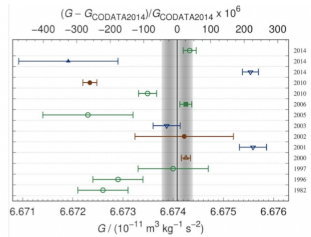
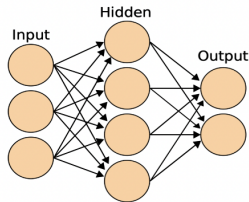
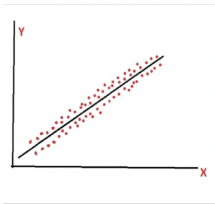


Seminar Series Kickoff

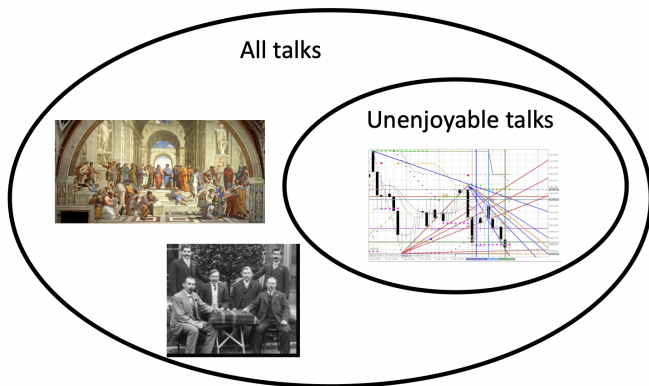
Various Remarks, “Data & Modeling”

Conor Rowan

University of Colorado Boulder, Aerospace Engineering



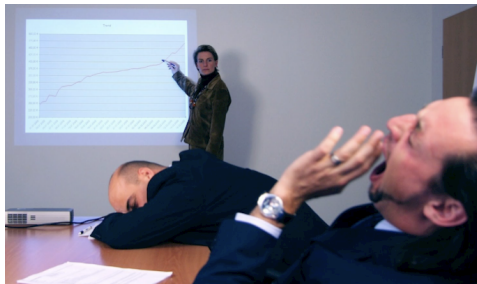
Background & Motivation



- Mostly underwhelmed by talks that I attend
- *In my opinion*, attending talks should be a fun way to get exposed to new ideas and engage with the community
- History supplies examples of the power of the right people talking to each other (in the right way)

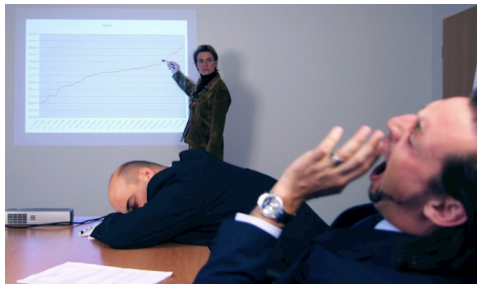
What are the failure modes?

- Poor presentation skills



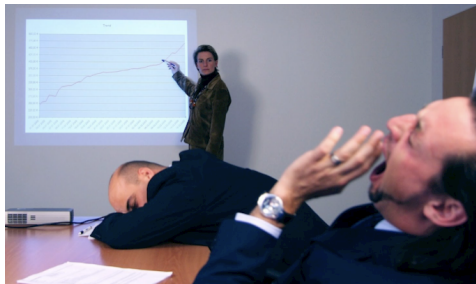
What are the failure modes?

- Poor presentation skills
- Difficult to follow



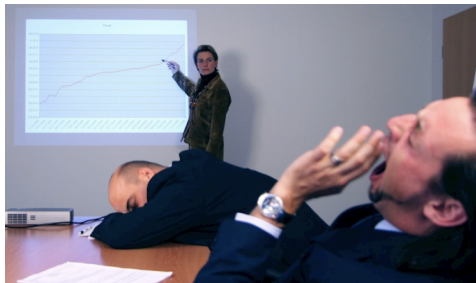
What are the failure modes?

