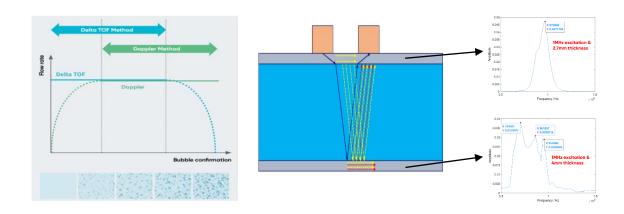




Features and Benefits

Strong measurement stability: 40db+ SNR index, high echo signal energy under large pipe diameter, stable measurement, strong penetration ability and easy measurement for rusted and scaled pipe sections.

High applicability to working conditions: automatic optimization of excitation frequency, selection of the most suitable excitation for pipe wall thickness, automatic switching of detection mode according to the amount of liquid bubbles



- High accuracy level, water medium achieves $\pm 0.5\%$ accuracy at a flow rate of $1\text{m/s}\sim10\text{m/s}$, and repeatability $\leq0.1\%$
- Simple and safe menu-guided sensor installation method to ensure highprecision measurement results
- Installed outside the pipeline, no need to interrupt process operation, no pressure
- Supports bidirectional measurement of medium flow direction
- Supports Bluetooth remote debugging to achieve rapid device configuration, transmitter and sensor binding, sharing of website training materials and operation videos, which improves user operation efficiency and convenience of instrument use
- Sensor protection level up to IP68
- Rapid sensor self-test, automatically determine whether the sensor is working properly
- Automatic evaluation of installation position, automatically recommend installation locations based on signal quality
- Automatic selection of measurement frequency, automatically scan the optimal detection frequency to improve measurement accuracy



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1. Product Introduction

1.1. Application

HIKMICRO FU00 series clamp-on ultrasonic flow meter adopts a non-contact measurement method to measure various types of water medium (drinking water, raw water, and sewage), oil (lubricating oil, diesel, fuel oil, and crude oil) and highly corrosive, toxic and harmful chemicals. It is not affected by process pressure and medium conductivity. The measurement pipe diameter can cover a maximum of DN5000. It is an economical and efficient flow measurement solution.

1.2. Measuring Principle

HIKMICRO clamp-on ultrasonic flowmeter uses a measurement method that automatically switches between the time difference method (TOF) and the Doppler method. When the medium is relatively uniform, the time difference method is used for measurement, and when the medium contains particles or bubbles, the Doppler method is used for measurement.

1. Time Difference Method (TOF) to Measure Flow Velocity

The flight time of the ultrasonic wave (TOF) is related to the flow velocity and sound velocity of the medium in the pipe section. By detecting the flight time, the flow velocity of the medium in the pipe section can be obtained, and finally the flow rate can be measured and calculated.

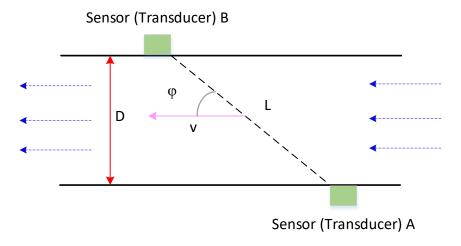


Figure 1 Schematic Diagram of Ultrasonic Sensor (Transducer) Installation



Known:

L = Sound Wave Transmission Length

D = Pipe Diameter

 ϕ = Angle between Sound Wave Transmission Path and Pipe

 T_{AB} = Sound Wave Flight Time from Sensor A to Sensor B

 T_{BA} = Sound Wave Flight Time from Sensor B to Sensor A

Unknown:

c = Sound Velocity in the Medium

v = Liquid Flow Rate in Pipe

Sound Wave Flight Time from Sensor A to Sensor B

$$T_{\rm AB} = \frac{L}{c + v cos \varphi}$$

Sound Wave Flight Time from Sensor B to Sensor A

$$T_{\rm BA} = \frac{L}{c - v cos \varphi}$$

Flow Velocity v:

$$\mathbf{v} = \frac{L}{2cos\varphi} \left(\frac{1}{T_{\mathrm{AB}}} - \frac{1}{T_{\mathrm{BA}}} \right) = \frac{L}{2cos\varphi} \left(\frac{T_{\mathrm{BA}} - T_{\mathrm{AB}}}{T_{\mathrm{AB}}T_{\mathrm{BA}}} \right)$$



2. Doppler Method for Measuring Flow Velocity

The Doppler method uses the Doppler principle in acoustics. By detecting the frequency offset between the reflected sound wave and the transmitted sound wave, the flow velocity of the fluid can be determined, and then the fluid flow rate can be measured. The Doppler method actually measures the velocity of the particles in the fluid, which is used to replace the fluid velocity to calculate the fluid flow rate.