- Poor presentation skills
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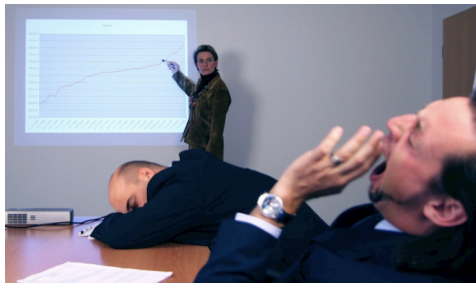
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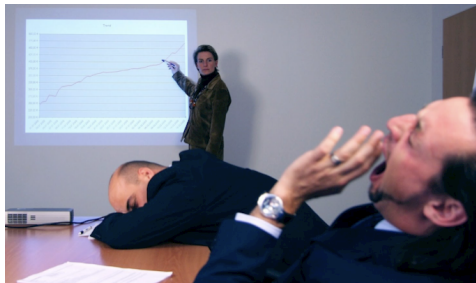
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- Poor presentation skills
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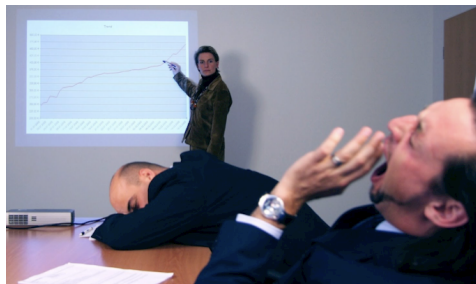
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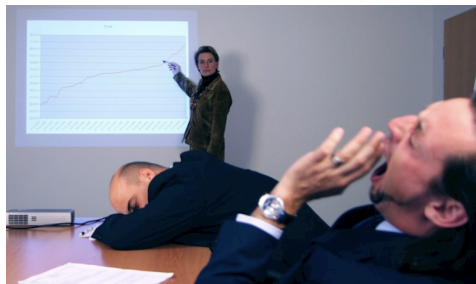
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- Too long
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What are the failure modes?

The bottom line, via Maya Angelou...

“People won’t remember what you said or did, they will remember how you made them feel.”

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- Difficult to follow
- Too specific, not relevant
- Poor framing or motivation
- No participation or discussion
- Too long
- Boring, no dynamics or “storytelling”
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- **Are there other worthy goals?**
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- Other thoughts?

Upcoming

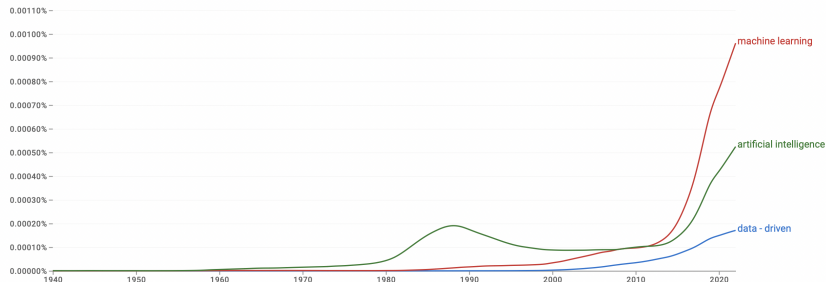
- Meeting 1: Data & Modeling (Conor)
- Meeting 2: Ethics of cold war weapons research (Abby)
- Meeting 3: Linguistic determinism (Grant)
- Meeting 4: ???

Table of Contents

1 Introduction

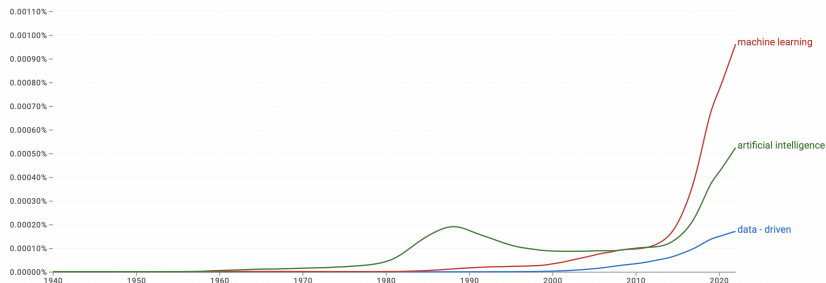
2 Data & Modeling

The Data Revolution



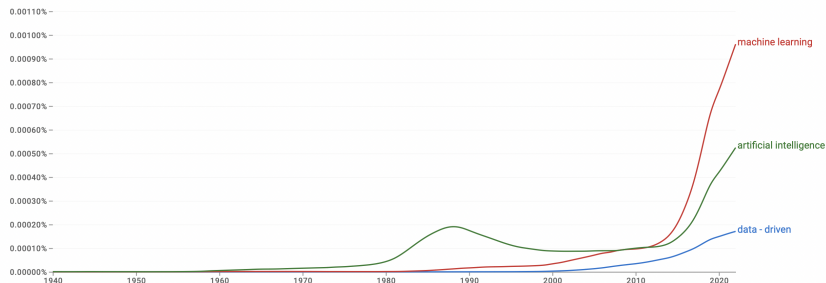
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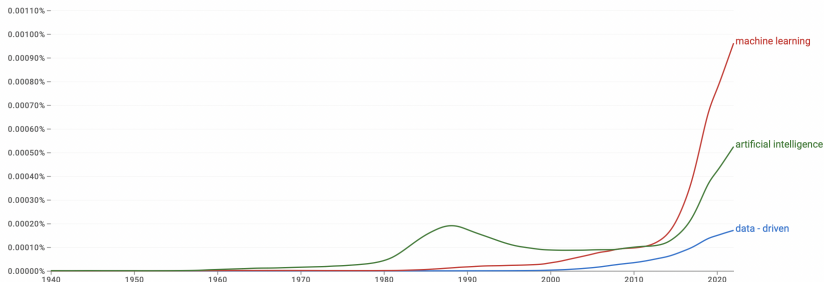
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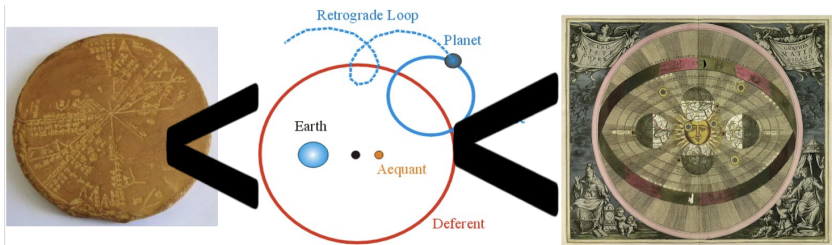
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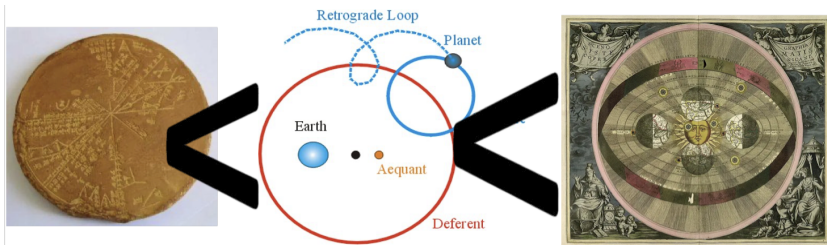
- “Big data” has emerged as a new paradigm in science
- Lots of success stories: AlphaFold, AlphaGo, DeepBlue, ChatGPT, etc.
- Data-driven models are often contrasted with more traditional rule- and physics-based methods—**does this make sense?**
- Bertrand Russell: “the point of philosophy is to start with something so simple as to seem not worth stating, and to end with something so paradoxical that no one will believe it.”

Data-driven, as opposed to what?



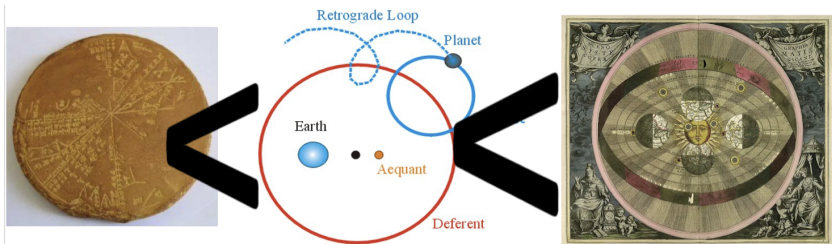
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Data-driven, as opposed to what?