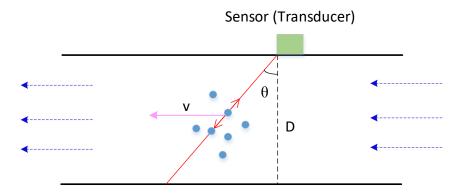


Figure 2 Schematic Diagram of Sensor (Transducer) Self-Transmission and Self-Reception

The sensor is first in the transmitting state, with a sound speed of c, and transmits an ultrasonic pulse with a frequency of f_T to the fluid containing particles. Then the transducer switches to the receiving state and receives the signal reflected by the particles. According to the Doppler Effect, the frequency of the ultrasonic wave reflected by the particles received by the receiver is f_R . When the particle flow velocity is v, there is the following relationship:

$$f_R = f_T (1 - \frac{v sin\theta}{c})^2 \approx f_T \left(1 - \frac{2v sin\theta}{c}\right)$$

Then the Doppler frequency shift is:

$$\Delta f = f_T - f_R = f_T \frac{2v sin\theta}{c}$$

Then the flow velocity v is:

$$\mathbf{v} = \frac{c}{2f_T sin\theta} \Delta f$$



2. Technical Parameters

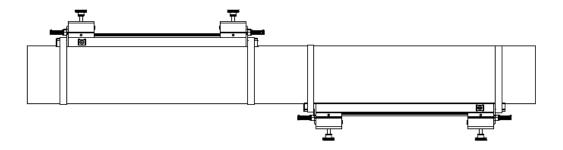
Measured Variables	Flow rate, volume flow
Accuracy and Repeatability (1 ~10 m /s)	Accuracy 0.5%, repeatability 0.1% (Time difference method) Accuracy 2.0%, repeatability 0.4% (Doppler method)
Power Supply (Power Consumption ≤ 10W)	AC: 85~265VAC, 50± 4Hz DC: 24V DC (12 ~36V DC)
Wire System	Four-wire
	$4\sim20$ mA HART Output range: $4\sim20$ mA (NAMUR standard) Load capacity: $700~\Omega$ Resolution : $0.4\mu A$ Mode: Active and Passive
Output	Pulse / function output Optional settings: Pulse output: Pulse width range 0.05~2,000ms, maximum pulse frequency 10 kHz Frequency output: Maximum frequency 10 kHz Function output: Switch value, which can be used to indicate status information, including: diagnostic response, limit value, flow direction check, and status.
Input	 4 ~ 20 mA input: maximum input voltage ≤ 30V (passive), supports active and passive input. Switch input: Maximum input value 30V, response time 5 ~200ms configurable. Low level: -3 ~5VDC, High level: 12 ~30VDC
Temperature Compensation	Manual setting, or optional PT1000
Diagnostic Function	Sound velocity, signal amplitude, signal quality
Measuring Pipe Diameter Range	DN10 ~DN5000
Fixing Method	The transmitter supports wall-mounted installation and pipe installation The sensor supports fixture installation and clamp installation
Operating Conditions	Ambient temperature range: -40 ~+60 °C Medium temperature range: -40~+180 °C Medium pressure range: static pressure is higher than saturated steam pressure to avoid medium gasification
Pressure Loss	No pressure loss



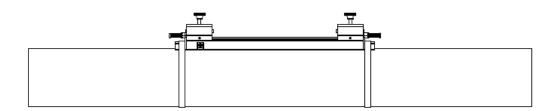
3. Installation Requirements

Select the corresponding installation method and installation distance according to the guidance settings.

The opposite installation method should ensure that the fixture is at both ends of the horizontal center of the pipeline



Opposite Side Installation



Same Side Installation

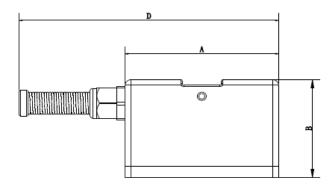


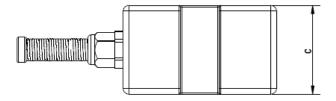
4. Mechanical Structure & Dimensional Drawing

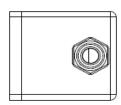
Weight: 2.3 kg

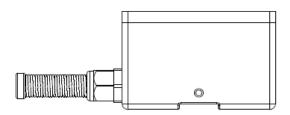
Dimensions & structural parameters:

4.1. Sensor









Material:

• Sensor body: SUS 316

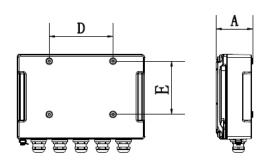
Anti-bending metal joint: SUS 316L

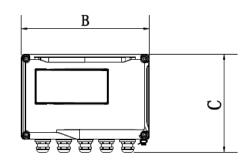
Size:

Unit	Α	В	С	D
mm (inch)	50.8 (2)	35.3 (1.39)	32 (1.26)	88.3 (3.48)



4.2.Transmitter





Material:

• Housing: Aluminum Silicon + Magnesium

• Cable gland: Nylon

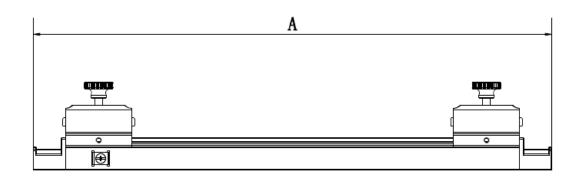
Gland seal: EPDM rubber

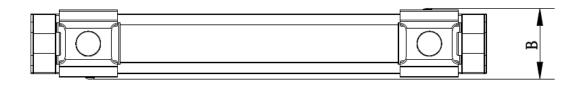
Size:

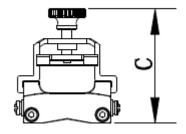
Unit	А	В	C	D	E
mm(inch)	66 (2.6)	240 (9.45)	188 (7.4)	120 (4.72)	100 (3.94)



4.3.Bracket







Material:

• Thumb screw: SUS304

• Bracket body: 6061

Size:

Unit	Unit A		С		
mm(inch)	400 (15.5)	62 (2.44)	67 (2.64)		



5. Ordering Information

The model code of HIKMICRO Ultrasonic Flow Meter is explained below. Each item from A to R must be specified at the time of ordering.



- A. Base Model-Ultrasonic Flow Meter
- B. Series
- C. Accuracy
- D. Number of Channels
- E. Medium to be Measured
- F. Nominal Diameter
- G. Nominal Pressure
- H. Process Connection
- I. Sealing Surface
- J. Housing
- K. Power Supply

- L. Output Signal
- M. Sensor Type
- N. Sensor Frequency
- O. Temp. Range (Medium)
- P. Sensor Material
- Q. Explosion-proof
- R. Sensor Protection Rating
- S. Cable Type
- T. Cable Length
- U. Installation Method

5.1. Model Code Description

Model Code Position	lodel Code Position Model Code Description									
Base Model- Ultrason	ic Flow Meter									
А	HM-FU	Product Category								
Series										
В	B 00 Product Series									
Accuracy										
С	0.5%									
С	G	1%								
Number of Channels										
D	1	Single Channel								
Medium to be Measure	ed									
E	L	Liquid (water, raw water, demineralized water)								
Nominal Diameter										
F	300	DN50~DN300								
F	F 122 DN350~DN1200									
Nominal Pressure	Nominal Pressure									



G	NO	NA
Process Connection		
Н	N	NA
Sealing Surface		
I	N	NA
Housing		
J	1	Square housing
Power Supply		
К	D	DC 24V
Output Signal		
L	1	4 ~ 20 mA + pulse + MODBUS
Sensor Type		
М	С	Standard A series
Sensor Frequency		
N	В	1MHz
Temp. Range (Medium)	
0	2	-40°C~120°C
Sensor Material		
Р	В	Stainless steel
Explosion-proof		
Q	N	Non-explosion proof
Sensor Protection Rati	ng	
R	D	IP68
Cable Type		
S	С	Standard cables
Cable Length		
Т	10	10m
Installation Method		
U	K	Aluminum clamp



5.2.Selection Table

				C	am	ıp-	-on	ı Ul	ltrc	ISOI	nic	Flo	W	Μe	ete	r				
X	Х	Х	Х	Х	Х	X	Х	X		X	Х	Х	Х	X	Х	Х	Х	Х	Х	Х
0 Series 00	Accuracy 0.5% F 1% G																			Installation Method K: Aluminum clamp
	Number of Single Char																		Cabl	e Length Om
(water, raw wat			d L																e Type tandare	d cables
		DN50	ominal Did 0~DN300 ~DN1200	300 122													Senso D: IP	r Protec	ction Ro	iting
			N		Pressure IA NO Cess Coni												sion-pro	oof osion pr	roof	
					N.	Sealing	Surface IA N									r Materi ainless s				
						Squa	ł re housin	Housing							Range (.0°C~120°)			
													Senso B 1	or Freque 1MHz	ency					
												Sensor 1 C Sto		A series						
											Output 1 4	Signal ∼20 mA	+ pulse ·	+ MODBI	JS					
										Power S	Supply DC 24V									

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