- We off-load the hard work of constructing theories to past generations
- Obviously data contributes to the development of basic theory
- Kuhn on theory construction: *“In the absence of a paradigm . . . all of the facts that could possibly pertain to the development of a given science are likely to seem equally relevant. As a result, early fact gathering is a far more nearly random activity than the one that subsequent scientific development makes familiar.”* [1]

Egyptian myth

“When bodies were placed in sarcophagi the flesh disappeared, leaving only the bones: so the body was thought to have been absorbed, or eaten, by the stone . . . this is an interesting case of a generalized observation serving as evidence for a magical or mythical view.” [2]

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Medieval challenges to Greek science

“[The] attack on science took the form of ‘occasionalism’—the doctrine that whatever happens is a singular occasion, governed not by any laws of nature but directly by the will of God.” [4]

Assume we have a (good) theory

- For the sake of argument, assume that the theory/model is “correct” (e.g. gravity is an inverse square law, continuum mechanics is the right way to model matter, etc.)

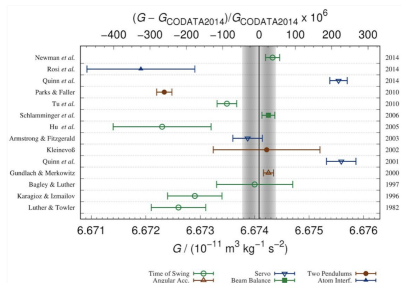


Figure: Measuring the gravitational constant G in $F = GMm/r^2$

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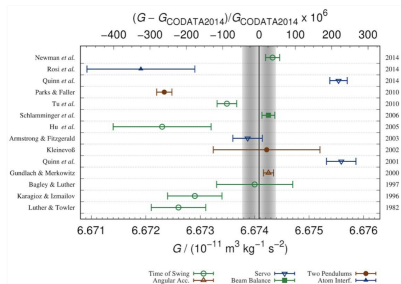


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- *Models still have empirical parameters which need to be estimated from data*
- **So what is the difference between physics-based and data-driven modeling?**

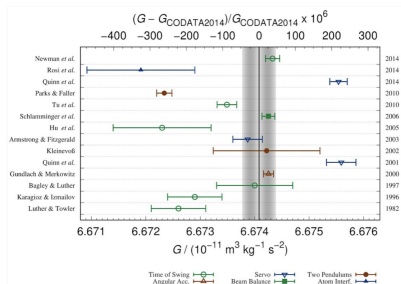
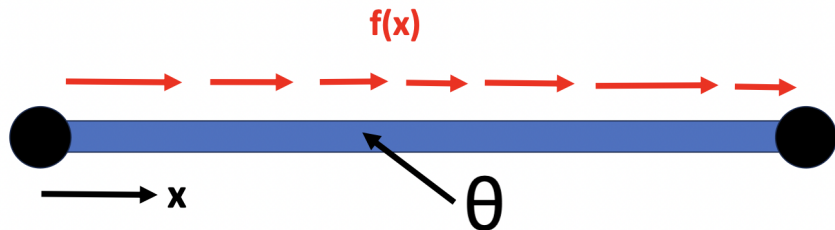


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Outlining and classifying some techniques in modeling

- 1) Numerical simulations, 2) regression, 3) classification, 4) equation discovery, 5) generative models, 6) reduced-order models, 7) surrogate models, 8) physics-informed machine learning, 9) data assimilation, 10) constitutive modeling

Canonical mechanics problem



$$\theta \frac{\partial^2 u}{\partial x^2} = f(x), \quad u(0) = u(1) = 0$$

$$u(x) = \int^x \int^y \frac{f(z)}{\theta} dz dy + cx := \mathcal{G}(f(x); \theta)(x)$$

- How do we estimate the material parameter θ if it is unknown?

Constitutive modeling

- Assume that we have data $\hat{u}(x)$ for a given force $f(x)$ at discrete points x_1, x_2, \dots, x_N :

$$\mathcal{L}(\theta) = \frac{1}{2} \sum_{i=1}^N \left(\mathcal{G}(f(x); \theta)(x_i) - \hat{u}(x_i) \right)^2 \implies \theta = \underset{\theta}{\operatorname{argmin}} \mathcal{L}(\theta)$$

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- Something like this has gone on behind the scenes of every physics-based model
- (Experimentalists can correct me if this is the wrong way of thinking about things)

Same problem, different approach

- We have the same data (and boundary conditions) but no knowledge of a governing equation
- Want to fit an input-output relationship—we are going to need more parameters!

$$u(x) = \mathcal{N}(f(x); \theta_1, \theta_2, \dots)(x)$$

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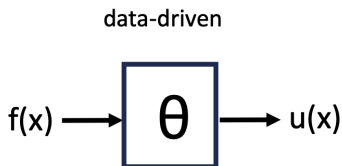
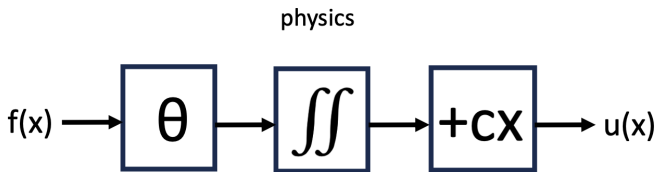
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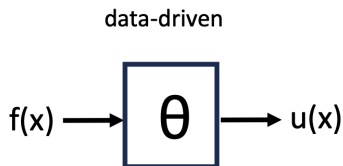
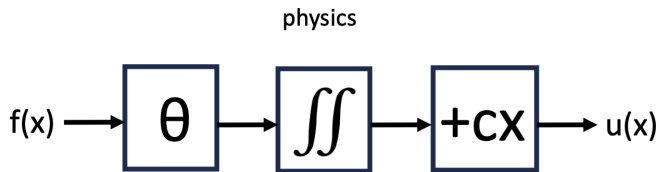
- This is just a funky regression problem— $f(x)$ is the “independent variable” and $u(x)$ is the “dependent variable”
- Choosing the structure of \mathcal{N} is like choosing a regression model (linear, quadratic, neural network, etc.)

What's the difference?



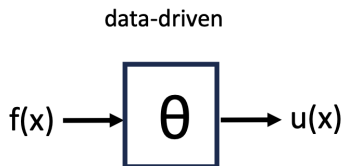
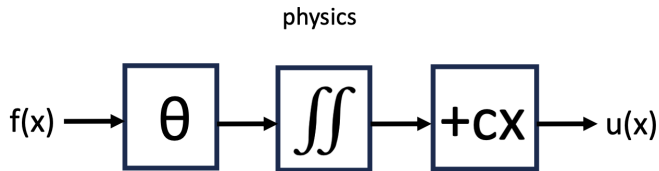
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- Physics model has fewer parameters (?)
- **Why do we expect the physics model to generalize better?**

A complicated story with a simple missing piece

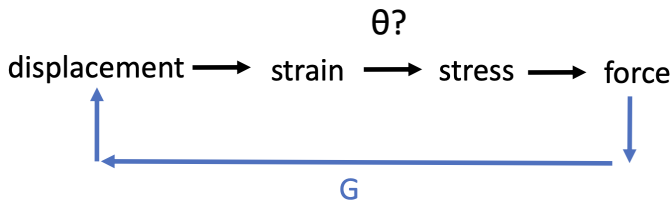
$$\frac{f(x)}{\theta} = \frac{\partial^2 u}{\partial x^2} \implies u(x) = \mathcal{G}(f(x), \theta)(x)$$

- “Applied forces create curvature in the displacement field at a rate controlled by an empirical parameter θ ”
- This knowledge is encoded in the operator \mathcal{G} , only a small and simple piece of the “story” needs to be filled in
- Small amount of data required

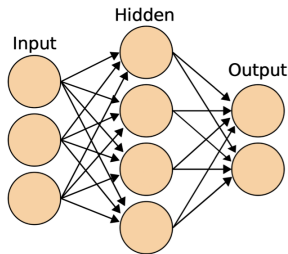
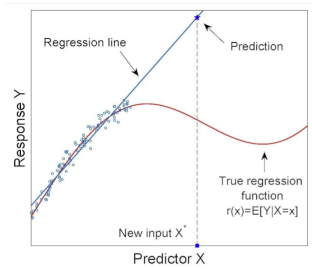
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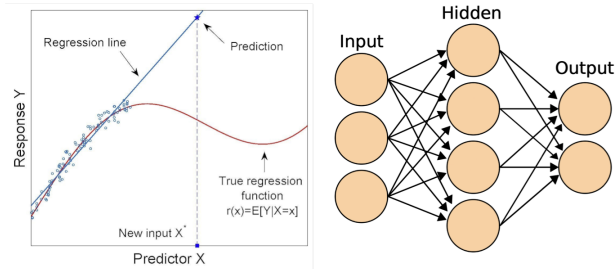


The data-driven model may not learn the story



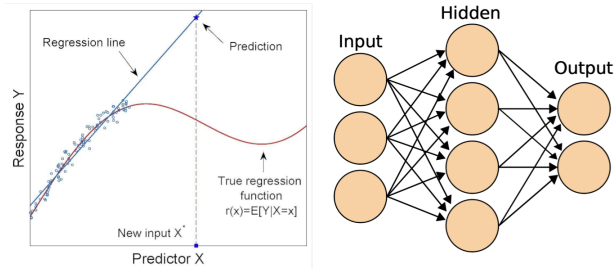
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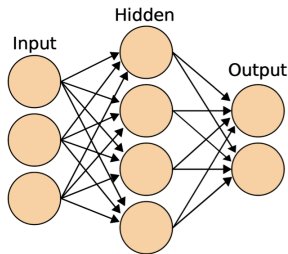
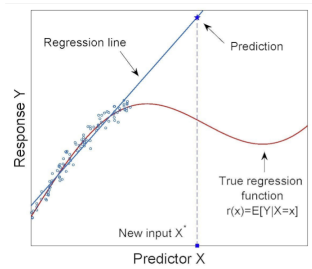
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- Needs a lot of data to even have a chance of being useful

My argument

- There is no sharp distinction between data-driven and physics-based models

My argument

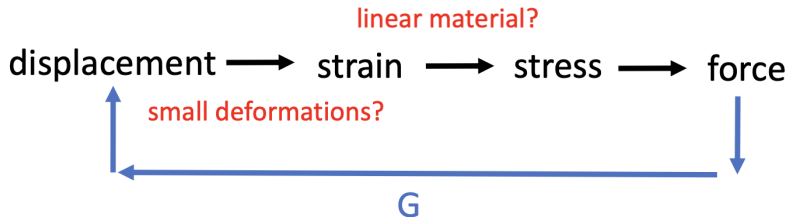
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- Maybe this tempers optimism as well? [5]

Another point on generalization



- When an operator is structured, it is built up from a number of steps which have clear assumptions
- Knowing the assumptions helps assess/predict generalization properties of the model

Thought experiment 1

- Suppose you are an executive at an international company, and you need to communicate to employees in another country that their weekly pay will be late by 1 day, but it will be double when it arrives

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Thought experiment 1

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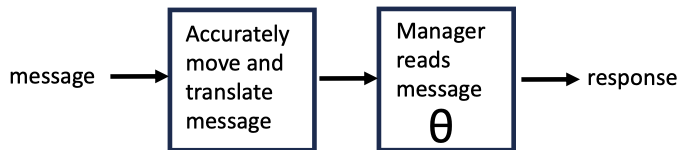
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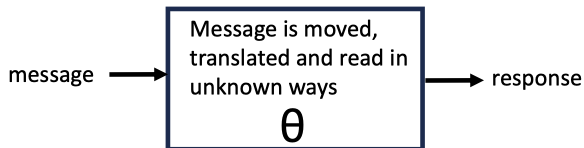
Visualizing the two cases

message → transcribe → mail → translate → read
→ response

Case 1



Case 2



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- When we don't know what mediates inputs and outputs, the “black box” is our only hope...

Applying this argument to an example

PINN's, ROM's



- Physics-informed neural networks (PINN's) and reduced-order models (ROM's) occupy an intermediate position between data and physics
- Can use the “operator structure” argument to justify this
- We will consider these two examples

PINN's (actually Deep Operator Network)

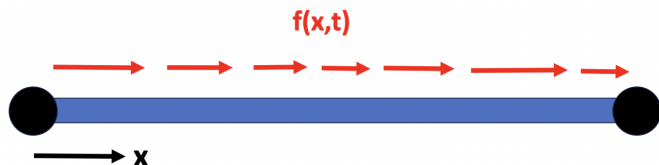
- Physics-informed Deep Operator Networks [6,7] build physics into a data-driven model in an unusual way
- Using a particular discretization of the solution (neural networks), tune parameters such that data is matched AND governing equations are satisfied:

$$u(x) = \sum_i c_i(f(x); \theta) \Psi_i(x; \theta)$$

$$\mathcal{L}^{data}(\theta) = \frac{1}{2} \sum_j \left(\sum_i c_i(f(x); \theta) \Psi_i(x_j; \theta) - \hat{u}(x_j) \right)^2$$

$$\mathcal{L}^{physics}(\theta) = \frac{1}{2} \sum_j \left(\sum_i c_i(f(x); \theta) \frac{\partial^2 \Psi_i}{\partial x^2}(x_j; \theta) - f(x_j) \right)^2$$

$$\theta = \operatorname{argmin}_{\theta} \mathcal{L}^{data}(\theta) + \mathcal{L}^{physics}(\theta)$$



$$\frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2} - f(x, t), \quad u(x, 0) = u(0, t) = u(1, t) = 0$$

$$u(x, t) \approx \sum_{i=1}^N a_i(t) \psi_i(x)$$

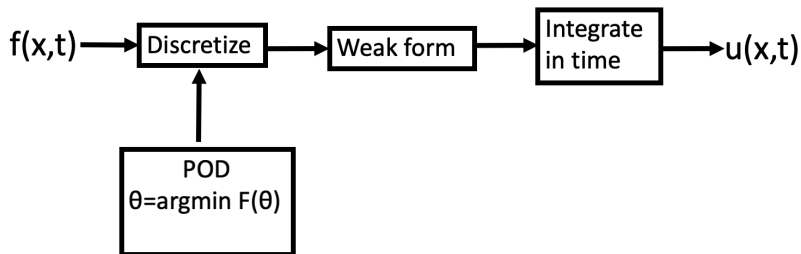
- Cannot write down solution for dynamics of elastic bar, the problem must be solved numerically
- Solution expanded with time varying coefficients $a_i(t)$ scaling given spatial shape functions $\psi_i(x)$

Proper orthogonal decomposition (POD)

$$\underline{\underline{X}} = \begin{bmatrix} u(x_1, t_1) & u(x_2, t_1) & \dots & u(x_N, t_1) \\ u(x_1, t_2) & u(x_2, t_2) & \dots & u(x_N, t_2) \\ \vdots & \vdots & \dots & \vdots \\ u(x_1, t_T) & u(x_2, t_T) & \dots & u(x_N, t_T) \end{bmatrix}$$

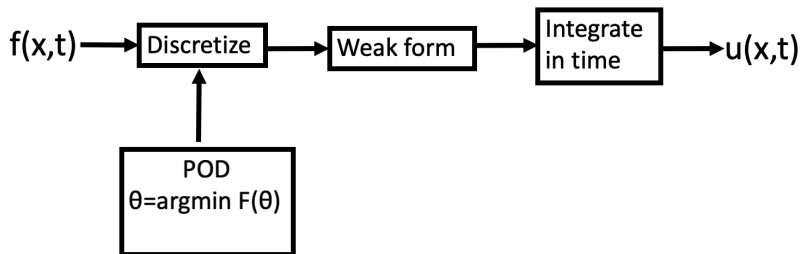
- POD is a common model reduction technique
- Uses data on a dynamical system to find an “optimal” set of spatial shape functions $\Psi_i(x)$ [8]
- Using our same notation, we could say abstractly that $\Psi_i(x) = \Psi_i(x; \theta)$ because they are computed from data

Operator structure with POD



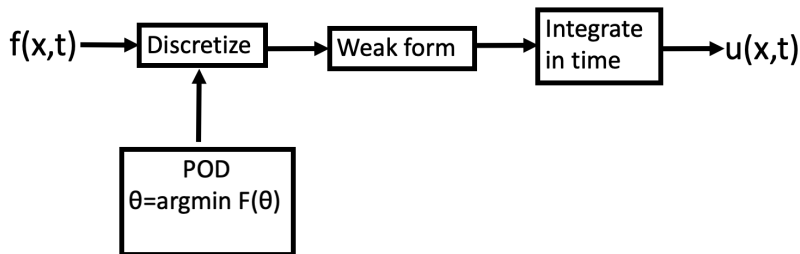
- Data used to compute the spatial shape functions $\Psi_i(x)$

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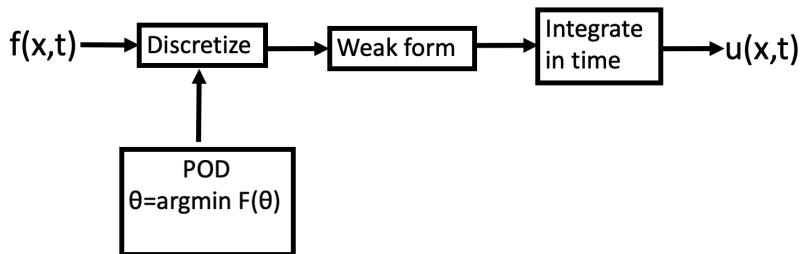
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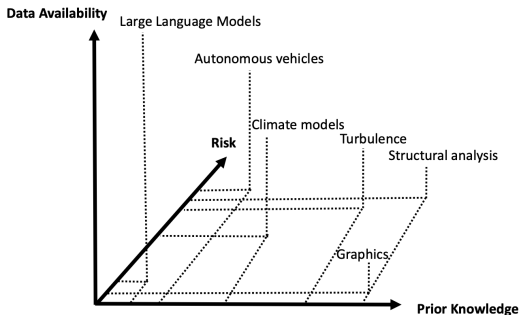
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- These inform the “Discretize” step in the operator
- Assumption is that shape functions computed from one forcing will “generalize” to others
- Data plays a more complex role in forming the solution operator than determining a single constitutive parameter, but physics still enforced

Final thought: classifying models along three dimensions



- Talked about data and generalization...are there other things to consider?
- Risk refers to the “cost” associated with model error—this depends on the application and determines the importance of generalization
- More prior knowledge of the problem → more “hard-coded” structure in operator → less data needed → more predictable generalization

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- More structured operators hard-code rules and will tend to generalize better and more predictably
- When deploying a model in the “real world,” it is necessary to consider risk
- Data-driven models are best-suited for situations with high data availability, minimal prior knowledge, and low risk

Thanks!

Questions? Comments? Concerns?

- [1] Kuhn, T. S., The structure of Scientific Revolutions, Chicago, Ill: The University of Chicago Press, 2015.
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- [3] Toulmin, S. E., and Goodfield, J., The fabric of the heavens, Chicago: Univ. of Chicago Press, 1999.
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- [5] Anderson, C., "The end of theory: The Data Deluge makes the scientific method obsolete," Wired Available: [here](#)
- [6] Lu, L., Jin, P., Pang, G., Zhang, Z., and Karniadakis, G. E., "Learning nonlinear operators via DeepONet based on the universal approximation theorem of operators," Nature Machine Intelligence, vol. 3, Mar. 2021.

- [7] Goswami, S., Bora, A., Yu, Y., Karniadakis, G.E., “Physics-Informed Deep Neural Operator Networks,” Springer, 2023.
- [8] Kutz, N., “Optimal basis elements: the POD expansion,” YouTube Available: [here](#)

Images, in order of appearance

Neural network, available [here](#)

Gravitational constant, available [here](#)

Plato's academy, available [here](#)

Vienna Circle, available [here](#)

Crazy plot, available [here](#)

Boring presentation, available [here](#)

Babylonian tablet, available [here](#)

Ptolemaic system, available [here](#)

Copernican system, available [here](#)

Generalization error, available [here](#)